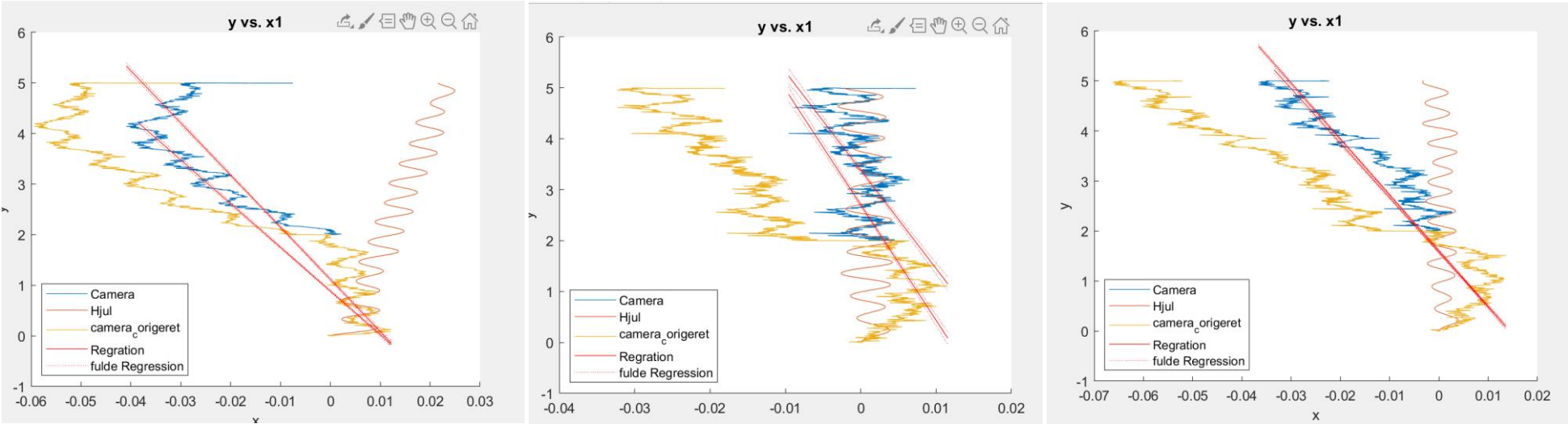


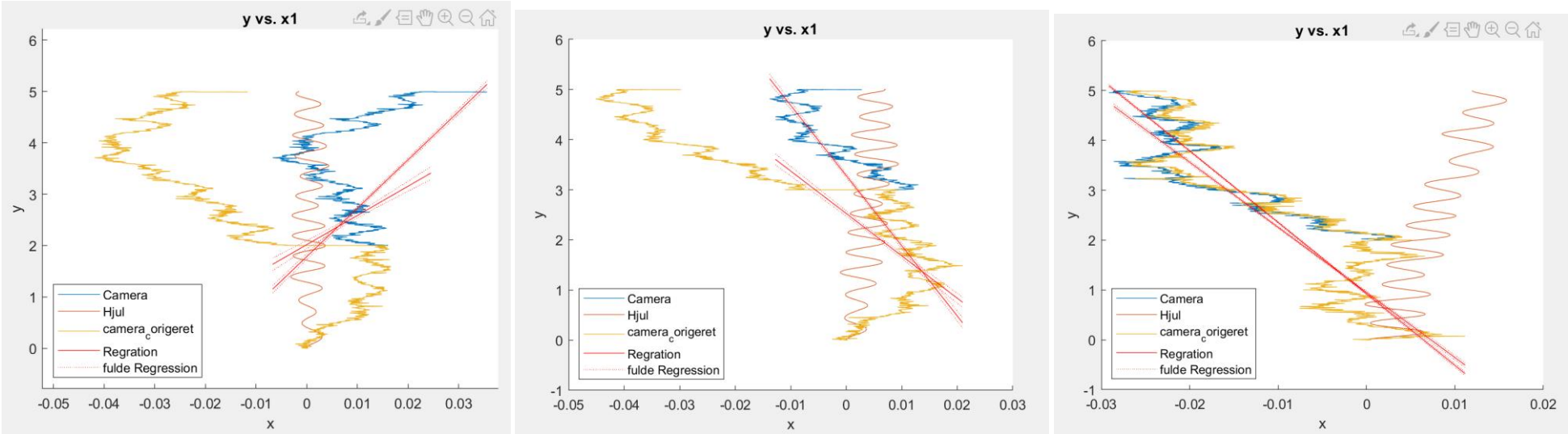
Appendices (various plots of the executed runs)

5m Asta

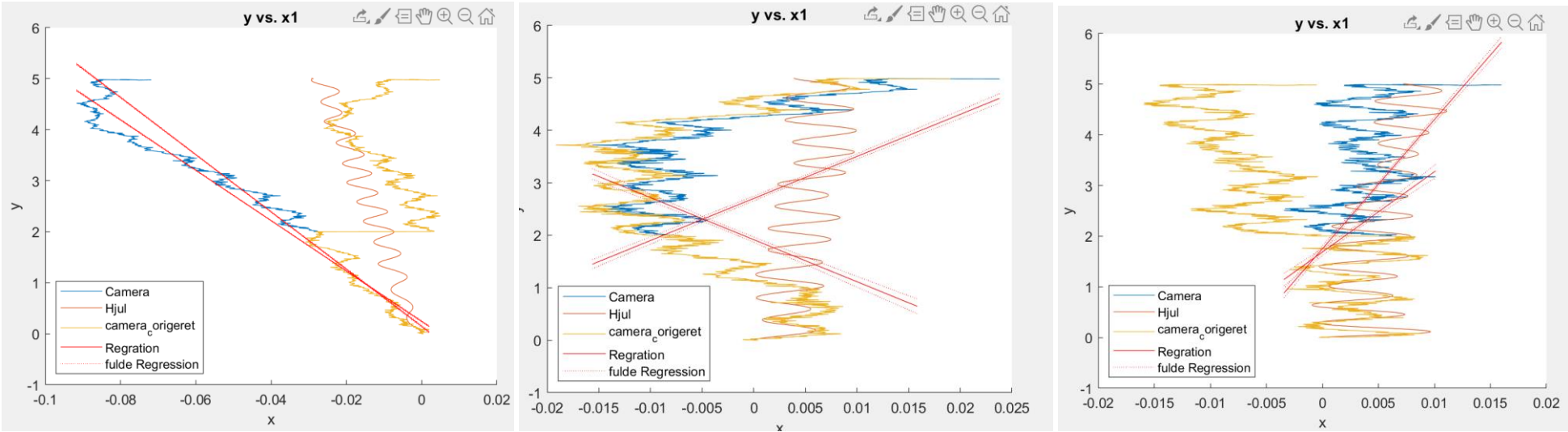
1- 3



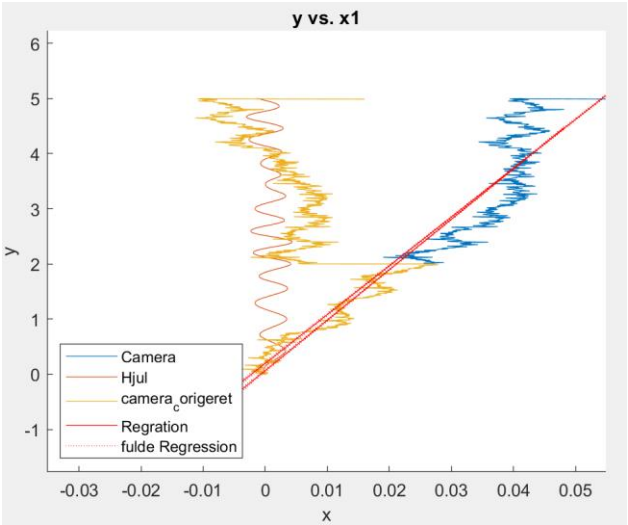
4 – 6



7-9



10



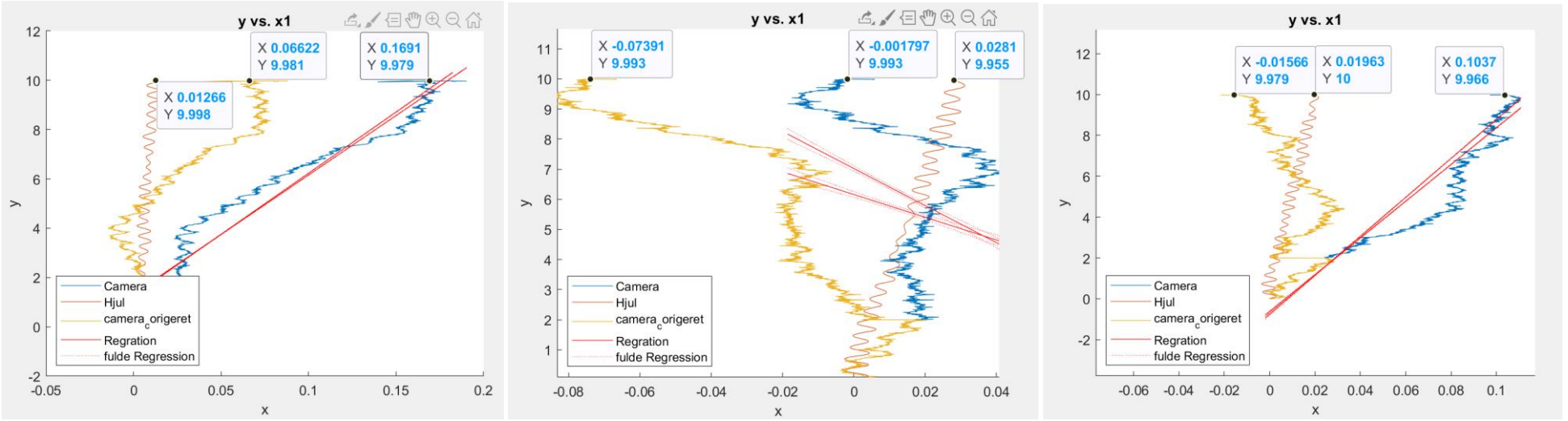
**Actual Deviation From 0**

- Tur 1, 5m , 11 cm skewed (left)
- Tu 2, 5m, 0cm
- Tur 3, 5m, 0cm
- Tur 4, 5m, 0cm
- Tur 5, 5m, 0cm
- Tur 6, 5m, 0cm
- Tur 7, 5m, 2cm left
- Tur 8, 5m, 3cm left
- Tur 9, 5m, 0cm
- Tur 10, 5m, 2cm left

