Algorithm 2 Fashion Landmark Detection	
1: Input: Fashion image dataset	
	Output: Fashion landmarks and bounding boxes
3:	Model: EfficientDet with modifications
4:	- Backbone: EfficientNet
5:	- Feature Pyramid Network: BiFPN
6:	- Prediction Head: 3x3 convolution followed by convolution with filter
	size 3, stride 1, and padding 1
7:	- Number of anchors: 9
8:	- Number of classes: 13
9:	- Number of landmarks: 294
10:	- Loss Function: Focal Loss, Complete IoU Loss, Rooted Mean Squared
	Error
11:	
12:	Procedure:
13:	1. Pretrain EfficientNet backbone
14:	2. Modify EfficientDet with BiFPN structure
15:	3. Design prediction head for fashion landmarks and bounding boxes
16:	4. Train the model using Focal Loss, Complete IoU Loss, Rooted Mean
l	Squared Error
17:	
18:	Loss Function:
19:	- Focal Loss for classification:
20:	$L_{cls} = -\alpha_t (1 - p_t)^{\gamma} \log(p_t)$
21:	$\alpha = 0.25, \gamma = 2$
22:	
23:	- Complete IoU Loss for bounding box regression:
24:	$V = \pi^2(\arctan(h) - \arctan(h_{gt}))$
25:	$\alpha = V$ if IoU < 0.5, else $\alpha = 1 - IoU + V$
26:	$L_{bbox} = 1 - IoU + c_w^2 + c_h^2 + \alpha V$
27:	
28:	- Rooted Mean Squared Error for landmark prediction:
29:	v is the visibility of clothing landmarks. If $v$ does not exist, it is not
ł	reflected in the loss.
30:	$L_{landmark} = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (y_i - \tilde{y}i)^2}$ if $v > 0$ , else $Llandmark = 0$
31:	<b>V</b>
32:	- Total Loss:

$$\begin{split} L_{tot} &= L_{cls} + L_{bbox} + \lambda_{size} L_{landmark} + \lambda_{off} L_{off} \\ \lambda_{size} &= 0.1, \lambda_{off} = 1 \end{split}$$

33: 34: