

CSE 323: Operating System Design

Condition Variable & Semaphore

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Original slides by Mathias Payer and Sanidhya Kashyap [EPFL]

- Condition Variables
- Producer-Consumer Problem
- Semaphores
- Signaling through condition Variables and Semaphores
- Concurrency Bugs

This slide deck covers chapters 30, 31, 32 in OSTEP.

Condition Variables (CV)

In concurrent programming, a common scenario is one thread waiting for another thread to complete an action.

```
1  bool done = false;
2
3  /* called in the child to signal termination */
4  void thr_exit() {
5      done = true;
6  }
7  /* called in the parent to wait for a child thread */
8  void thr_join() {
9      while (!done);
10 }
```

Condition Variables (CV)

- Locks enable mutual exclusion of a shared region.
 - Unfortunately they are oblivious to ordering
- Waiting and signaling (i.e., T2 waits until T1 completes a given task) could be implemented by spinning until the value changes

Condition Variables (CV)

- Locks enable mutual exclusion of a shared region.
 - Unfortunately they are oblivious to ordering
- Waiting and signaling (i.e., T2 waits until T1 completes a given task) could be implemented by spinning until the value changes
- But spinning is incredibly *inefficient*
- New synchronization primitive: ***condition variables***

Condition Variables (CV)

- A CV allows:
 - A thread to wait for a condition
 - Another thread signals the waiting thread
- Implement CV using queues

Condition Variables (CV)

- A CV allows:
 - A thread to wait for a condition
 - Another thread signals the waiting thread
- Implement CV using queues
- API: wait, signal or broadcast
 - wait: wait until a condition is satisfied
 - signal: wake up one waiting thread
 - broadcast: wake up all waiting threads
- On Linux, pthreads provides CV implementation

Signal parent that child has exited

```
1  bool done = false;
2  pthread_mutex_t m = PTHREAD_MUTEX_INITIALIZER;
3  pthread_cond_t c = PTHREAD_COND_INITIALIZER;
4  /* called in the child to signal termination */
5  void thr_exit() {
6      pthread_mutex_lock(&m);
7      done = true;
8      pthread_cond_signal(&c);
9      pthread_mutex_unlock(&m);
10 }
11 /* called in the parent to wait for a child thread */
12 void thr_join() {
13     pthread_mutex_lock(&m);
14     while (!done)
15         pthread_cond_wait(&c, &m);
16     pthread_mutex_unlock(&m);
17 }
```


Signal parent that child has exited (2)

- `pthread_cond_wait(pthread_cond_t *c, pthread_mutex_t *m)`
 - Assume mutex `m` is held; *atomically* unlock mutex when waiting, retake it when waking up
- Question: Why do we need to check a condition before sleeping?

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- Thread may have already exited, i.e., no need to wait
 - Principle: Check the condition before sleeping
- Question: Why can't we use `if` when waiting?
- There can be multiple threads to wait on the same CV. **Race Condition!**
 - Principle: `while` instead of `if` when waiting (more on this later...)

Signal parent that child has exited (3)

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Signal parent that child has exited (3)

- Question: Why do we need to protect done with mutex m ?
- Mutex m allows one thread to access done for protecting against missed updates
 - Parent reads `done == false` but is interrupted
 - Child sets `done = true` and signals but no one is waiting
 - Parent continues and goes to sleep (forever)
- Lock is therefore required for wait/signal synchronization

Producer/Consumer Problem

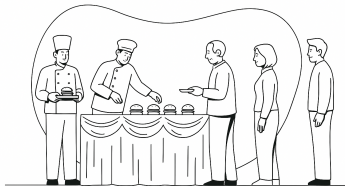


Figure 1: Producer-Consumer/Bounded Buffer Problem

- Producer/consumer is a common programming pattern
- For example: map (producers) / reduce (consumer)
- For example: a concurrent database (consumers) handling parallel requests from clients (producers)
 - Clients produce new requests (encoded in a queue)
 - Handlers consume these requests (popping from the queue)

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 - Want concurrent production and consumption
 - Use as many cores as available
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Producer/Consumer with Bounded Buffer