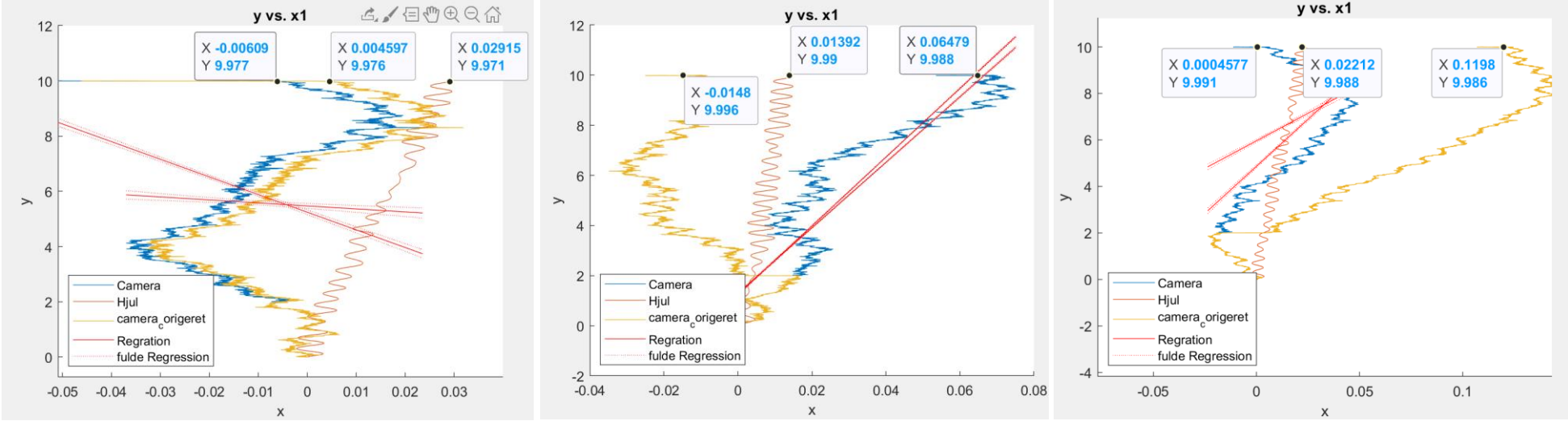
Appendices (various plots of the executed runs)

10m ASTA

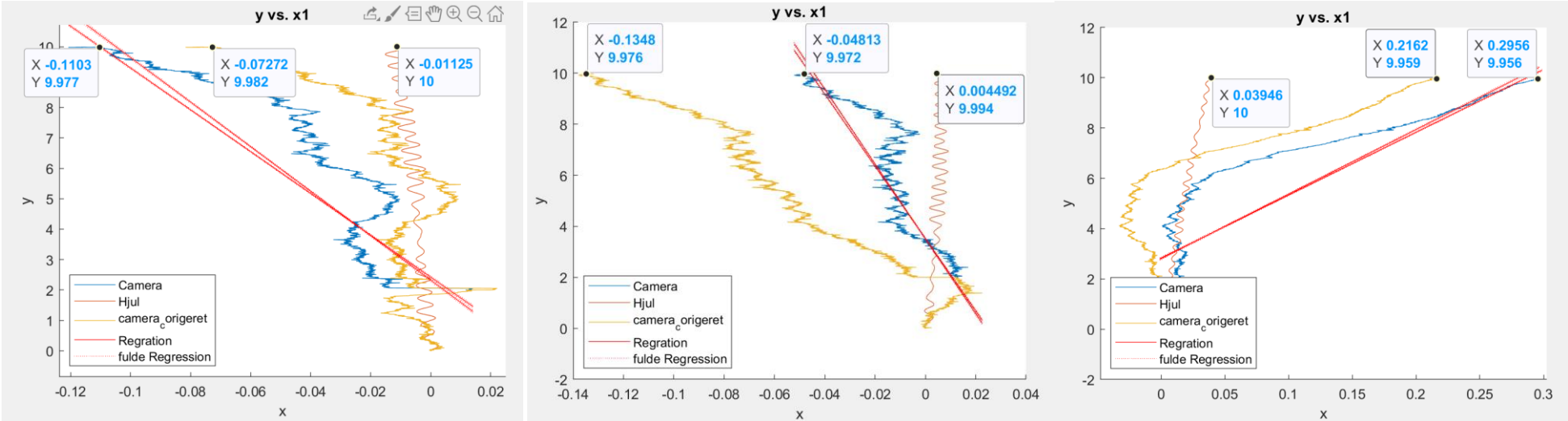
1-3



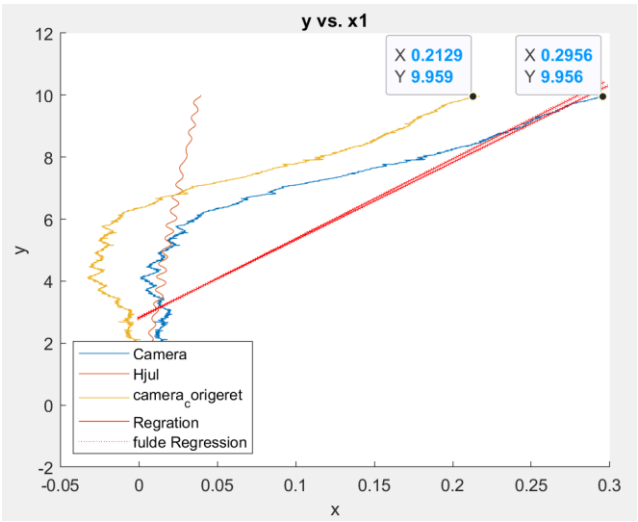
4-6



7-9



10

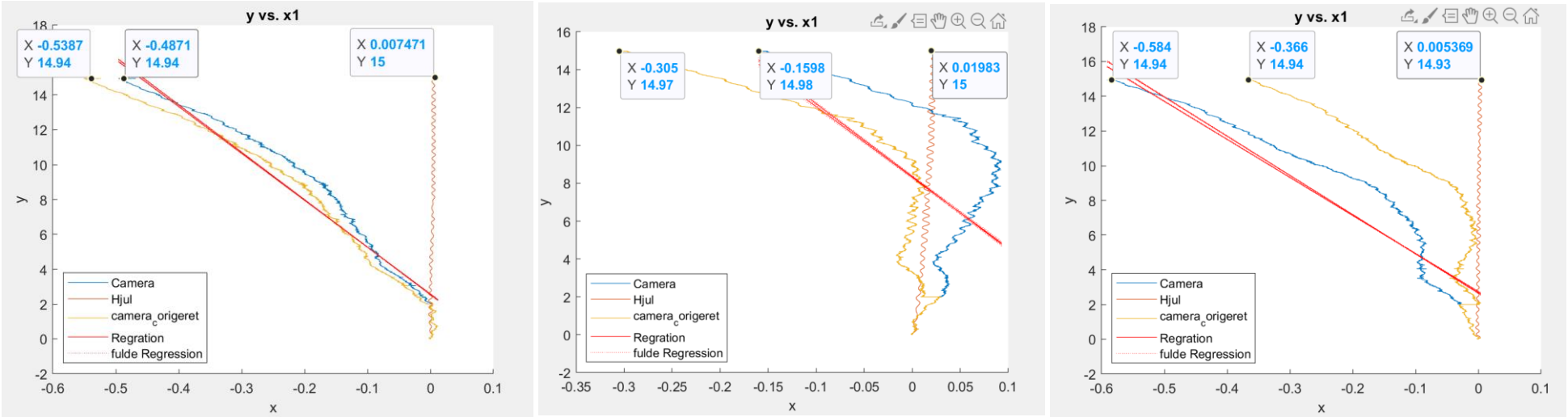


Actual Deviation From 0	
10 m – Stopped at 9.985m	
1,	9.985m, 0cm
2,	9.985m , 15cm left
3,	9.985m, 12cm left
4,	9.985m, 10cm right
5,	9.985m, 5cm right
6,	9.985m, 0cm
7,	9.985m, 1cm left
8,	9.985m, 16cm left
9,	9.985m, 17cm left
10,	9.985m, 30cm left

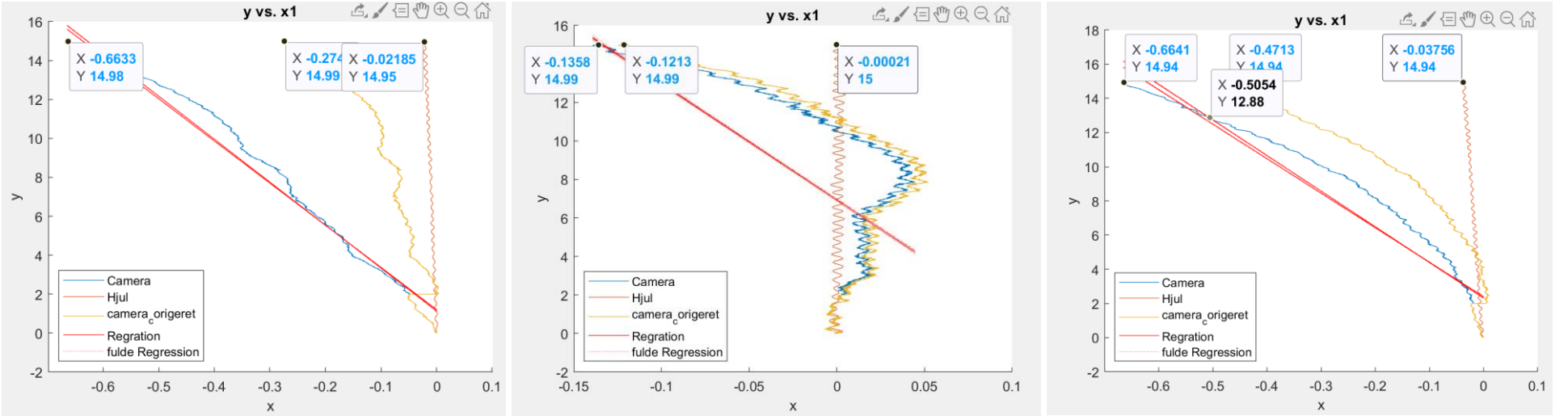
Appendices (various plots of the executed runs)

15m ASTA

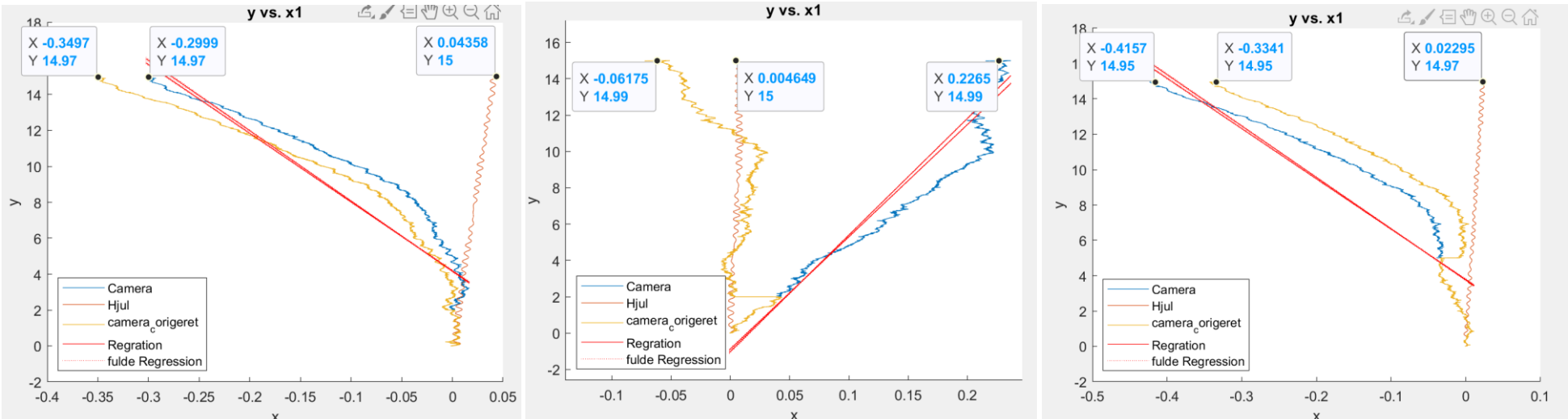
1-3



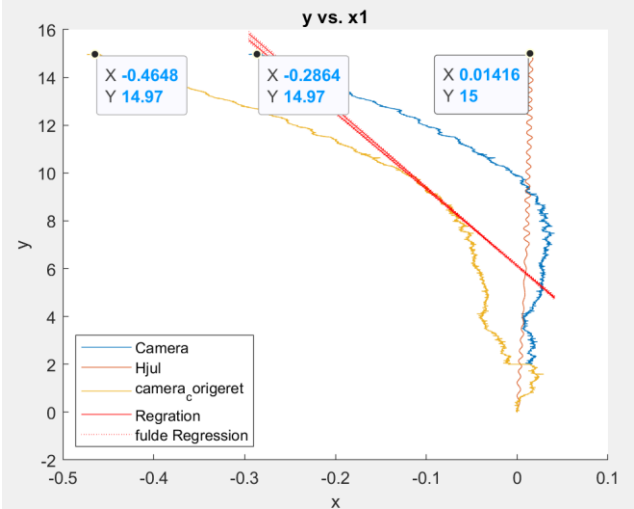
4-6



7-9



10



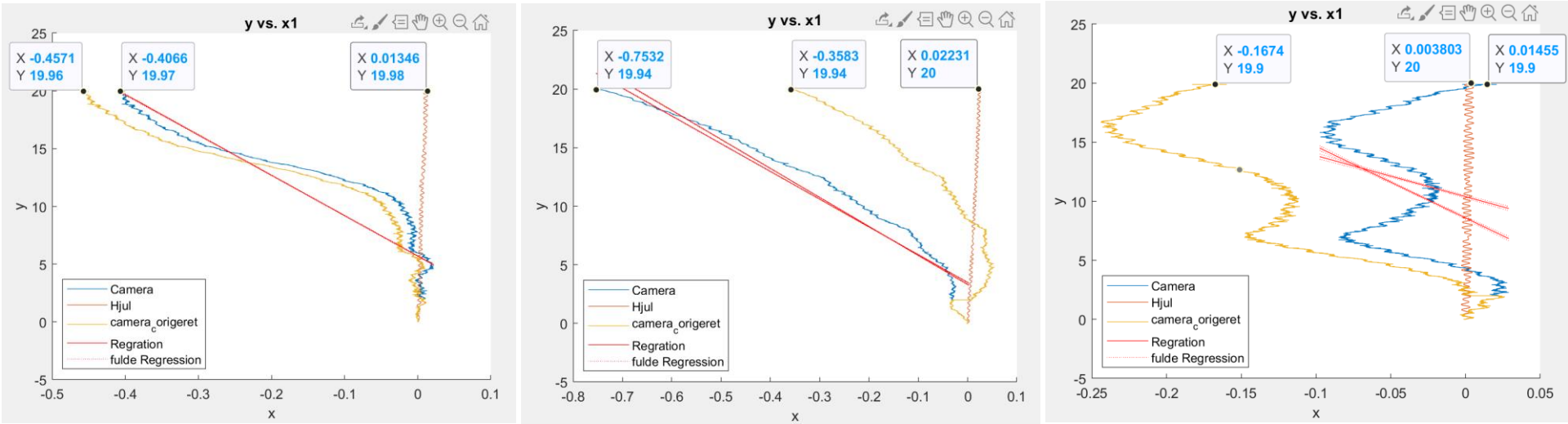
Actual Deviation From 0	
15 m – Stopped at 14.975m	
1,	14.975m, 25cm left
2,	14.975m, 0cm but runs an arc to the left
3,	14.975m, 10cm left
4,	14.975m, 26cm left
5,	14.975m, 12cm left
6,	14.975m, 79 cm left
7,	14.975m, 14cm left
8,	14.975m, 3cm right
9,	14.975m, 30cm left
10,	14.975m, 8cm left



