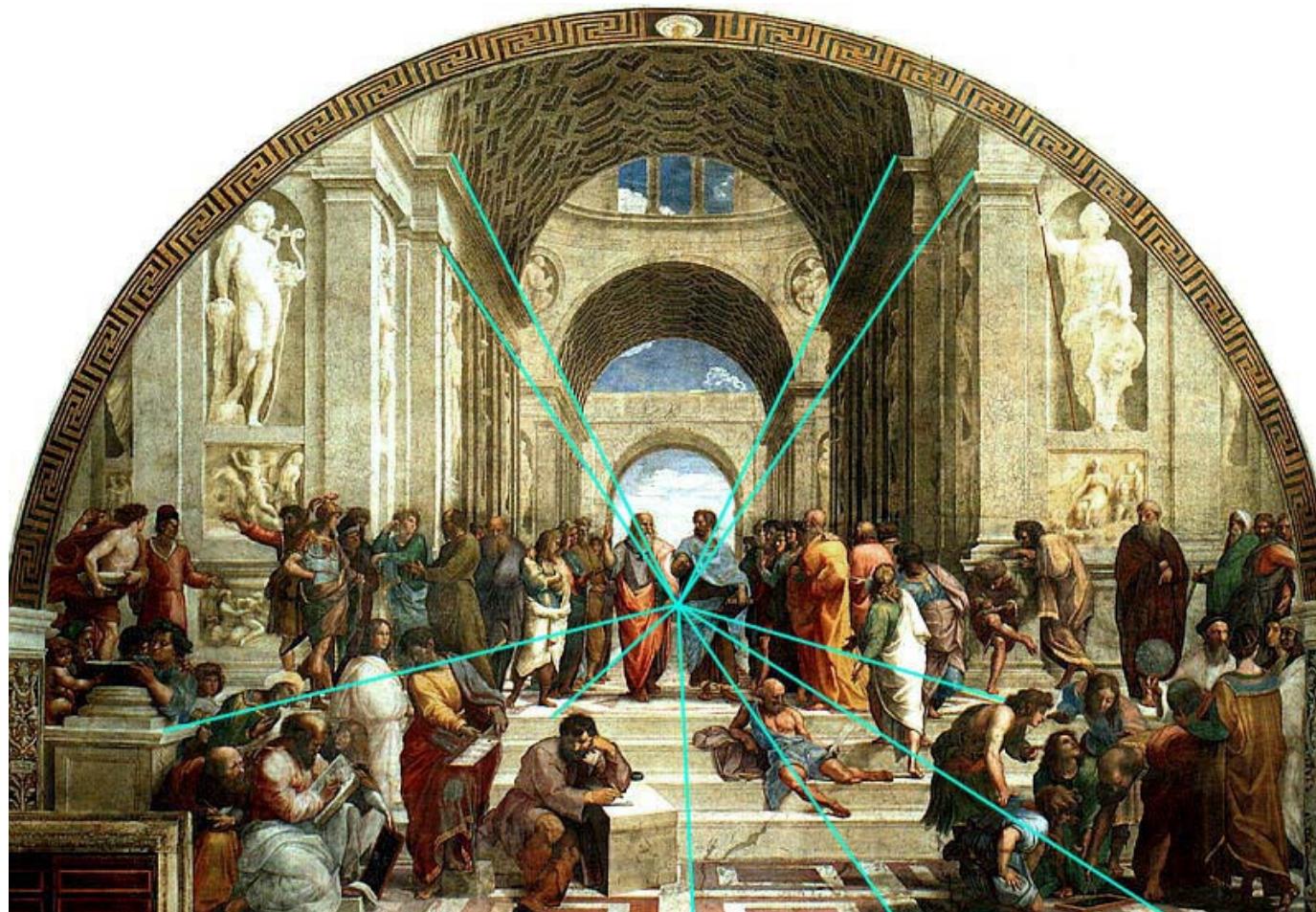

Hough Transform

COMP 4900D
Winter 2006

Lines

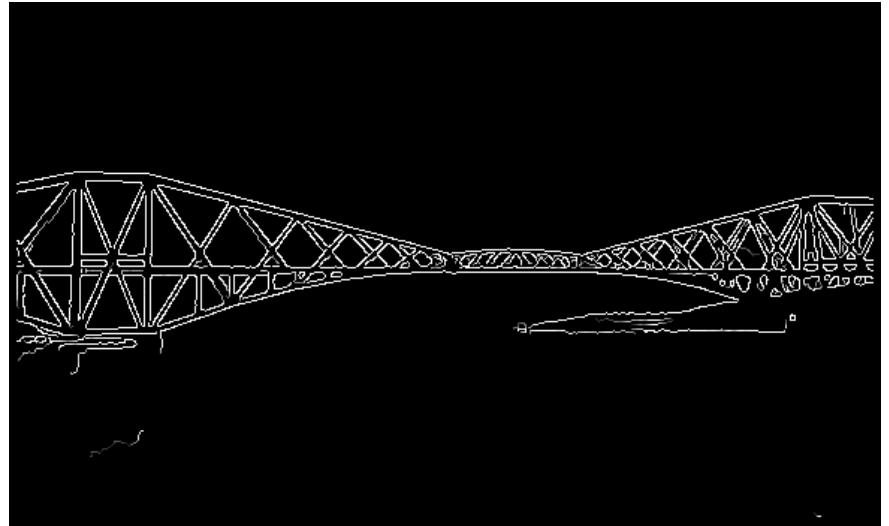


Lines



Rafael, The School of Athens (1518)

Line Detection



The problem:

- How many lines?
- Find the lines.

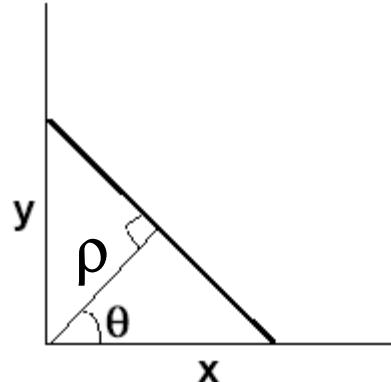
Equations for Lines

