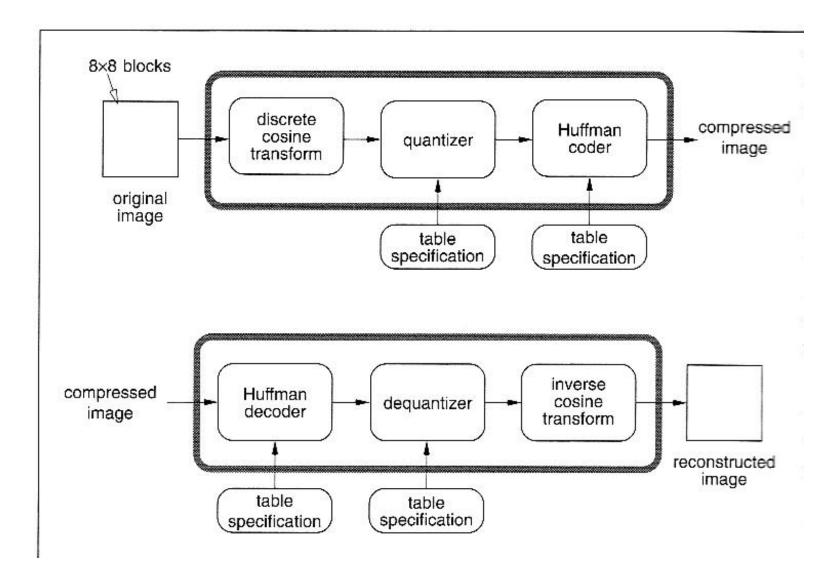
Wavelet Transform

CS6025 Data Encoding

Yizong Cheng

2-5-15

JPEG Encoding and Decoding



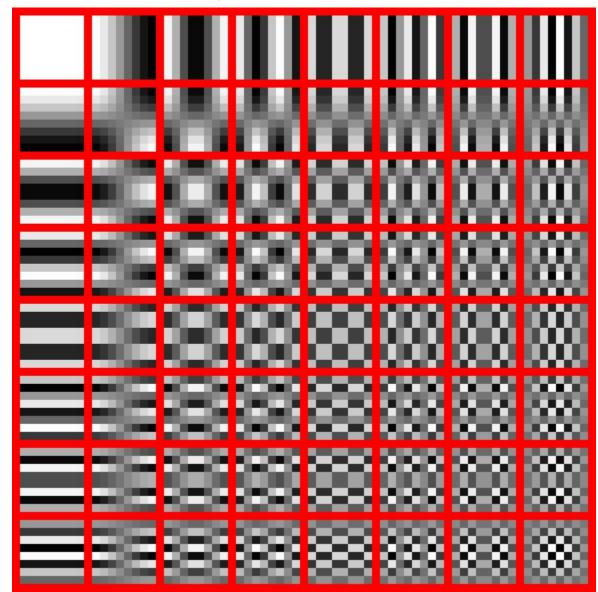
Discrete Cosine Transform

$$G_{ij} = \frac{1}{4} C_i C_j \sum_{x=0}^{7} \sum_{y=0}^{7} p_{xy} \cos\left(\frac{(2x+1)i\pi}{16}\right) \cos\left(\frac{(2y+1)j\pi}{16}\right),$$
where $C_f = \begin{cases} \frac{1}{\sqrt{2}}, & f = 0, \\ 1, & f > 0, \end{cases}$ and $0 \le i, j \le 7.$

Inverse DCT

$$p_{xy} = \frac{1}{4} \sum_{i=0}^{7} \sum_{j=0}^{7} C_i C_j G_{ij} \cos\left(\frac{(2x+1)i\pi}{16}\right) \cos\left(\frac{(2y+1)j\pi}{16}\right)$$
where $C_f = \begin{cases} \frac{1}{\sqrt{2}}, & f = 0; \\ 1, & f > 0. \end{cases}$

DCT Components wikipedia



Practical DCT

- components can be pre-calculated.
- amounts to three 8x8 matrices multiplied together.
- VLSI chips may accelerate transform.
- Purpose of DCT: The eye is more sensitive to low frequency components.
- G_{00} is the mean, or DC component
- Others are AC components.

JPEG Quantization

- Each of the 64 frequency components in a data unit is divided by a separate quantization coefficient (QC) and rounded to the nearest integer.
- These 64 integers are encoded using both run length and selfdelimiting coding.

