

Support Vector Machines

CSC 411 Tutorial

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Many thanks to Renjie Liao, Jake Snell, Yujia Li and Kevin Swersky for much of the following material.

Brief Review of SVMs

Out[9]:

Machine Learning



what society thinks I
do



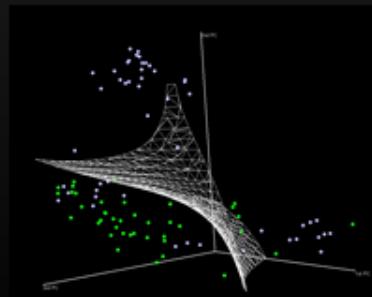
what my friends think
I do



what my parents think
I do

$$\begin{aligned}L_p &= \frac{1}{2}\|\mathbf{w}\|^2 - \sum_{i=1}^l \alpha_i y_i (\mathbf{x}_i \cdot \mathbf{w} + b) + \sum_{i=1}^l \alpha_i \\ \alpha_i &\geq 0, \forall i \\ \mathbf{w} &= \sum_{i=1}^l \alpha_i \mathbf{x}_i, \sum_{i=1}^l \alpha_i y_i = 0 \\ \nabla \hat{g}(\theta_t) &= \frac{1}{n} \sum_{i=1}^n \nabla \ell(x_i, y_i; \theta_t) + \nabla r(\theta_t). \\ \theta_{t+1} &= \theta_t - \eta_t \nabla \ell(x_{i(t)}, y_{i(t)}; \theta_t) - \eta_t \cdot \nabla r(\theta_t) \\ \mathbb{E}_{i(t)}[\ell(x_{i(t)}, y_{i(t)}; \theta_t)] &= \frac{1}{n} \sum_i \ell(x_i, y_i; \theta_t).\end{aligned}$$

