

# CSE 323: Operating System Design

## Condition Variables

Salman Shamil



North South University (NSU)  
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Original slides by Mathias Payer and Sanidhya Kashyap [EPFL]

- Condition Variables
- Producer-Consumer Problem

This slide deck covers chapters 30 in OSTEP.

# Condition Variables (CV)

In concurrent programming, a common scenario is one thread waiting for another thread to complete an action.

```
1  bool done = false;
2
3  /* called in the child to signal termination */
4  void thr_exit() {
5      done = true;
6  }
7  /* called in the parent to wait for a child thread */
8  void thr_join() {
9      while (!done);
10 }
```

# Condition Variables (CV)

- Locks enable mutual exclusion of a shared region.
  - Unfortunately they are oblivious to ordering
- Waiting and signaling (i.e., T2 waits until T1 completes a given task) could be implemented by spinning until the value changes

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- Locks enable mutual exclusion of a shared region.
  - Unfortunately they are oblivious to ordering
- Waiting and signaling (i.e., T2 waits until T1 completes a given task) could be implemented by spinning until the value changes
- But spinning is incredibly *inefficient*
- New synchronization primitive: ***condition variables***

# Condition Variables (CV)

- A CV allows:
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  - Another thread signals the waiting thread
- Implement CV using queues

# Condition Variables (CV)

- A CV allows:
  - A thread to wait for a condition
  - Another thread signals the waiting thread
- Implement CV using queues
- API: wait, signal or broadcast
  - wait: wait until a condition is satisfied
  - signal: wake up one waiting thread
  - broadcast: wake up all waiting threads
- On Linux, pthreads provides CV implementation

# Signal parent that child has exited

```
1  bool done = false;
2  pthread_mutex_t m = PTHREAD_MUTEX_INITIALIZER;
3  pthread_cond_t c = PTHREAD_COND_INITIALIZER;
4  /* called in the child to signal termination */
5  void thr_exit() {
6      pthread_mutex_lock(&m);
7      done = true;
8      pthread_cond_signal(&c);
9      pthread_mutex_unlock(&m);
10 }
11 /* called in the parent to wait for a child thread */
12 void thr_join() {
13     pthread_mutex_lock(&m);
14     while (!done)
15         pthread_cond_wait(&c, &m);
16     pthread_mutex_unlock(&m);
17 }
```



## Signal parent that child has exited (2)

- `pthread_cond_wait(pthread_cond_t *c, pthread_mutex_t *m)`
  - Assume mutex `m` is held; *atomically* unlock mutex when waiting, retake it when waking up
- Question: Why do we need to check a condition before sleeping?

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  - Principle: Check the condition before sleeping
- Question: Why can't we use `if` when waiting?
- Multiple threads could be woken up, racing for done flag
  - Principle: `while` instead of `if` when waiting

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- Question: Why do we need to protect done with mutex  $m$ ?
- Mutex  $m$  allows one thread to access done for protecting against missed updates
  - Parent reads done == false but is interrupted
  - Child sets done = true and signals but no one is waiting
  - Parent continues and goes to sleep (forever)
- Lock is therefore required for wait/signal synchronization

# Producer/Consumer Problem

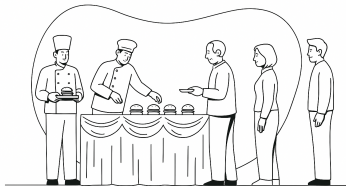


Figure 1: Producer-Consumer/Bounded Buffer Problem

- Producer/consumer is a common programming pattern
- For example: map (producers) / reduce (consumer)
- For example: a concurrent database (consumers) handling parallel requests from clients (producers)
  - Clients produce new requests (encoded in a queue)
  - Handlers consume these requests (popping from the queue)

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- One or more consumers process items from buffer
- Need synchronization for buffer
  - Want concurrent production and consumption
  - Use as many cores as available
  - Minimize access time to shared data structure
- Strategy: use CV to synchronize
  - Make producers wait if buffer is full
  - Make consumers wait if buffer is empty (nothing to consume)