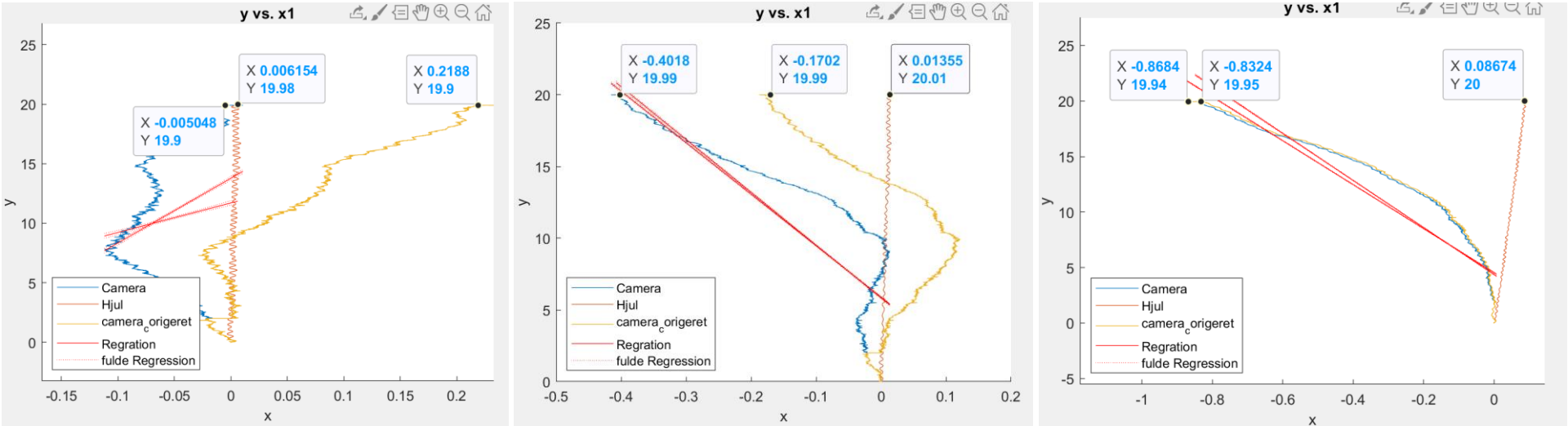
Appendices (various plots of the executed runs)

20m ASTA

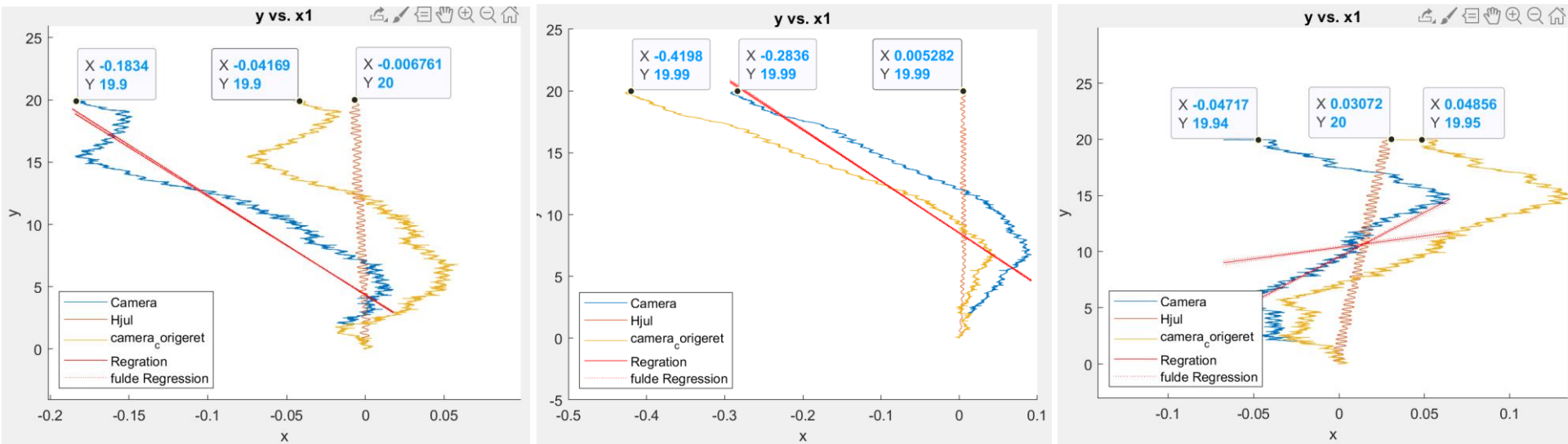
1-3



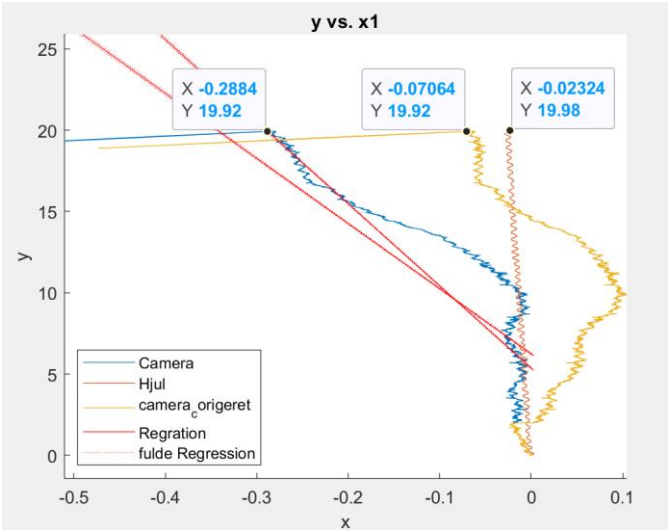
4-6



7-9



10

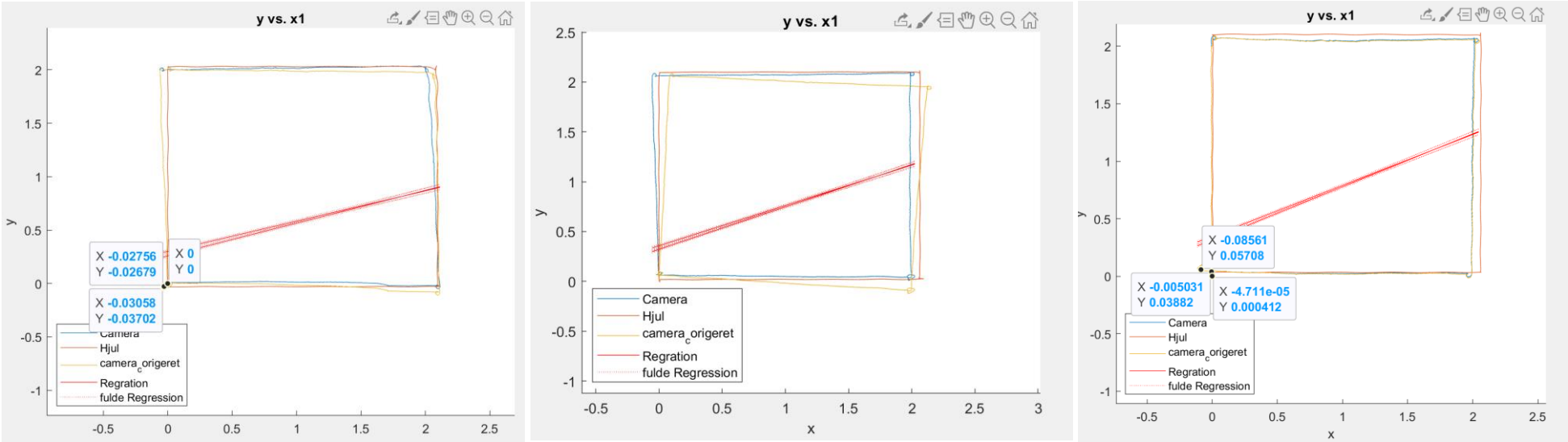


Actual Deviation From 0	
1,	19.965m, 1 cm right
2,	19.965m, 34 cm left
3,	19.965m, 5cm right – drove completely straight along the cord until about 17m (hit small bumps)
4,	19.965m, 12cm right
5,	19.965m 7cm right
6,	19.945m , 30cm left
7,	19.96m, 10cm left
8,	19.96, 25cm left
9,	19.955, 30 cm left
10,	19.965, 0 cm

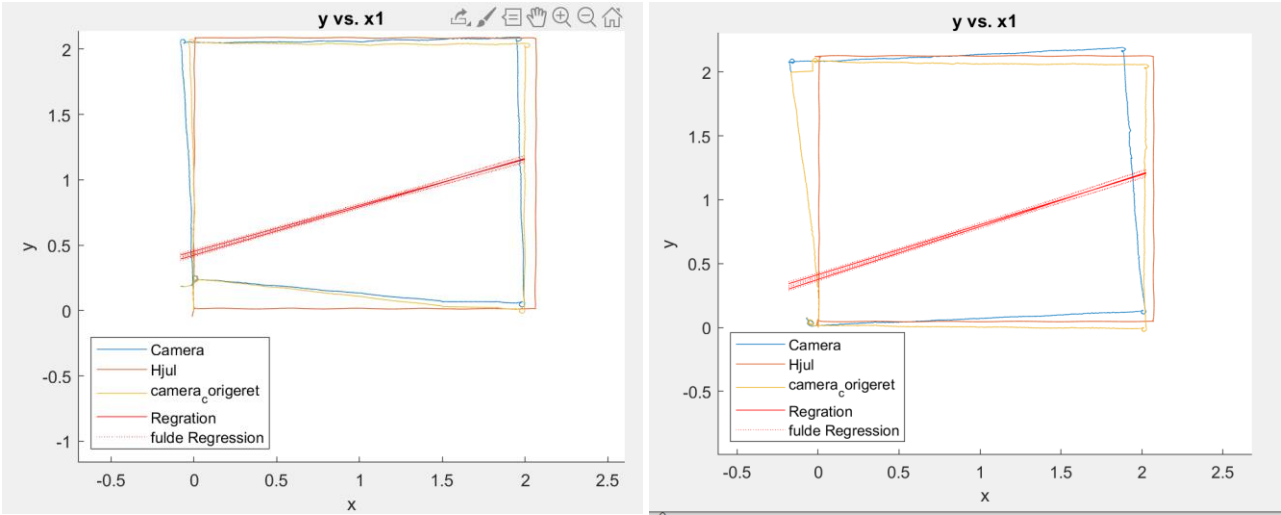
Appendices (various plots of the executed runs)