Quantization Coefficients

16	11	10	16	24	40	51	61	17	18	24	47	99	99	99	
12	12	14	19	26	58	60	55	18	21	26	66	99	99	99	
14	13	16	24	40	57	69	56	24	26	56	99	99	99	99	
14	17	22	29	51	87	80	62	47	66	99	99	99	99	99	
18	22	37	56	68	109	103	77	99	99	99	99	99	99	99	
24	35	55	64	81	104	113	92	99	99	99	99	99	99	99	
49	64	78	87	103	121	120	101	99	99	99	99	99	99	99	
72	92	95	98	112	100	103	99	99	99	99	99	99	99	99	

Luminance

Chrominance

A Typical Quantization Result

1118	2	0	0	0	0	0	0
0	0	0	0	0	0	0	0
-2	0	0	-1	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

Zigzag Order of Components

Coding DC Components

- 1118 = row 11 column 930
- 111111111110 01110100010
- 11 1's, a zero, 11-bit binary 930

0									0	0:
10								1	-1	1:
110						3	2	-2	-3	2:
1110		7	6	5	4	-4	-5	-6	-7	3:
11110	15	 10	9	8	-8	-9	* * *	-14	-15	4:
111110	31	 17	16	-16	-17		-29	-30	-31	5:
1111110	63	 33	32	-32	-33		-61	-62	-63	6:
11111110	127	 65	64	-64	-65		-125	-126	-127	7:
1111111111111110	16383	 8193	8192	-8192	-8193		-16381	-16382	-16383	14:
111111111111111110	32767	 16385	16384	-16384	-16385		-32765	-32766	-32767	15:
111111111111111111									32768	16:

Differences of DC Components

- After the first data unit, DC components are represented by their differences to the previous DC components.
- A difference of -4 is at row 3 column 3 and is encoded as 1110 011.

Coding AC Components

- For each nonzero component x, find the number Z of consecutive zeros preceding x.
- Find x resides at row R and column C.
- C is written as an R-bit number, concatenated by the code for (Z,R) in the following table.

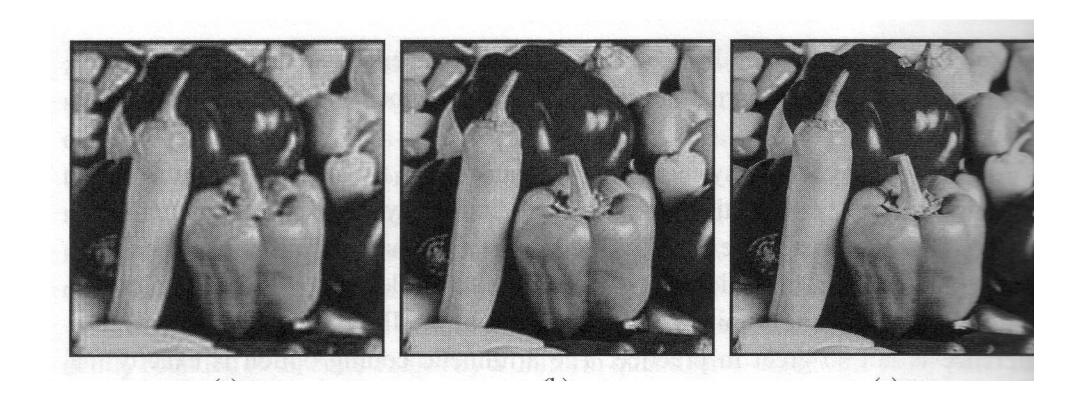
The (Z, R) Table

	88		R		
Z	1	2	3	4	5
	6	7	8	9	A
0	00	01	100	1011	11010
_	1111000	11111000	1111110110	11111111110000010	11111111110000011
1	1100	11011	11110001	111110110	11111110110
	11111111110000100	11111111110000101	11111111110000110	11111111110000111	11111111110001000
2	11100	11111001	1111110111	111111110100	1111111110001001
	1111111110001010	1111111110001011	1111111110001100	1111111110001101	1111111110001110
3	111010	111110111	1111111110101	11111111110001111	11111111110010000
	11111111110010001	1111111110010010	11111111110010011	11111111110010100	111111111110010101
4	111011	1111111000	11111111110010110	11111111110010111	11111111110011000
	11111111110011001	11111111110011010	11111111110011011	111111111100111100	111111111110011101
5	1111010	111111110111	11111111110011110	1111111110011111	11111111110100000
	11111111110100001	11111111110100010	11111111110100011	11111111110100100	111111111110100101
6	1111011	111111110110	11111111110100110	11111111110100111	11111111110101000
	11111111110101001	11111111110101010	111111111110101011	11111111110101100	111111111110101101
7	11111010	1111111110111	11111111110101110	11111111110101111	11111111110110000
	11111111110110001	11111111110110010	111111111110110011	11111111110110100	111111111110110101
8	111111000	1111111111000000	11111111110110110	11111111110110111	11111111110111000
	11111111110111001	111111111110111010	111111111110111011	11111111110111100	111111111110111101

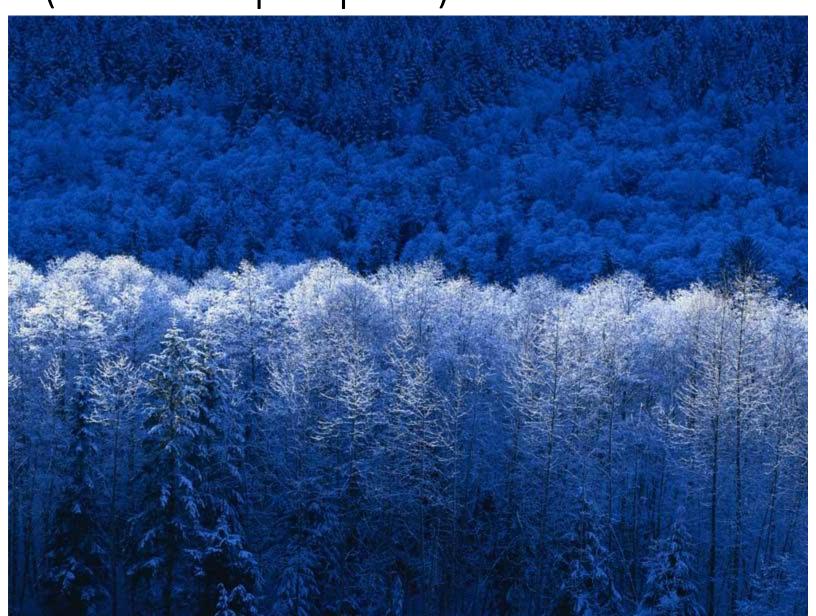
JFIF

- Graphics file format for JPEG
- divided into marker segments
- The first 2 bytes in each segment is the marker ffxx with xx from c0 to fe
- begins with marker ffd8 and ends with ffd9
- Segments specifying quantization and Huffman code.
- Scans ffda with concatenated codewords for symbols that are zero runs-size followed by size many bits.

JPEG with .1, .2, and 1 bit/pixel



Winter.jpg 800x600 105,542 bytes (1.76 bits per pixel)



Complexity of DCT

- Discrete cosine transform can be decomposed into that applied on rows followed by that applied on columns.
- Each is a linear transform representable by the matrix $M_{ij} = \cos((2j+1)i \pi/N)$.
- DCT on NxN block requires 2N³ multiplications and additions and is very time-consuming.
- JPEG uses DCT only on 8x8 blocks.

Matrix Multiplication

- To complete a 1D DCT transform, the following for loops are needed.
- for (i=0;i<N;i++){ y[i]=0;
- for (j=0;j<N;j++) y[i]+=x[j]*M[i][j];
- }
- This requires N² multiplications.
- This has to be done for every column and thus the complexity of N³.

M with k non-zeros each row

- What happens if M has a lot of zeros?
- Suppose there are only k non-zeros each row. The number of multiplications for 1D transform will be reduced to kN.
- We can even reformulate the double for loop so that the number of iterations is reduced to kN.
- The over all complexity is $O(N^2)$, not $O(N^3)$

The Quadrature Mirror Filter

```
h_0 h_1 h_2 h_3 0 0 0 0 ... 0 0
0 \ 0 \ h_0 \ h_1 \ h_2 \ h_3 \ 0 \ 0 \dots 0 \ 0
• • •
h_2 h_3 0 0 0 0 0 0 ... h_0 h_1
h_1 - h_0 0 0 0 0 0 \dots h_3 - h_2
• • •
0 \ 0 \ \dots \ 0 \ h_3 - h_2 \ h_1 - h_0 \ 0 \ 0
0 \ 0 \ \dots \ 0 \ 0 \ h_3 \ -h_2 \ h_1 \ -h_0
```

