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OBJECTIVE

A motivated individual with in-depth knowledge of languages and development tools, seeking a position in a growth-oriented company where I can use my skills to the advantage of the company while having the scope to develop my own skills.



EDUCATION

BS Computer Science | UNIVERSITY OF ENGINEERING & TECHNOLOGY, LAHORE

2016 – CURRENT

FSC PRE-ENGINEERING | GOVT COLLEGE TOWNSHIP, LAHORE

2014 – 2016



EXPERIENCE

Fiverr | FULL-STACK FREELANCE DEVELOPER

OCT, 2018 -

Worked with 50+ freelance projects and have 30+ international clients.

KICS, UET | ROBOTICS RESEARCH INTERN

JUN, 2019 - SEP, 2019

I have worked with autonomous navigation robot using SLAM project and also completed my own autonomous robot as a part of my final year project.

QUVA | LARAVEL DEVELOPER

JUN, 2018 – SEP, 2018

I have worked as intern Full-Stack laravel developer at Quva and completed thier GRE preparation web application.

TEAM CYBER SWITCH | PENTESTER

2014 - 2016

I was a crew member of Team Cyber Switch for two years and during these two years I accessed and patched more than 500+ websites by exploiting sql injection vulnerability.



SKILLS

- **NodeJS**

Completed small scale applications using Node Js with MongoDB, MySQL DB and socket.io.

- **Django**

Developed multiple web apps and used its services in mobile applications.

- **Laravel**

Completed multiple projects with PHP laravel.

- **ASP.NET MVC 5**

Developed multiple web applications and apis.

- **JavaScript & jQuery**

Completed more than a dozen small scale web applications.

- **React-Native, Redux, Firebase**

Developed three Android/iOS applications with react native and firebase as database.

- **ROS(Robot Operating System)**

Made autonomous navigation Robot using SLAM as my final year project.

- **PHP Core**

Developed multiple web applications and apis.

- **.NET desktop app development**

Developed management systems and small scale applications.

- **HTML/CSS**

Developed some basic website themes.

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FINAL YEAR PROJECT

I worked on AGV(Automatic Guided Vehicle) based interpretation using SLAM(Simultaneous localization and mapping) as my final year project. The project is based on two modules, first module is AGV and second one is scene interpretation. Software part of AGV module is developed using ROS indigo and connected it to hardware part via ROS-Arduino Bridge. Scene interpretation uses Openpose for joint detection and CNN for object detection (objects as pistol,knife and baggage).

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EXTRA CURRICULAR ACTIVITES

SCHOOL AWARENESS CAMPAIGN 19 | ORGANIZER

MAR 2019

Organizer of school awareness campaign UET 2019

NAQSH 18 | ORGANIZER

DEC 2018

Organizer of UET NAQSH 2018.

UET STREET ART 18 | ORGANIZER

DEC 2018

Organizer of UET STREET ART 2018.

APEX 18 | ORGANIZER

MAY 2018

Organizer of All Pakistan Environmental Art Exhibition.

SKM SCIENCE FAIR | PARTICIPANT

FEB 2011

Made a DIY wind power mobile charger.

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LANGUAGES

- Khowar
- Urdu
- Punjabi
- English

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INTERESTS

- Video Games
- Movies
- Football