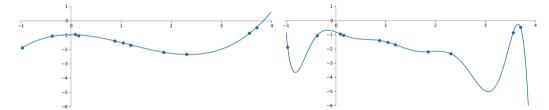
# Principles of Machine Learning: Exercise 5

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#### Exercise 4.1: Overview

- Goal: Fitting a polynomial to noisy data via polynomial regression
- **②** First step: Compute a feature map, where the *i*th column is composed of the powers  $x_i^0, \ldots, x_i^d$
- **Second step:** Compute the weights:  $\hat{w} = [\Phi \Phi^{\mathsf{T}}]^{-1} \Phi y$  using a numerically stable inversion algorithm (i.e. using QR decomposition)
- Third step: Compute the fitted model:  $\hat{f}(x) = \varphi(x)^{\mathsf{T}} \hat{w}$

#### Results: Plots



**Figure:** Polynomial fit for d = 3

**Figure:** Polynomial fit for d = 9

#### Results: Discussion

- While d = 9 naturally gives a much better MSE, we not only know (because our data was generated by adding noise to a third degree polynomial), but can clearly see that we are overfitting!
- Therefore we would prefer our cubic fit, even if it isn't a perfect

Exercise 5.2

We now compute the solution to regularized least squares in the same way:

 $\hat{w} = [\Phi \Phi^{\mathsf{T}} + \lambda I]^{-1} \Phi y$  for different lambda:

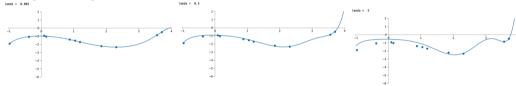


Figure: Polynomial fit for

$$\lambda = 0.005$$
  $\lambda = 0.5$ 

Figure: Polynomial fit for

**Figure:** Polynomial fit for 
$$\lambda = 5$$

#### Regularized least squares

- Great results for smaller  $\lambda = 0.5, 0.005$
- $oldsymbol{\bullet}$   $\lambda=5$  gives a worse result, which intuitively makes sense, because we are adding a larger value, decreasing the impact of our gram matrix before inverting!

## Setting

- Lecture 07 showed that the dual least squares solution is given by  $\hat{w} = \Phi[\Phi\Phi^{T}]^{-1}y$
- After regularization this becomes  $\hat{w} = \Phi[\Phi\Phi^{\intercal} + \lambda I]^{-1}y$
- We kernelize the expression  $\hat{f}(x) = \phi^{\intercal}(x) \Phi[\Phi \Phi^{\intercal} + \lambda I]^{-1} y$  to get

$$\hat{f}(x) = k(x)^{\mathsf{T}}[K + \lambda I]^{-1}y$$

ullet Good choices for the model parameters where given:  $\lambda=0.5, b=1, d=3$ 

#### Results

- b tranlates the result.
- d is the degree of the polynomial, therefore influencing the shape of our model in the usual ways
- This, similarly to the previous task, leads to better results for d=9, again because of the regularization

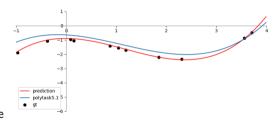


Figure: Polynomial fit for the given parameters

# Least squares SVMs for regression

- Adding to the lecture we can use SVMs for regression as well
- We want to build a least squares SVM regression model

$$\hat{f}(x) = \varphi(x)^{\mathsf{T}} \Phi \hat{\lambda} + \hat{b}$$

Where

$$\begin{bmatrix} \hat{\lambda} \\ \hat{b} \end{bmatrix} = \begin{bmatrix} \Phi^{\mathsf{T}}\Phi + \frac{1}{C}I & 1 \\ 1^{\mathsf{T}} & 0 \end{bmatrix} \begin{bmatrix} y \\ 0 \end{bmatrix}$$

• Which can easily be kernelized:

$$\begin{bmatrix} \hat{\lambda} \\ \hat{b} \end{bmatrix} = \begin{bmatrix} K + \frac{1}{C}I & 1 \\ 1^{\mathsf{T}} & 0 \end{bmatrix} \begin{bmatrix} y \\ 0 \end{bmatrix}$$

and

$$\hat{f}(x) = k(x)^{\mathsf{T}} \hat{\lambda} + \hat{b}$$

- Good results for a wider range of parameters (keeping the d fixed)
- Results differ more when changing the degree *d*

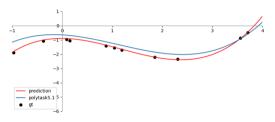
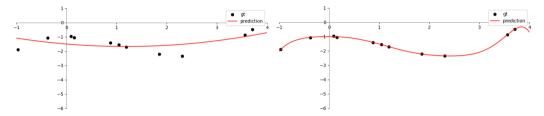


Figure: Polynomial fit for the given parameters

### Other degrees



**Figure:** Polynomial fit for the given parameters d = 2

**Figure:** Polynomial fit for the given parameters d = 9

# Minimum enclosing balls

- We already saw how to compute the minimal enclosing ball for a given dataset in lecture 08:
  - Using Frank-Wolfe solve

$$\operatorname*{argmin}_{\mu} \mu^{\mathsf{T}} X^{\mathsf{T}} X \mu - \mu^{\mathsf{T}} z$$