Firkant 2 m med uret

1-3



4-5

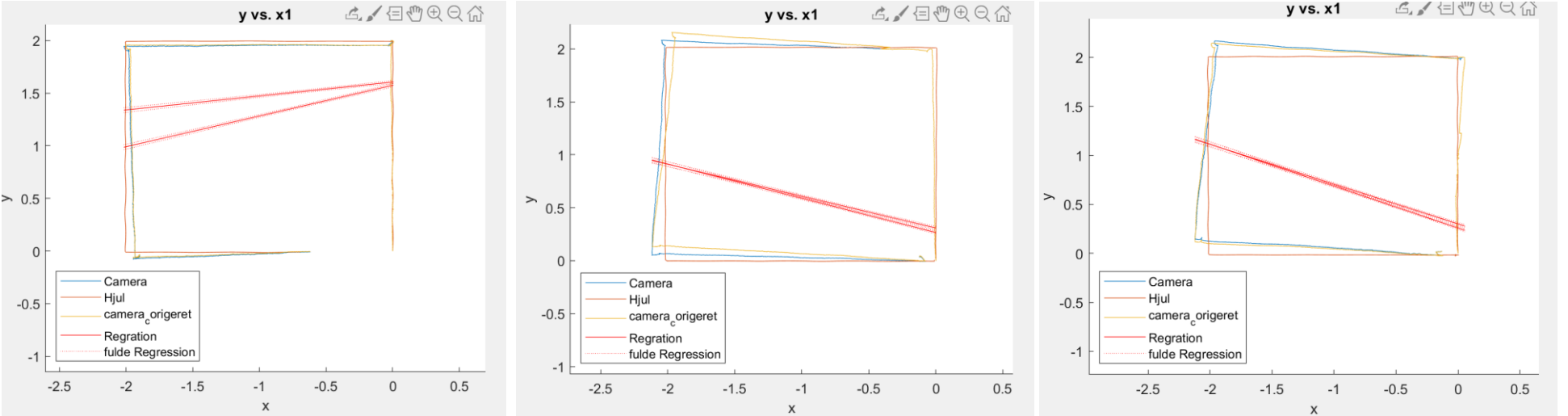


Actual Deviation From 0

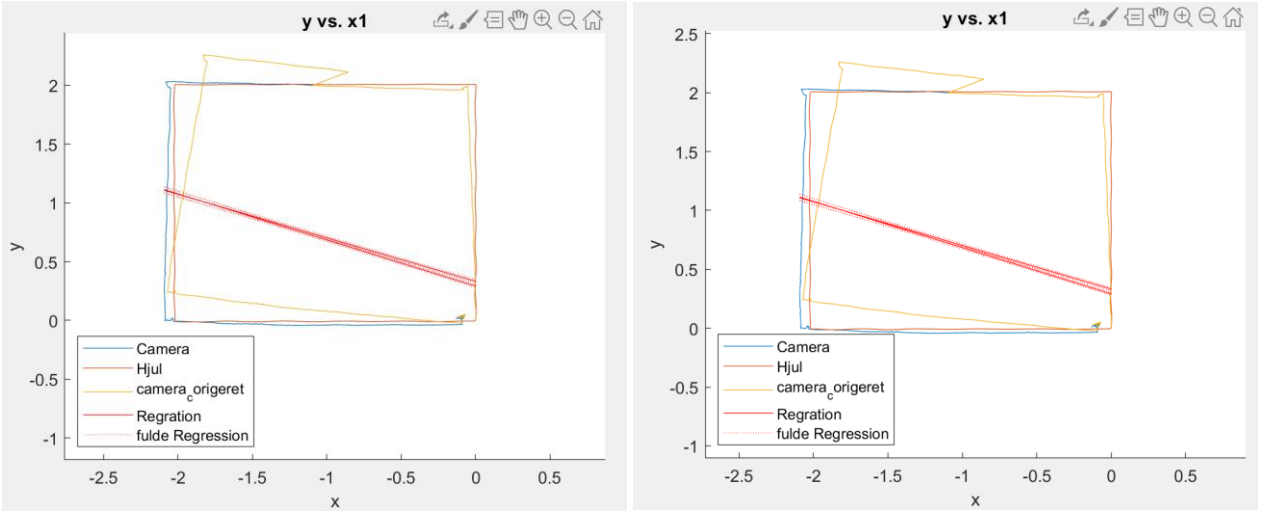
- 1, Square clockwise (2 cm to the left - straight ahead)
- 2, Square 2 clockwise (5 cm to the left and 7 cm to the front)
- 3, Square 3 clockwise (12 cm to the left and 10 cm in front)
- 4, Square 4 clockwise (10 left and 10 forward)
- 5, Square 5 clockwise (11 to the left of 6, 10 in front)

Firkant 2 m mod uret

1-3



4-5



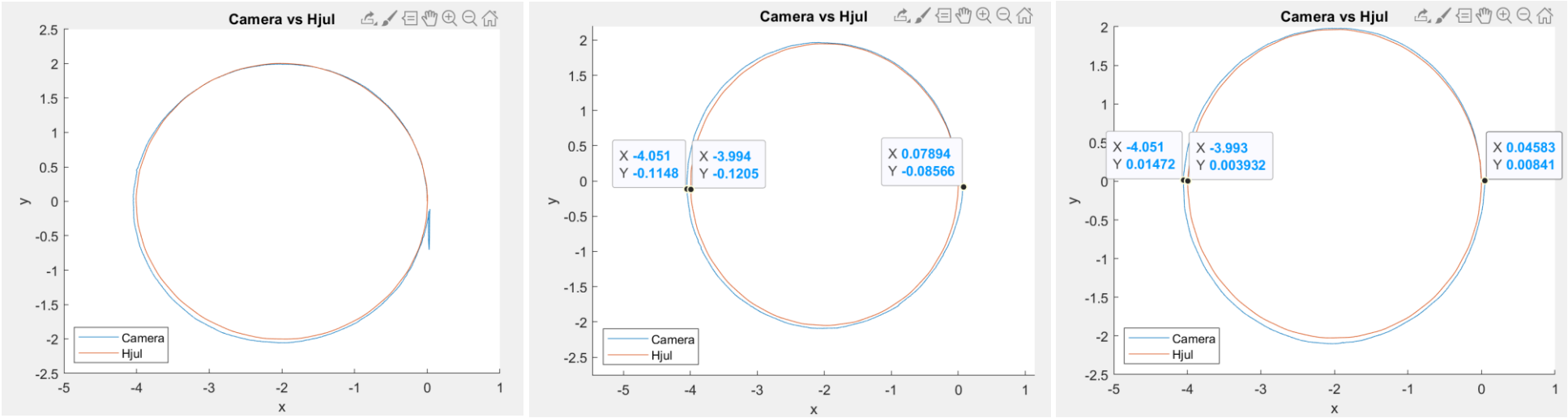
Actual Deviation From 0

- 1, Square 2 with turn, ended 2cm to the left of the cord, but straight on starting position and have the same direction
- 2, Square 2m turn again to the side, it holds 5cm to the left
- 3, Square 2m with turn ran the wire over eventually so slightly uneven change in the same direction of (a little over 5cm)
- 4, Square 2m with turn is 10cm on the right side also 10cm forward
- 5, Square 2m, 7cm far forward but straight on the cord to the sides.

