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Performance portable FDTD Implementation

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Overview

1.	Governing	equations

2. Field Discretization

3. Particle Discretization and Interpolation

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Ι.	Governing	equations

2. Field Discretization

3. Particle Discretization and Interpolation

4. Outlool

Field Update

Define the four potential $A^{\alpha}=(\phi,\mathbf{A})$ which evolves according to a wave equation:

$$\frac{\partial^2 A^{\alpha}}{\partial t^2} = \Delta A^{\alpha} + S^{\alpha}$$
 where $S^{\alpha} = (\rho, \mathbf{J})$

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 where $S^{\alpha} = (\rho, \mathbf{J})$

The magnetic and electric fields can be evaluated with

$$\mathbf{E} = -\nabla \phi - \frac{\partial \mathbf{A}}{\partial t}$$

2. Field Discretization

3. Particle Discretization and Interpolation

4. Outlool

Stencil

Use a three-point second derivative stencil:

$$\frac{\partial^2 A^{\alpha}}{\partial \beta^2}(\vec{x}) \approx \frac{1}{\beta^2} \left(A^{\alpha}(\vec{x} + \beta) - 2A^{\alpha}(\vec{x}) + A^{\alpha}(\vec{x} - \beta) \right)$$

where β is an arbitrary vector.

In a cartesian grid this simplifies to

$$\frac{\partial^2 A^\alpha}{\partial x^2}(\vec{x}) \approx \frac{1}{\Delta x^2} \left(A^\alpha_{i+1,\dots} - 2 A^\alpha_{i,\dots} + A^\alpha_{i-1,\dots} \right)$$

where i is the index corresponding to the direction of x

FDTD Formulation

$$\begin{split} \frac{\partial^2 \psi(x,y,z,t)}{\partial x^2} &= \frac{\psi^n_{i+1,j,k} - 2\psi^n_{i,j,k} + \psi^n_{i-1,j,k}}{\Delta x^2} \\ \frac{\partial^2 \psi(x,y,z,t)}{\partial y^2} &= \frac{\psi^n_{i,j+1,k} - 2\psi^n_{i,j,k} + \psi^n_{i,j-1,k}}{\Delta y^2} \\ \frac{\partial^2 \psi(x,y,z,t)}{\partial z^2} &= \frac{\psi^n_{i,j,k+1} - 2\psi^n_{i,j,k} + \psi^n_{i,j,k-1}}{\Delta z^2} \\ \frac{\partial^2 \psi(x,y,z,t)}{\partial t^2} &= \frac{\psi^n_{i,j,k} - 2\psi^n_{i,j,k} + \psi^{n-1}_{i,j,k}}{\Delta t^2} \end{split}$$

where ψ represents a component of the four-potential.

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where ψ represents a component of the four-potential.

Only unknown: $\psi_{i,j,k}^{n+1}$.

Consider the one-dimensional analytical function around $x_0 = 0$

$$f(x) = f(0) + xf'(0) + \frac{x^2}{2}f''(0) + \frac{x^3}{6}f'''(0) + \frac{x^4}{24}f''''(0) + \mathcal{O}(\Delta x^5)$$

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$$+ f(0) - \Delta x f'(0) + \frac{\Delta x^2}{2} f''(0) - \frac{\Delta x^3}{6} f'''(0) + \frac{\Delta x^4}{24} f''''(0) + \mathcal{O}(\Delta x^5)$$

$$-2f(0) = \Delta x^2 f''(0) + \frac{\Delta x^4}{12} f''''(0) + \mathcal{O}_E(\Delta x^6)$$

where \mathcal{O}_E implies only even terms.

We therefore can see that

$$\frac{1}{\Delta x^2} \left(f(\Delta x) + f(-\Delta x) - 2f(0) \right) = f''(0) + \frac{\Delta x^2}{12} f''''(0) + \mathcal{O}_E(\Delta x^4)$$

approximates the second derivative of f in 0 with an error that is proportional to f''''(0)

Consider the 1D wave equation

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial^2 f}{\partial t^2}$$
$$f(t = 0, x) = \sin(\pi x)$$

with periodic boundary conditions defined on [-1, 1].

