# Soumo Roy

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#### **EDUCATION**

# Vellore Institute of Technology (VIT)

Vellore, Tamil Nadu, India

Bachelor of Technology in Electronics and Communication Engineering

July 2021 - May 2025

*CGPA*: 8.83/10 (**Top 10**% of the batch)

TECHNICAL SKILLS

**Programming Languages:** Python, C++, MATLAB, LaTeX

Libraries and Tools: PyTorch, Sklearn, Pandas, Numpy, OpenCV, Git, Docker, Linux(Ubuntu)

Simulation Packages: ROS1, ROS2, Gazebo, RVIZ, MuJuCo, pybullet, OpenAI Gym

Boards: NVIDIA Jetson Nano(2 GB), Intel Atom, Arduino Uno, Raspberry pi 3b, STM32 black pill, blue pill, ESP32

**WORK EXPERIENCE** 

#### Research Associate

IIIT Hyderabad, Telangana, India

January 2025 - present

- \* Working under Dr Madhava Krishna at RRC (Robotics Research Center) at IIIT Hyderabad
- \* Implemented a path planner for an autonomous wheelchair for navigating in crowded environments using generative AI (VQ-VAE and PixelCNN) with a novel sampling optimiser which improved efficiency by 40% compared to state of the art learning based approaches.

## SN Bose Summer Research Intern

NIT Silchar, Assam, India

June 2024 - July 2024

- \* Worked under Dr Yogesh Singh at Advanced Robotics Research Lab, NIT Silchar
- \* Collaborated on a MATLAB simulation of shape memory alloy(SMA) based assistive robotic glove simulation for patients with wrist mobility issues, which reduced strain by 78%.

# SURGE Research Intern

IIT Kanpur, Uttar Pradesh, India

May 2024 - July 2024

- \* Guided by Dr. Tushar Sandhan and Mr. Prem Raj at Intelligent System Control Lab, IIT Kanpur
- \* Contributed to a human robot collaboration project using imitation learning with UR5 collaborative robot and Intel RealSense camera for the collaborative action of heavy object lifting with an efficiency of 68% compared to reinforcement learning approaches.
- \* Was one among 42 students selected under the institute project funded category at the IIT Kanpur

# **Robotics System Validation Intern**

Unbox Robotics, Maharashtra, India

August 2023 – November 2023

\* Developed on a project to automate the testing of the web page used for controlling robots using webdriver.io and JavaScript, Docker and deployed it on GitLab CI/CD pipeline, which improved validation teams' testing efficiency by 20%.

## **PROJECTS**

- **Spoon feeder**, Implemented reinforcement learning algorithms (PPO, SAC and DDPG) across different manipulators simulating feeding and drinking tasks on OpenAI gym, which was published in IEEE INDICON-24 conference <a href="GitHub">GitHub</a>
- **Crowdsurfer-ROS**, Utilized generative AI with sampling optimiser for path planning for a mobile robot to navigate in a crowded environment with dynamic obstacles, won best bachelor thesis award for the project <u>GitHub</u>
- Eyantra Robotics Competition (IIT Bombay), Navigated a mobile robot with the help of SLAM algorithms in a warehouse by detecting and localising the packages placed on racks, and manipulating the robotic arm to pick them up where we were among the top 5 performing teams to represent our college at IIT Bombay. GitHub

## **PUBLICATIONS**

- S. Roy, J. Viju, B. Bhattacharya, "Adaptive Robotic Manipulator Simulation for Enhanced Feeding and Drinking Assistance", 21st IEEE INDICON-2024 DOI: 10.1109/INDICON63790.2024.10958301 <u>Link</u>
- S. Chowdhury, S. Roy, D. G. Chowdhury, S. Chakraborty, K. P. Jain, B. Bhattacharya, "SKIDS: An Object Classification and Smart Communication based Waste Bin", 3rd IEEE International Conference on Artificial Intelligence for Internet of Things (AIIoT-2024) DOI: 10.1109/AIIoT58432.2024.10574647 Link

#### **ACHIEVEMENTS**

- Featured in Telengana state newspaper during R&D showcase 2025, and attracted more than 300+ visitors to our poster based on my bachelor thesis (link)
- Won a seed grant of Rs 1.5 lakh (\$1790) from VIT faculty-student sponsored project fund for a medical assistive robot project under Dr. Budhaditya Bhattacharyya at Advance Digital Signal Processing Lab as a part of my final year project Link