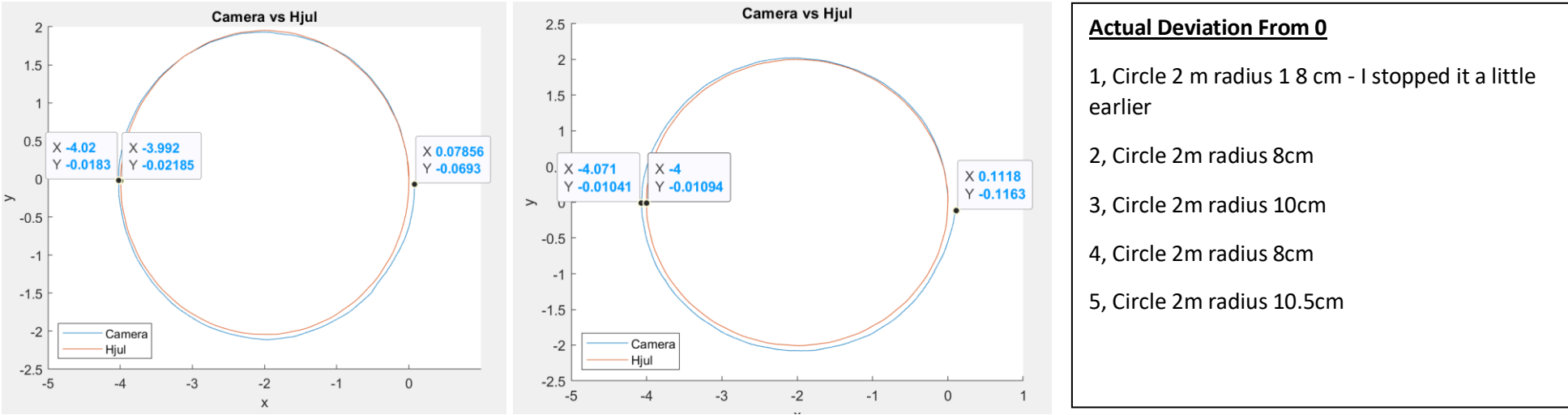
Appendices (various plots of the executed runs)

Cirkel 5m i diameter

1-3

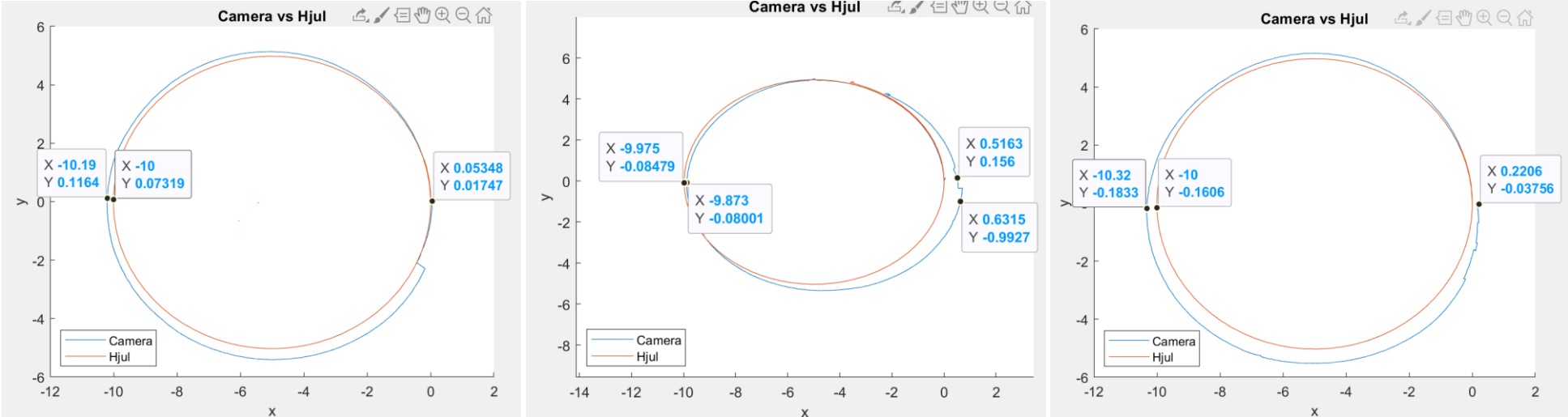


4-5

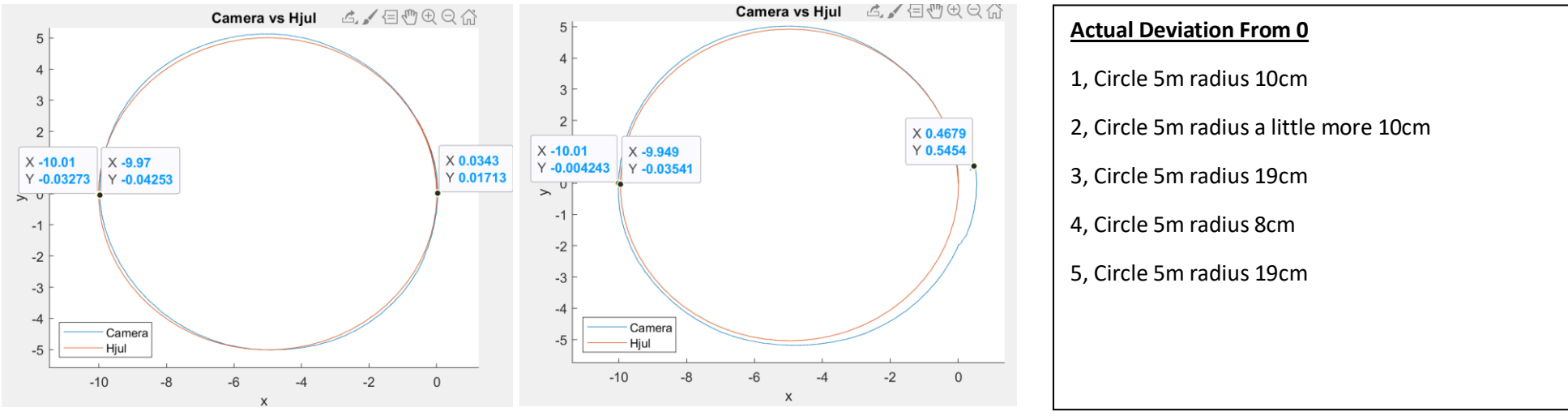


Cirkel 10m diameter

1-3



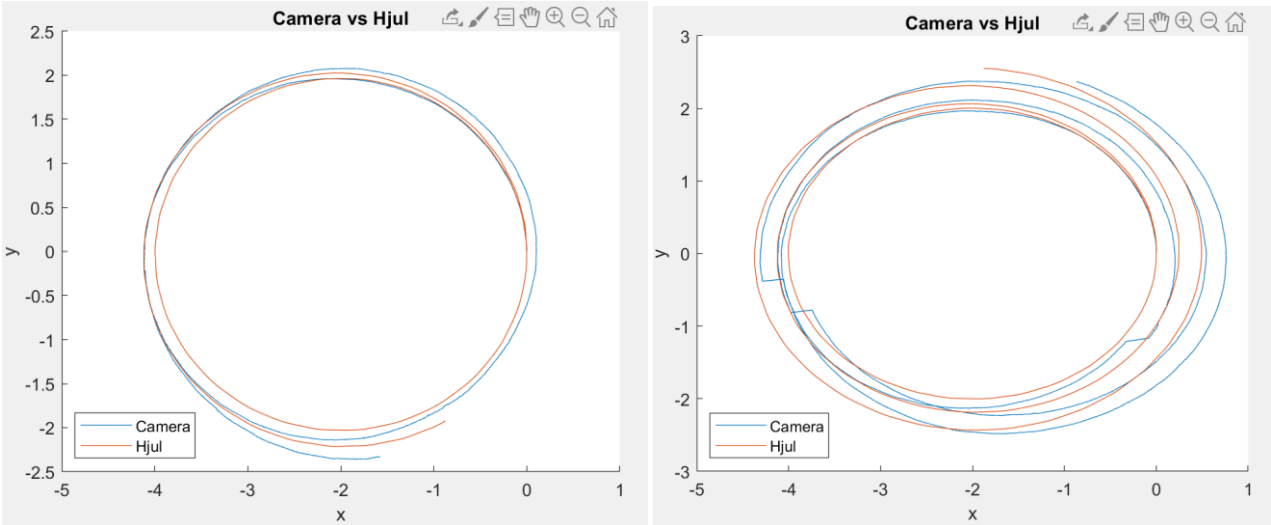
4-5



Appendices (various plots of the executed runs)

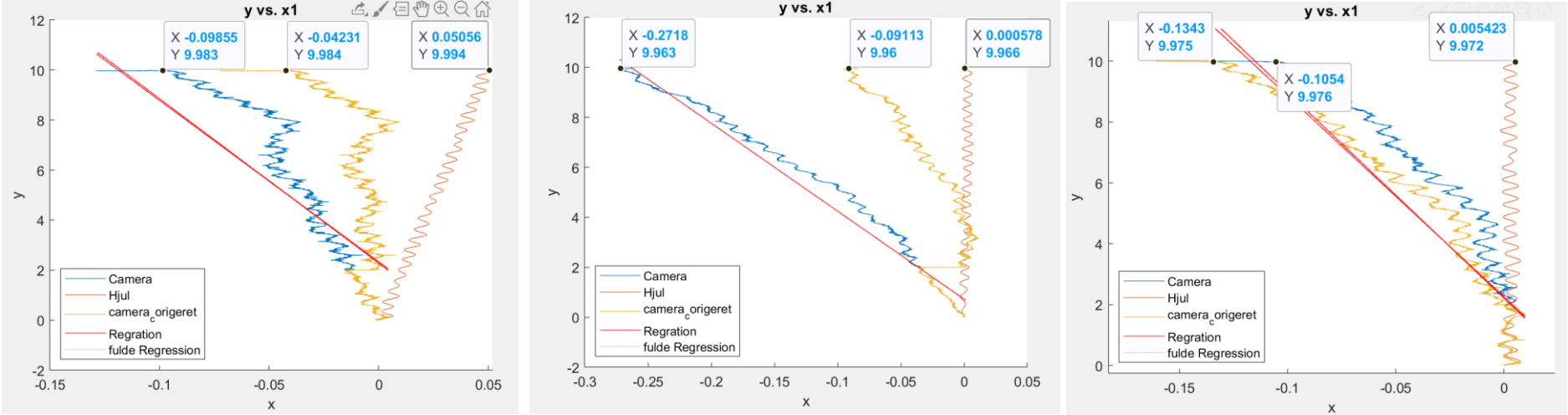
Cirkel bare kørt rundt 2 m radius = 4m diameter

