



EDUCATION

Beijing Institute of Technology, School of Automation

PH.D. in Control Science and Engineering

Major: Navigation, Guidance and Control

Beijing, China

Sep 2020 - Expected June 2026

Beijing Institute of Technology, School of Xuteli

Bachelor of Engineering; Ranking:4/13

Beijing, China

Aug 2016 - June 2020

PUBLICATIONS

Journal Paper

- **Zhao S**, Shi L, Zhang W, Deng Z. Global dynamic path-planning algorithm in gravity-aided inertial navigation system[J]. IET Signal Processing, 2021, 15(8): 510-520. (SCI Q3, IF: 1.7) [\[paper\]](#)
- **Zhao S**, Xiao X, Wang Y, Deng Z. An improved particle filter based on gravity measurement feature in gravity-aided inertial navigation system[J]. IEEE Sensors Journal, 2022, 23(2): 1423-1435. (SCI Q1, IF: 4.3) [\[paper\]](#)
- **Zhao S**, Xiao X, Deng Z, Shi L. Gravity matching algorithm based on correlation filter[J]. IEEE Sensors Journal, 2022, 23(3): 2618-2629. (SCI Q1, IF: 4.3) [\[paper\]](#)
- **Zhao S**, Xiao X, Pang X, Wang Y, Deng Z. Gravity Matching Algorithm Based on Backtracking for Small Range Adaptation Area[J]. IEEE Transactions on Instrumentation and Measurement, 2024, 73, 9504413. (SCI Q1, IF: 5.6) [\[paper\]](#)
- **Zhao S**, Deng Z, Wang Q, Zhang W, Gong X. Terrain Matching Algorithm Based on Trajectory Reconstruction and Correlation Analysis of Sliding Measurement Sequence[J]. IEEE/ASME Transactions on Mechatronics, 2024. (SCI Q1, IF: 6.1)
- Wang Y, Deng Z, Zhang P, Wang B, **Zhao S**. A Gravity-Aided Navigation Matching Algorithm Based on Triangulation[J]. IEEE Sensors Journal, 2024. (SCI Q1, IF: 4.3)

Conference Paper

- Wang Y, Deng Z, Zhang W, **Zhao S**. An improved ICCP gravity matching algorithm based on Mahalanobis distance[C]//2021 40th Chinese Control Conference (CCC). IEEE, 2021: 3503-3508. (EI) [\[paper\]](#)
- **Zhao S**, Pang X, Deng Z. Gravity Matching Algorithm Based on Backtracking[C]//2022 China Inertia Technology Symposium, 2022, Dalian, China.
- **Zhao S**, Zhang W, Wang Y, Deng Z. The analysis of influencing factors on geophysical field matching[C]//2024 International Conference on Guidance, Navigation and Control (ICGNC), Springer, 2024. (EI)
- Chen X, Jiao Z, **Zhao S**, Deng Z. Research on Polar Navigation Problem of North-Seeking Strapdown Inertial Navigation System[C]//2024 International Conference on Guidance, Navigation and Control (ICGNC), Springer, 2024. (EI)
- Wang Q, Gong X, Bai X, Deng Z, **Zhao S**. The method for selecting adaptation zones of terrain matching based on Arctic seabed terrain features[C]//2024 International Conference on Guidance, Navigation and Control (ICGNC), Springer, 2024. (EI)

Patents

CN202110545814.3 (3rd), CN202311811811.5 (2nd), CN202311694509.6 (3rd), CN202110545816.2 (3rd), CN202110838109.2 (3rd), CN202211221726.9 (4th), CN202210856742.9 (2nd), CN201911385476.0 (4th).

AWARDS

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|---|------------|
| Technical Invention Award of Chinese Society of Inertial Technology (First Prize) | Aug, 2022 |
| APMCM Mathematical Modeling (First Prize, TOP 4) | Jan, 2022 |
| Huawei Cup Mathematical Modeling (Third Prize) | Dec, 2021 |
| MathorCup Mathematical Modeling (Third Prize) | Jun, 2021 |
| Outstanding graduate of School of Xuteli | Jun, 2020 |
| The Artificial Intelligence Challenge of Robomaster, perception (Excellence Award) | Jun, 2020 |
| NXP National College Student Smart Car Competition (Second Prize in North China) | July, 2020 |
| China Undergraduate Mathematical Contest in Modeling (Second Prize in Beijing) | Jan, 2019 |

EXPERIENCE

Underwater geophysical field matching navigation

*PH.D student, Supervisor: **Zhihong Deng***

Beijing China

May 2019 - Now

The accumulated error of inertial navigation system is corrected by using underwater geophysical field for matching and positioning. My work content is to study the underwater carrier path planning method and matching positioning method. In the field of path planning, I consider the change rate of gravity field and mismatching phenomenon, and use Astar and DWA algorithms to plan the trajectory of underwater vehicles. In order to integrate inertial navigation information, geophysical field reference map and gravimeter measurement information, some matching algorithms are designed to realize positioning. It includes introducing the correlation filter in target recognition and particle filter, considering the potential relationship of geophysical field characteristics.

In the past, I worked on gravity field aided navigation. Now I work on terrain aided navigation and positioning. The localization of underwater vehicle is studied by inertial navigation system, single-beam echosounder or multi-beam echosounder.

Robomaster robot positioning and decision making

*Undergraduate students, Supervisor: **Robomaster Team***

Beijing China

Sep 2019 - May 2020

In the specified area, four robots need to fight against enemy robots, by designing different decision-making strategies to defeat the enemy robots. I work on robot positioning and decision making. The calculation amount is reduced by optimizing the AMCL algorithm, and the comparison of several algorithms is made. Handle battlefield complexities by designing different decisions, such as how robots behave when they don't have bullets.

Hardware circuit design of intelligent energy-saving car

*Undergraduate students, Supervisor: **Smart Car Club***

Beijing China

Sep 2019 - July 2020

In the case that the battery is not applicable as a power source, the coil and the changing magnetic field are used to provide power for the smart car, so that the car can complete the driving within the specified time. My work is to design the circuit of the whole car and the design of the PCB, including the voltage regulator circuit design, control circuit design and signal circuit design. After that, as vice captain of the team club, participated in guiding the preparation and organization of the next race.