

SES Lab 2: Digital Signals

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Electronics and Electrical Engineering Discipline
Week 5

With Grateful Thanks to **Prof Alan Murray!**



Week 5: Digital Signals

This week we will move on to look at Digital Signals:

- We will begin by discussing several basic types of digital signals and waveforms
- In Week 3, you designed an audio amplifier... now consider how we convert an audio signal into digital samples
- Also consider digitisation issues and artefacts



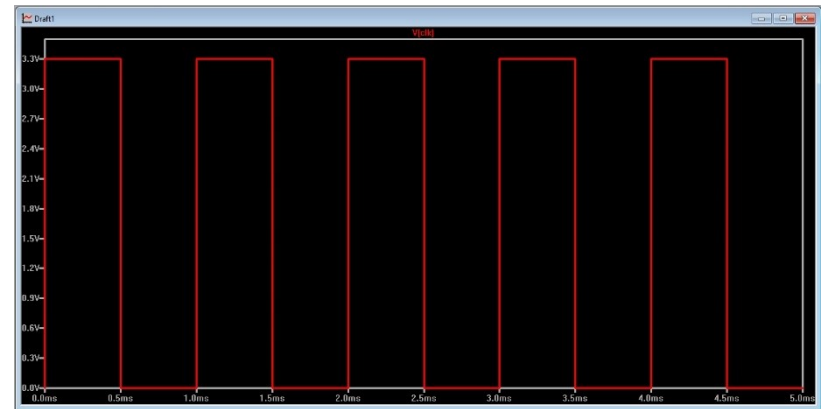
Digital Signals

- A microprocessor, such as the STM32 chip, understands digital signals and codes, based on voltages:
 - A low voltage (0V) can represent LOW or FALSE
 - A high voltage (e.g. 3.3V) can represent HIGH or TRUE
- The STM32 chip has many digital inputs/outputs that enable information to be communicated to/from the device
- Why are digital representations so widely used?
 - Results can be reproduced reliably on many devices
 - Designing digital processors is relatively easy and logical
 - Digital representations can be processed very rapidly, allowing high speed operation

Clock Signals

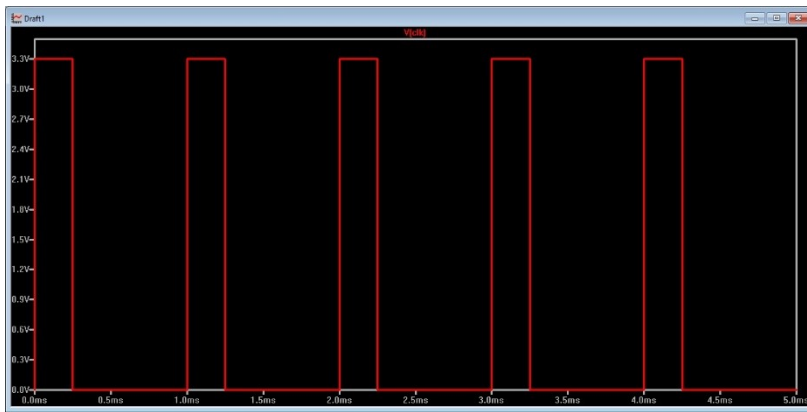
- In digital circuits, **square waves** are frequently encountered as clock signals or for conveying information
- Commonly clock signals have a 50% on/off duty cycle
- Usually the rising/falling edge of the clock signal will trigger an operation, such as:
 - Carrying out an instruction in a microprocessor
 - Updating a counter in the processor
 - Collecting a signal sample in an analogue-to-digital converter
 - Communicating data to/from a microprocessor