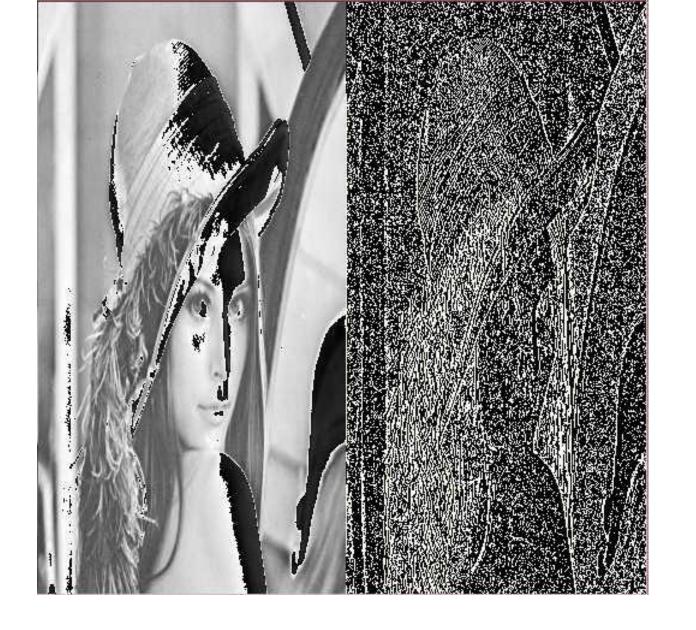
Orthonormal QMF

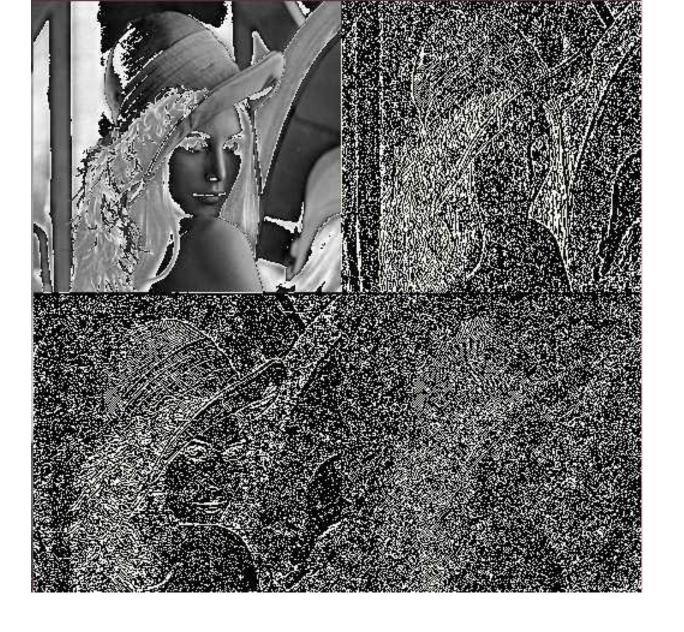
- M is orthonomal so M⁻¹=M^T.
- To be normalized, $h_0^2 + h_1^2 + h_2^2 + h_3^2 = 1$.
- Innerproducts of columns are zero.
- Innerproducts of rows $h_0h_2+h_1h_3=0$.
- Wave should be smooth (Daubechies):
- $h_0-h_1+h_2-h_3=0$
- $4h_0-3h_1+2h_2-h_3=0$
- h_0 =0.483, h_1 =0.837, h_2 =0.224, h_3 =-0.129.