what other programmers
think I do



what I think I do

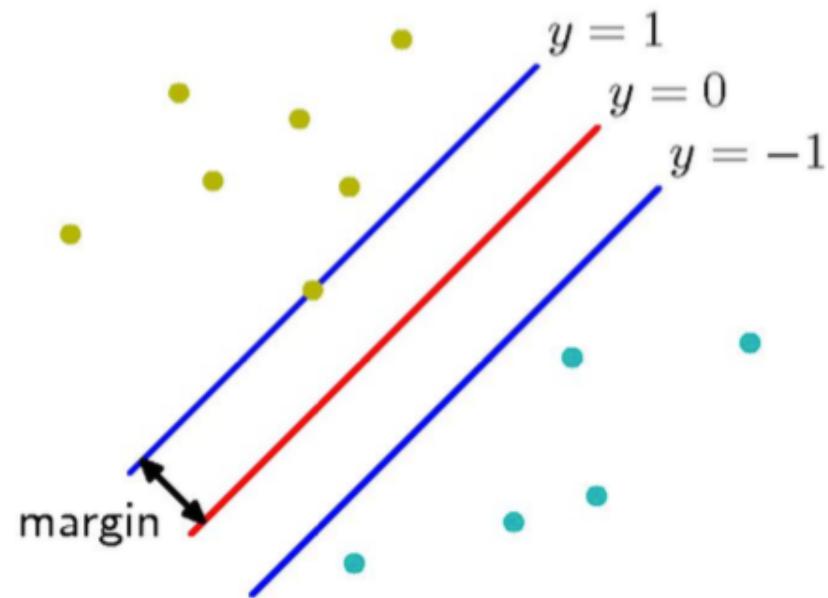
```
>>> from sklearn import svm
```



what I really do

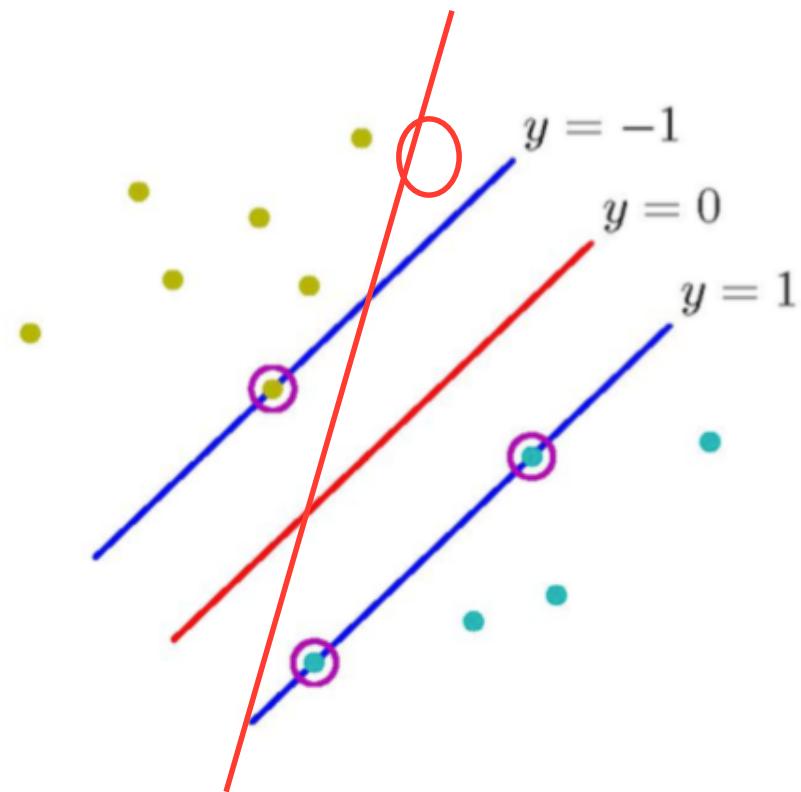
Geometric Intuition

Out[13]:



