

## Pull This Repo!!!

https://github.com/RacingAI/Reactive-Methods-Workshop



### What is it?

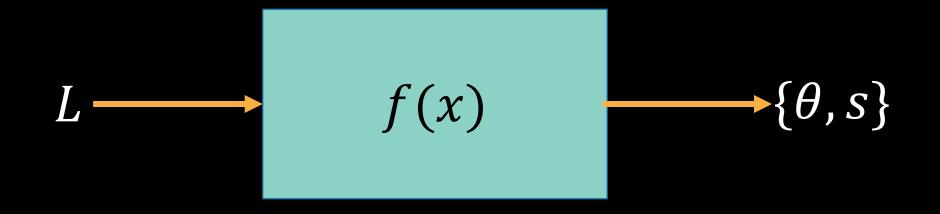
- > Reactive
- Consists of 2 main steps:
  - Find the longest safely traversable distance
  - Follow that line



### What is it?



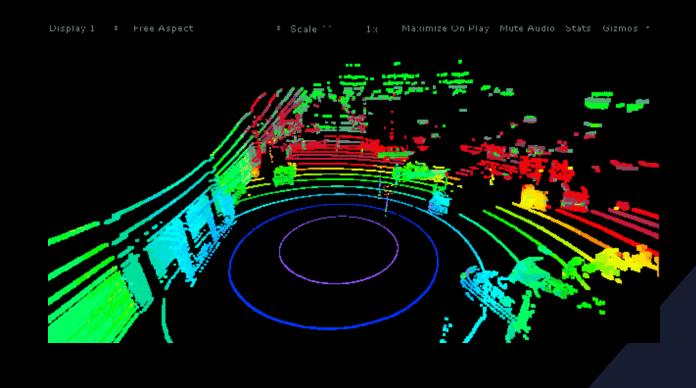
### What is it?





Get the LiDAR scans
from the sensors

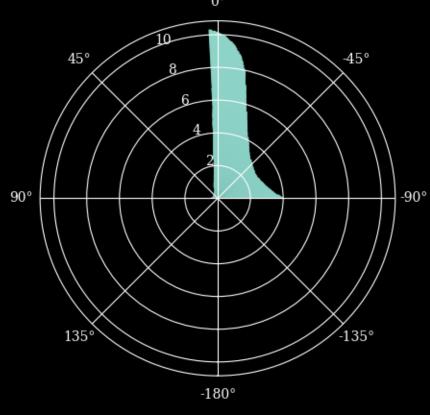




#### Get the LiDAR scans from the sensors



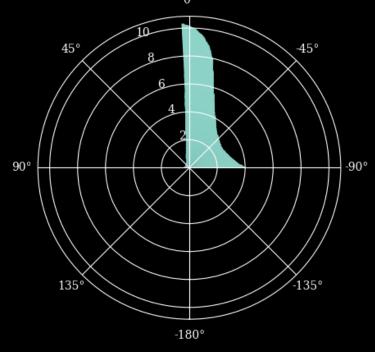




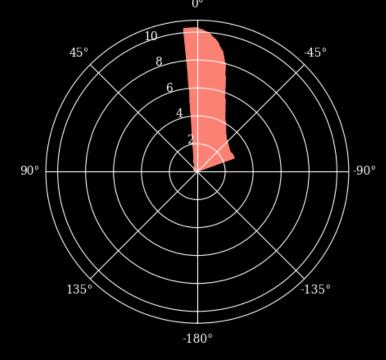
# Remove the LiDAR scans from behind you and limit your FOV





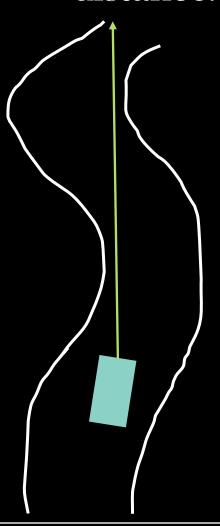


#### LiDAR Scan Data (Pre Processed)



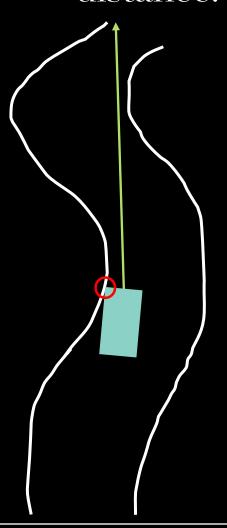
# What happens if we only travel the longest distance?





