* Introduction
* Related Work
  + Discuss others that have implemented PID in UAVs
  + Discuss others that have developed control systems on bio-inspired wings
* Methodology
  + Outline of system architecture. Three servos, load cell (calibration), code base.
  + Details of PID done by Bailey
  + Details of experiment
    - Wind tunnel details - Bernoulli calculator for speed of wind tunnel
    - What we’re outputting.
    - How we plan to compare to DRL, time to stable flight or minimise error/quality of transition to stable.
* Results (if relevant)
* Evaluation & Discussion
* Conclusion