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ml02450 / toolbox_extended.py

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Thomas Nilsson Added toolbox
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0 contributors
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```
Raw Blame History
181 lines (138 sloc) | 4.29 KB
      import numpy as np
      def adaboost(delta, rounds):
          # Initial weights
          delta = np.array(delta)
          n = len(delta)
          weights = np.ones(n) / n
  8
  9
          # Run all rounds
 10
          for i in range(rounds):
              eps = np.mean(delta == 1)
              alpha = 0.5 * np.log((1 - eps) / eps)
              s = np.array([-1 if d == 0 else 1 for d in delta])
 14
              # Calculate weight vector and normalize it
              weights = weights.T * np.exp(s * alpha)
              weights /= np.sum(weights)
 18
              # Print resulting weights
 20
          for i, w in enumerate(weights):
              print('w[%i]: %f' % (i, w))
      ### NAIVE BAYES PROB
 24
      def naive_bayes(y, x, *obs):
          y = np.array(y)
          classes = set(y)
          X = np.array(obs).T
 28
          N, M = X.shape
          C = len(classes)
 30
          priors = np.zeros(C)
          # Class priors
          for i, c in enumerate(classes):
 34
              priors[i] = sum(y == c) / N
 36
          # Probs
          probs = np.zeros((C, M))
 38
          for i, c in enumerate(classes):
             for j in range(M):
                  probs[i, j] = sum((X[:, j] == x[j]) & (y == c)) / sum(y == c)
 40
 41
 42
          # Joint probs
 43
          joint = np.prod(probs, axis=1)
 44
 45
          # Naive baves
 46
          return (joint * priors) / sum(joint * priors)
 47
```

```
49
      # ### Confusion Matrix
 50
      def confusion_matrix(matrix=None, tp=None, fn=None, tn=None, fp=None):
          if matrix:
             [tp, fn], [fp, tn] = matrix
          print("TP:", tp, "FN:", fn, "TN:", tn, "FP:", fp)
 54
 56
          n = tp + fn + tn + fp
          accuracy = (tp + tn) / n
 58
          error = 1 - accuracy
 59
          recall = tp / (tp + fn)
 60
          prec = tp / (tp + fp)
          fpr = fp / (fp + tn)
          tpr = tp / (tp + fn)
 64
          print('Accuracy:', accuracy)
          print('Error rate:', error)
          print('Recall:', recall)
          print('Precision:', prec)
 68
          print('FPR:', fpr)
 69
          print('TPR:', tpr)
 70
     ### SUPPORT
      def supp(A):
         A = np.array(A)
 74
          return sum(A.all(axis=0)) / len(A[0])
     ### CONFIDENCE
      def conf(A, B):
 78
          AB = np.concatenate((A, B))
 79
          return supp(AB) / supp(A)
 80
 81
      ### LIFT
82
      def lift(A, B): return conf(A, B) / supp(B)
83
 84
      ### DENSITY FOR ARD
85
      def density(d):
         return 1 / d.mean()
 86
 87
 88
      ### SIMILIARITY MEASURES
 89
      def sim(x, y):
         f11 = sum((x == 1) & (y == 1))
 90
         f10 = sum((x == 1) & (y == 0))
91
 92
         f01 = sum((x == 0) & (y == 1))
93
        f00 = sum((x == 0) & (y == 0))
94
         return f11, f10, f01, f00
 96
 97
     def SMC(x, y):
 98
         f11, f10, f01, f00 = sim(x, y)
99
          M = len(x)
          return (f11 + f00) / M
101
102
103
     def J(x, y):
        f11, f10, f01, f00 = sim(x, y)
104
         return f11 / (f11 + f10 + f01)
106
107
108
     def cos(x, y):
        f11, f10, f01, f00 = sim(x, y)
110
          return f11 / (np.linalg.norm(x) * np.linalg.norm(y))
     def EJ(x, y):
        a = x.T * y
          b = np.linalg.norm(x) ** 2 + np.linalg.norm(y) ** 2 - a
116
         return a / b
     # Impurity measures
120
      def gini(v): return 1 - ((v / sum(v)) ** 2).sum()
```

```
def class_error(v): return 1 - v[np.argmax(v)] / v.sum()
      def kmeans3_main(data, centroids):
          c1, c2, c3 = centroids
          dif1, dif2, dif3 = data - c1, data - c2, data - c3
          cat1, cat2, cat3 = [], [], []
128
129
          for i in range(0, len(data)):
             if abs(dif1[i]) <= abs(dif2[i]) and abs(dif1[i]) <= abs(dif3[i]):</pre>
130
                  cat1.append(data[i])
              elif abs(dif2[i]) <= abs(dif1[i]) and abs(dif2[i]) <= abs(dif3[i]):</pre>
              elif abs(dif3[i]) <= abs(dif1[i]) and abs(dif3[i]) <= abs(dif2[i]):</pre>
134
                 cat3.append(data[i])
              else:
                  print("ERROR")
138
          # Print clusterings
          print(cat1, cat2, cat3)
141
142
          # Return new centroids
143
          return np.array([np.mean(cat1), np.mean(cat2), np.mean(cat3)])
146
     def kmeans3(data, centroids):
147
         current = np.array(centroids)
148
          old = np.zeros(3)
          while np.any(current != old):
150
             old = current
              current = kmeans3_main(data, current)
          print("terminated!\ncentroids:", current)
154
      def kmeans2_main(data, centroids):
156
          c1, c2 = centroids
          dif1, dif2 = data - c1, data - c2
          cat1, cat2 = [], []
160
          for i in range(0, len(data)):
161
              if abs(dif1[i]) <= abs(dif2[i]):</pre>
                  cat1.append(data[i])
              elif abs(dif2[i]) <= abs(dif1[i]):</pre>
164
                 cat2.append(data[i])
              else:
166
                  print("ERROR")
          # Print clusterings
          print(cat1, cat2)
170
          # Return new centroids
          return np.array([np.mean(cat1), np.mean(cat2)])
174
      def kmeans2(data, centroids):
176
         current = np.array(centroids)
          old = np.zeros(2)
178
          while np.any(current != old):
179
              old = current
180
              current = kmeans2_main(data, current)
181
          print("terminated!\ncentroids:", current)
```