- One or more producers create items, store them in buffer
- One or more consumers process items from buffer
- Need synchronization for buffer
 - Want concurrent production and consumption
 - Use as many cores as available
 - Minimize access time to shared data structure
- Strategy: use CV to synchronize
 - Make producers wait if buffer is full
 - Make consumers wait if buffer is empty (nothing to consume)

Solving Producer/Consumer Problem

- **Setup:**
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 - One producer and one consumer

Solving Producer/Consumer Problem

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```
int buffer;
int count = 0; // initially empty

void put(int value) {
    assert(count == 0);
    count = 1;
    buffer = value;
}

int get() {
    assert(count == 1);
    count = 0;
    return buffer;
}
```

```
void *producer(void *arg) {
    int i;
    int loops = (int) arg;
    for (i = 0; i < loops; i++) {
        put(i);
    }
}

void *consumer(void *arg) {
    while (1) {
        int tmp = get();
        printf("%d\n", tmp);
    }
}
```

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```

- **Problems with this solution**

- Critical sections in put() and get(). **Use locks...**

Solving Producer/Consumer Problem

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}
```

- **Problems with this solution**

- Critical sections in put() and get(). **Use locks...**
- Producer-Consumer dependency for fetching. **Needs CV!**

Solving Producer/Consumer Problem

```
cond_t cond;
mutex_t mutex;

void *producer(void *arg) {
    int i;
    int loops = (int) arg;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        if (count == 1)
            Pthread_cond_wait(&cond, &mutex);
        put(i);
        Pthread_cond_signal(&cond);
        Pthread_mutex_unlock(&mutex);
    }
}

void *consumer(void *arg) {
    int i;
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    for (i = 0; i < loops; i++) {
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    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        if (count == 0)
            Pthread_cond_wait(&cond, &mutex);
        int tmp = get();
        Pthread_cond_signal(&cond);
        Pthread_mutex_unlock(&mutex);
        printf("%d\n", tmp);
    }
}
```

Does it work?

- Fine for single producer and single consumer.
- Change the setup to accommodate multiple producers and/or multiple consumers. How about now?

Solving Producer/Consumer Problem (2)

- **Setup:**

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No recheck after waking up.

- Consider a consumer thread (C1) is waiting for an item
- What if a second consumer thread (C2) sneaks in just after an item is produced? ... skipping the wait() call.
- Producer's signal() wakes C1 up, but C2 already fetched the item!
- Solution: Use while instead of if to recheck upon waking up.

Solving Producer/Consumer Problem (2)

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- Consider a consumer thread (C1) is waiting for an item
- What if a second consumer thread (C2) sneaks in just after an item is produced? ... skipping the `wait()` call.
- Producer's `signal()` wakes C1 up, but C2 already fetched the item!
- Solution: Use `while` instead of `if` to recheck upon waking up.

Producers and consumers both waiting on the same CV.

- Two consumers C1 and C2 runs and sleeps by calling `wait()`.
- Producer runs and `signal()` wakes up C1 (or C2).
- After consuming the item C1 can wake up producer again.
- But what if C1's `signal()` wakes up C2 instead?
- Solution: Use separate conditions for directed signaling.

Solving Producer/Consumer Problem (2)

```
cond_t empty, full;
mutex_t mutex;

void *producer(void *arg) {
    int i;
    int loops = (int) arg;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        while (count == 1)
            Pthread_cond_wait(&empty, &mutex);
        put(i);
        Pthread_cond_signal(&full);
        Pthread_mutex_unlock(&mutex);
    }
}

void *consumer(void *arg) {
    int i;
    int loops = (int) arg;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        while (count == 0)
            Pthread_cond_wait(&full, &mutex);
        int tmp = get();
        Pthread_cond_signal(&empty);
        Pthread_mutex_unlock(&mutex);
        printf("%d\n", tmp);
    }
}
```

