Robot Project Accuracy Algorithm

1. Set numTimes = 0
2. Make robot move straight
3. Rotate robot 360 degrees
4. Rotate robot -360 degrees
5. Make robot stop moving
6. Add 1 to numTimes
7. If numTimes < 5, repeat step 2-6
8. Speak "I am the winner"
9. Make lights flash multicolored for 5 seconds