The slope-intercept equation of line

$$y = ax + b$$

What happens when the line is vertical? The slope a goes to infinity.

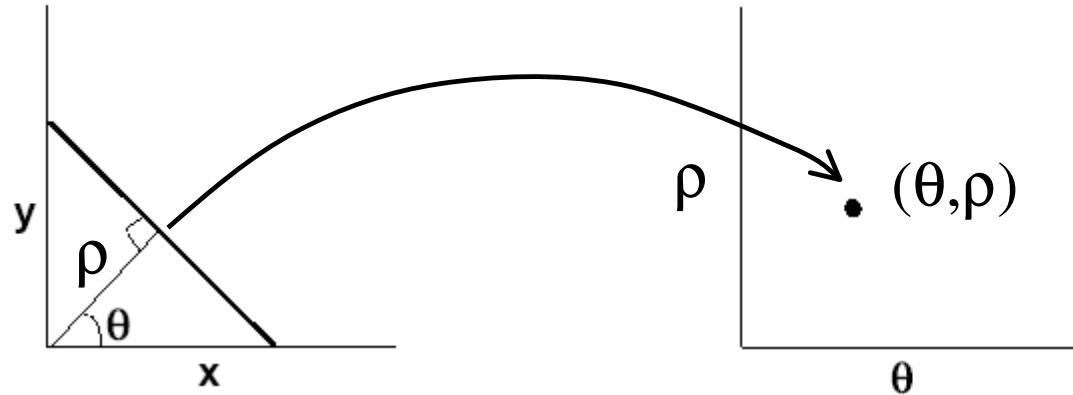
A better representation – the polar representation



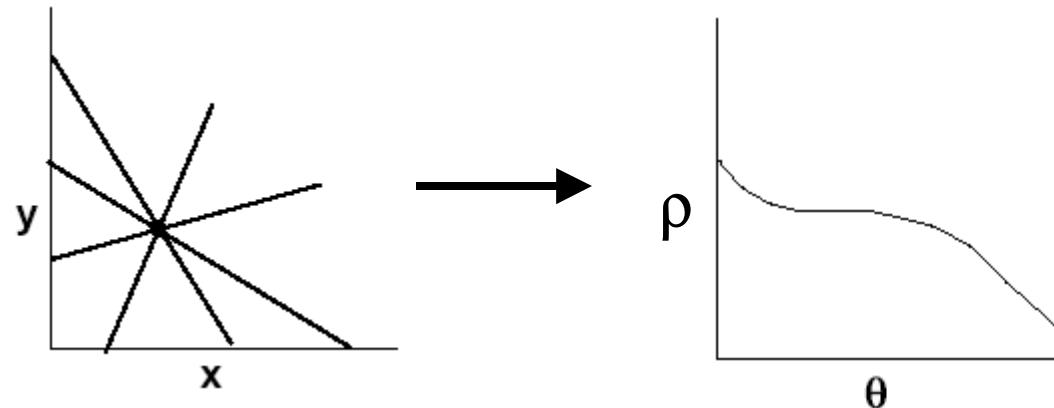
$$\rho = x \cos \theta + y \sin \theta$$

Hough Transform: line-parameter mapping

A line in the plane maps to a point in the θ - ρ space.

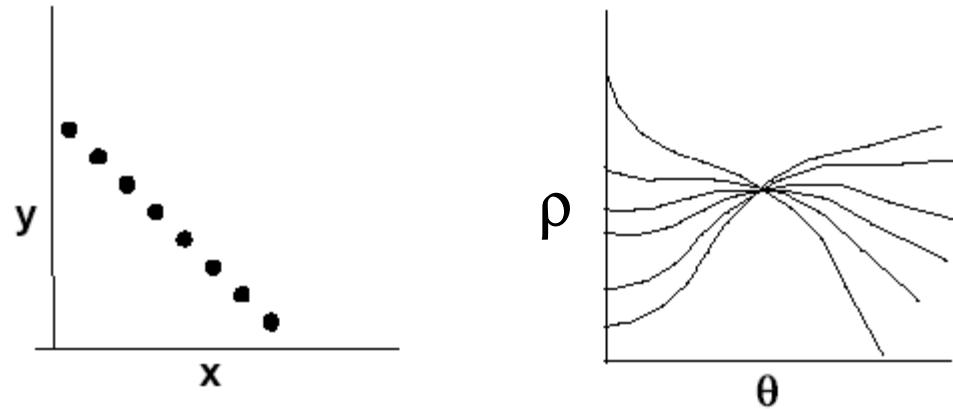


All lines passing through a point map to a sinusoidal curve in the θ - ρ (parameter) space.



$$\rho = x \cos \theta + y \sin \theta$$

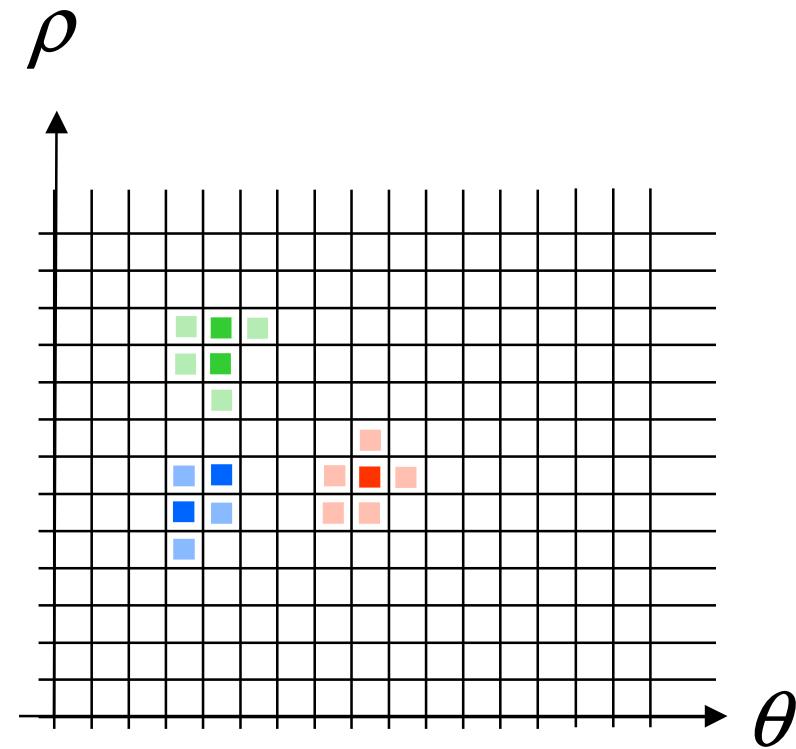
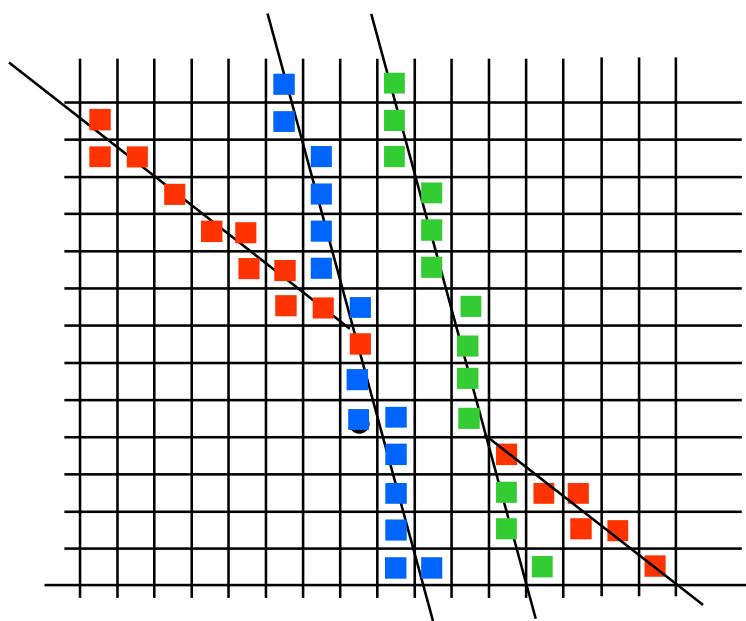
Mapping of points on a line



Points on the same line define curves in the parameter space that pass through a single point.

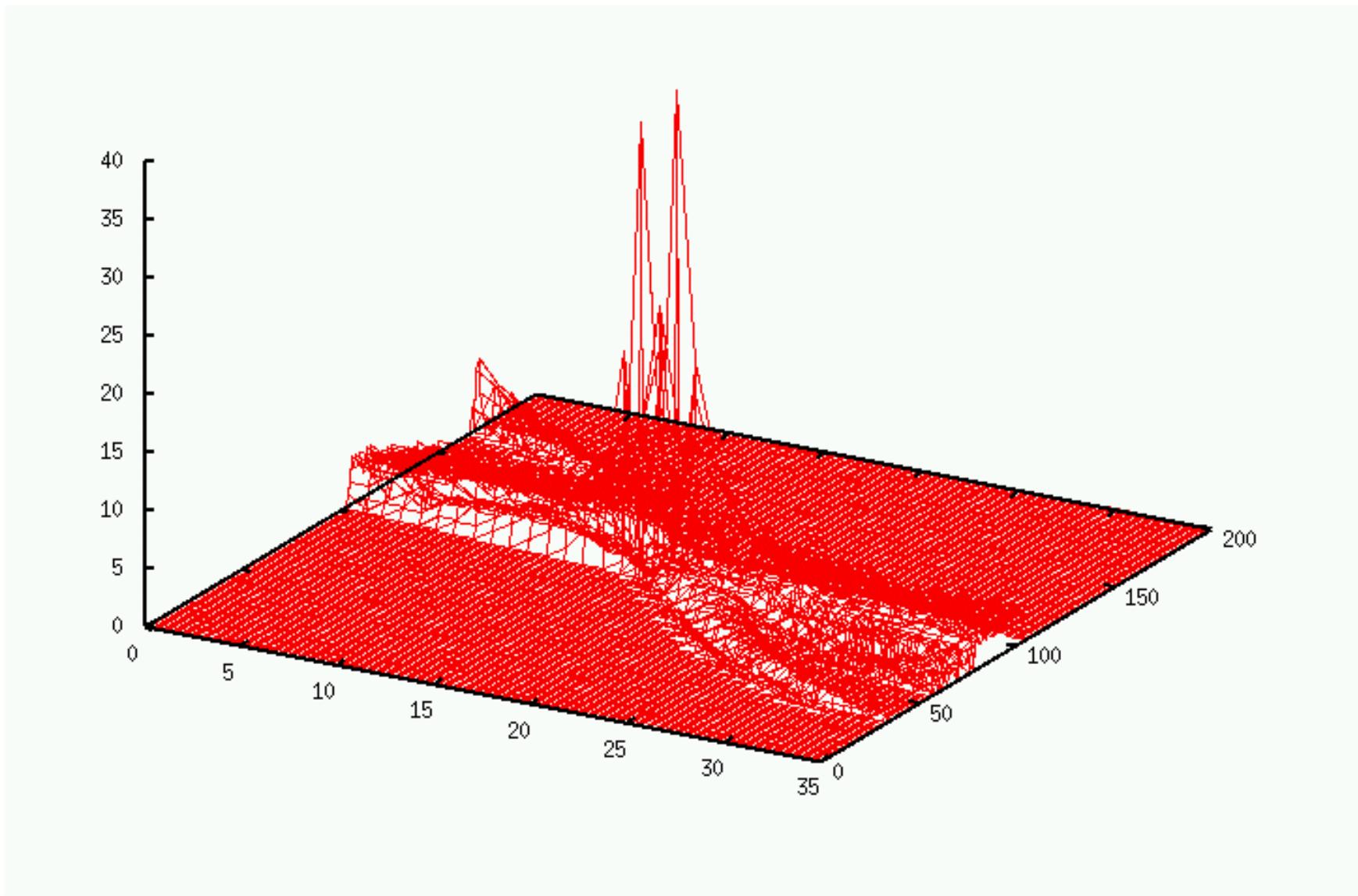
Main idea: transform edge points in x - y plane to curves in the parameter space. Then find the points in the parameter space that has many curves passing through.