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with periodic boundary conditions defined on [-1, 1]. Analytical solution:

$$\begin{split} f(t,x) &= &\sin(\pi x)\cos(\pi t)\\ \text{implying} &\frac{\partial^4 f}{\partial x^4}(0) = \pi^4\sin(\pi x)\cos(\pi t)\\ \text{and} & f(1,x) = -\sin(\pi x) \end{split}$$

Evolving this equation numerically with $\Delta x \neq \Delta t$ up to t = 1 yields

$$f_n(1,x) = -\sin(\pi x) + k\frac{\Delta t}{\Delta t}(\Delta x^2) + \mathcal{O}(\Delta x^4)$$

Due to linearity, we can separate the evolution of the exact solution and the error.

$$f_n(1,x) = -\sin(\pi x) + k\Delta x^2 + \mathcal{O}_E(\Delta x^4)$$

$$\implies f_n(2,x) = \sin(\pi x) - k\Delta x^2 + k\Delta x^2 + \mathcal{O}_{12}(\Delta x^4) + \mathcal{O}_E(\Delta x^4)$$

$$= \sin(\pi x) + \mathcal{O}(\Delta x^4)$$

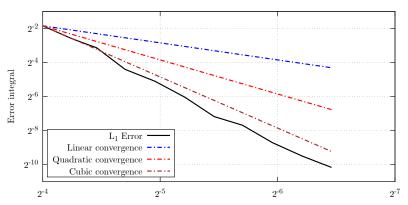
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$$= \sin(\pi x) + \mathcal{O}(\Delta x^4)$$

 L_1 Error after 2 time units



Additionally, in the case of $\Delta t = \Delta x$, the numerical wave operator

$$\frac{1}{\Delta x^2} \left(A^{\alpha}_{i+1,...} - 2A^{\alpha}_{i,...} + A^{\alpha}_{i-1,...}\right) - \frac{1}{\Delta t^2} \left(A^{\alpha}_{...,n+1} - 2A^{\alpha}_{...,n} + A^{\alpha}_{...,n-1}\right)$$

reduces to zero for the exact solution

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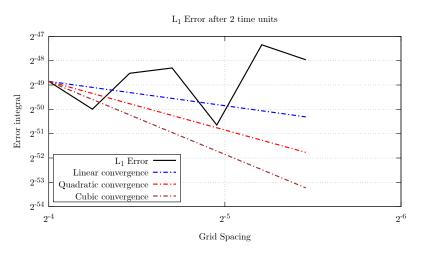
$$f(t,x) = \sin(\pi x)\cos(\pi t)$$

because the even derivatives cancel:

$$\frac{\partial^{2n} f(t, x)}{\partial t^{2n}} = \frac{\partial^{2n} f(t, x)}{\partial x^{2n}} = \pi^{2n} \sin(\pi x) \cos(\pi t)$$

Exact stepper

This results in machine precision accuracy for any grid spacing:



Boundary conditions

Absorbing boundary conditions: Custom timestep rule on the boundary.

Mathematical formulation:

$$\left(\frac{\partial}{\partial x} - \frac{\partial}{\partial t}\right)\psi\bigg|_{x=0} = 0 \text{ according to Mur [1981]}$$
 (1)

$$\left(\frac{\partial^2}{\partial x \partial t} - \frac{\partial^2}{\partial t^2}\right) \psi \bigg|_{x=0} = 0 \text{ according to according to Fallahi [2020]}$$
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Equation 2 can be used for boundaries with $\frac{\partial \psi}{\partial x}$, i.e. external fields:

$$\mathbf{E} = \mathbf{e}_x$$
 $\phi = x$

is a stationary solution only for 2.