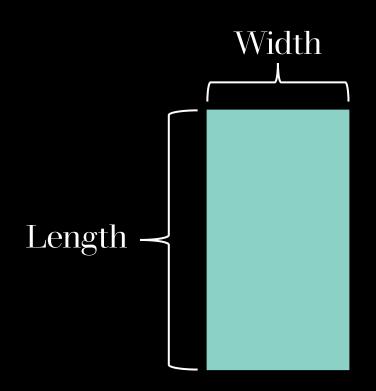
# What happens if we only travel the longest distance?





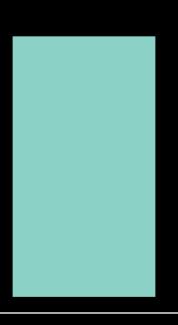
# What happens if we only travel the longest distance?

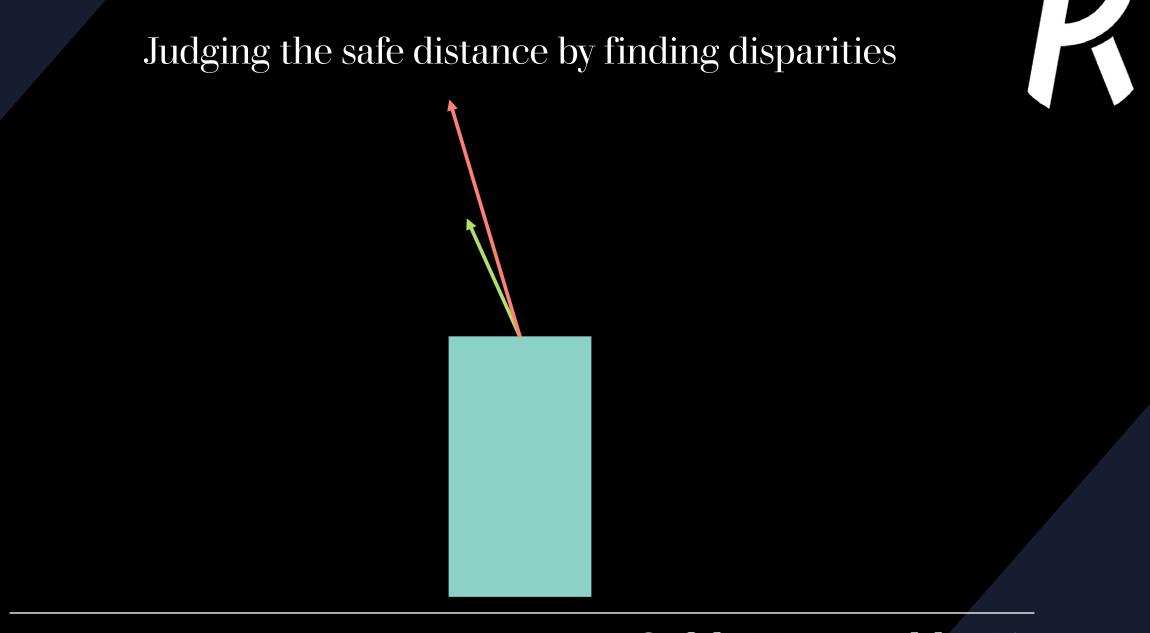




