IADS Coursework 3: Heuristics for the Travelling Salesman Problem

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C. Algorithm

Motivation

One of the simplest ways to construct an effective heuristic for TSP is to repeatedly apply small transformations to the current permutation and see how they affect the overall cost. Swap and 2-Opt heuristics are examples of this idea. My algorithm uses slightly more complicated transformations - it cuts the permutation in up to four places and considers combinations of putting the path back together. As only the ends of subpaths might get reconnected to different vertices, this transformation preserves most of the original solution.

Notes:

If improvement over a single iteration was less than 1%, we switch to more cuts so that we perform more complex transformations only if simpler ones fail. Also, in each iteration we return a solution immediately if it is significantly better.

Pseudocode

```
Data: perm
Result: best permutation found by the heuristic
m_{opt} \leftarrow 1;
for iterations \leftarrow 0 to 30n do
   improvement, perm \leftarrow MyHeuristicIteration(m_{opt});
   if improvement smaller than 0.1% of current solution cost then
       increase m_{opt} by 1;
   else
      m_{opt} \leftarrow 1
end
                           Algorithm 1: Main method
Data: perm, m_{opt}
Result: best improvement found when cutting in m_{opt} places (one iteration)
best-tour \leftarrow perm;
forall indices i, j, k, l dividing perm;
                                                // some might be -1s, if m_{opt} < 4
do
   intervals \leftarrow subpaths after cutting the solution in i, j, k, l;
   forall reversed-subpaths \leftarrow possibilities of reversing some subpaths do
       forall permuted-subpaths \leftarrow possibilities of permuting reversed-subpaths do
           new-tour ← Concatenate(permuted-subpaths);
           if improvement bigger than 1% of current solution cost then
           return new-tour
           else if TourValue(new-tour) < TourValue(perm) then</pre>
              best-tour \leftarrow new-tour
       end
   end
   return new-tour
end
```

Algorithm 2: MyHeuristicIteration method

Time and memory complexity

Let n be the number of vertices in the graph.

Time complexity

First, we are doing $\Theta(n)$ iterations. Now, each iteration takes at most $O(n^5)$ time as for $m_{opt} = 4$, we need to iterate over all possibilities to cut the permutation in 4 places (there are n * (n-1) * (n-2) * (n-3)/4! of them) and for all such cuts we do $\Theta(n)$ work (there is a constant number of permutations, constant number of reversing subpaths). Therefore, the total time complexity is $O(n^6)$.

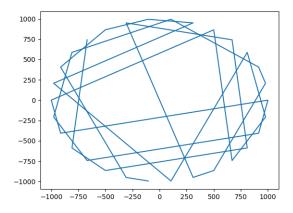
Memory complexity

The memory complexity is $O(n^2)$ as we need to maintain costs of edges and we do not need to maintain more than that at any time.

D. Experiments

	Description	Swap	2-Opt	Greedy	My heuristic
1	30 random points with coordinates	257	101	115	99
	with magnitudes of 10 and less				
2	30 random points with $x \in <-10, 10>$	120826	37385	37386	37385
	and $y \in <-10000, 10000>$				
3	30 points placed evenly on a circle of radius 1000,	29025	6272	6272	6272
	shuffled randomly				
4	5 per circle with radii: $1k$, $2k$, $4k$, $8k + 5$ random,	104617	68729	75383	64982
	sorted by distance from the origin				
5	20 per circle with radii: 1k, 2k, 4k, 8k,	265427	117870	103379	101286
	sorted by distance from the origin				
6	50 vertices with edge weights	1536	318	392	266
	chosen randomly from $< 1,100 >$				200

- 1. As expected, heuristics that used more general transformations got better results (My heuristic had a smaller cost than 2-Opt and it, in turn, had a smaller cost than Swap).
- 2. Making the interval for y-s significantly wider increased the gap between Swap and the rest. As distances increase linearly with scaling, this wider gap should be caused by the increasingly worse relative quality of solutions that Swap yields. I have confirmed this with further tests (I have taken $y \in <-10^7, 10^7>$).
- 3. Even though the points were shuffled, all but one heuristics managed to get the optimal solution (going along the circle). Therefore, this suggest that there are local minima which are significantly higher than the global minimum for swaps. The results for Swap and Two-Opt can be seen in Figure 1.



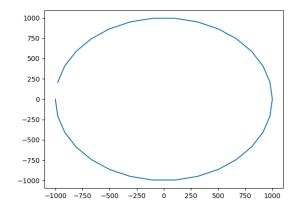


Figure 1: Swap and Two-Opt solutions for points placed evenly on a circle, shuffled

- 4. All other heuristics outperformed Swap again. From what I saw when I plotted the solution, it did not go strictly along the circles (and this state was a local minimum). My heuristic performed significantly better I suspect this was due to the fact that it was able to do more complicated transformations and get itself out of more local minima.
- 5. This test is very similar to the previous one. What is interesting is that Greedy outperformed 2-Opt (as it followed the circles, because of its design). The results are visualised in Figure 2.

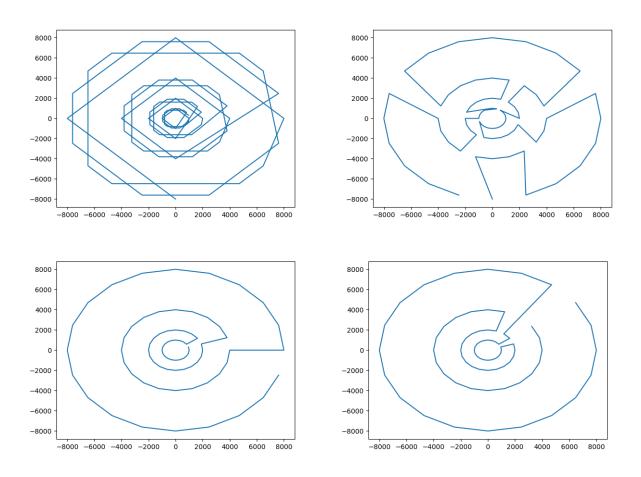


Figure 2: Solutions for points placed evenly on 4 circles with radii 1000, 2000, 4000, 8000, initially sorted by distance from the origin (same order as in the table)