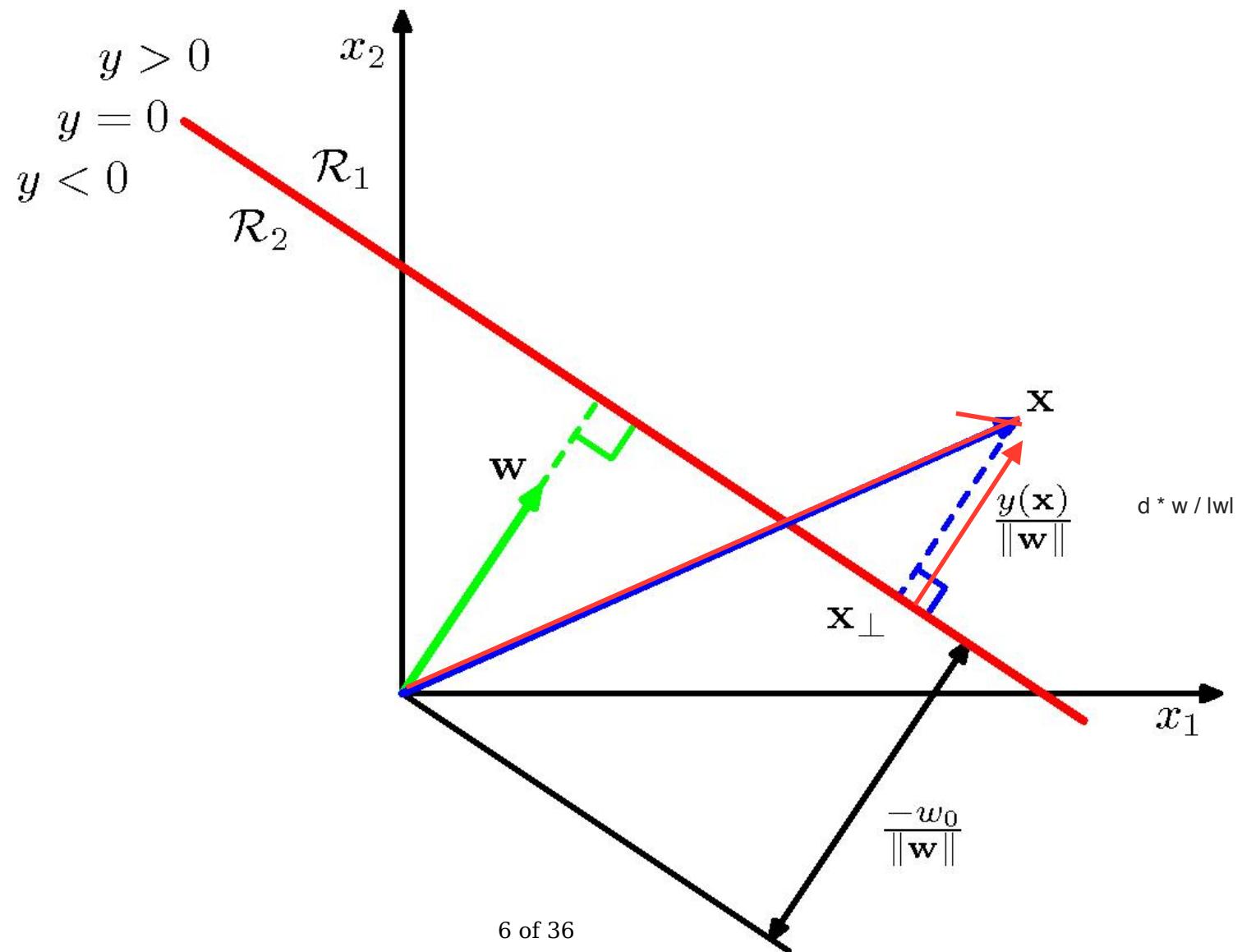
Geometric Intuition

Out[14]:



Margin Derivation

Out[16]:



Margin Derivation

Compute the distance d_n of an arbitrary point x_n in the (+) class to the separating hyperplane.

$$\begin{aligned} w^T \left(x_n - d_n \frac{w}{\|w\|} \right) + b &= 0 \\ w^T x_n - d_n \frac{w^T w}{\|w\|} + b &= 0 \\ w^T x_n + b &= d_n \|w\| \\ d_n &= \frac{w^T x_n + b}{\|w\|} \end{aligned}$$

If we let $t_n \in \{1, -1\}$ denote the class of x_n , then the distance becomes

$$d_n = \frac{t_n(w^T x_n + b)}{\|w\|}$$

We can set $d_n = \frac{1}{\|w\|}$ for the point x_n closest to the decision boundary, leading to the problem:

$$\begin{aligned} &\max \frac{1}{\|w\|} \\ \text{s.t. } &t_n(w^T x_n + b) \geq 1, \text{ for } n = 1 \dots N \end{aligned}$$

SVM Problem

But scaling $w \rightarrow \kappa w$ and $b \rightarrow \kappa b$ doesn't change $d_n = \frac{t_n(w^T x_n + b)}{\|w\|}$.

or equivalently:

$$\begin{aligned} & \min \frac{1}{2} \|w\|^2 \\ \text{s.t. } & t_n(w^T x_n + b) \geq 1, \text{ for } n = 1 \dots N \end{aligned}$$