Example of a 1kHz,
3.3V Square Wave
clock signal in LT-
Spice

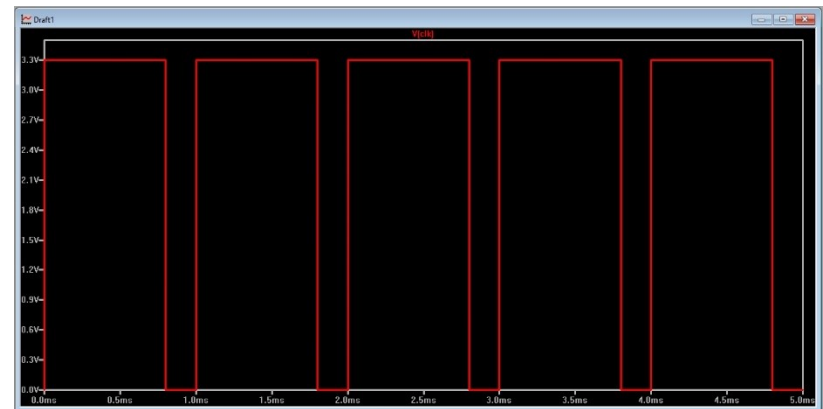


Pulse Width Modulation

- Digital signals can be used to control many different physical devices
- Sometimes it is useful to vary the ON/OFF duty cycle to vary the voltage received by a device such as robotic motor
- The longer the ON time, the more electrical energy that is delivered
- This is often called **pulse width modulation (PWM)** and most micro-processors have PWM digital lines

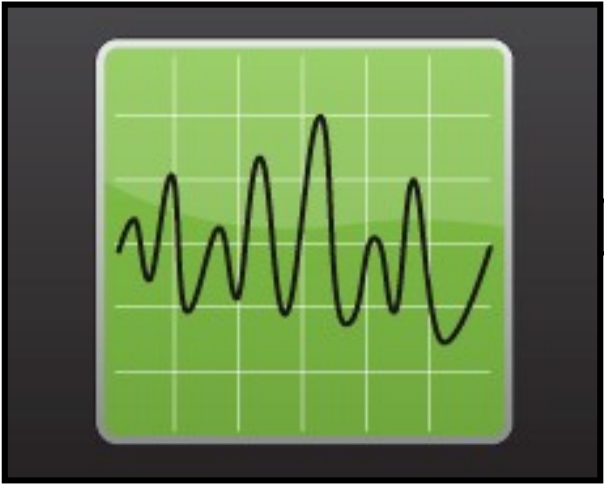


25% ON Duty Cycle Example

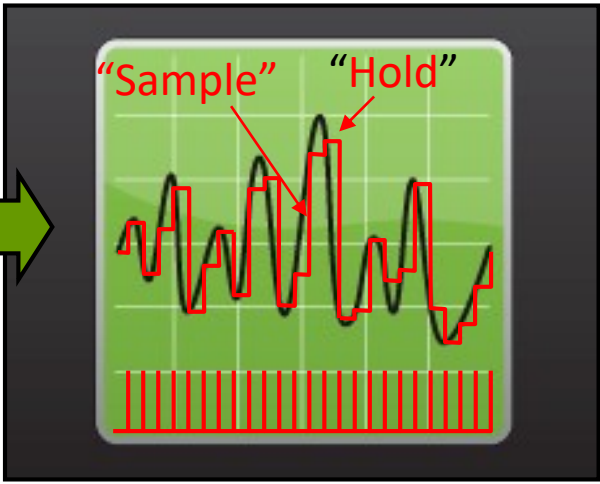


80% ON Duty Cycle Example

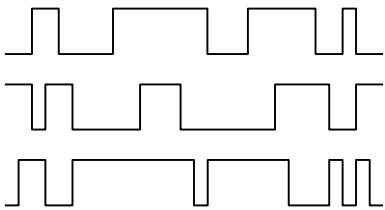
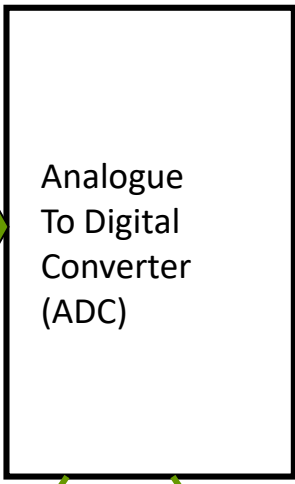
Analogue and Digital Signals - Overview



