* Introduction - Noah
* Related Work - Noah
  + Discuss others that have implemented PID in UAVs
  + Discuss others that have developed control systems on bio-inspired wings
* Methodology - Split
  + Outline of system architecture. Three servos, load cell (calibration), code base. - Matt
  + Details of PID done - Bailey
  + Details of experiment - Noah
    - Wind tunnel details - Bernoulli calculator for speed of wind tunnel
    - What we’re outputting.
    - How we plan to compare to DRL, time to stable flight or minimise error/quality of transition to stable.
* Results (if relevant) - Bailey
* Evaluation & Discussion - Matt
* Conclusion - any/all