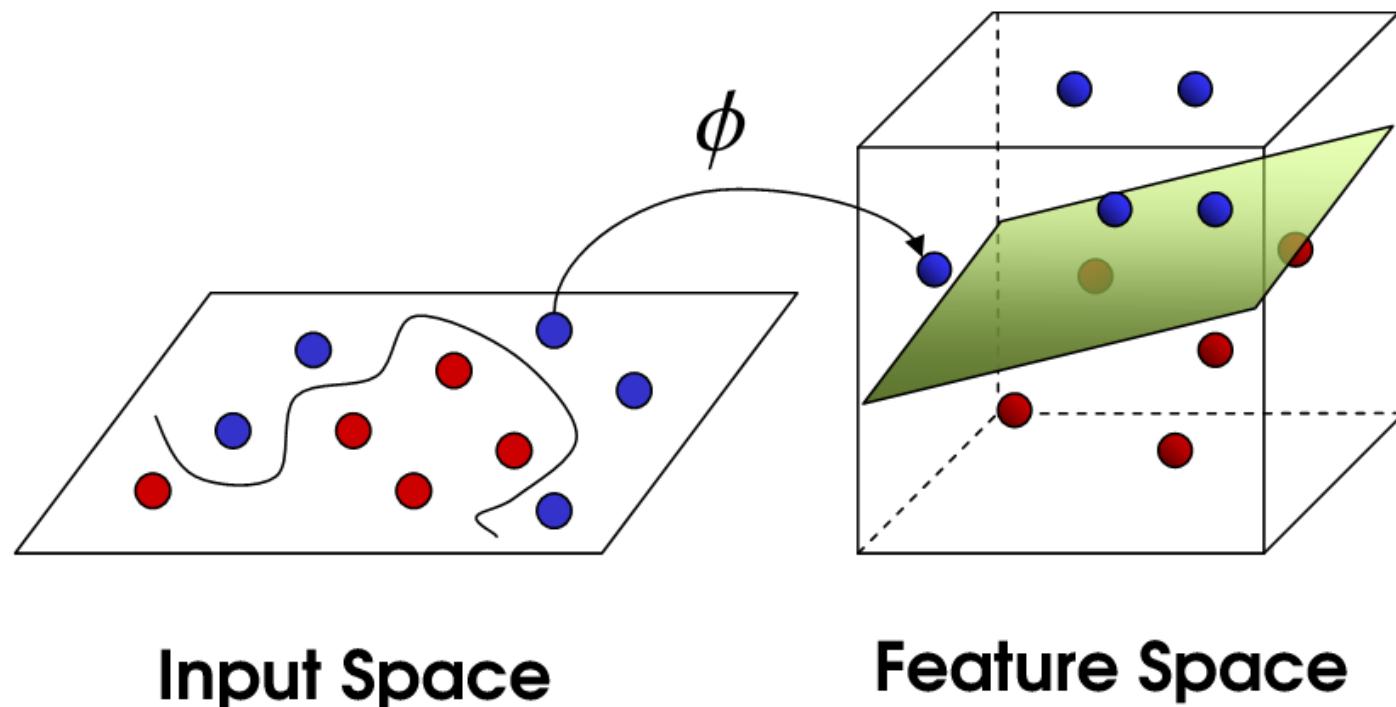
Non-linear SVMs

For a linear SVM, $y(x) = w^T x + b$.

We can just as well work in an alternate feature space: $\tilde{y}(x) = w^T \phi(x) + b$.

<http://i.imgur.com/Wuxy0.png>

Out[17]:



Non-linear SVMs

<http://www.youtube.com/watch?v=3liCbRZPrZA>

Out[19]: SVM with polynomial kernel visualization



Non-linear SVMs

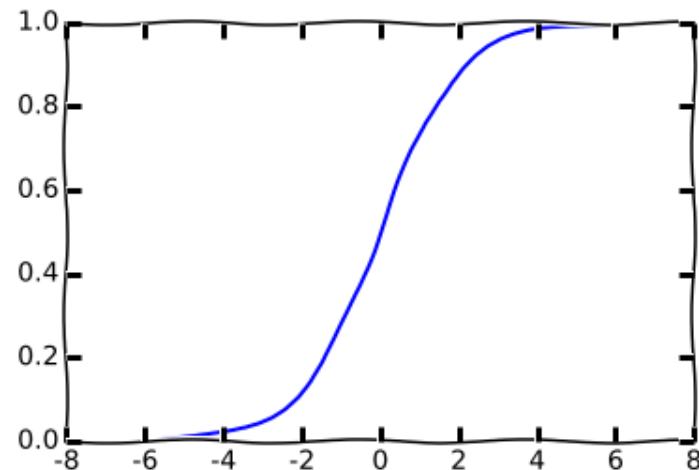
Demo (by Andrej Karpathy and LIBSVM):

<http://cs.stanford.edu/people/karpathy/svmjs/demo/>
<https://www.csie.ntu.edu.tw/~cjlin/libsvm/>

SVMs vs Logistic Regression

Logistic Regression

Out[21]: [`<matplotlib.lines.Line2D at 0x7fb3ad1af0f0>`]