Producer/Consumer Buffer with Multiple Slots

```
int buffer[MAX];
int fill_ptr = 0;
int use_ptr = 0;
int count = 0;

void put(int value) {
    buffer[fill_ptr] = value;
    fill_ptr = (fill_ptr + 1) % MAX;
    count++;
}
```

```
int get() {
    int tmp = buffer[use_ptr];
    use_ptr = (use_ptr + 1) % MAX;
    count--;
    return tmp;
}
```

```
cond_t empty, fill;
mutex_t mutex;
```

```
void *producer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        while (count == MAX)
            Pthread_cond_wait(&empty, &mutex);
        put(i);
        Pthread_cond_signal(&fill);
        Pthread_mutex_unlock(&mutex);
    }
}
```

```
void *consumer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        while (count == 0)
            Pthread_cond_wait(&fill, &mutex);
        int tmp = get();
        Pthread_cond_signal(&empty);
        Pthread_mutex_unlock(&mutex);
        printf("%d\n", tmp);
    }
}
```

Semaphore

- A semaphore extends a CV with an integer as internal state
- `int sem_init(sem_t *sem, unsigned int value):`
creates a new semaphore with value slots
- `int sem_wait(sem_t *sem):` waits until the semaphore has at least one slot, decrements the number of slots
- `int sem_post(sem_t *sem):` increments the semaphore (and wakes one waiting thread)
- `int sem_destroy(sem_t *sem):` destroys the semaphore and releases any waiting threads

Producer/Consumer: Use Semaphores!

```
sem_t csem, psem;
```

```
/* BUFSIZE items are available for producer to create */  
sem_init(&psem, 0, BUFSIZE);
```

```
/* 0 items are available for consumer */  
sem_init(&csem, 0, 0);
```

Producer: Semaphores

```
1 void put(unsigned int val) {
2     /* we wait until there is buffer space available */
3     sem_wait(&psem);
4
5     /* store element in buffer */
6     buffer[ppos] = val;
7     ppos = (ppos + 1) % BUFSIZE;
8
9     /* notify consumer that data is available */
10    sem_post(&csem);
11 }
```


Consumer: Semaphores

```
1  unsigned int get() {
2      /* wait until data is produced */
3      sem_wait(&csem);
4
5      /* consumer entry */
6      unsigned long val = buffer[cpos];
7      cpos = (cpos + 1) % BUFSIZE;
8
9      /* notify producer that a space has freed up */
10     sem_post(&psem);
11     return val;
12 }
```

Producer/Consumer: Remaining Issues?

- We now synchronize between consumers and producers
 - Producer waits until buffer space is available
 - Consumer waits until data is ready

Producer/Consumer: Remaining Issues?

- We now synchronize between consumers and producers
 - Producer waits until buffer space is available
 - Consumer waits until data is ready
- How would you handle multiple producers/consumers?
 - Currently no synchronization between producers (or consumers)

Multiple Producers: Use Locking!

```
/* mutex handling mutual exclusive access to ppos */
1  pthread_mutex_t pmutex = PTHREAD_MUTEX_INITIALIZER;
2
3  void put(unsigned int val) {
4      unsigned int mypos;
5      /* we wait until there is buffer space available */
6      sem_wait(&psem);
7      /* ppos is shared between all producers */
8      pthread_mutex_lock(&pmutex);
9      mypos = ppos;
10     ppos = (ppos + 1) % BUFSIZE;
11     /* store information in buffer */
12     buffer[mypos] = val;
13     pthread_mutex_unlock(&pmutex);
14     sem_post(&csem);
15 }
```

Semaphores/Spin Locks/CVs are interchangeable

- Each is implementable through a combination of the others
- Depending on the use-case one is faster than the other
 - How often is the critical section executed?
 - How many threads compete for a critical section?
 - How long is the lock taken?

Implementing a Mutex with a Semaphore

```
1 sem_t sem;  
2 sem_init(&sem, 1);  
3  
4 sem_wait(&sem);  
5 ... // critical section  
6 sem_post(&sem);
```

Implementing a Semaphore with CV/Locks

```
1  typedef struct {
2      int value;           // sem value
3      pthread_mutex_t lock; // access to sem
4      pthread_cond_t cond;  // wait queue
5  } sem_t;
6
7  void sem_init(sem_t *s, int val) {
8      s->value = val;
9      pthread_mutex_init(&(s->lock), NULL);
10     pthread_cond_init(&(s->cond), NULL);
11 }
```