Analogue Signal



Sampled Analogue Signal



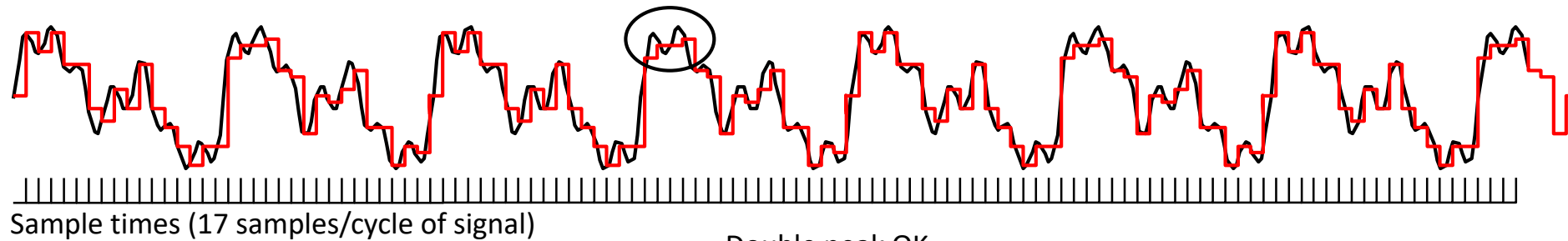
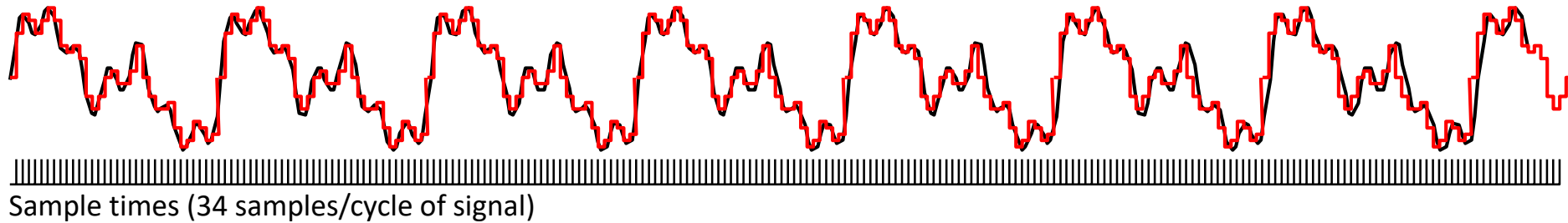
or ...



Multi-bit digital output



Sampling a musical signal ...



