

CS5321 Numerical Optimization Homework 4

Due Jan 04 2016

1. (20%) Consider the problem

$$\begin{array}{ll} \min_{x_1, x_2} & 0.1 * (x_1 - 3)^2 + x_2^2 \\ \text{s.t.} & x_1^2 + x_2^2 - 1 \leq 0 \end{array} \quad (1)$$

- (a) Write down the KKT conditions for (1).
 - (b) Solve the KKT conditions and find the optimal solutions, including the Lagrangian parameters.
 - (c) Compute the reduced Hessian and check the second order conditions for the solution.
2. (20%) The trust region method (for unconstrained optimization problem) needs to solve a local model in each step

$$\begin{array}{ll} \min_{\vec{p}} & m(\vec{p}) = \frac{1}{2} \vec{p}^T A \vec{p} + \vec{g}^T \vec{p} \\ \text{s.t.} & \vec{p}^T \vec{p} \leq \Delta^2. \end{array}$$

Prove that the optimal solution \vec{p}^* of the local model satisfies

$$\begin{aligned} (A + \lambda I) \vec{p}^* &= -\vec{g} \\ \lambda(\Delta - \|\vec{p}^*\|) &= 0 \\ (A + \lambda I) &\text{ is positive semidefinite.} \end{aligned}$$

(Hint: to prove the last statement, you only need to consider the directions in the *critical cone*.)

3. (60%) Implement the Interior Point Method (IPM), as shown in Figure 1, to solve linear programming problem.

$$\begin{array}{ll} \min_{\vec{x}} & \vec{c}^T \vec{x} \\ \text{s.t.} & A\vec{x} - \vec{s} = \vec{b} \\ & \vec{s} \geq 0 \end{array}$$

You can assume $\vec{x}_0 = 0$ is a feasible interior point.

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- (1) Given \vec{x}_0 , $\vec{\lambda}_0$, and \vec{s}_0 , in which $\vec{\lambda}_0, \vec{s}_0 \geq 0$.
 - (2) For $k = 0, 1, \dots$
 - (3) Choose $\sigma_k \in [0, 1]$ and solve

$$\begin{pmatrix} 0 & -A^T & 0 \\ -A & 0 & I \\ 0 & S^k & \Lambda^k \end{pmatrix} \begin{pmatrix} \Delta x_k \\ \Delta \lambda_k \\ \Delta s_k \end{pmatrix} = \begin{pmatrix} A^T \vec{\lambda}_k - \vec{c} \\ A \vec{x}_k - \vec{s}_k - \vec{b} \\ \sigma_k \mu_k e - \Lambda^k S^k e \end{pmatrix},$$

where $\mu_k = \frac{\vec{\lambda}_k^T \vec{s}_k}{m}$, $\Lambda^k = \text{diag}(\vec{\lambda}_k)$, $S^k = \text{diag}(\vec{s}_k)$.

- (4) Compute α_k such that

$$(\vec{x}_{k+1}, \vec{\lambda}_{k+1}, \vec{s}_{k+1}) = (\vec{x}_k, \vec{\lambda}_k, \vec{s}_k) + \alpha_k (\Delta x_k, \Delta \lambda_k, \Delta s_k)$$

is in the region $N(\gamma) = \{(\vec{x}, \vec{\lambda}, \vec{s}) | \lambda_i s_i \geq \gamma \mu_k, \forall i = 1, 2, \dots, n\}$
for some $\gamma = 10^{-3}$.

Figure 1: The interior point method for solving linear programming