Logistic Regression

- Assign probability to each outcome

$$P(y = 1|x) = \sigma(w^T x + b)$$

- Train to maximize likelihood

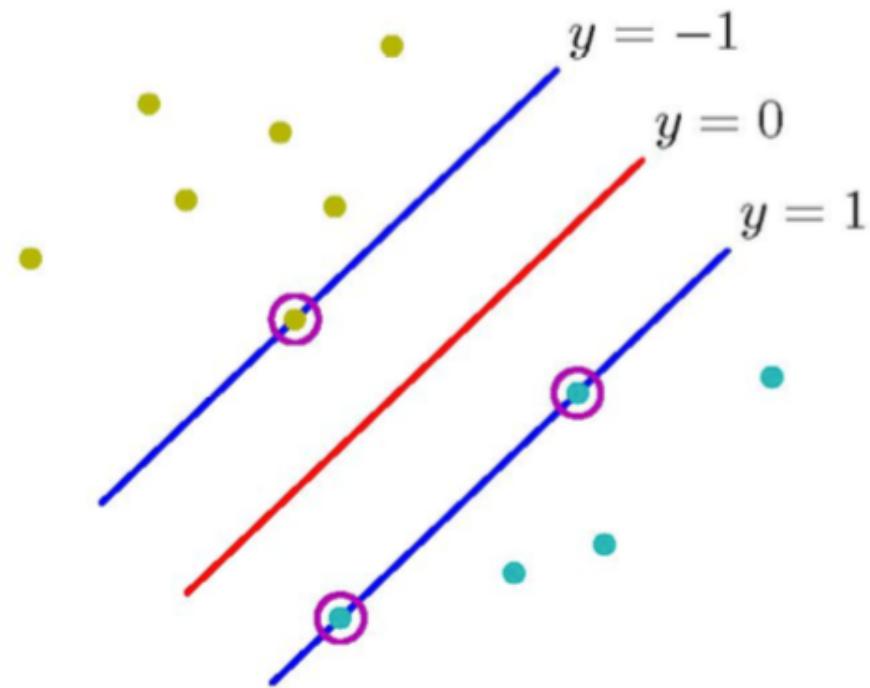
$$\mathcal{L}(w) = \prod_{n=1}^N \sigma(w^T x_n + b)^{y_n} (1 - \sigma(w^T x_n + b))^{1-y_n}$$

- Linear decision boundary

$$\hat{y} = I[w^T x + b \geq 0]$$

SVMs

Out[22]:



SVMs

- Enforce a margin of separation
 $y_n(w^T x_n + b) \geq 1$, for $n = 1 \dots N$
- Linear decision boundary
 $\hat{y} = I[w^T x + b \geq 0]$

- Train to find the maximum margin

$$\begin{aligned} & \min \frac{1}{2} \|w\|^2 \\ \text{s.t. } & y_n(w^T x_n + b) \geq 1, \text{ for } n \\ & = 1 \dots N \end{aligned}$$

Comparison

- **Logistic regression** wants to maximize the probability of the data.
 - The greater the distance from each point to the decision boundary, the better.
- **SVMs** want to maximize the distance from the closest points (support vectors) to the decision boundary.
 - Doesn't care about points that aren't support vectors.

A Different Take

Consider an alternate form of the logistic regression decision function:

$$\hat{y} = \begin{cases} 1 & \text{if } P(y = 1|x) \geq P(y = 0|x) \\ 0 & \text{otherwise} \end{cases}$$
$$P(y = 1|x) \propto \exp(w^T x + b)$$
$$P(y = 0|x) \propto 1$$

A Different Take

Suppose we don't actually care about the probabilities. All we want to do is make the right decision.

We can put a constraint on the likelihood ratio, for some constant $c > 1$:

$$\frac{P(y = 1|x_n)}{P(y = 0|x_n)} \geq c$$

A Different Take

Take the log of both sides:

$$\log P(y = 1|x_n) - \log P(y = 0|x_n) \geq \log c$$

Recalling that $P(y = 1|x_n) \propto \exp(w^T x_n + b)$ and $P(y = 0|x_n) \propto 1$:

$$\begin{aligned} w^T x_n + b - 0 &\geq \log c \\ w^T x_n + b &\geq \log c \end{aligned}$$

But c is arbitrary, so set it s.t. $\log c = 1$:

$$w^T x_n + b \geq 1$$

Similiarly the negative sample case should be:

$$-(w^T x_n + b) \geq 1$$

Try to derive it by yourself.

A Different Take

So now we have $(2y_n - 1)(w^T x_n + b) \geq 1$, for $n = 1 \dots N$. But this may not have a unique solution, so put a quadratic penalty on the weights to make the solution unique:

$$\begin{aligned} & \min \frac{1}{2} \|w\|^2 \\ \text{s.t. } & (2y_n - 1)(w^T x_n + b) \geq 1, \text{ for } n = 1 \dots N \end{aligned}$$

This gives us a SVM!