1-2

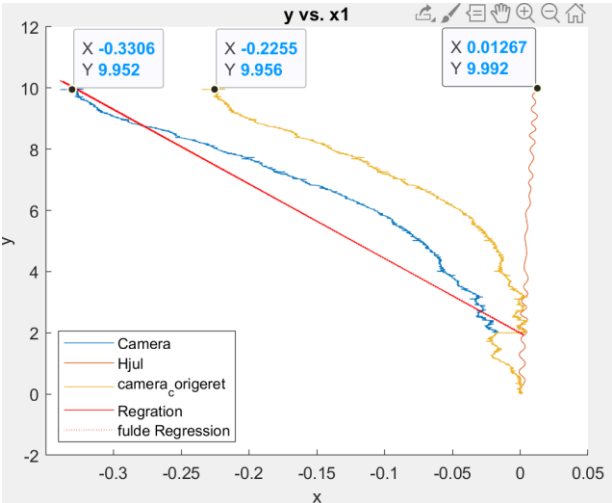


10 m lavet som ekstra

1-3



4-6



Actual Deviation From 0

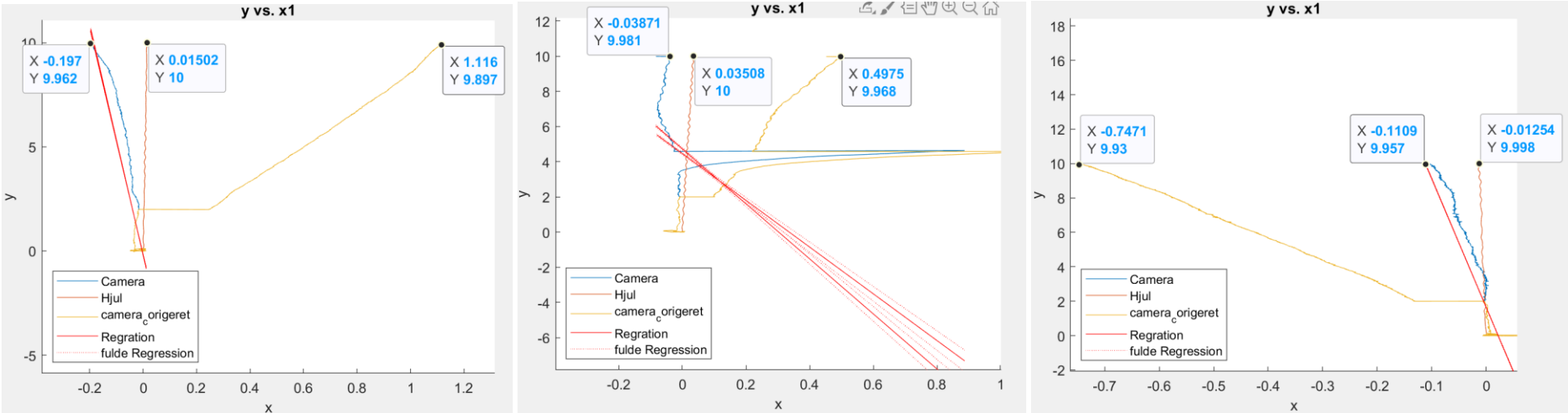
- 1, 10m made extra 0cm - completely straight
- 2, 10m made extra 27.5cm to the left
- 3, 10m made extra 0cm - completely straight
- 4, 10m made extra 21cm to the left



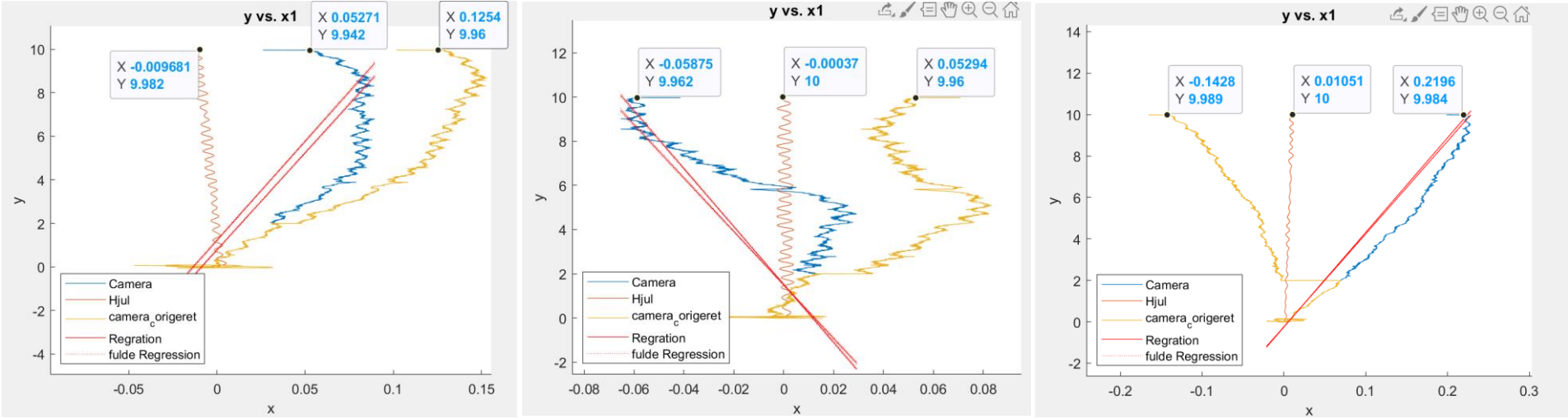
Appendices (various plots of the executed runs)