Quantize Parameter Space

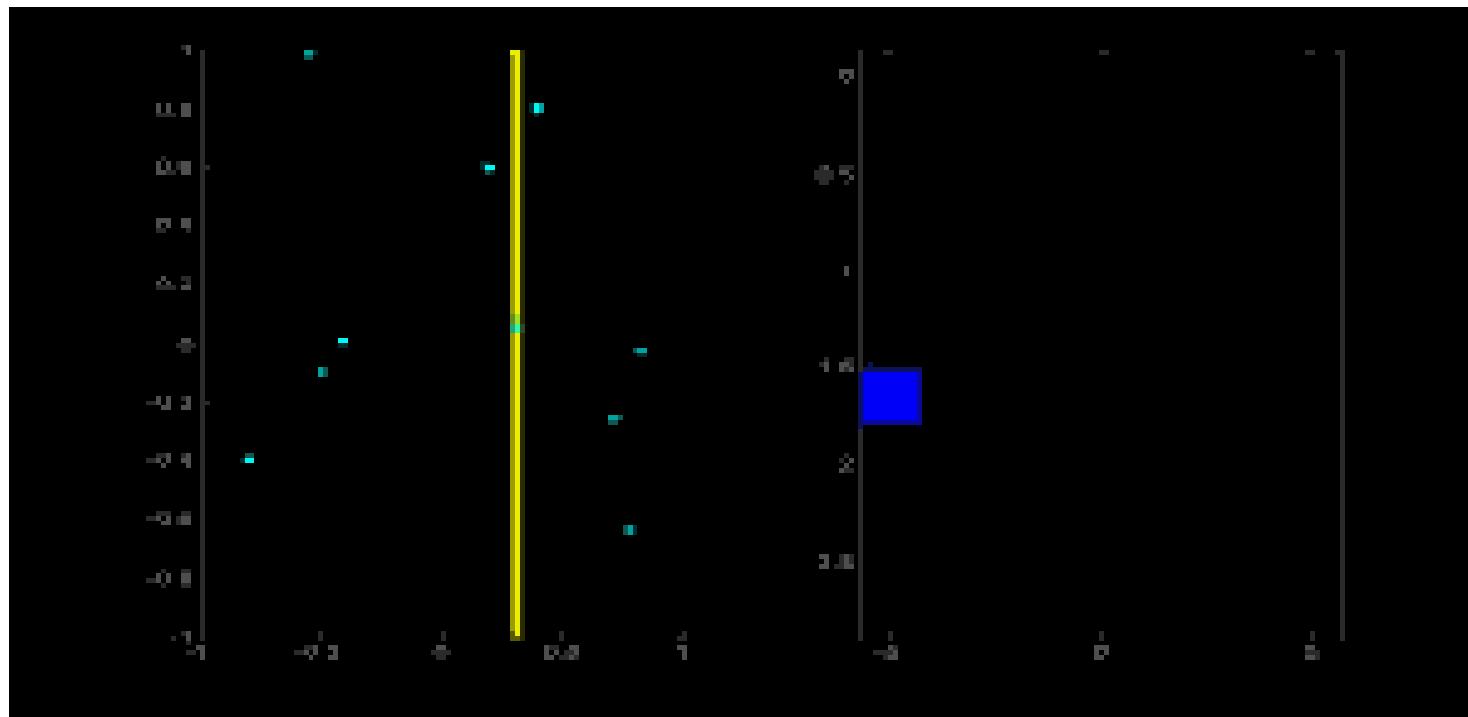


Detecting Lines by finding maxima / clustering in parameter space.

