# **Tropical Semirings**

A general method for declaratively solving graph problems

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#### Handout

- You may obtain a copy of these notes and code samples on my website
- Code samples are in Haskell and were tested on GHC 9.2.4

#### Links

- https://simonzeng.com/tropical.pdf
- https://simonzeng.com/tropical.hs

### Dijkstra's Shortest Path Algorithm

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# Dijkstra's Shortest Path Algorithm

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- A: Dijkstra's algorithm

#### Pseudocode

```
01 function Dijkstra(Graph, source):
02
       dist[source] <- 0
03
       create vertex priority queue Q
04
       for each vertex v in Graph. Vertices:
05
           if v != source
               (dist[v], prev[v]) <- INFINITY, UNDEFINED
06
07
           Q.add_with_priority(v, dist[v])
08
       while Q is not empty:
           u <- Q.extract_min()
09
10
           for each neighbor v of u:
               alt <- dist[u] + Graph.Edges(u, v)
11
               if alt < dist[v]:
12
                   (dist[v], prev[v]) <- alt, u
13
14
                   Q.decrease_priority(v, alt)
15
       return dist, prev
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- Very classic, but:
  - Uses lots of state and mutation
  - Hard to tell what's going on from just reading the code

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- The rest of Dijkstra's tells us only when we look at a particular node
- Dijkstra's is just node ordering boilerplate around this core operation

#### A Functional Kernel

• The original calculates, then compares, then (sometimes) sets

#### Original Pseudocode

```
11 alt <- dist[u] + Graph.Edges(u, v)
12 if alt < dist[v]:
13 dist[v] <- alt
```

The comparison+set can be written as a single function call

#### Refined pseudocode

```
dist[v] <- min(dist[v], dist[u] + Graph.Edges(u, v))</pre>
```

- This is the core of path algorithms!
- Remember this for later