

Smart usage of context information for the analysis, design and generation of power-aware polices for mobile sensing apps

Presented by: Rafael Pérez Torres

Thesis advisors: Dr. César Torres Huitzil Hiram Galeana Zapién, PhD

LTI Cinvestav Tamaulipas

Problem statement Methodology State-of-art Proposed solution Important results Future work Conclusions Reference

Table of contents

Problem statement

Methodology

State of art related techniques

Proposed solution

Important results

Future work

Conclusions

Introduction

- The popularity of mobile devices is a result of advances in their computation, sensing, and communication dimensions [8].
 - The sensing facilities improve interaction with user, turning them into omni-sensors able to know about its surrounding environment.
 - Smartphones have become context-aware, gaining understanding about user's activity and environment.
- However, battery is not evolving at the same pace than the advances in other smartphone's characteristics [11], growing only 5-10% each year [15, 7].
 - The energy constraint becomes more critical when continuous access to sensors is needed, which is the core requirement of mobile sensing applications.

Stages of mobile sensing applications

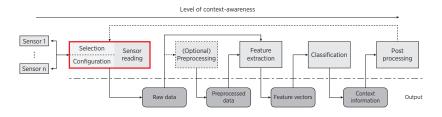


Figure: Stages of mobile sensing applications

There is a tradeoff between the accuracy of context information retrieved and the associated energy consumption [26, 25]. How to face it?

Hypothesis

Hypothesis

Intelligent policies produced through context information built from sensors data can be employed to reduce the energy consumption in a mobile device when performing continuous sensor readings.

- An intelligent policy is a special rule that defines how sensors should be selected and configured to reduce energy consumption and achieve the mobile sensing app's requirements. It is intelligent in terms of self-adaptness to changes detected in context information
- This research work is aimed at employing GPS and inertial sensors data (accelerometer) for inferring context information in terms of mobility patterns. This context information will then be exploited to adapt sensors' operation and produce power savings.

Problem statement

Problem statement: Mobility pattern identification

Given a set $V = \{v_1, v_2, \dots, v_n\}$ of data values read from sensor S in the time interval $T \in [t_1, t_2]$, identify the current mobility pattern p_S that represents the activity of user.

$$PatternIdentifier(V) \longrightarrow p_S \in Patterns$$
 (1)

Where *Patterns* is a set of patterns that represent an interesting state in user mobility, specifically the set {no_movement, walking, running, vehicle_transportation}.

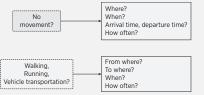


Figure: Context information related to mobility patterns

Problem statement

Problem statement: Policy generation

Given the set of detected mobility patterns $\mathcal{P} = \{p_{S_1}, p_{S_2}, \dots, p_{S_n}\}$ in data from sensors $\mathcal{S} = \{S_1, S_2, \dots, S_n\}$, accuracy required a, and physical constraints status c of a mobile device, find a policy that select the proper set of sensors \mathcal{S}_{new} and its associated configuration $\mathcal{S}_{new_{conf}}$ while meeting application requirements.

PolicyGeneration(
$$\mathcal{P}, a, c$$
) $\longrightarrow \mathcal{S}_{new}, \mathcal{S}_{new_{conf}}$ (2)

The $S_{new_{conf}}$ configuration is referred as the *adaptive duty cycle* of associated sensor.

Interaction between problems

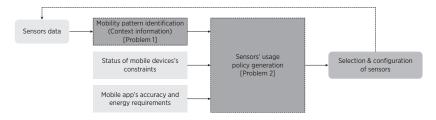


Figure: Interaction between the thesis work's problems

roblem statement Methodology State-of-art Proposed solution Important results Future work Conclusions Referenc 200000●0 0 0000 0000 000 0000 00

Objectives

Main objective

To reduce energy consumption in the mobile sensing apps, which perform continuous sensor readings, through self-adapting power-aware policies generated from context information obtained from sensors data.

Particular objectives

- To identify mobility patterns from context information obtained from an inertial sensor (accelerometer) and location providers (GPS, WPS).
- To generate policies for a self-adapting sensors' usage from identified mobility patterns, accuracy and energy requirements of mobile application, and status of mobile device's constraints.
- To ease the development of mobile sensing applications that require user location tracking, i.e., LBS, isolating the complexity of sensors' access and the associated efficient energy management.

Problem's scenario

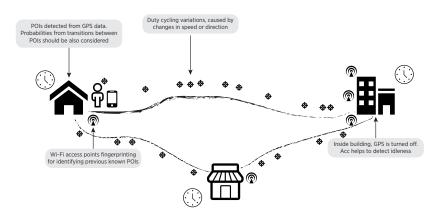


Figure: Basic problem's scenario

Methodology

- 1. Familiarization with state-of-art power-aware sensing related techniques
- 2. Formal definition and selection of mobility patterns to be identified
- Research on pattern recognition algorithms focused on mobility patterns identification
- 4. Design of the Pattern Identification Element (PIE)
- Research on and proposition of adaptive policies for energy efficient usage of sensors
- 6. Design of the Policy Generation Element (PGE)
- Development of a middleware involving the PIE and PGE for the Android platform
- 8. Experimentation in terms of accuracy and energy efficiency

Problem statement Methodology State-of-art Proposed solution Important results Future work Conclusions Reference

Taxonomy of state of art solutions

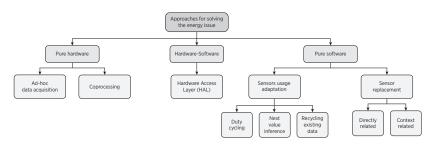


Figure: Taxonomy of solutions, seen from the sensors adaptation's perspective

Distribution of approaches

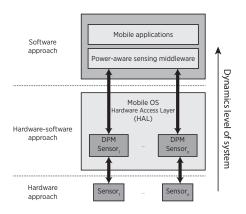


Figure: Distribution of approaches across mobile platform's layers

Characteristics of pure software approach solutions

Distinctive characteristics of pure software solutions

- Optimization oriented (OO): Optimization orientation focused on minimizing energy consumption and/or the error in activity tracking.
- Online learning (OL): Online learning from context information, enabling predictive features thanks to observance over long-time windows of sensory data.
- User state oriented (US): Modeling of an enriched version of the context information, user state (US), for achieving full activity-awareness and ease the adaptation over the sensing dimension.

Framework for analyzing pure software solutions

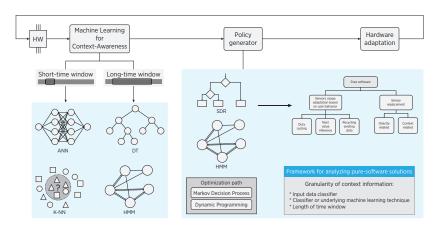


Figure: Decomposition of solutions

Proposed solution

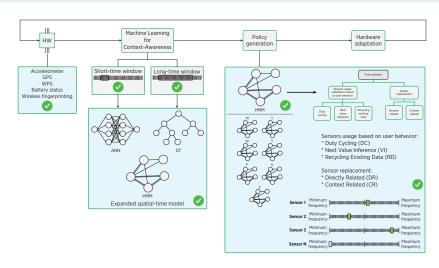


Figure: Decomposition of our solution

Proposed solution

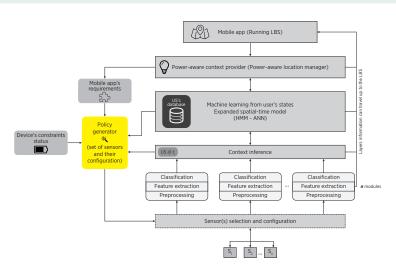


Figure: Overview of current solution

The model of information learned in proposed solution

- The overall problem can be divided into learning and detection of stay points, and the trajectory tracking.
- The information can be represented through an expanded-spatial time model.

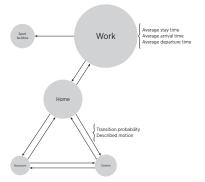


Figure: Basic unit of information learned in the expanded spatial-time model (User state)

The model of information learned in proposed solution

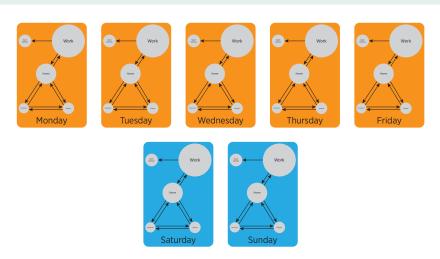


Figure: The spatial-time models can be built and learned over longer time windows

Problem statement Methodology State-of-art Proposed solution Important results Future work Conclusions Reference ○○○○○○○○ ○ ○○○○ ○○○○ ◆○○ ○○○○ ○○○

First steps towards expanded spatial-time model: a proof of concept

- A proof-of-concept experimentation for studying the feasibility of on-device learning the spatial-time model has been conducted.
- An event-oriented methodology was followed.
- The methodology involved the adaptation of classic stay points algorithms [19, 31] for online operation, while reducing memory footprint.