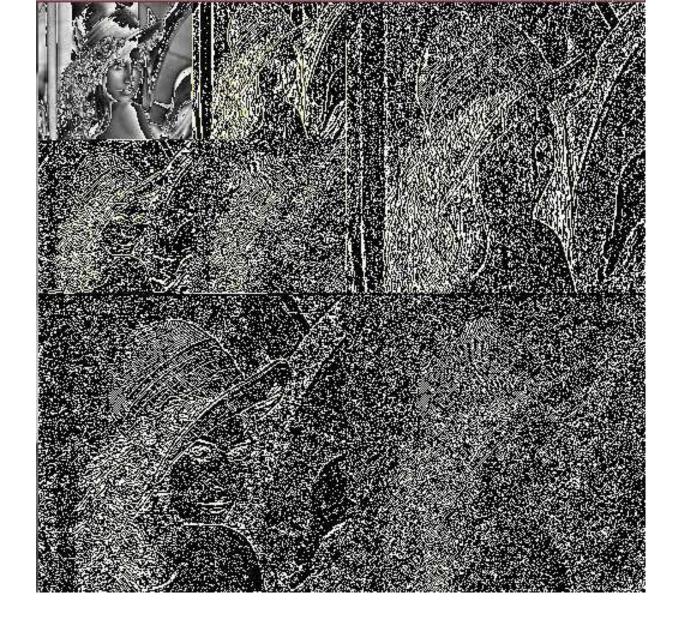
Wavelets with Integer Arithmetic

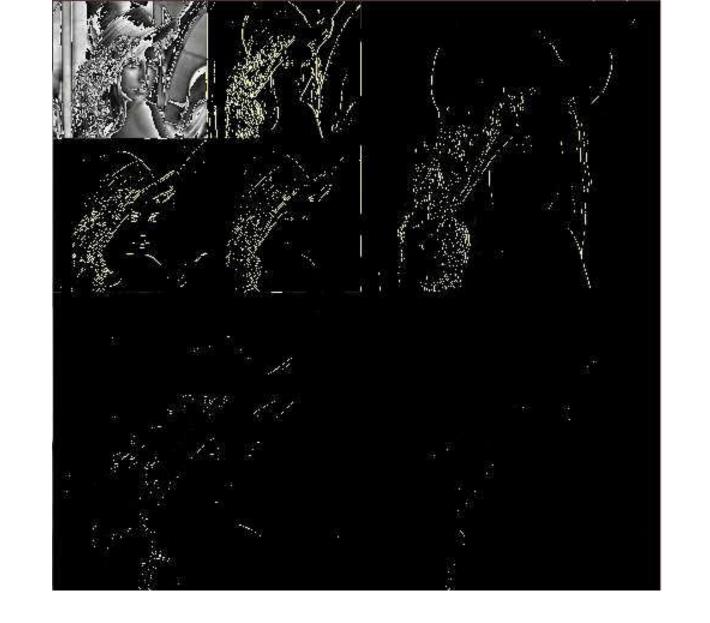
- Approximates spline wavelets.
- Can be implemented using integer arithmetic.
- Lossless and reversible for digital images.
- mandatory for JPEG2000
- Indexing requires symmetric extension of the arrays.









