

# **ASSINGMENT 9**

**A graph G is defined as a pair (V, E) where V is a set of nodes/vertices and E is a set of edges connecting**

**pairs of vertices. Graphs may be directed or undirected and may have weighted or unweighted edges.**

**They can be represented using an adjacency matrix, adjacency list, or edge list.**

**Write a program to implement the following graph algorithms:**

- 1. Breadth First Search (BFS)**
- 2. Depth First Search (DFS)**
- 3. Minimum Spanning Tree (Kruskal and Prim)**
- 4. Dijkstra's Shortest Path Algorithm**

```
#include <iostream>
#include <vector>
#include <queue>
#include <algorithm>
using namespace std;

class Graph {
public:
    int V;
    vector<vector<pair<int,int>>> adj; // node, weight

    Graph(int v) {
        V = v;
    }
}
```

```

adj.resize(V);

}

void addEdge(int u, int v, int w=1, bool undirected=true) {
    adj[u].push_back({v, w});
    if (undirected)
        adj[v].push_back({u, w});
}

// ----- BFS -----
void BFS(int start) {
    vector<bool> visited(V, false);
    queue<int> q;

    visited[start] = true;
    q.push(start);

    cout << "BFS: ";
    while (!q.empty()) {
        int node = q.front();
        q.pop();
        cout << node << " ";

        for (auto &nbr : adj[node]) {
            if (!visited[nbr.first]) {
                visited[nbr.first] = true;
                q.push(nbr.first);
            }
        }
    }
}

```

```

        }
    }

    cout << endl;
}

// ----- DFS -----
void dfsUtil(int node, vector<bool>& visited) {
    visited[node] = true;
    cout << node << " ";

    for (auto &nbr : adj[node]) {
        if (!visited[nbr.first])
            dfsUtil(nbr.first, visited);
    }
}

void DFS(int start) {
    vector<bool> visited(V, false);
    cout << "DFS: ";
    dfsUtil(start, visited);
    cout << endl;
}

// ----- Kruskal (MST) -----
struct Edge {

    int u, v, w;
};

```

```

int findSet(int x, vector<int>& parent) {
    if (parent[x] == x)
        return x;
    return parent[x] = findSet(parent[x], parent);
}

void unionSet(int u, int v, vector<int>& parent, vector<int>& rank) {
    u = findSet(u, parent);
    v = findSet(v, parent);

    if (rank[u] < rank[v])
        parent[u] = v;
    else if (rank[v] < rank[u])
        parent[v] = u;
    else {
        parent[v] = u;
        rank[u]++;
    }
}

void Kruskal() {
    vector<Edge> edges;

    // Convert adjacency list to edge list
    for (int u = 0; u < V; u++) {
        for (auto &p : adj[u]) {
            int v = p.first, w = p.second;
            if (u < v) edges.push_back({u, v, w});
        }
    }
}

```

```

    }

}

sort(edges.begin(), edges.end(),
[]](Edge a, Edge b) { return a.w < b.w; });

vector<int> parent(V), rank(V, 0);
for (int i = 0; i < V; i++)
    parent[i] = i;

cout << "Kruskal MST:\n";
int mst_cost = 0;

for (auto &e : edges) {
    int pu = findSet(e.u, parent);
    int pv = findSet(e.v, parent);

    if (pu != pv) {
        cout << e.u << " - " << e.v << " (w=" << e.w << ")\n";
        mst_cost += e.w;
        unionSet(pu, pv, parent, rank);
    }
}

cout << "Total weight = " << mst_cost << "\n";
}

// ----- Prim (MST) -----

```

```

void Prim(int start) {

    vector<int> key(V, 1e9), parent(V, -1);
    vector<bool> inMST(V, false);

    key[start] = 0;
    priority_queue<pair<int,int>, vector<pair<int,int>>, greater<pair<int,int>>> pq;
    pq.push({0, start});

    cout << "Prim MST:\n";

    while (!pq.empty()) {
        int u = pq.top().second;
        pq.pop();
        inMST[u] = true;

        for (auto &p : adj[u]) {
            int v = p.first, w = p.second;

            if (!inMST[v] && w < key[v]) {
                key[v] = w;
                parent[v] = u;
                pq.push({w, v});
            }
        }
    }

    int cost = 0;
    for (int v = 0; v < V; v++) {

```

```

    if (parent[v] != -1) {
        cout << parent[v] << " - " << v << " (w=" << key[v] << ")\n";
        cost += key[v];
    }
}

cout << "Total weight = " << cost << "\n";
}

// ----- Dijkstra -----
void Dijkstra(int src) {
    vector<int> dist(V, 1e9);
    dist[src] = 0;

    priority_queue<pair<int,int>, vector<pair<int,int>>, greater<pair<int,int>>> pq;
    pq.push({0, src});

    while (!pq.empty()) {
        auto top = pq.top(); pq.pop();
        int d = top.first;
        int u = top.second;

        if (d > dist[u]) continue;

        for (auto &p : adj[u]) {
            int v = p.first, w = p.second;

            if (dist[u] + w < dist[v]) {

```

```

        dist[v] = dist[u] + w;
        pq.push({dist[v], v});
    }
}

cout << "Dijkstra from " << src << ":\n";
for (int i = 0; i < V; i++)
    cout << "Distance to " << i << " = " << dist[i] << endl;
}

int main() {
    int V = 6;
    Graph g(V);

    // Sample weighted graph
    g.addEdge(0, 1, 4);
    g.addEdge(0, 2, 1);
    g.addEdge(2, 1, 2);
    g.addEdge(1, 3, 5);
    g.addEdge(2, 3, 8);
    g.addEdge(3, 4, 6);
    g.addEdge(4, 5, 3);

    cout << "==== GRAPH ALGORITHMS ===\n\n";

    g.BFS(0);
}

```

```
g.DFS(0);

cout << "\n--- Minimum Spanning Trees ---\n";
g.Kruskal();
cout << endl;
g.Prim(0);

cout << "\n--- Dijkstra Shortest Path ---\n";
g.Dijkstra(0);

return 0;
}
```

```
==== GRAPH ALGORITHMS ====
```

```
BFS: 0 1 2 3 4 5
```

```
DFS: 0 1 2 3 4 5
```

```
--- Minimum Spanning Trees ---
```

```
Kruskal MST:
```

```
0 - 2 (w=1)
```

```
1 - 2 (w=2)
```

```
4 - 5 (w=3)
```

```
1 - 3 (w=5)
```

```
3 - 4 (w=6)
```

```
Total weight = 17
```

```
Prim MST:
```

```
2 - 1 (w=2)
```

```
0 - 2 (w=1)
```

```
1 - 3 (w=5)
```

```
3 - 4 (w=6)
```

```
4 - 5 (w=3)
```

```
Total weight = 17
```

```
--- Dijkstra Shortest Path ---
```

```
Dijkstra from 0:
```

```
Distance to 0 = 0
```

```
Distance to 1 = 3
```

```
Distance to 2 = 1
```

```
Distance to 3 = 8
```

```
Distance to 4 = 14
```

```
Distance to 5 = 17
```