Initial conditions

For an initial source term

$$S = \begin{bmatrix} \rho_0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

we solve the poisson equation

$$-\Delta\phi = \rho_0$$

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For inital conditions with one moving particle:

$$\begin{split} \phi(\vec{r},0) &= \frac{q}{4\pi(1-\vec{\beta}\cdot\vec{n})||\vec{r}-\vec{R}(t_{ret})||} \\ \text{and } \mathbf{A}(\vec{r},0) &= \phi(r,0)\vec{\beta}_{ret} \end{split}$$

where
$$t_{ret} = -||\vec{r} - \vec{R}(t_{ret})||$$

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For p particles and n gridpoints: $\mathcal{O}(p \cdot n)$!

2. Field Discretization

3. Particle Discretization and Interpolation

4. Outlook

Particle Update

Lorentz Force:

$$\vec{F_L} = q \mathbf{E} + q \vec{v} \times \mathbf{B}$$

Lorentz acceleration:

$$\vec{a_L} = \frac{q}{m_r} \mathbf{E} + q \vec{v} \times \mathbf{B}$$

where $m_r = \gamma m_0$

Particle timestep

Boris update scheme with boosted E and B: Fallahi [2020]

$$(r^m, \gamma \beta^{m-\frac{1}{2}}) \to (r^{m+1}, \gamma \beta^{m+\frac{1}{2}})$$

$$\mathbf{t}_1 = \gamma \beta^{m-\frac{1}{2}} + \frac{e\Delta t_b \mathbf{E}_t^m}{2m}$$

$$\vdots$$

$$\mathbf{r}^{m+1} = r^m + \frac{\Delta t_b \gamma \beta^{m+\frac{1}{2}}}{\sqrt{1 + \|\gamma \beta^{m+\frac{1}{2}}\|^2}}$$

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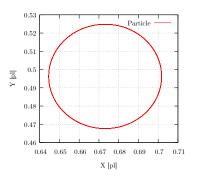
$$\mathbf{r}^{m+1} = r^m + \frac{\Delta t_b \gamma \beta^{m+\frac{1}{2}}}{\sqrt{1 + \|\gamma \beta^{m+\frac{1}{2}}\|^2}}$$

Note that

$$\beta = \frac{\gamma \beta}{\sqrt{1 + \|\gamma \beta\|^2}}$$
$$\gamma = \sqrt{1 + \|\gamma \beta\|^2}$$

Test of Boris Stepper

Setup: Shoot charged particle in constant z-aligned magnetic field



- · Traces a perfect circle
- · Conserves energy up to machine precision

Particle Discretization

Interpolation of a particle attribute to the grid: For a particle with position

$$p = \begin{bmatrix} p_x \\ p_y \\ p_z \end{bmatrix} = \begin{bmatrix} \begin{vmatrix} \frac{p_x}{\Delta x} \\ \frac{p_y}{\Delta y} \\ \frac{p_z}{\Delta z} \end{vmatrix} \Delta y + \delta_y \\ \frac{p_z}{\Delta z} \begin{vmatrix} \Delta z + \delta_z \\ \Delta z + \delta_z \end{bmatrix} = \begin{bmatrix} i\Delta x + \delta_x \\ j\Delta x + \delta_y \\ k\Delta x + \delta_z \end{bmatrix}$$
(3)

the Cloud-In-Cell interpolation is done as follows

$$\rho_{i+I,j+J,k+K}^{p} = \rho \left(\frac{1}{2} + (-1)^{I} \left| \frac{1}{2} - \frac{\delta x}{\Delta x} \right| \right) \left(\frac{1}{2} + (-1)^{J} \left| \frac{1}{2} - \frac{\delta y}{\Delta y} \right| \right) \left(\frac{1}{2} + (-1)^{K} \left| \frac{1}{2} - \frac{\delta z}{\Delta z} \right| \right) \tag{4}$$

with $(I, J, K) \in \{0, 1\}^3$.

