Sign Language Recognition Using Neural Networks A Two-Layer Implementation for Static Gesture Recognition

Oleksandr Solovei

Universidade de Aveiro

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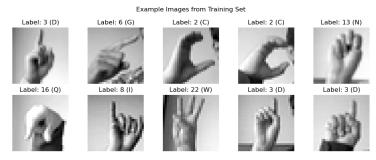
Overview

- Introduction
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- Neural Network Architecture
- 4 Results
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Problem Statement & Motivation

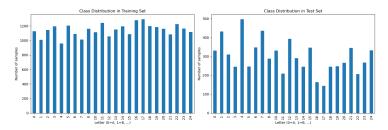
- Goal: Develop an accessible sign language recognition system
- Approach: Two-layer neural network for static gesture classification
- Dataset: Sign Language MNIST
 - 27,455 training images
 - 7,172 test images
 - 24 ASL letters (excluding J, Z which require motion)
- Impact: Enhanced communication tools for deaf community

Dataset Characteristics



- 28×28 grayscale images (784 features)
- Centered hand gestures
- Varying lighting conditions

Dataset Distribution



- Imbalanced classes (144-498 samples per class)
 - Most frequent: Letter E (498 samples)
 - Least frequent: Letter Q (144 samples)

Dataset Examples



Preprocessing Pipeline

Data Normalization

- Pixel scaling: $X_{normalized} = \frac{X}{255}$
- Range: [0, 1]

Label Processing

- One-hot encoding (24 classes)
- Label adjustment for J, Z gaps

Data Splitting

- Training Set: 27,455 samples
- Testing Set: 7,172 samples

Model Architecture

Network Structure

• Input Layer: 784 neurons (28×28 pixels)

• Hidden Layer: 256 neurons

• Output Layer: 24 neurons (one per letter)

Activation Functions

Hidden Layer: SigmoidOutput Layer: Sigmoid

Parameters

Total trainable parameters: 207128

Xavier initialization

Xavier Initialization

Layer-specific scaling factors:

$$\epsilon_1 = \sqrt{\frac{6}{784 + 256}} \approx 0.084$$

$$\epsilon_2 = \sqrt{\frac{6}{256 + 24}} \approx 0.149$$

• Weight matrices initialized uniformly:

$$W_1 \sim U(-\epsilon_1, \epsilon_1)$$

$$W_2 \sim U(-\epsilon_2, \epsilon_2)$$

Bias Vectors:

$$b_1 = 0 \in \mathbb{R}^{256 \times 1}$$

$$b_2 = 0 \in \mathbb{R}^{24 \times 1}$$

Benefits

- Prevents vanishing/exploding gradients
- Maintains activation variance across layers
- Enables faster convergence

Momentum in Training

Standard Gradient Descent:

$$W = W - \alpha \nabla L$$

Only uses current gradient

• Momentum Update ($\beta = 0.9$) :

$$v = \beta v - \alpha \nabla L$$
$$W = W + v$$

Accumulates previous updates

- Benefits:
 - Accelerates training in consistent directions
 - Helps escape local minima
 - Reduces oscillations in gradient updates



Training Strategy

- Optimization Parameters
 - Initial learning rate: 0.1
 - Momentum (β): 0.9
- Regularization Techniques
 - L2 penalty (λ): 0.01
- Loss Function Components
 - Binary cross-entropy

- Batch size: 64
- Total iterations: 80

Decay: 0.95 / 50 steps

L2 regularization term

Mathematical Framework

Forward Propagation:

$$Z_1 = W_1 X + b_1$$
 $Z_2 = W_2 A_1 + b_2$ $A_1 = \sigma(Z_1)$ $A_2 = \sigma(Z_2)$

Loss Function:

$$L_{BCE} = -\frac{1}{m} \sum_{i=1}^{m} \sum_{k=1}^{24} [y_k^{(i)} \log(a_k^{(i)}) + (1 - y_k^{(i)}) \log(1 - a_k^{(i)})]$$
 (1)

$$L_{total} = L_{BCE} + \frac{\lambda}{2m} \sum_{i,j} (W_{1_{ij}}^2 + W_{2_{ij}}^2)$$
 (2)

Weight Updates:

$$\mathbf{v}_W = \beta \mathbf{v}_W - \alpha \frac{\partial L}{\partial W}$$

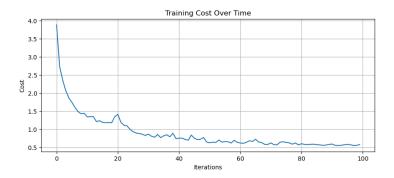
$$\mathbf{W} = \mathbf{W} + \mathbf{v}_W$$

Learning Rate Decay:

$$\alpha_t = \alpha_0 \cdot 0.95^{\lfloor t/50 \rfloor}$$



Cost Over Time Analysis



Performance Analysis

Overall Metrics

• Test Accuracy: 77.36%

• Weighted F1-score: 0.77

• Macro F1-score: 0.75

Best Performing Letters (F1-score)

O: 1.00

• B: 0.96

• C: 0.96

• A: 0.94

Challenging Letters (F1-score)

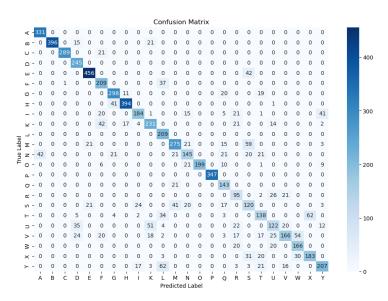
• R: 0.46

• Q: 0.55

• M: 0.57

• S: 0.57

Confusion Matrix



Interactive Web Implementation

User Interface:

- Live webcam feed
- Image capture functionality
- Preview of original capture

- Processed 28×28 preview
- Top-3 predictions display
- Confidence percentages

• Processing Pipeline:

- Real-time grayscale conversion
- Size normalization to 28×28
- Pixel value normalization (0-1 range)

Network Visualization:

- Layer-by-layer activation monitoring
- Neuron activity visualization
- Confidence distribution display

Improvements & Extensions

Model Enhancements

- Data augmentation for underrepresented classes
- Feature engineering for hand shape detection
- Deeper architecture exploration

Practical Applications

- Real-time recognition system
- Mobile application development
- Educational tools

Research Extensions

- Dynamic gesture recognition
- Multi-modal approaches
- Transfer learning exploration

Conclusion

Key Achievements

- Successful static gesture recognition
- Balanced performance-complexity trade-off
- Identified clear paths for improvement

Impact

- Foundation for accessible communication tools
- Benchmark for future implementations
- Insights for sign language recognition systems