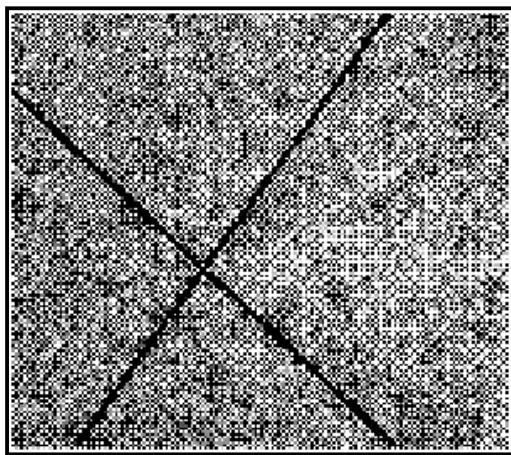
Parameter space – 3D view



A Voting Scheme



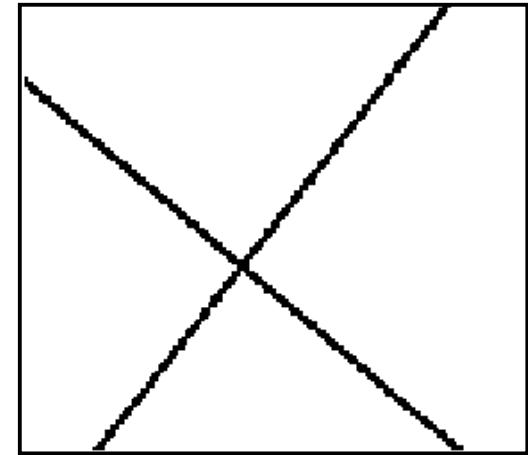
Examples



Image



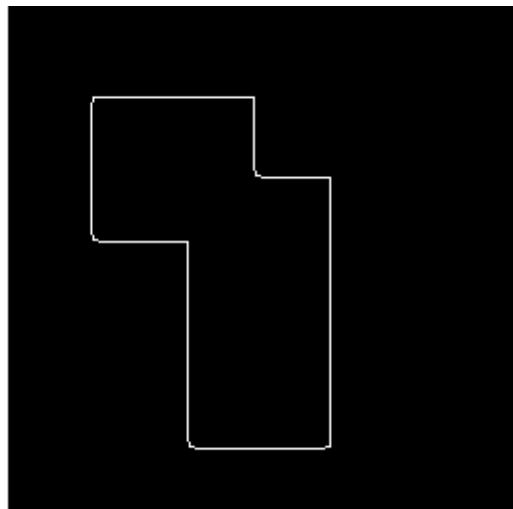
Edge detection



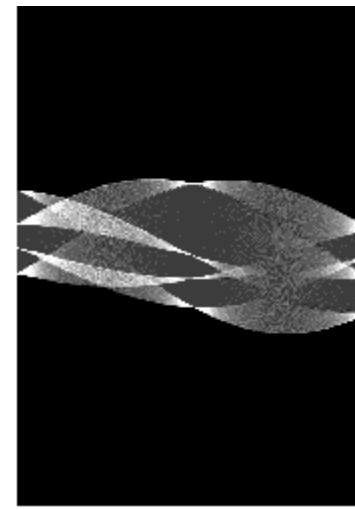
Hough Transform

Examples

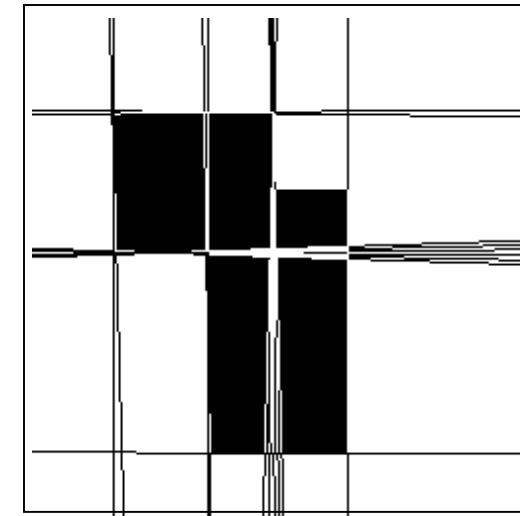
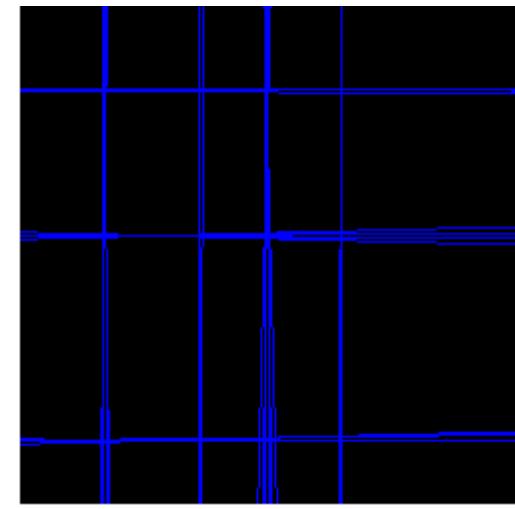
input image