Double peak OK

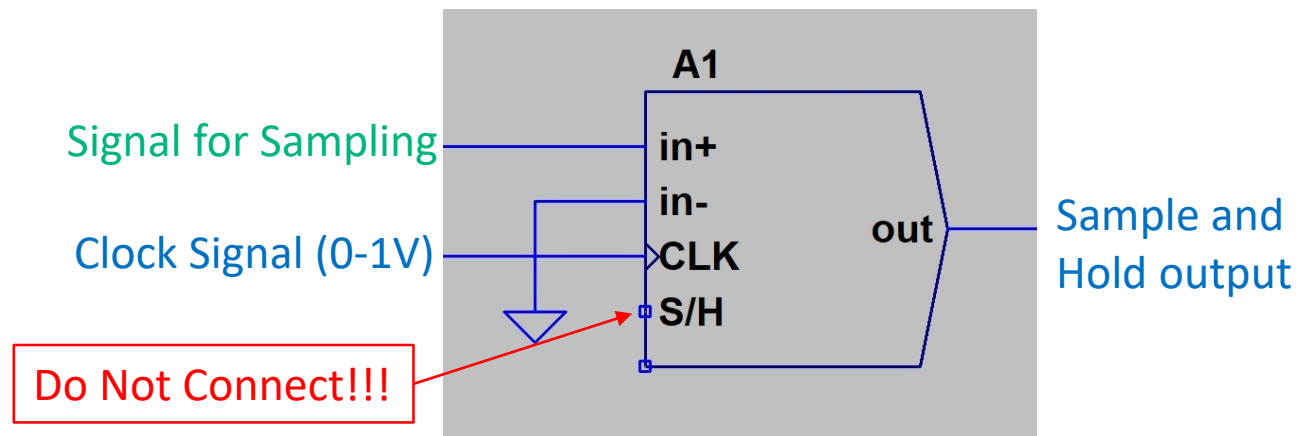


Double peak absent

More frequent samples = higher quality

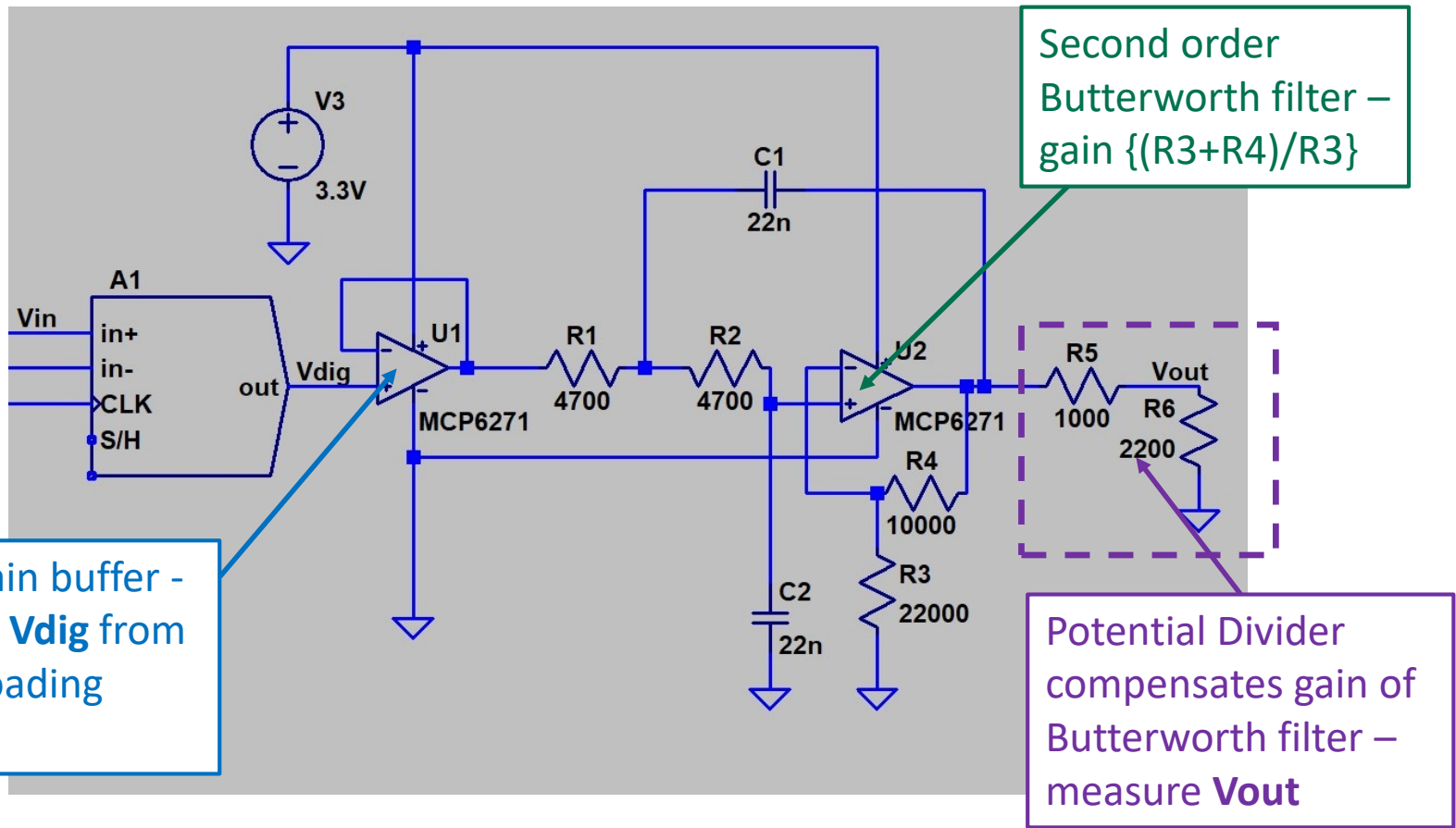
LT-Spice Sample and Hold

- LT-Spice contains a component “sample” that allows you to mimic a **sample-and-hold device**
- This is an important part of an Analogue-to-Digital Converter
- Connect up this device as shown below to operate