Gathering field attributes

Interpolating field attributes to particles works analogously:

$$\psi^{P} = \sum_{I,I,K \in \left\{0,1\right\}^{3}} \psi\left(\frac{1}{2} + (-1)^{I} \bigg| \frac{1}{2} - \frac{\delta x}{\Delta x} \bigg|\right) \left(\frac{1}{2} + (-1)^{J} \bigg| \frac{1}{2} - \frac{\delta y}{\Delta y} \bigg|\right) \left(\frac{1}{2} + (-1)^{K} \bigg| \frac{1}{2} - \frac{\delta z}{\Delta z} \bigg|\right)$$

Current Deposition

Cloud-In-Cell deposition of current: We define the deposition point p^m as the midpoint between two adjacent timesteps:

$$p^{m} = \begin{bmatrix} \frac{p_{x}^{n} + p_{x}^{n+1}}{p_{x}^{n} + p_{y}^{n}} \\ \frac{p_{y}^{n} + p_{y}^{n+1}}{2} \\ \frac{p_{x}^{n} + p_{z}^{n+1}}{2} \end{bmatrix} = \begin{bmatrix} \frac{p_{x}^{m}}{\Delta x} & \Delta x + \delta_{x} \\ \frac{p_{y}^{m}}{\Delta y} & \Delta y + \delta_{y} \\ \frac{p_{z}^{m}}{\Delta z} & \Delta z + \delta_{z} \end{bmatrix}$$
 (5)

$$\mathbf{J}_{i+I,j+J,k+K}^{p} = \rho \mathbf{v} \left(\frac{1}{2} + (-1)^{I} \left| \frac{1}{2} - \frac{\delta x}{\Delta x} \right| \right) \left(\frac{1}{2} + (-1)^{J} \left| \frac{1}{2} - \frac{\delta y}{\Delta y} \right| \right) \left(\frac{1}{2} + (-1)^{K} \left| \frac{1}{2} - \frac{\delta z}{\Delta z} \right| \right)$$
(6)

where
$$\mathbf{v} = \frac{r^{m+1} - r^{m-1}}{2\Delta t}$$
 (7)

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where
$$\mathbf{v} = \frac{r^{m+1} - r^{m-1}}{2\Delta t}$$
 (7)

If a particle travels across a cell boundary, this scheme violates

$$\nabla \cdot \mathbf{E} = \rho$$
 (8)

Boris Correction

To satisfy

$$\nabla \cdot \mathbf{E} = \rho$$

we simply add a correction term equivalent to the negative error Lehe [2016]:

$$\mathbf{E}' = \mathbf{E} - \nabla \delta \phi \text{ with } \nabla \cdot (\nabla \delta \phi) = \nabla \cdot \mathbf{E} - \rho \tag{9}$$

Zigzag Current Deposition

Alternatively change current deposition scheme: Particle motion from p_1 to p_2 is decomposed into two separate movements, p_1 to p_r and p_r to p_2 Fallahi [2020].

$$\begin{split} x_T &= \min \left(\min(i_1 \Delta x, i_2 \Delta x) + \Delta_x, \max \left(\min(i_1 \Delta x, i_2 \Delta x), \frac{x_1 + x_2}{2} \right) \right) \\ y_T &= \min \left(\min(j_1 \Delta x, j_2 \Delta y) + \Delta_y, \max \left(\min(j_1 \Delta y, j_2 \Delta y), \frac{y_1 + y_2}{2} \right) \right) \\ z_T &= \min \left(\min(k_1 \Delta x, k_2 \Delta z) + \Delta_z, \max \left(\min(k_1 \Delta z, k_2 \Delta z), \frac{z_1 + z_2}{2} \right) \right) \end{split}$$

Then two Cloud-In-Cell interpolations of with points $\frac{p_1+p_r}{2}$ and $\frac{p_r+p_2}{2}$ Umeda et al. [2003] satisfy the conservation of current.

Test of current deposition and field update

Idea: Compare simulated radiation to Larmor:

$$P = \frac{q^2}{6\pi} \gamma^6 (||\dot{\vec{\beta}}||^2 - ||\vec{\beta} \times \dot{\vec{\beta}}||^2)$$

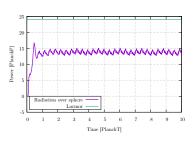


Figure: $\sigma_{init} = 0.02$

Setup:

- · Initialize particles with gaussian distribution
- Rotate particles around center with fixed speed.

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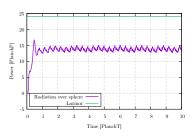


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Observations:

- · Constant outward radiation
- · Different particle trajectories interfere destructively

Test of current deposition and field update

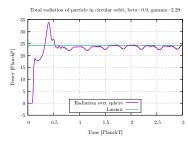


Figure: $\sigma_{init} = 0.005$

Setup:

- · Initialize particles with gaussian distribution
- · Rotate particles around center with fixed speed.

Observations:

- · Constant outward radiation
- · Different particle trajectories interfere destructively

Test of coupled field and particle update

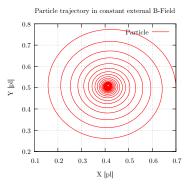


Figure: $\sigma_{init} = 0.0$

Setup:

- · Initialize particles with gaussian distribution
- \cdot Let particles be guided by Lorentz force

Observations:

· Particle progressively loses energy and spirals inward

Test of coupled field and particle update

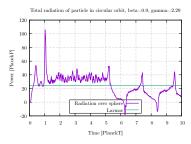


Figure: $\sigma_{init} = 0.0$

Setup:

- · Initialize particles with gaussian distribution
- · Let particles be guided by Lorentz force

Observations:

· Constant outward radiation up until all energy is lost

1. Governing equations

2. Field Discretization

3. Particle Discretization and Interpolation

4. Outlook

Undulators and Lorentz boosts

Transformation of undulator fields:

$$\mathbf{B}_{lab}(\mathbf{r}) = \begin{bmatrix} 0 \\ B_0 \cosh(k \cdot y_{lab}) \sin(k \cdot z_{lab}) \\ B_0 \sinh(k \cdot y_{lab}) \cos(k \cdot z_{lab}) \end{bmatrix}$$

Undulators and Lorentz boosts

Transformation of undulator fields:

$$\begin{aligned} \mathbf{B}_{lab}(\mathbf{r}) &= \begin{bmatrix} 0 \\ B_0 \cosh\left(k \cdot y_{lab}\right) \sin\left(k \cdot z_{lab}\right) \\ B_0 \sinh\left(k \cdot y_{lab}\right) \cos\left(k \cdot z_{lab}\right) \end{bmatrix} \\ r_{lab} &= \mathbf{\Lambda}^{-1}(r_{bunch}) \\ \mathbf{E}_{bunch} &= \gamma(\mathbf{E}_{lab} + \mathbf{v} \times \mathbf{B}_{lab}) - (\gamma - 1) \left(\mathbf{E}_{lab} \cdot \frac{\mathbf{v}}{||\mathbf{v}||}\right) \\ \mathbf{B}_{bunch} &= \gamma(\mathbf{B}_{lab} - \mathbf{v} \times \mathbf{E}_{lab}) - (\gamma - 1) \left(\mathbf{B}_{lab} \cdot \frac{\mathbf{v}}{||\mathbf{v}||}\right) \\ \text{or equivalently } \mathbf{F}_{bunch}^{\alpha\beta} &= \mathbf{\Lambda}_{\alpha}^{\beta} \mathbf{F}_{lab}^{\alpha\beta} \mathbf{\Lambda}_{\beta}^{\alpha} \\ \text{code:} \\ \\ \text{lorentzBoost < double > boost ({0.0, 0.0, 0.99});} \\ // \text{Lab to bunch frame} \\ \text{ippl :: Matrix < double, 4, 4> mat = boost.unprimedToPrimed ();} \end{aligned}$$

In code:

Resampling

Assign weight w_i to each particle p_i .

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$$\sum_{i=1}^{N_b} w_i^b = \sum_{j=1}^{N_a} w_j^a$$

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Preferrably also conserve

$$\overline{\mathbf{r}} = \sum_{i=1}^{N} \frac{\mathbf{r_i}}{N}$$
 (Center of mass)

$$\sigma = \sum_{i=1}^{N} \frac{(\mathbf{r_i} - \overline{\mathbf{r}})}{N} \quad \text{(Variance)}$$

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