Hough space

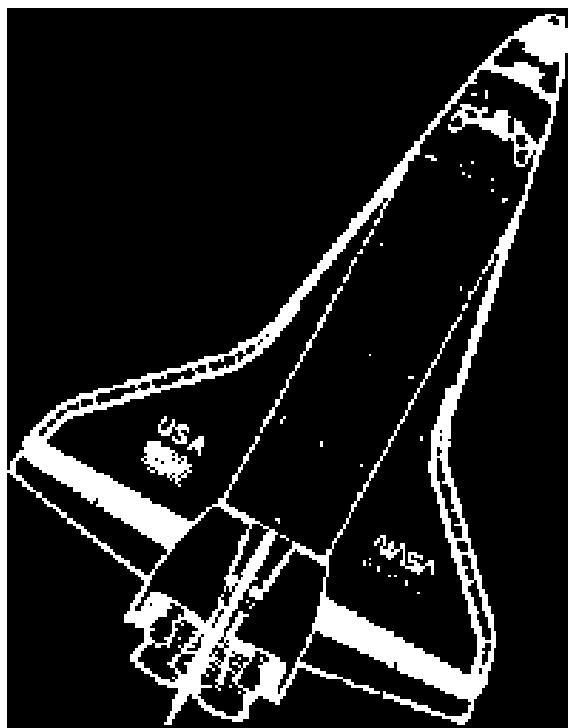


lines detected

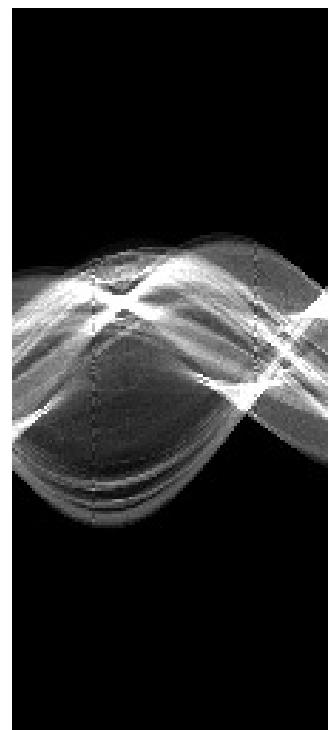


Examples

input image



Hough space



lines detected

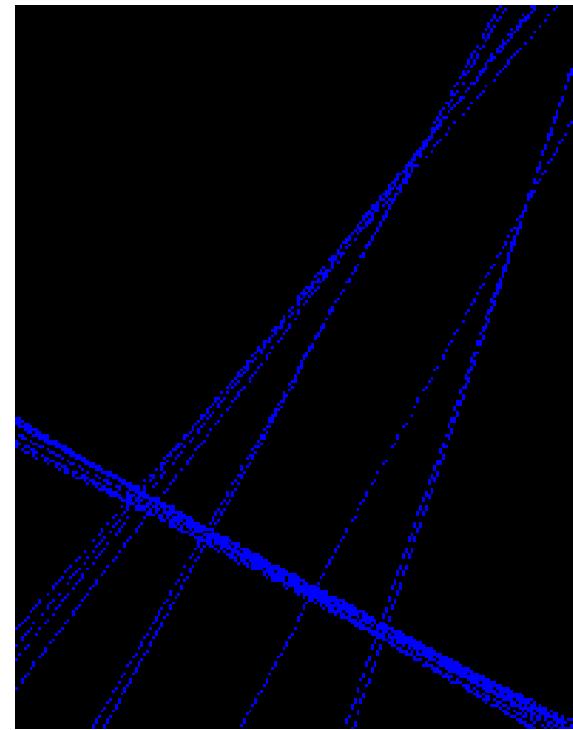
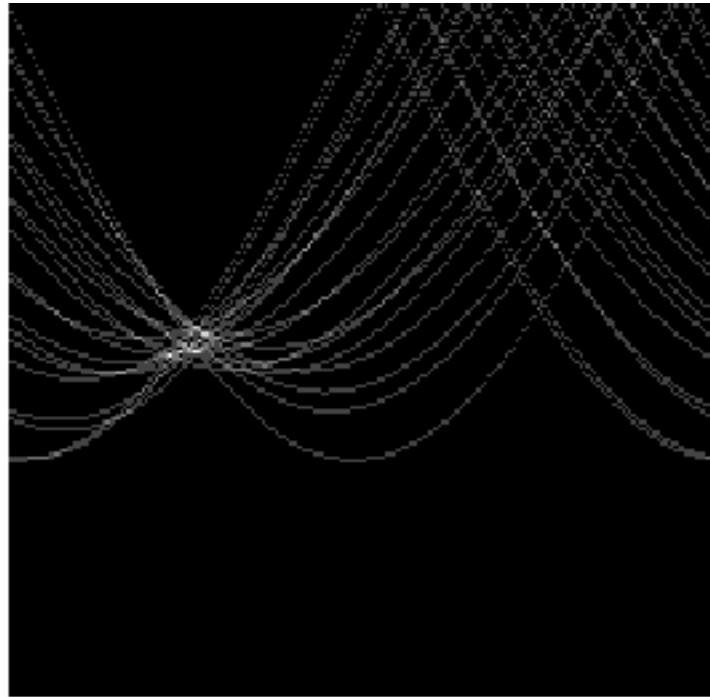
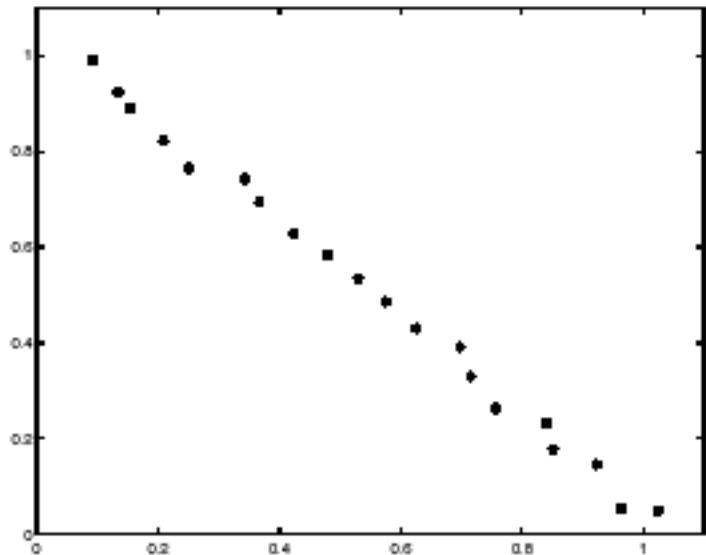


Image credit: NASA Dryden Research Aircraft Photo Archive

Algorithm

1. Quantize the parameter space
 $\text{int } P[0, \rho_{\max}][0, \theta_{\max}]; // \text{ accumulators}$
2. For each edge point (x, y) {
 For $(\theta = 0; \theta \leq \theta_{\max}; \theta = \theta + \Delta\theta)$ {
 $\rho = x \cos \theta + y \sin \theta // \text{ round off to integer}$
 $(P[\rho][\theta])++;$
 }
}
3. Find the peaks in $P[\rho][\theta]$.

Cell Size



Choose the parameter cell size such that the algorithm is robust to noise.