10m med hund til at rette ind

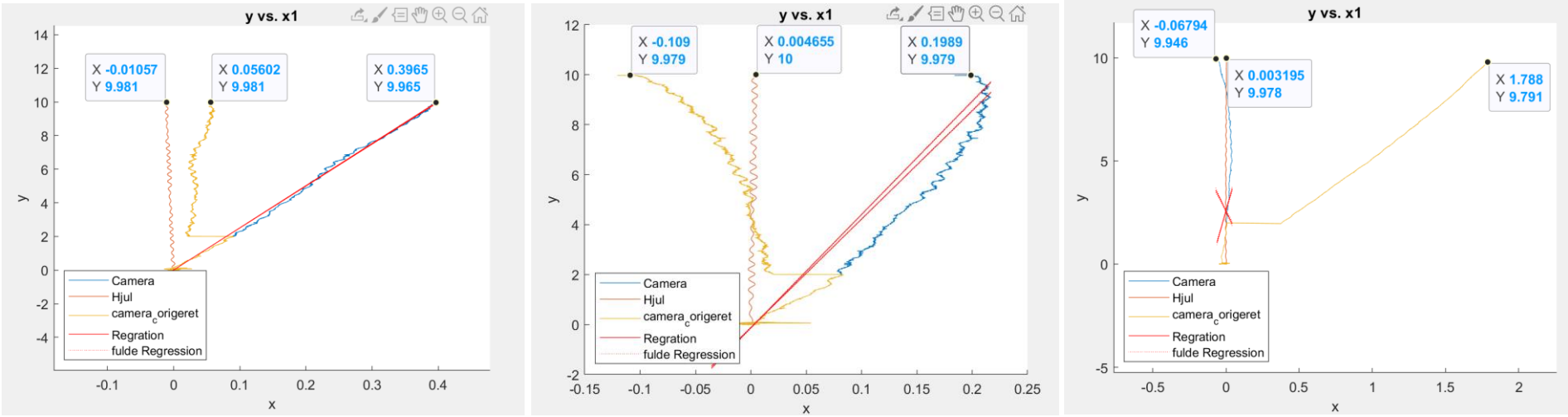
1-3



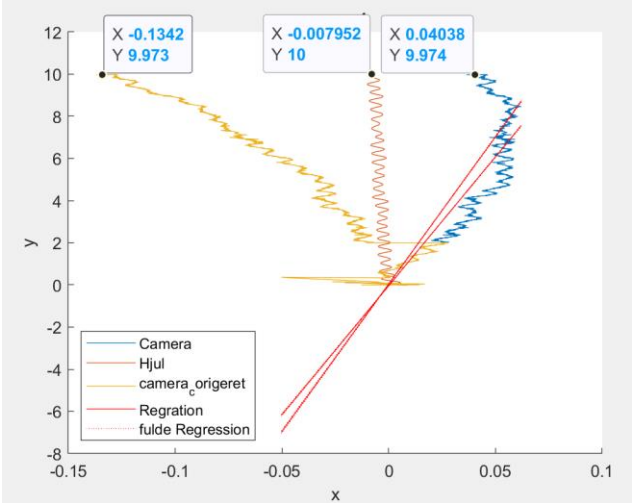
4-6



7-9



10



Actual Deviation From 0

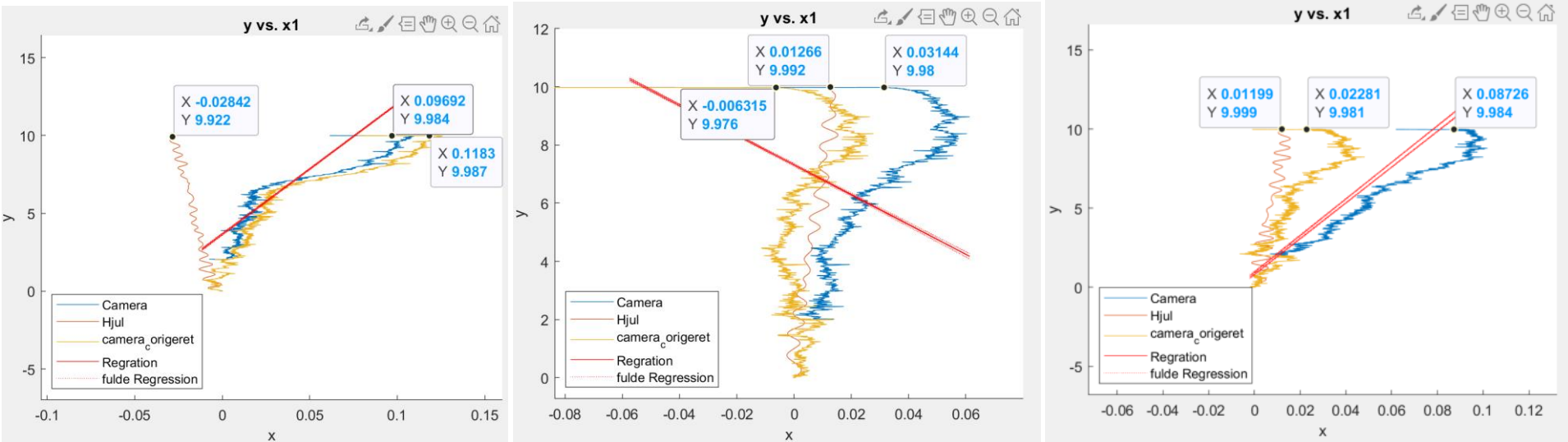
- 1, 10 m dog 19,975 20 cm to the left - started a little skewed to the left
- 2, 10 m dog 19.98 2.5cm to the right - followed the leash more or less all the way
- 3, 10 m dog 19.98 24 cm to the left - started a little skewed to the left
- 4, 10 m dog 19.98 5 cm to the right - started a little crooked to the right
- 5, 10 m dog 19.98 11 cm to the left
- 6, 10 m dog 19.98 4.5 cm to the right - started a little crooked to the right
- 7, 10 m dog 19.98 10 cm to the right
- 8, 10 m dog 19.98 5 cm to the right - started a little crooked to the right
- 9, 10 m dog 19.98 22 cm to the left
- 10, 10 m dog 19.98 6 cm to the left



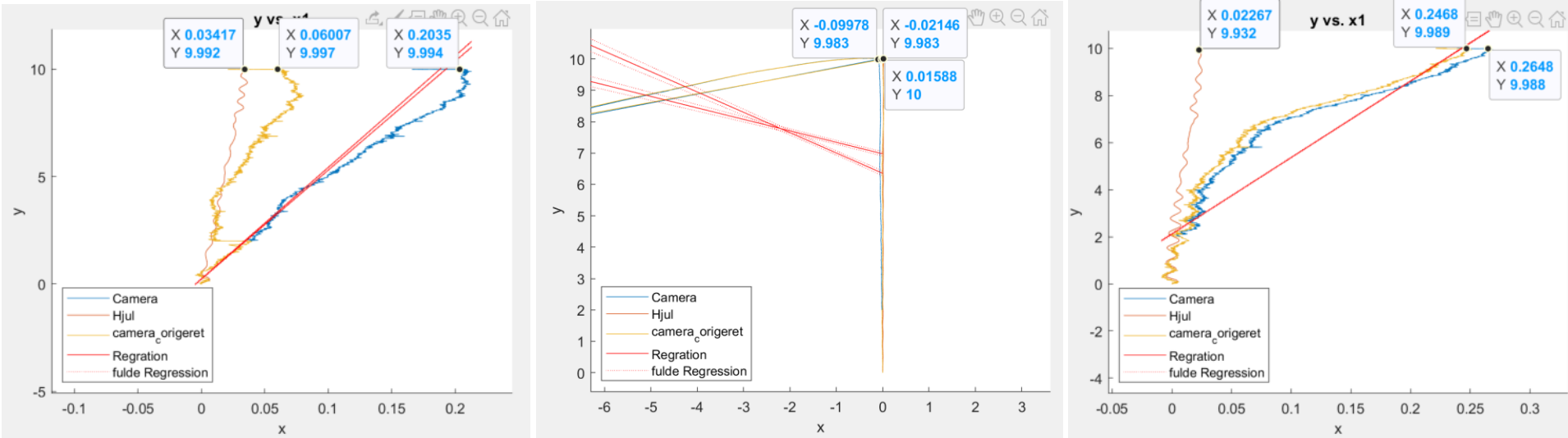
Appendices (various plots of the executed runs)

10m Fast

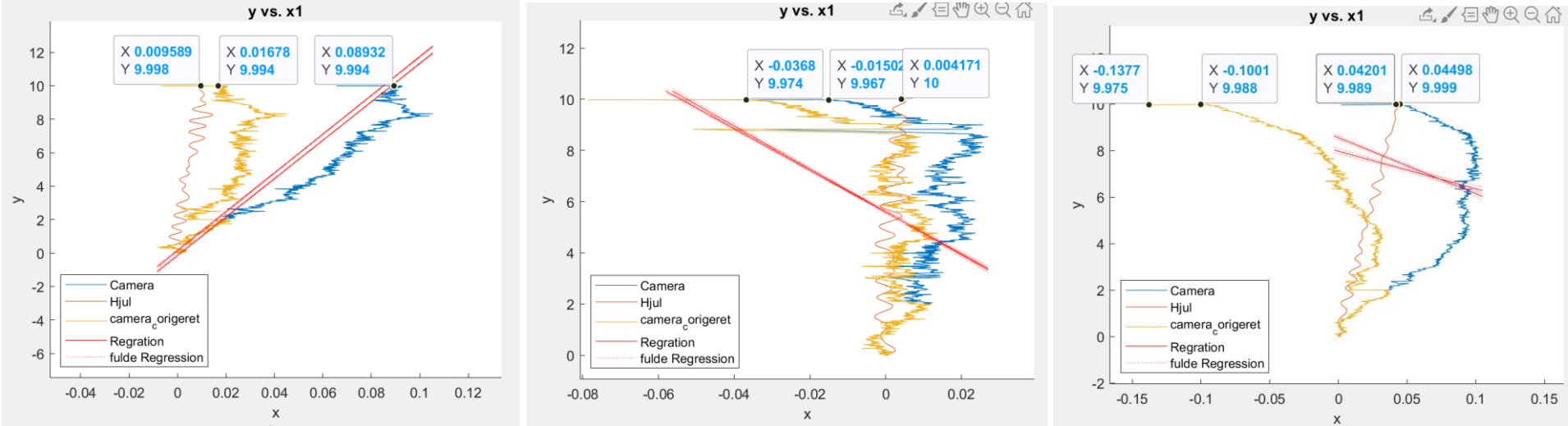
1-3



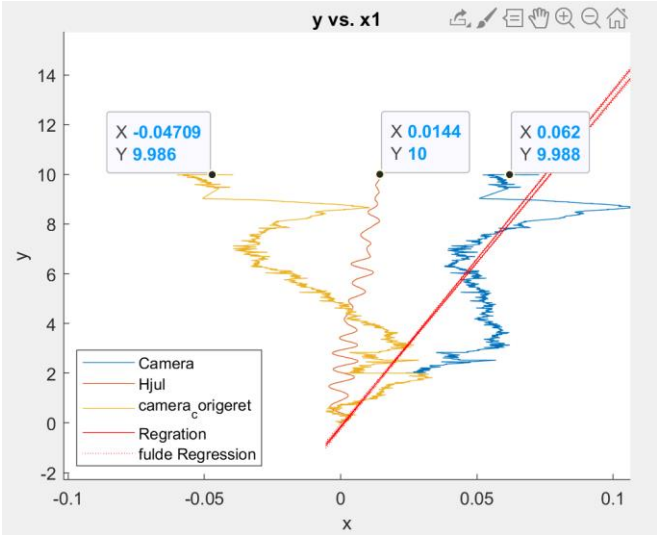
4-6



7-9



10



Actual Deviation From 0

- 1, 10m\_Fast, 9.975, 14 cm right
- 2, 10m\_Fast, 9.98, 19 cm to the right
- 3, 10m\_Fast, 9.98, 2 cm to the right
- 4, 10m\_Fast, 9.975, 7 cm to the Right
- 5, 10m\_Fast, 9.98, 16 cm to the left
- 6, 10m\_Fast, 9.975, 19 cm to the right
- 7, 10m\_Fast, 9.98, 17.5 cm to the right
- 8, 10m\_Fast, 9.98, 11 cm to the left
- 9, 10m\_Fast, 9.98, 18 cm to the left
- 10, 10m\_Fast, 9.985, 5 cm to the left