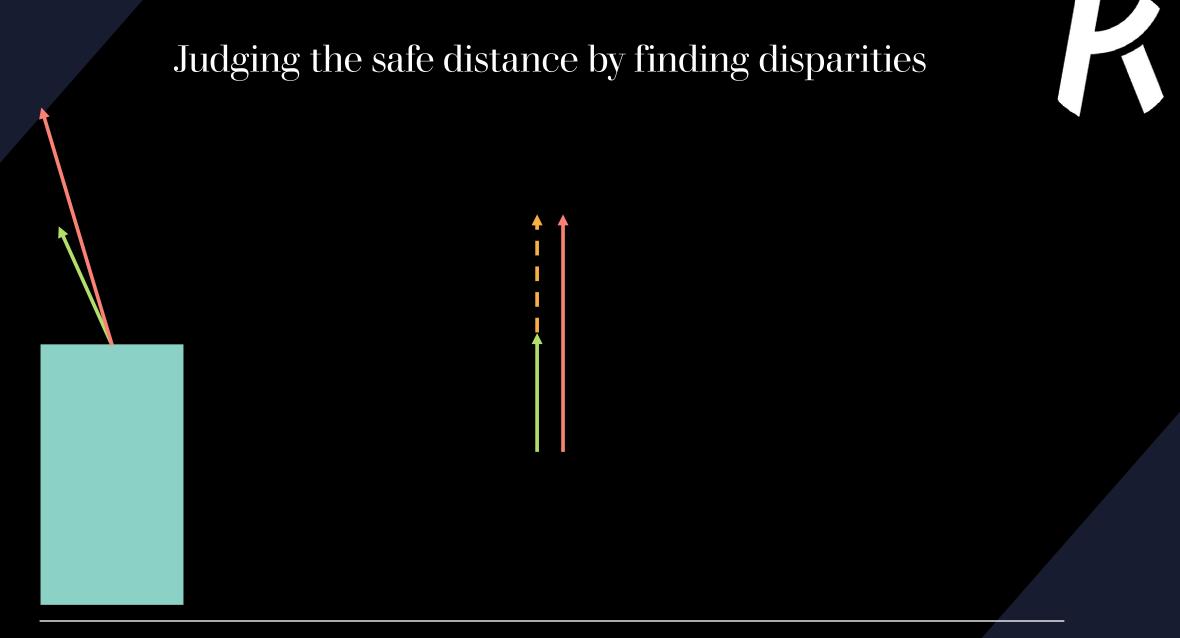








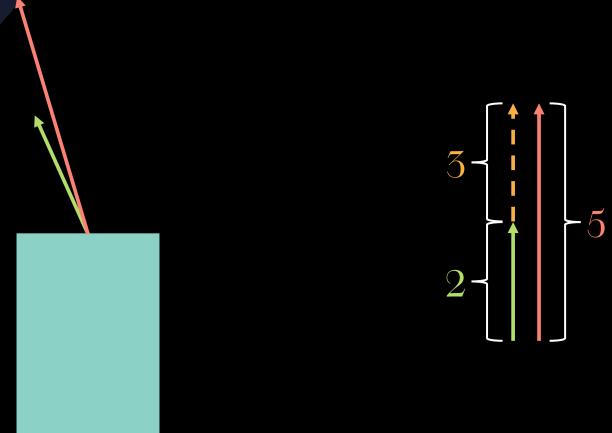




Longest Safely Traversable Distance

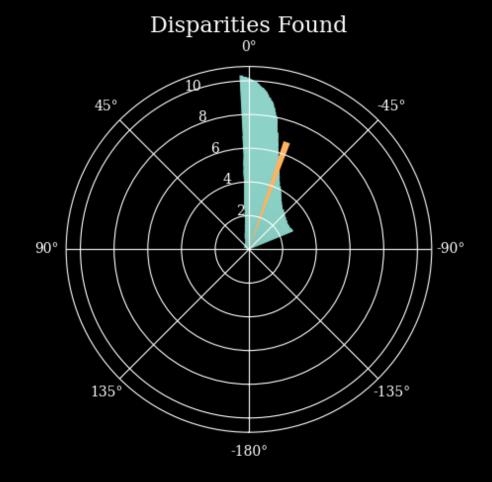