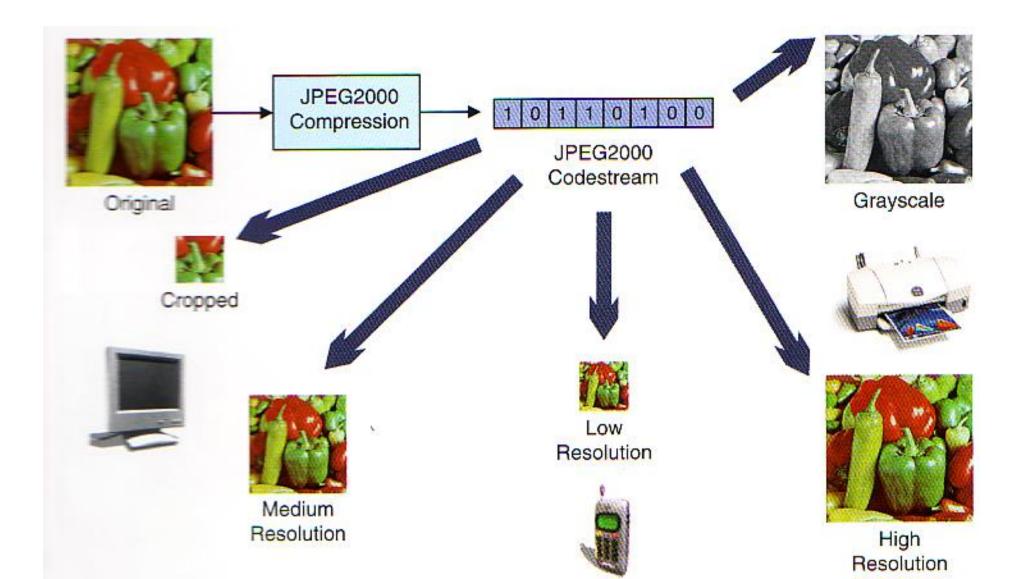




JPEG2000

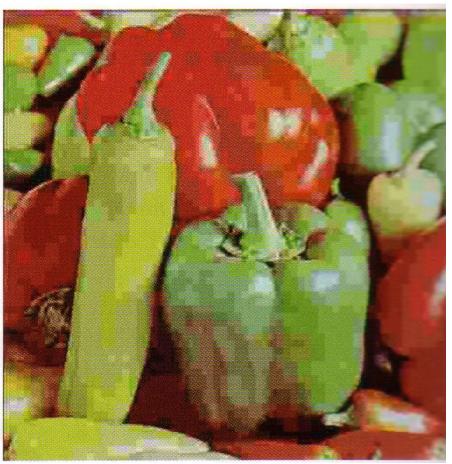
- Single codestream for lossy and lossless compression of various resolutions.
- Locate, extract, and decode only the bytes of the desired image product.
- Uses wavelet transform.
- The minimum decoder supports the (9,7) wavelet transform and the (5,3) wavelet transform.

JPEG2000 Functionality

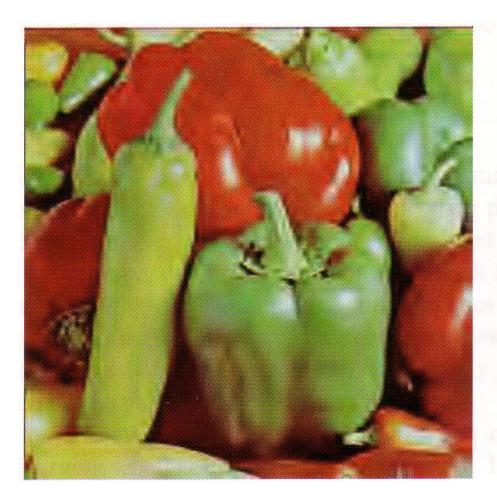


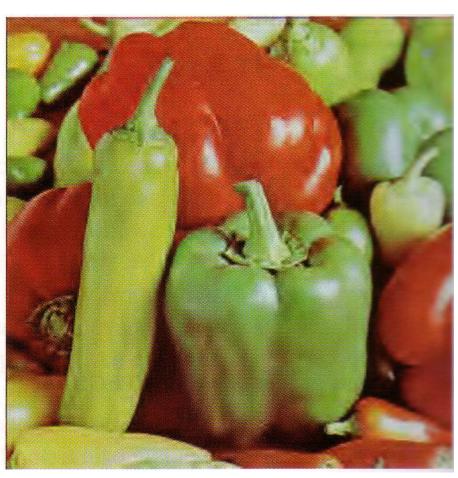
JPEG at 0.088 and 0.155 bpp





JPEG2000 at 0.088/0.155 bpp





(5,3) Wavelet Transform

$$C(2i+1) = P(2i+1) - \left\lfloor \frac{P(2i) + P(2i+2)}{2} \right\rfloor, \quad \text{for } k-1 \le 2i+1 < m+1,$$

$$C(2i) = P(2i) + \left\lfloor \frac{C(2i-1) + C(2i+1) + 2}{4} \right\rfloor, \quad \text{for } k \le 2i < m+1.$$

Figure 8.70: Extending a Row of Pixels.

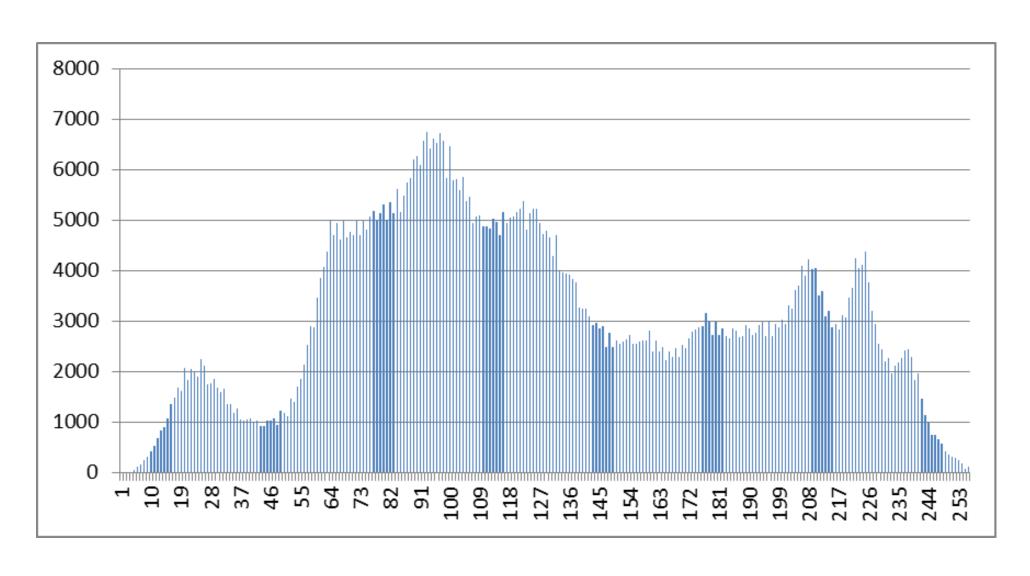
(5,3) Transform on Rows

```
void rowTransform(){
  int halfWidth = width / 2;
  for (int k = 0; k < 3; k++)
   for (int i = 0; i < height; i++){
    for (int j = 0; j < halfWidth - 1; j++)
      coeffs[i][2 * j + 1][k] = raw[i][2 * j + 1][k] -
       (raw[i][2 * j][k] + raw[i][2 * j + 2][k]) / 2;
    coeffs[i][width - 1][k] =
      raw[i][width - 1][k] - raw[i][width - 2][k];
    for (int j = 1; j < halfWidth; j++)
      coeffs[i][2 * i][k] = raw[i][2 * i][k] +
  (coeffs[i][2 * j - 1][k] + coeffs[i][2 * j + 1][k] + 2) / 4;
    coeffs[i][0][k] = raw[i][0][k] + (coeffs[i][1][k] + 1) / 2;
```