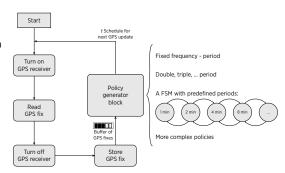


Figure: Logical workflow of the platform for on-device stay points detection

Results of early experimentation

- The first experiment is aimed at ensuring the calculation of stay points locally at the smartphone ¹.
- Spending power to save power (process GPS data for learning mobility patterns and use this information for sensory adaptation) can be possible.

| GPS reading period | Algorithm | Stay points detected | Average fixes | Maximum fixes | GPS accesses | Running time (hours) |
|----------------------|--------------------|----------------------|---------------|---------------|--------------|----------------------|
| 1 minute | Sigma Montoliou | 27 | 70 | 652 | 2251 | 43.68 |
| 1 minute | Buffered Montoliou | 26 | 79 | 685 | 2334 | 43.92 |
| 3 minutes | Sigma Montoliou | 47 | 27 | 248 | 1361 | 71.84 |
| 3 minutes | Buffered Montoliou | 28 | 41 | 248 | 1241 | 64.96 |
| 5 minutes | Sigma Montoliou | 43 | 25 | 154 | 1119 | 95.88 |
| 5 minutes | Buffered Montoliou | 45 | 21 | 154 | 1021 | 87.78 |
| Doubling 1-2-4-8-16 | Sigma Montoliou | 59 | 17 | 80 | 1223 | 189.69 |
| Linear 1-3-5-9-12-15 | Sigma Montoliou | 35 | 21 | 84 | 888 | 144.85 |

Table: Results of the first experiment

¹Samsung Galaxy Note II, quadcore 1.6 GHz processor, 16 GB RAM, 3,100 mAh battery

iblem statement Methodology State-of-art Proposed solution Important results Future work Conclusions Reference
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Scientific products

- As a product of the analysis of related solutions, we have prepared a survey² covering:
 - Smartphone-based sensing's characteristics.
 - The power-awareness challenge in smartphone-based sensing.
 - A taxonomy of the solutions for energy efficiency in smartphone-based sensing.
 - The tendencies and open challenges of the field.
- The aforementioned experimentation is work in progress for preparing an article focused on:
 - On-device learning of mobility information with an event-oriented perspective.
 - The usage of this information for a power efficient adaptation of the sensing dimension.
 - Setting the base for further modules and strategies for boosting the learning of mobility patterns.

² Power management techniques in smartphone-based mobile sensing: a survey, first review round, Pervasive and mobile computing (Elsevier)

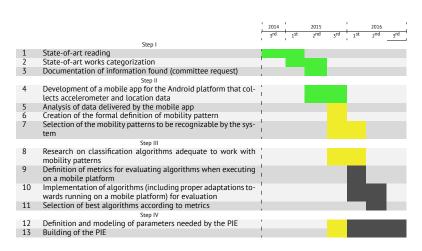


Table: Schedule of activities (each column represents a four months period)

Schedule

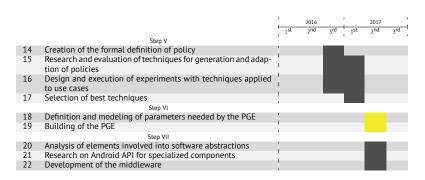


Table: Schedule of activities (each column represents a four months period)

Schedule

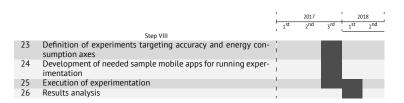


Table: Schedule of activities (each column represents a four months period)

Schedule



Table: Schedule of required activities

* Survey was out of original schedule, however, it brings added value to our work and also acts as a scientific booster for improving and achieving our solution.

Conclusions

- A brief analysis of the problem addressed by this thesis work has been presented.
- A summary of related state of art solutions, as suggested by committee, has been covered:
 - A taxonomy for categorizing of the solutions.
 - A new framework for decomposing and studying them.
- The general approach of our solution, which is based on an expanded spatial-time model for identifying and learning user mobility, has been introduced.
- An experimental step that shows the feasibility of performing the on-device building of such expanded models has been also presented.

Thank You for your attention!

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Montoliou's algorithm for stay points detection [19]

```
Require: A GPS trajectory T = \{p_1, p_2, \dots, p_N\}, a distance threshold \theta_d, a minimum time threshold \theta_{tmin}, and a
    maximum time threshold \theta_{tmax}.
Ensure: A set of points of interest \Pi
1: i \leftarrow 1
2: Π ← Ø
 3: while i < N do
       i = i + 1
         while i < N do
6:
             t \leftarrow \mathsf{timeDifference}(p_i, p_{i-1})
              if t > \theta_{tmax} then
8:
                  i \leftarrow i
9:
                  break
10:
              end if
11:
              d \leftarrow distance(p_i, p_i)
12:
              if d > \theta_d then
13:
                   t \leftarrow \mathsf{timeDifference}(p_i, p_{i-1})
14:
                   if t > \theta_{tmin} then
                        \pi.\mathsf{lat} = \sum_{k=i}^{j-1} \frac{p_k.\mathsf{lat}}{|i-1-i|}
15:
                        \pi.lon = \sum_{k=i}^{j-1} \frac{p_k.lon}{|i-1-i|}
16:
17:
                        \pi.at = p_i.ts
18:
                        \pi.dt = p_{i-1}.ts
19:
                        \Pi \leftarrow \Pi \cup \pi
20:
                    end if
21:
                   i \leftarrow i
22:
                   break
23:
              end if
24:
              i \leftarrow i + 1;
25:
          end while
26: end while
```