- A sample is recorded every time the clock goes high – a 0V/1V square wave should be sufficient to drive the device



Reconstruction Filter for 8 kHz Sampler

- **Second order** Butterworth low pass filter smooths the square pulses of the sample-and-hold, to reconstruct the original signal

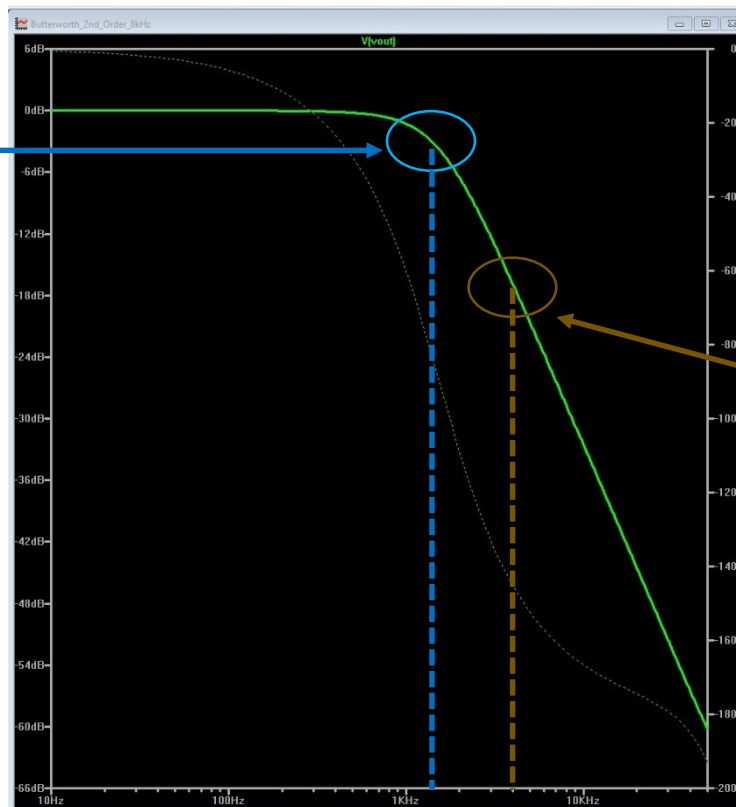


Reconstruction Filter Freq Response

- **Frequency response** for second order Butterworth filter
- Sample at 8 kHz, so the maximum frequency (Nyquist) is 4 kHz