By asking logistic regression to make the right **decisions** instead of maximizing the **probability** of the data, we derived an SVM.

Likelihood Ratio

The **likelihood ratio** drives this derivation:

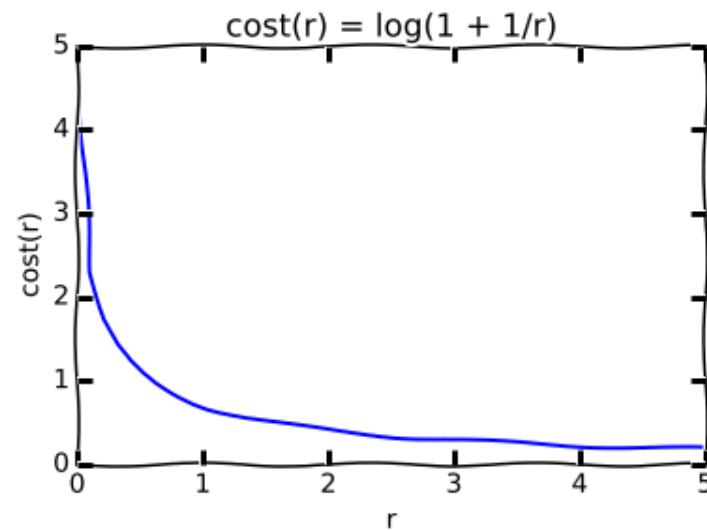
$$r = \frac{P(y=1|x)}{P(y=0|x)} = \frac{\exp(w^T x + b)}{1} = \exp(w^T x + b)$$

Different classifiers assign **different costs** to r .

LR Cost

Choose $\text{cost}(r) = \log\left(1 + \frac{1}{r}\right)$ (for a positive example)

Out[23]: <matplotlib.text.Text at 0x7fb3ad135748>



LR Cost

$$\begin{aligned}\log\left(1 + \frac{1}{r}\right) &= \log\left(1 + \exp(-(w^T x + b))\right) \\ &= -\log \frac{1}{1 + \exp(-(w^T x + b))} \\ &= -\log \sigma(w^T x + b)\end{aligned}$$

Minimizing $\text{cost}(r)$ is the same as minimizing the negative log-likelihood objective for logistic regression!