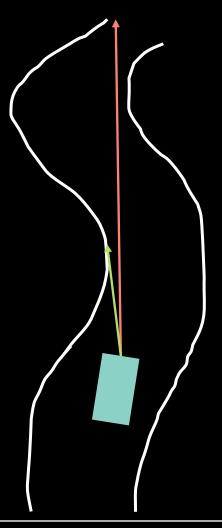


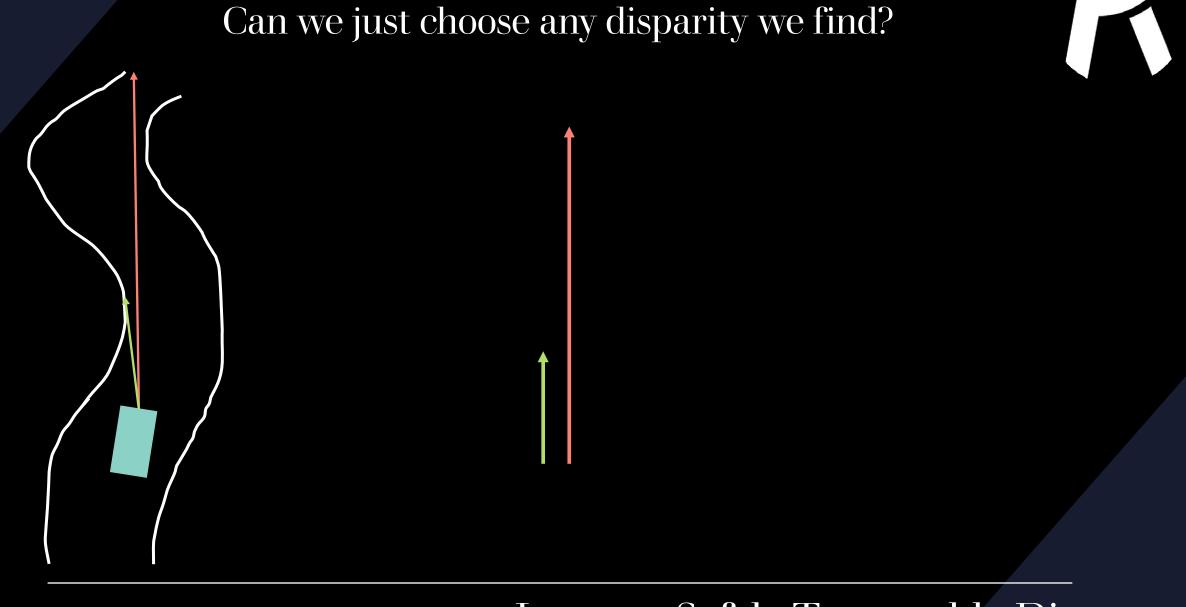






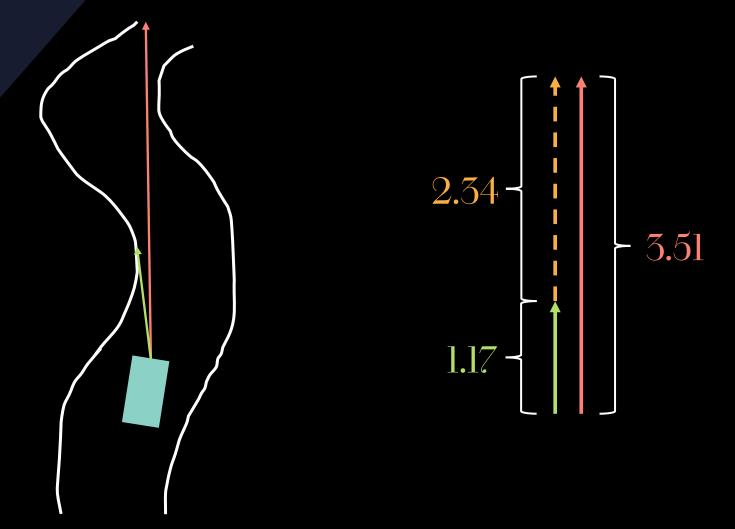






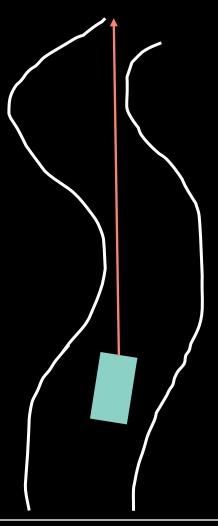


Can we just choose any disparity we find?