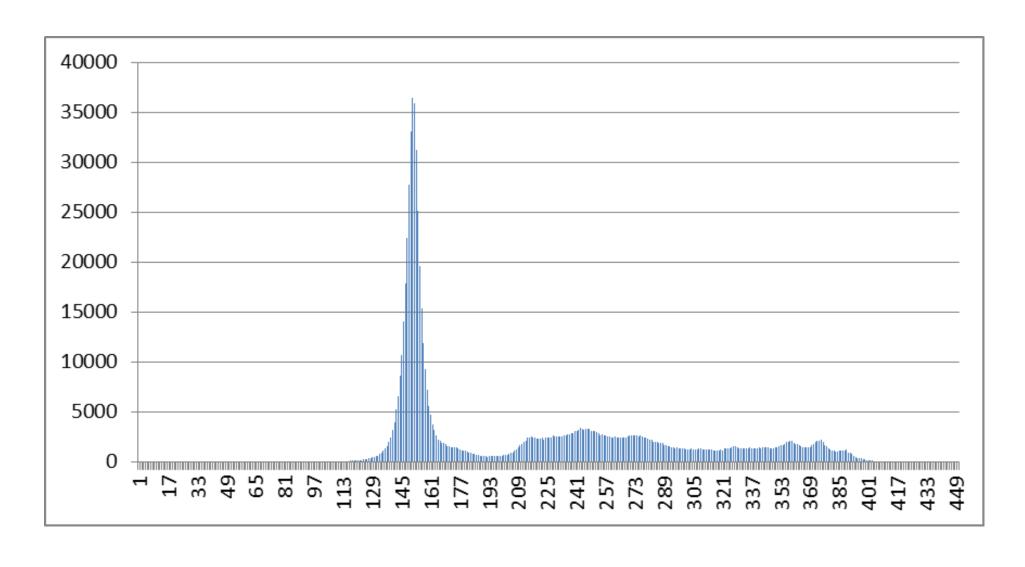
LenaRGB.bmp 512x512, 24-bit



Lena Pixel Values Entropy = 7.75



Lena Row (5,3) Wavelet entropy = 7.17



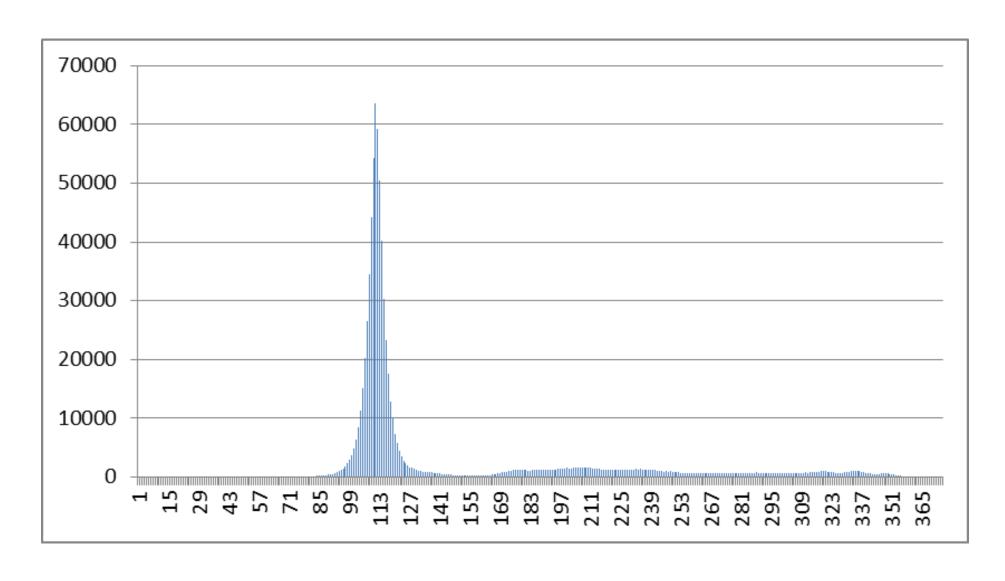
Inverse of Row Transform

```
void reverseRowTransform(){
  int halfWidth = width / 2;
  for (int k = 0; k < 3; k++)
   for (int i = 0; i < height; i++){
    raw[i][0][k] = coeffs[i][0][k] - (coeffs[i][1][k] + 1) / 2;
    for (int j = 1; j < halfWidth; j++)
      raw[i][2 * j][k] = coeffs[i][2 * j][k] -
  (coeffs[i][2 * j - 1][k] + coeffs[i][2 * j + 1][k] + 2) / 4;
    raw[i][width - 1][k] =
      coeffs[i][width - 1][k] + raw[i][width - 2][k];
    for (int j = 0; j < halfWidth - 1; j++)
      raw[i][2 * j + 1][k] = coeffs[i][2 * j + 1][k] +
       (raw[i][2 * j][k] + raw[i][2 * j + 2][k]) / 2;
```

(5,3) Transform on Columns

```
void columnTransform(){
  int halfHeight = height / 2;
  for (int k = 0; k < 3; k++)
   for (int j = 0; j < width; j++){
    for (int i = 0; i < halfHeight - 1; i++)
      raw[2 * i + 1][j][k] = coeffs[2 * i + 1][j][k] -
       (coeffs[2 * i][j][k] + coeffs[2 * i + 2][j][k]) / 2;
    raw[height - 1][j][k] = coeffs[height - 1][j][k] - coeffs[height - 2][j][k];
    for (int i = 1; i < halfHeight; i++)
      raw[2 * i][j][k] = coeffs[2 * i][j][k] +
       (raw[2 * i - 1][j][k] + raw[2 * i + 1][j][k] + 2) / 4;
    raw[0][j][k] = coeffs[0][j][k] + (raw[1][j][k] + 1) / 2;
```

Lena Row and Column Entropy = 6.08



Shrinkage: LenaRGB with 71% zeros

```
void shrink(){
  int threshold = 12;
  for (int k = 0; k < 3; k++)
    for (int i = 0; i < height; i++)
     for (int j = 0; j < width; j++){
      if (i \% 2 > 0 || j \% 2 > 0){
        if (raw[i][j][k] > 0 \& raw[i][j][k] <= threshold) raw[i][j][k] = 0;
        if (raw[i][j][k] < 0 \& raw[i][j][k] >= -threshold) raw[i][j][k] = 0;
        if (raw[i][j][k] != 0) raw[i][j][k] = raw[i][j][k] / 8 + 128;
    if (raw[i][j][k] < 0) raw[i][j][k] = 0;
    if (raw[i][j][k] > 255) raw[i][j][k] = 255;
```

Lossy Inverse of Shrinkage

```
void unshrink(){
  for (int k = 0; k < 3; k++)
    for (int i = 0; i < height; i++)
    for (int j = 0; j < width; j++)
    if (i % 2 > 0 || j % 2 > 0)
        if (raw[i][j][k] > 0)
        raw[i][j][k] = (raw[i][j][k] - 128) * 8;
}
```

Homework 8: due 2-11-15

- Implement the inverse of H8A.columnTransform() as H8B.reverseColumnTransform() and make H8B the inverse of H8A.
- H8A and H8B are (5,3)-wavelet transform and its inverse of rows and columns of an image with RGB colors.
- Recover the original image from test8.bmp.