- where X denotes the dataset  $X = [x_1, \dots, x_n] \in \mathbb{R}^{m \times n}$  and  $z = \text{diag}[X^\intercal X]$
- under the constraints  $1^T \mu = 1$  and  $\mu \geq 0$
- ullet given  $\hat{\mu}$  we can than either compute the radius and the center of the ball

$$\hat{c} = X\hat{\mu}$$
 and  $\hat{r} = \sqrt{\hat{\mu^\intercal}z - \hat{\mu}^\intercal X^\intercal X\hat{\mu}}$ 

which leads to a function

$$\chi_B(x) = ||x - \hat{c}||^2 - \hat{r}^2$$

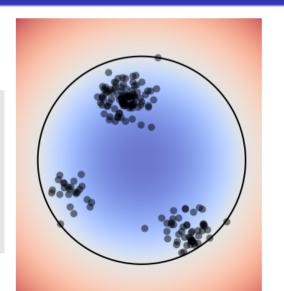
which is negative for  $x \notin B \cup \partial B!$ 

we can also rewrite

$$\chi_B(x) = x^\mathsf{T} x - 2x^\mathsf{T} X \hat{\mu} + \hat{\mu}^\mathsf{T} X^\mathsf{T} X \hat{\mu} - \hat{\mu}^\mathsf{T} z + \hat{\mu}^\mathsf{T} X^\mathsf{T} X \hat{\mu}$$

### Result and Frank-Wolfe-Implementation

```
def fwDualMEB(matX,vecZ,T=100):
m, n = matX.shape
vecM = np.ones(n)/n
for t in range(T):
    beta = 2 / (t+2)
    vecG = 2 * matX.T @ \
        matX @ vecM - vecZ
imin = np.argmin(vecG)
vecM *= (1-beta)
vecM[imin] += beta
return vecM
```



### Kernel minimum enclosing balls

• Using our second formulation

$$\chi_B(x) = x^{\mathsf{T}} x - 2x^{\mathsf{T}} X \hat{\mu} + \hat{\mu}^{\mathsf{T}} X^{\mathsf{T}} X \hat{\mu} - \hat{\mu}^{\mathsf{T}} z + \hat{\mu}^{\mathsf{T}} X^{\mathsf{T}} X + \hat{\mu}$$

we can kernalize everything:

• We get:

$$\chi_B(x) = K(x,x) - 2\kappa^{\mathsf{T}}\hat{\mu} - \hat{\mu}^{\mathsf{T}}k + 2\hat{\mu}^{\mathsf{T}}K\hat{\mu}$$

- where  $K(x,x)=\exp(0)=1\in\mathbb{R}$  and  $k=1\in\mathbb{R}^n$ , because  $k_j=K(x_j,x_j)=\exp(0)=1$ .
- Using a Gaussian kernel:

$$k(u, v) = \exp(-\frac{1}{2\sigma^2}||u - v||^2)$$

and the following Frank-Wolfe-Algorithm:

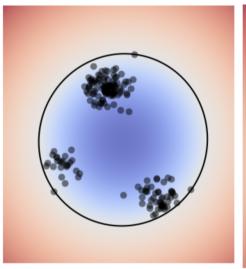
# Frank-Wolfe-Algorithm for kernel minimum enclosing balls

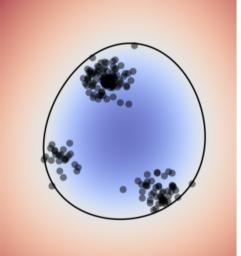
• Solving the minimization problem problem

$$\begin{aligned} & \underset{\mu}{\operatorname{argmin}} \ \mu^{\mathsf{T}} K \mu - \mu^{\mathsf{T}} k \\ &= \underset{\mu}{\operatorname{argmin}} \ \mu^{\mathsf{T}} K \mu - \mu^{\mathsf{T}} 1 \end{aligned}$$

ullet under the constraints  $\mathbf{1}^{\mathsf{T}}\mu=\mathbf{1}$  and  $\mu\geq\mathbf{0}$ 

```
def fwDualMEB2(K,k, T=100):
m, n = K.shape
vecM = np.ones(n)/n
for t in range(T):
    beta = 2 / (t+2)
    vecG = K @ vecM - k
    imin = np.argmin(vecG)
    vecM *= (1-beta)
    vecM[imin] += beta
return vecM
```





**Figure:**  $\sigma = 2$ 

Figure:  $\sigma = 4$ 

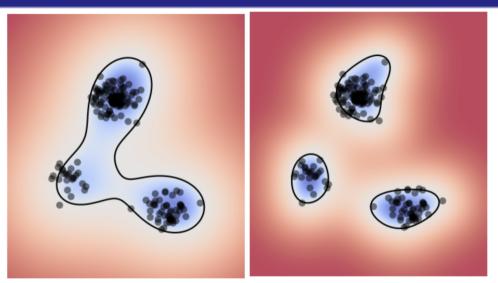


Figure:  $\sigma = 1$  Figure:  $\sigma = 0.5$