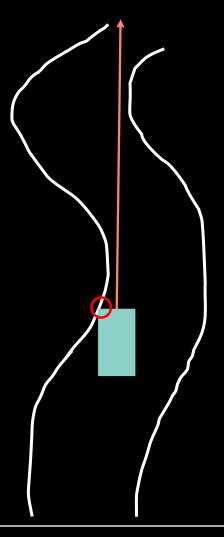


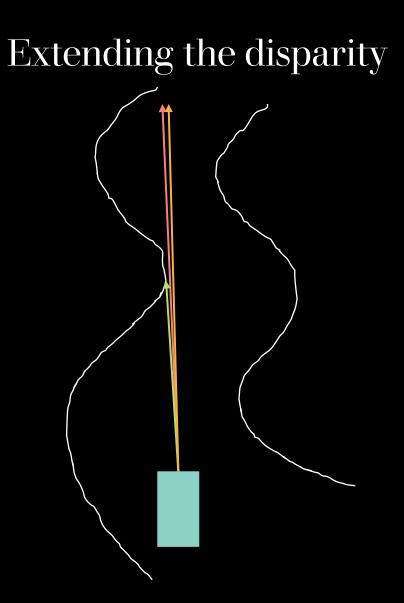








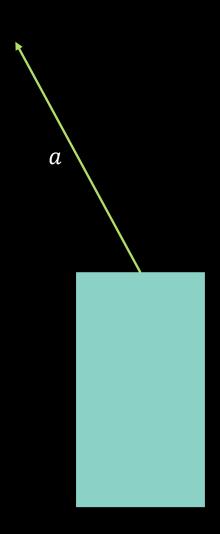






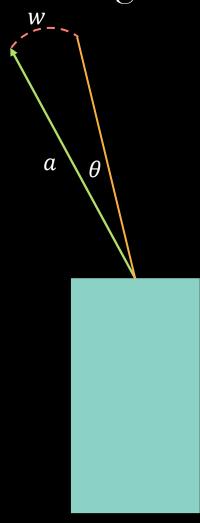






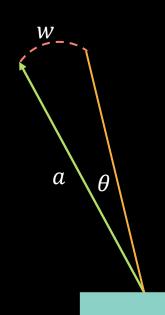






