

分組任務 1

What do you need to know

from <http://www.coppeliarobotics.com/helpFiles/index.html> to implement a four-wheeled robot?

依照 BubbleRob tutorial 跟 Line following

BubbleRob tutorial，要使一個四輪車驅動的話每一個輪子要配有一個馬達，若要規劃其移動路徑，則須配合視覺感測器(vision sensors)以及路徑規劃(Menu bar --> Add --> Path --> Circle type)的功能還有程式的搭配。