



ERGO THEOREM

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► **Theorem:** If X_t is a π -irreducible, π -invariant, Harris recurrent Markov chain, then for any integrable function $f : \mathbb{X} \rightarrow \mathbb{R}$ the following limit a.s. holds

$$\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T f(X_t) = \pi[f]$$

► Unlike the Monte Carlo estimator, this is biased for a finite time T

- Given a function $f: \mathbb{X} \rightarrow \mathbb{R}$ we can approximate expectation using the average

$$\hat{\pi}_T[f] = \frac{1}{T} \sum_{t=1}^T f(X_t)$$

► How long does it take to forget the initial distribution $X_0 \sim \mu$ and enter the stationary regime approximating the target π ?

► A μ -irreducible Markov chain X_t is Harris recurrent if $\forall x \in \mathbb{X}$, and $\mu(A) > 0$,

$$\mathbb{P}_x \left[\sum_t 1_A(X_t) = \infty \right] = 1$$

ERGODIC THEOREM

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MIXING-TIME

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