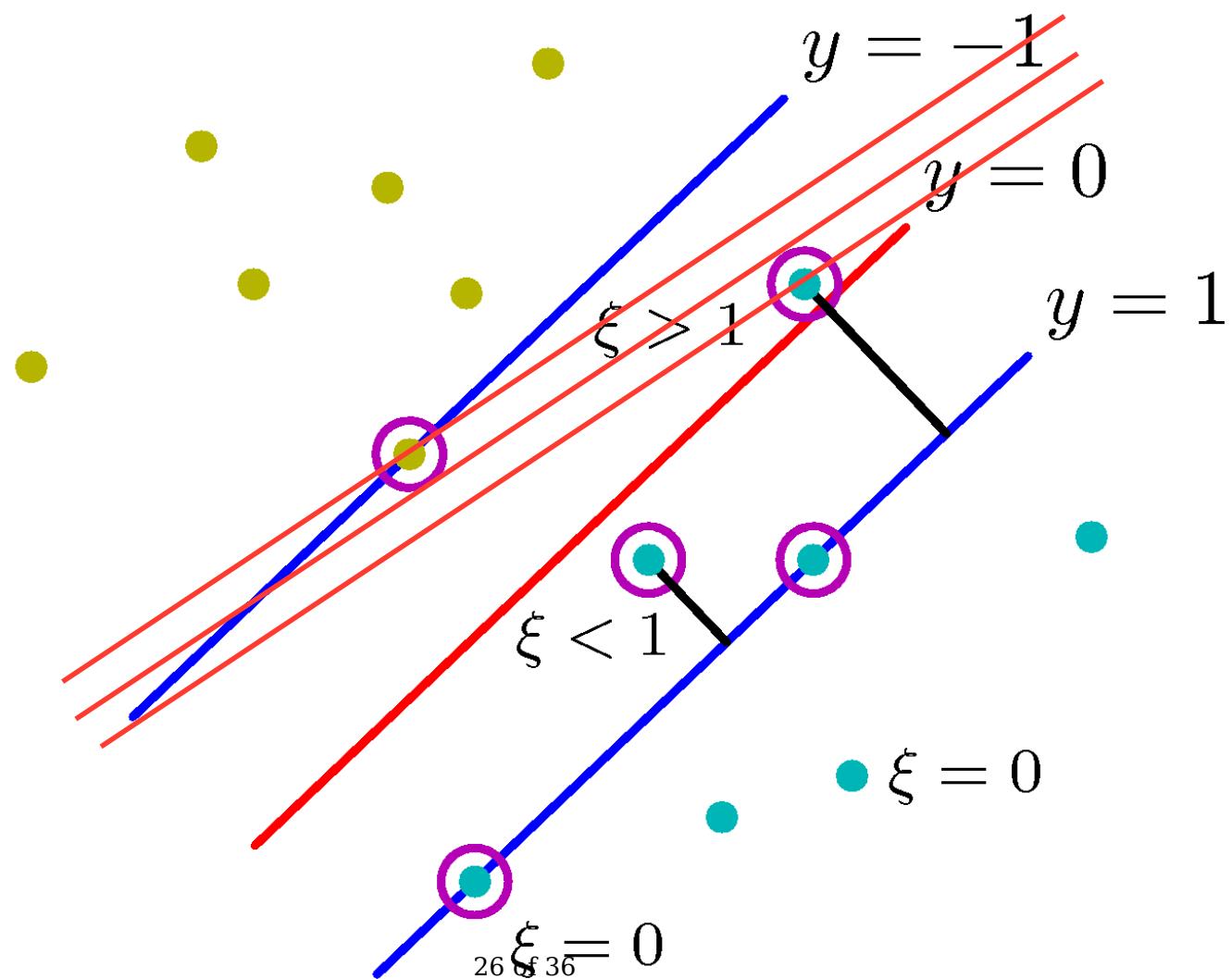
SVM with Slack Variables

If the data is not linearly separable, we can introduce slack variables.

$$\begin{aligned} & \min \frac{1}{2} \|w\|^2 + C \sum_{n=1}^N \xi_n \\ \text{s.t. } & y_n (w^T x_n + b) \geq 1 - \xi_n, \text{ for } n = 1 \dots N \\ & \text{and } \xi_n \geq 0, \text{ for } n = 1 \dots N \end{aligned}$$

SVM with Slack Variables

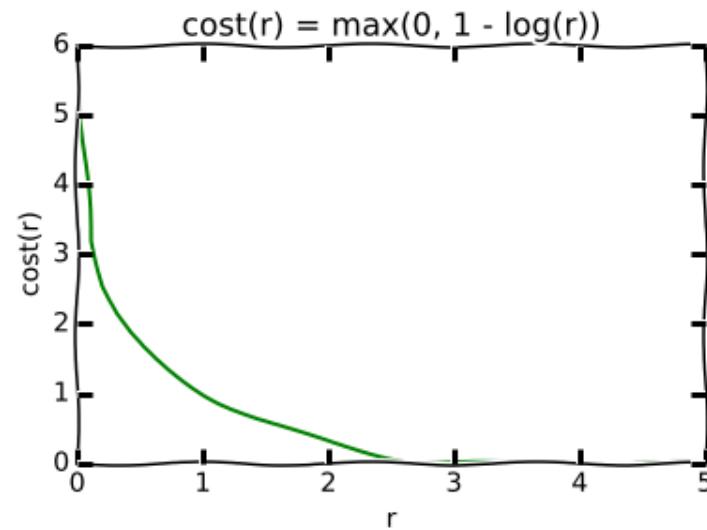
Out[24]:



SVM Cost

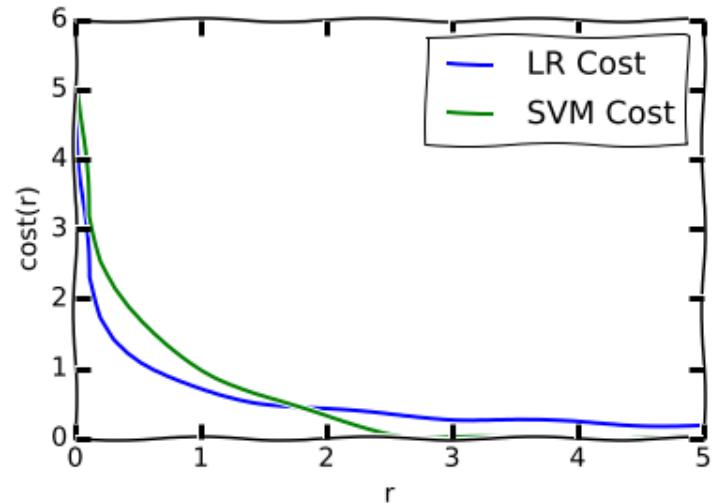
Choose $\text{cost}(r) = \max(0, 1 - \log(r)) = \max(0, 1 - (w^T x + b))$

Out[25]: <matplotlib.text.Text at 0x7fb3ad09c208>



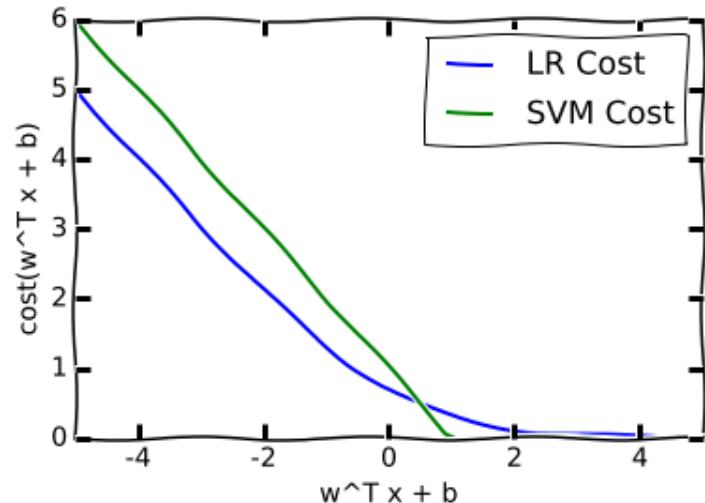
Plotted in terms of r

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Plotted in terms of $w^T x + b$

Out[27]: <matplotlib.legend.Legend at 0x7fb3acf98710>



Exploiting the Connection between LR and SVMs

Kernel Trick for LR

In the dual form, the SVM decision boundary is

$$y(x) = w^T \phi(x) + b = \sum_{n=1}^N \alpha_n t_n K(x, x_n) + b = 0$$

We could plug this into the LR cost:

$$\log \left(1 + \exp \left(- \sum_{n=1}^N \alpha_n t_n K(x, x_n) - b \right) \right)$$

Multi-class SVMs

Recall multi-class logistic regression

$$P(y = i|x) = \frac{\exp(w_i^T x + b_i)}{\sum_k \exp(w_k^T x + b_k)}$$

Multi-class SVMS

Suppose instead we just want the decision rule to satisfy

$$\frac{P(y = i|x)}{P(y = k|x)} \geq c, \text{ for } k \neq i$$

Taking logs as before,

$$(w_i^T x + b_i) - (w_k^T x + b_k) \geq 1, \text{ for } k \neq i$$

Multi-class SVMS

Now we have the quadratic program for multi-class SVMs.

$$\begin{aligned} & \min \frac{1}{2} \|w\|^2 \\ \text{s.t. } & (w_{y_n}^T x_n + b_{y_n}) - (w_k^T x_n + b_k) \geq 1, \text{ for } n = 1 \dots N, k \neq y_n \end{aligned}$$

LR and SVMs are closely linked

- Both can be viewed as taking a probabilistic model and miminizing some cost associated with the likelihood ratio.
- This allows use to extend both models in principled ways.

Which to Use?

Logistic regression

- Gives calibrated probabilities that can be interpreted as confidence in a decision.
- Unconstrained, smooth objective.
- Can be used within Bayesian models.

SVMs

- No penalty for examples where the correct decision is made with sufficient confidence, which can lead to good generalization.
- Dual form gives sparse solutions when using the kernel trick, leading to better scalability.