# Solving Producer/Consumer Problem

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int buffer;
int count = 0; // initially empty

void put(int value) {
    assert(count == 0);
    count = 1;
    buffer = value;
}

int get() {
    assert(count == 1);
    count = 0;
    return buffer;
}
```

```
void *producer(void *arg) {
    int i;
    int loops = (int) arg;
    for (i = 0; i < loops; i++) {
        put(i);
    }
}

void *consumer(void *arg) {
    while (1) {
        int tmp = get();
        printf("%d\n", tmp);
    }
}
```

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- **Problems with this solution**

- Critical sections in put() and get(). **Use locks...**

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```

- **Problems with this solution**

- Critical sections in put() and get(). **Use locks...**
- Producer-Consumer dependency for fetching. **Needs CV!**

# Solving Producer/Consumer Problem

```
cond_t cond;
mutex_t mutex;

void *producer(void *arg) {
    int i;
    int loops = (int) arg;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        if (count == 1)
            Pthread_cond_wait(&cond, &mutex);
        put(i);
        Pthread_cond_signal(&cond);
        Pthread_mutex_unlock(&mutex);
    }
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void *consumer(void *arg) {
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            Pthread_cond_wait(&cond, &mutex);
        int tmp = get();
        Pthread_cond_signal(&cond);
        Pthread_mutex_unlock(&mutex);
        printf("%d\n", tmp);
    }
}
```

## Does it work?

- Fine for single producer and single consumer.
- Change the setup to accommodate multiple producers and/or multiple consumers. How about now?



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- **Setup:**

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## No recheck after waking up.

- Consider a consumer thread (C1) is waiting for an item
- What if a second consumer thread (C2) sneaks in just after an item is produced? ... skipping the wait() call.
- Producer's signal() wakes C1 up, but C2 already fetched the item!
- Solution: Use while instead of if to recheck upon waking up.

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- Consider a consumer thread (C1) is waiting for an item
- What if a second consumer thread (C2) sneaks in just after an item is produced? ... skipping the `wait()` call.
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- Solution: Use `while` instead of `if` to recheck upon waking up.

## Producers and consumers both waiting on the same CV.

- Two consumers C1 and C2 runs and sleeps by calling `wait()`.
- Producer runs and `signal()` wakes up C1 (or C2).
- After consuming the item C1 can wake up producer again.
- But what if C1's `signal()` wakes up C2 instead?
- Solution: Use separate conditions for directed signaling.

# Solving Producer/Consumer Problem (2)

```
cond_t empty, full;
mutex_t mutex;

void *producer(void *arg) {
    int i;
    int loops = (int) arg;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        while (count == 1)
            Pthread_cond_wait(&empty, &mutex);
        put(i);
        Pthread_cond_signal(&full);
        Pthread_mutex_unlock(&mutex);
    }
}

void *consumer(void *arg) {
    int i;
    int loops = (int) arg;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        while (count == 0)
            Pthread_cond_wait(&full, &mutex);
        int tmp = get();
        Pthread_cond_signal(&empty);
        Pthread_mutex_unlock(&mutex);
        printf("%d\n", tmp);
    }
}
```

# Producer/Consumer Buffer with Multiple Slots

```
int buffer[MAX];
int fill_ptr = 0;
int use_ptr = 0;
int count = 0;

void put(int value) {
    buffer[fill_ptr] = value;
    fill_ptr = (fill_ptr + 1) % MAX;
    count++;
}

int get() {
    int tmp = buffer[use_ptr];
    use_ptr = (use_ptr + 1) % MAX;
    count--;
    return tmp;
}

cond_t empty, fill;
mutex_t mutex;
```

```
void *producer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        while (count == MAX)
            Pthread_cond_wait(&empty, &mutex);
        put(i);
        Pthread_cond_signal(&fill);
        Pthread_mutex_unlock(&mutex);
    }
}

void *consumer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        Pthread_mutex_lock(&mutex);
        while (count == 0)
            Pthread_cond_wait(&fill, &mutex);
        int tmp = get();
        Pthread_cond_signal(&empty);
        Pthread_mutex_unlock(&mutex);
        printf("%d\n", tmp);
    }
}
```

- A semaphore extends a CV with an integer as internal state
- `int sem_init(sem_t *sem, unsigned int value):`  
creates a new semaphore with value slots
- `int sem_wait(sem_t *sem):` waits until the semaphore has at least one slot, decrements the number of slots
- `int sem_post(sem_t *sem):` increments the semaphore (and wakes one waiting thread)
- `int sem_destroy(sem_t *sem):` destroys the semaphore and releases any waiting threads