3dB Cutoff freq is about 1.45 kHz

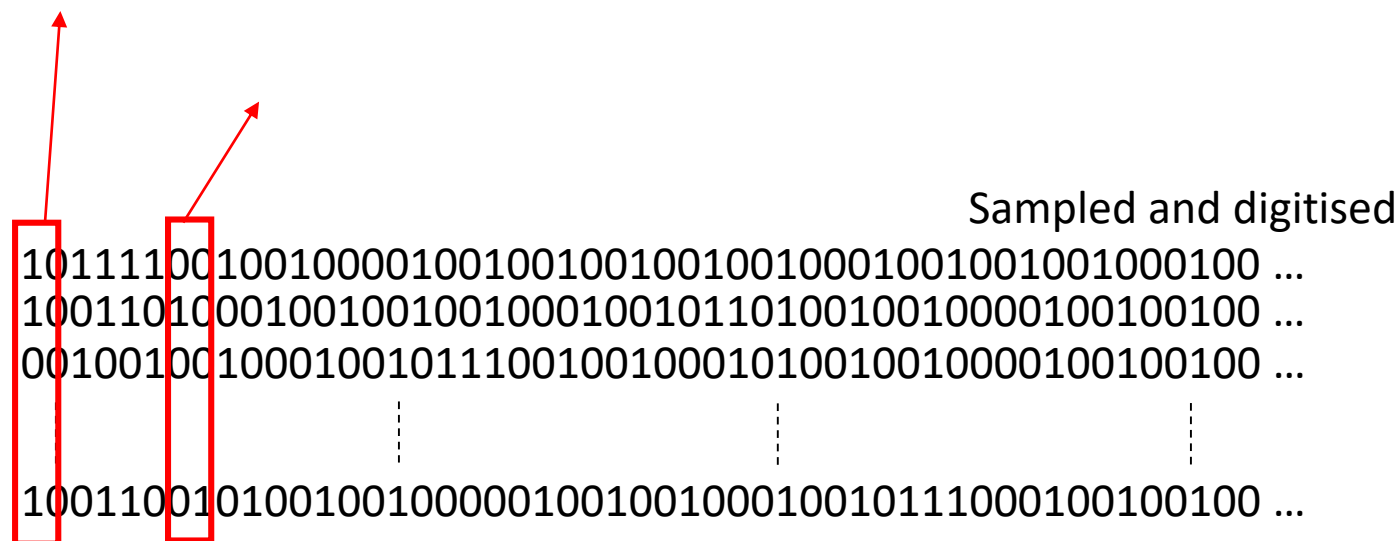
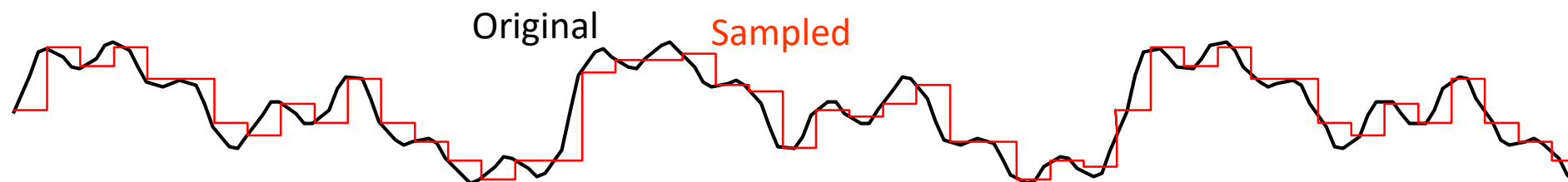
Reconstruction filter removes high frequency components > 4 kHz to allow the original signal to be seen