State-of-art solutions

| Name | Variants | Machine learning technique | Sensors involved | Complex- ity | OL | 00 | US |
|----------------------|--|----------------------------|-----------------------------------|-----------------|----|----------|----|
| G-Sense [23] | User behavior learning (DC) | SDR | GPS | low | | | |
| Perez-Torres [24] | User behavior learning (DC) | SDR | GPS | low | | | |
| SenseLess [1] | User behavior learning (DC), Sensor replacement (CR, DR) | SDR | WPS, GPS, ACC | low | | | |
| SensTrack [30] | User behavior learning (DC), Sensor replacement (CR, DR) | SDR | ACC, orientation sensor, GPS, WPS | low | | | |
| Man and Ngai [17] | User behavior learning (DC, VI), Sensor replacement (CR) | SDR | ACC, magnetic field sensor, GPS | low | | | |
| EnLoc [5] | User behavior learning (DC, VI), Sensor replacement (DR) | SDR, Mobility Tree | WPS, GPS, cellular ID | medium | | ✓ | |
| EnTracked [12] | User behavior learning (DC), Sensor replacement (CR) | SDR | ACC, GPS | medium | | ✓ | |

Problem statement Methodology State-of-art Proposed solution Important results Future work Conclusions Reference

State-of-art solutions

| Name | Variants | Machine learning technique | Sensors involved | Complex- ity | OL | 00 | US |
|--------------------------------|-----------------------------|-------------------------------|--|-----------------|----|----|----|
| Alvarez, Morillo [2, 20] | - | Ameva algorithm | ACC | medium | | | |
| Mazilu [18] | Sensor replacement (CR) | DT | Temperature, humidity, pressure | medium | | | |
| Srinivasan [27] | User behavior learning (DC) | DT | ACC | medium | | | |
| Khalifa [9] | Sensor replacement (CR) | KNN | Model of ACC-based harvesting device | medium | | | |

State-of-art solutions

| Name | Variants | Machine learning technique | Sensors involved | Complex- ity | OL | 00 | US |
|--------------|--|--|--|-----------------|----------|----------|----|
| SensLoc [10] | User behavior learning (DC, RD), Sensor replacement (CR) | SDR | Wi-Fi fingerprinting, GPS, ACC | medium | ✓ | | |
| CAPS [22] | User behavior learning (DC, RD), Sensor replacement (CR) | SDR | GPS, cellular ID | medium | ✓ | | |
| RAPS [21] | User behavior learning (DC, RD), Sensor replacement (CR, DR) | SDR | WPS, GPS, ACC, Bluetooth, cellular ID | medium | ~ | | |
| A-Loc [13] | User behavior learning (DC, RD), Sensor replacement (CR, DR) | HMM, Bayesian estimation framework | GPS, WPS, Bluetooth, cellular ID | medium | ✓ | ✓ | |
| SmartDC [4] | User behavior learning (DC, RD), Sensor replacement (CR, DR) | HMM and LZ predictor | GPS, WPS, Wi-Fi and cellular ID fingerprinting | medium | ~ | ✓ | |

Problem statement Methodology State-of-art Proposed solution Important results Future work Conclusions Reference

State-of-art solutions

| Name | Variants | Machine learning technique | Sensors involved | Complex- ity | OL | 00 | US |
|---------------|--|--|---|-----------------|----------|----------|----------|
| Jigsaw [14] | User behavior learning (DC), Sensor replacement (CR) | Microphone: NB with Gaussian Mixture Model (GMM). ACC: DT. GPS: MDP. | ACC, Microphone, GPS | high | | ✓ | ~ |
| Donohoo [6] | User behavior learning (DC) | Several. KNN and NN selected as best. | ACC, GPS, WPS, cellular ID, light, device data, mobile app requirements | high | | | ✓ |
| EEMSS [28] | User behavior learning (DC), Sensor replacement (CR, DR) | GPS and ACC: SDR. Microphone: SSCH algorithm. | ACC, microphone, GPS | high | | | ✓ |
| iLoc [16] | User behavior learning (RD), Sensor replacement (CR) | НММ | Wi-Fi & GSM fingerprinting | high | ✓ | | ✓ |
| Yurur [29] | User behavior learning (DC, RD) | НММ | ACC | high | ✓ | | ✓ |
| FreeTrack [3] | User behavior learning (DC, RD), Sensor replacement (CR, DR) | НММ | GPS, Wi-Fi, cellular ID, battery status | high | ✓ | | ✓ |