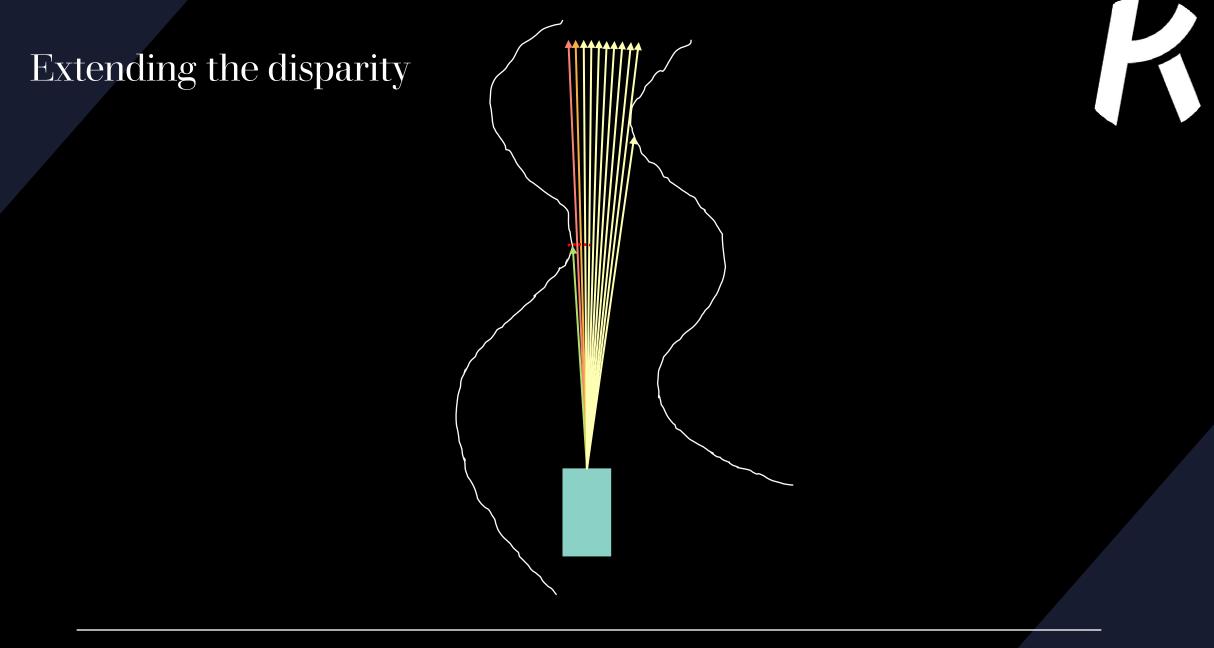




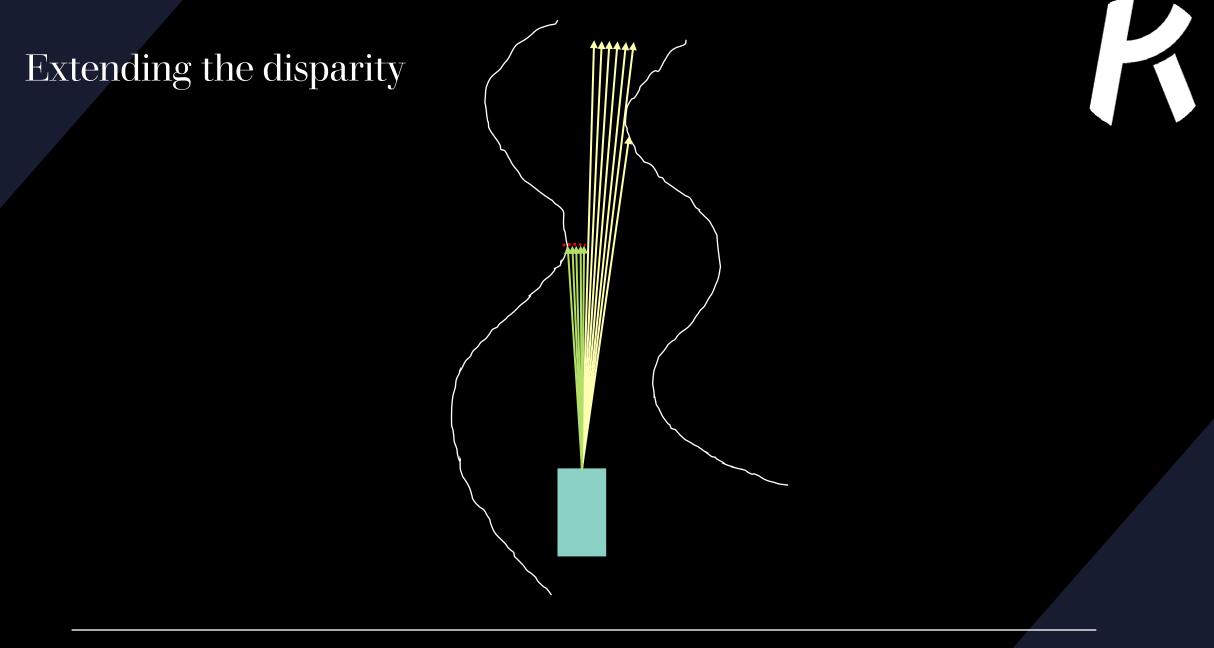


$$w = a\theta$$

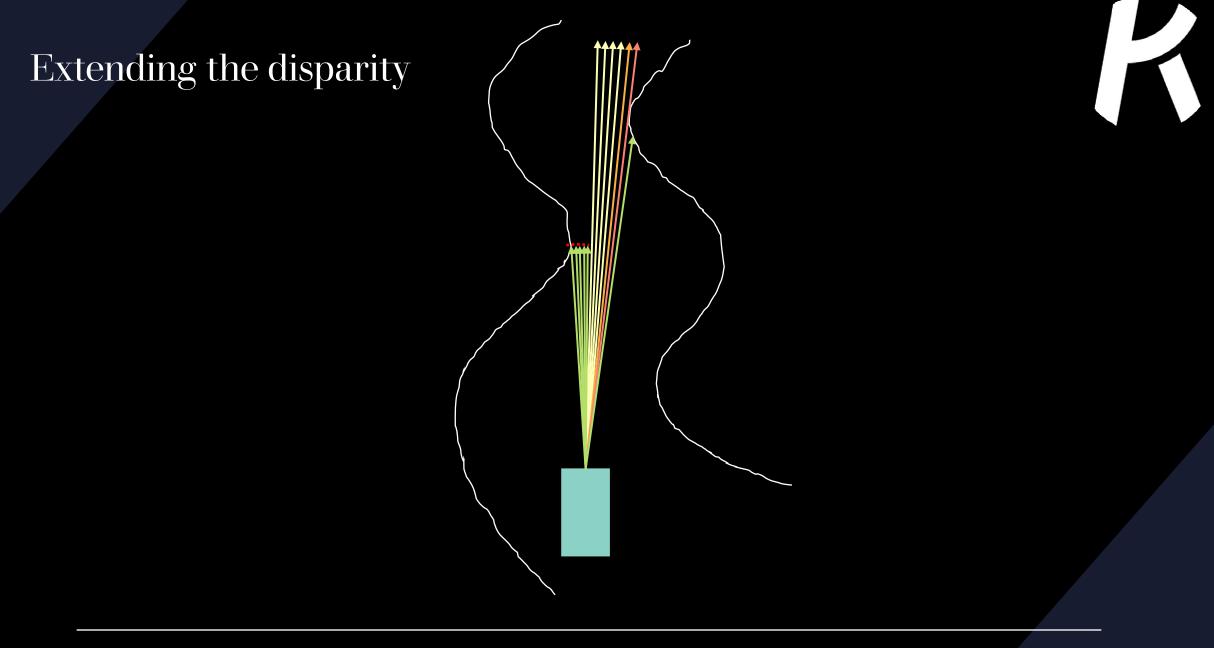
$$\theta = \frac{w}{a}$$



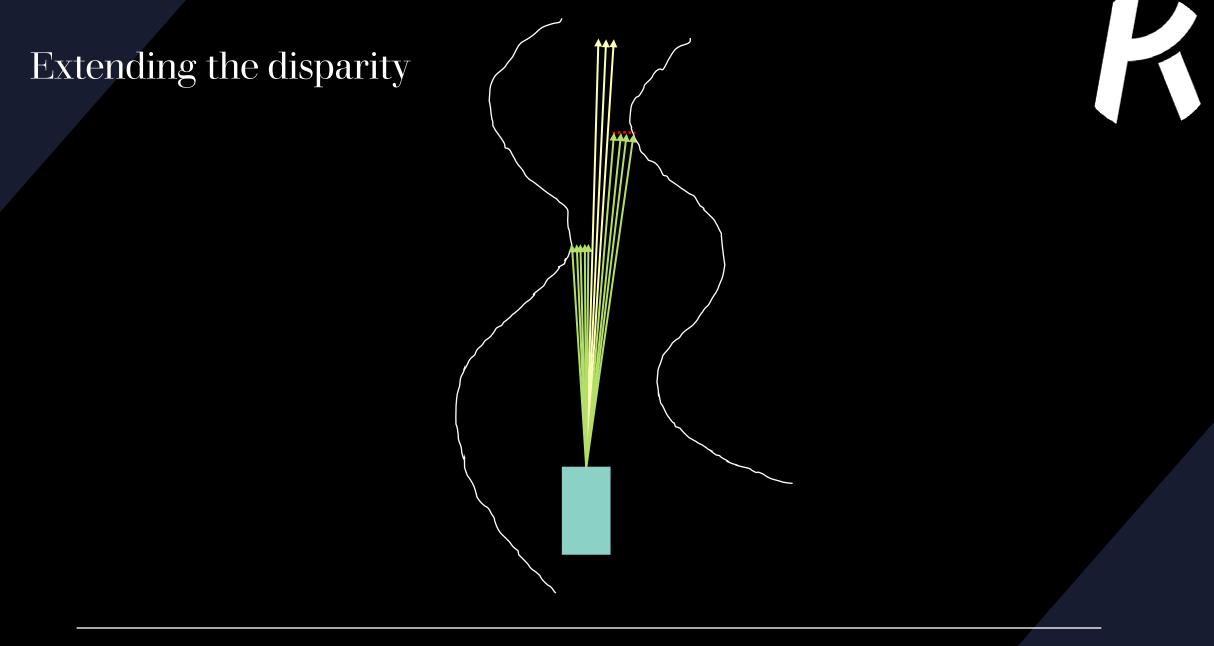
Longest Safely Traversable Distance