Gain at 4 kHz (Nyquist) is -17 dB

Now Work Through the Questions in **Worksheet 1**

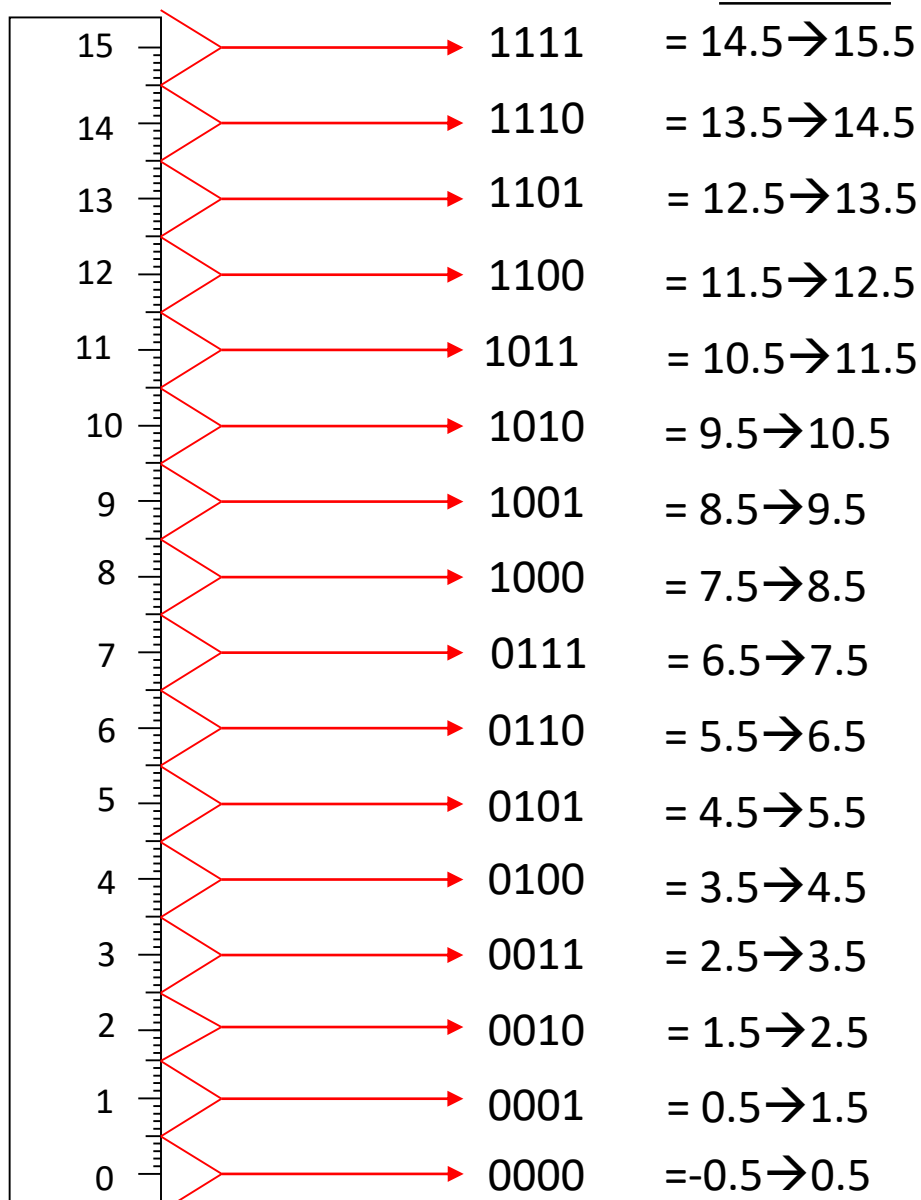
Sampled – now digitise



Analogue-Digital

Reproducer 4-Bit Binary
Values Patterns

15	=	1111
14	=	1110
13	=	1101
12	=	1100
11	=	1011
10	=	1010
9	=	1001
8	=	1000
7	=	0111
6	=	0110
5	=	0101
4	=	0100
3	=	0011
2	=	0010
1	=	0001
0	=	0000



Granular
Region
 Samples
 between -0.5
 and 15.5

Overload
Region:
 Samples
 below -0.5 or
 above 15.5

Quantisation in MATLAB

- MATLAB allows us to implement the effect of analogue-to-digital conversion using the function **quantiz()**
- To use this function we need to specify three things:
 - The data samples that we plan to quantise, stored in a vector
 - The reproducer values that the quantiser uses to represent each value
 - The decision boundaries between adjacent reproducer values
 - This function outputs the chosen reproducer values for our data
- Slide 11 shows that the reproducer values and decision boundaries have a regular structure
 - Use the MATLAB **colon operator** $a:b:c$ to create these values
 - The value a is the first value, b is the step value and c is the final value
 - Example: to create the reproducer values in Slide 11 we can use the code: `0:1:15`
 - **Overload Region**: Two values needed to tell MATLAB what to use below minimum boundary (-0.5) and above the maximum one (15.5)
 - Here we just repeat the minimum/maximum reproducer values

Now Work Through the Questions in **Worksheet 2**