Implementing a Semaphore with CV/Locks

```
1  void sem_wait(sem_t *s) {
2      pthread_mutex_lock(&(s->lock));
3      while (s->value <= 0)
4          pthread_cond_wait(&(s->cond), &(s->lock));
5      s->value--;
6      pthread_mutex_unlock(&(s->lock));
7  }
8
9  void sem_post(sem_t *s) {
10     pthread_mutex_lock(&(s->lock));
11     s->value++;
12     pthread_cond_signal(&(s->cond));
13     pthread_mutex_unlock(&(s->lock));
14 }
```


Reader/Writer Locks

- A single (exclusive) writer, multiple (N) concurrent readers
- Implement using two semaphores: `lock` for the data structure, `wlock` for the writer
 - Both semaphores initialized with (1)
 - Writer only waits/posts on `wlock` when acquiring/releasing
 - Reader waits on `lock`, increments/decrements reader count
 - If number of readers==0, must wait/post on `wlock`

Reader/Writer Locks

```
1 void rwlock_acquire_readlock(rwlock_t *rw) {
2     sem_wait(&rw->lock);
3     rw->readers++;
4     if (rw->readers == 1)
5         sem_wait(&rw->wlock); // first r, also grab wlock
6     sem_post(&rw->lock);
7 }
8
9 void rwlock_release_readlock(rwlock_t *rw) {
10    sem_wait(&rw->lock);
11    rw->readers--;
12
13    if (rw->readers == 0)
14        sem_post(&rw->wlock); // last r, also release wlock
15    sem_post(&rw->lock);
16 }
```

Bugs in concurrent programs

- Writing concurrent programs is hard!
- **Atomicity bug:** concurrent, unsynchronized modification (lock!)
- **Order-violating bug:** data is accessed in wrong order (use CV!)
- **Deadlock:** program no longer makes progress (locking order)

Atomicity bugs

One thread checks value and prints it while another thread concurrently modifies it.

```
1  int shared = 24;
2
3  void T1() {
4      if (shared > 23) {
5          printf("Shared is >23: %d\n", shared);
6      }
7  }
8  void T2() {
9      shared = 12;
10 }
```

Atomicity bugs

One thread checks value and prints it while another thread concurrently modifies it.

```
1  int shared = 24;
2
3  void T1() {
4      if (shared > 23) {
5          printf("Shared is >23: %d\n", shared);
6      }
7  }
8  void T2() {
9      shared = 12;
10 }
```

- T2 may modify shared between if check and printf in T1.
- Fix: use a common mutex between both threads when accessing the shared resource.

Order-violating bug

One thread assumes the other has already updated a value.

Thread 1::

```
void init() {  
    mThread = PR_CreateThread(mMain, ...);  
    mThread->State = ...;  
}
```

Thread 2::

```
void mMain(...) {  
    mState = mThread->State;  
}
```

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One thread assumes the other has already updated a value.

Thread 1::

```
void init() {  
    mThread = PR_CreateThread(mMain, ...);  
    mThread->State = ...;  
}
```

Thread 2::

```
void mMain(...) {  
    mState = mThread->State;  
}
```

- Thread 2 may run before mThread is assigned in T1.
- Fix: use a CV to signal that mThread has been initialized.

Deadlock

Locks are taken in conflicting order.

```
void T1() {  
    lock(L1);  
    lock(L2);  
}
```

```
void T2() {  
    lock(L2);  
    lock(L1);  
}
```


Deadlock

Locks are taken in conflicting order.

```
void T1() {  
    lock(L1);  
    lock(L2);  
}
```

```
void T2() {  
    lock(L2);  
    lock(L1);  
}
```

- Threads 1/2 may be stuck after taking the first lock, program makes no more progress
- Fix: acquire locks in increasing (global) order.

- Spin lock, CV, and semaphore synchronize multiple threads
 - Spin lock: atomic access, no ordering, spinning
 - Condition variable: atomic access, queue, OS primitive
 - Semaphore: shared access to critical section with (int) state
- All three primitives are equally powerful
 - Each primitive can be used to implement both other primitives
 - Performance may differ!
- Synchronization is challenging and may introduce different types of bugs such as atomicity violation, order violation, or deadlocks.