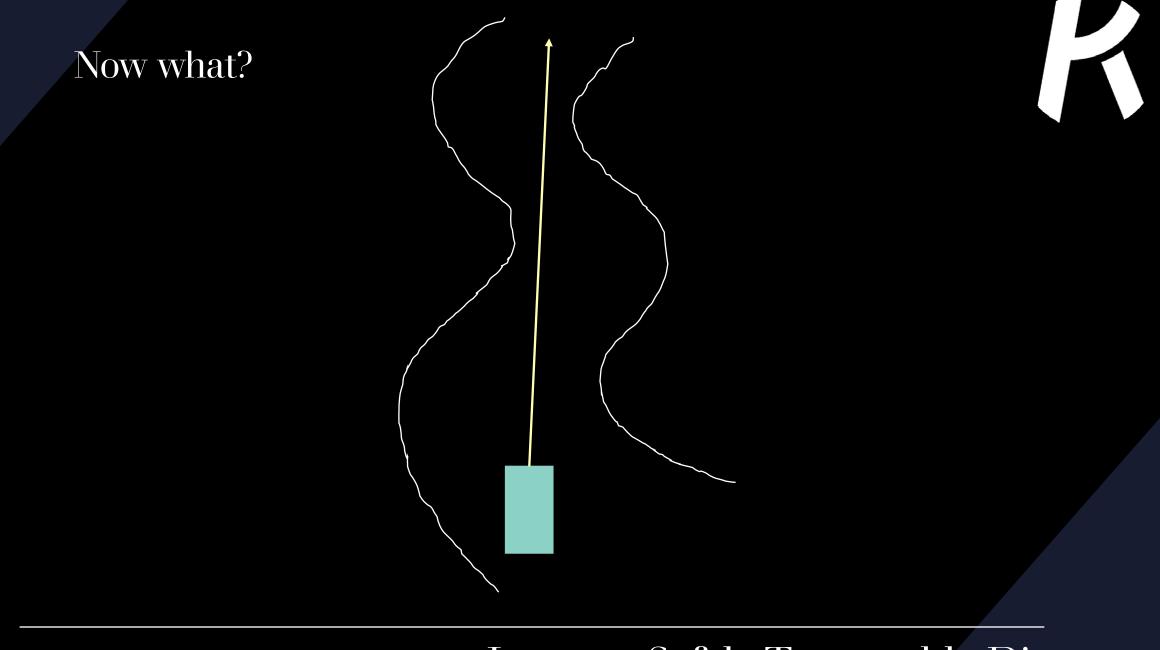
Longest Safely Traversable Distance



Longest Safely Traversable Distance

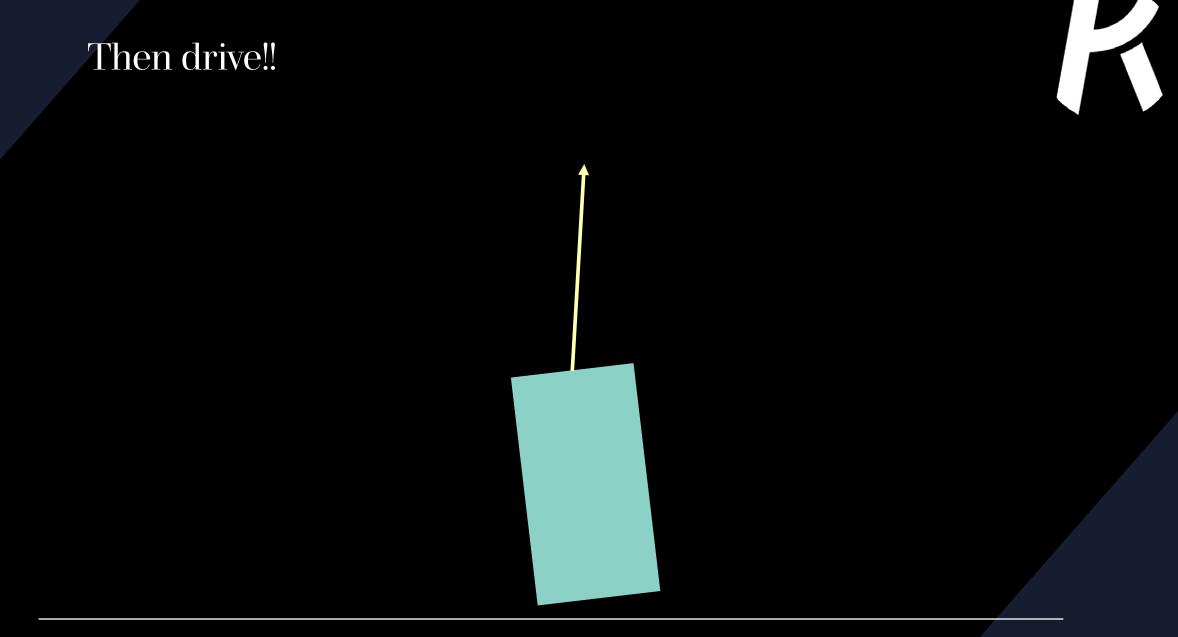


Longest Safely Traversable Distance



Longest Safely Traversable Distance

Now what?



Longest Safely Traversable Distance



What about speed?



## Where to go from here?

Virtual Competition - November 2022

Physical Competition - March 2023



### Thank You

Follow us on our Instagram @racing.ai

Contact us with any questions racingai.contact@gmail.com

