Turboshaft Fault
Detection using Machine
Learning



Workshop: Predictive Maintenance using ML

Helicopter Turboshaft Fault Detection

Explore the real-world application of machine learning in aviation for predictive maintenance. This workshop covers data preprocessing, model training, and deployment.

- Hands-on: Build and test your own fault detection model.
 - The goal is to:
 - i. Detect potential failures or faults in turboshaft engines before they occur
 - ii. Minimize unplanned downtime
 - iii. Reduce maintenance costs and risk
 - iv. Increase operational efficiency and safety
- Gain practical skills for aviation ML applications.
- Enhance understanding of ML model lifecycle.

■ Dataset Overview

Dataset Description

Our dataset is derived from simulated turboshaft engine sensor data, comprising thousands of operational sessions.

Key Features:

- Temperature & Pressure readings
- Engine Speed & Vibration metrics
- Altitude & Fuel Flow data
- Ambient Environmental conditions

Target Variable:

- Fault_Label: Categorical classes indicating engine health.
- Classes include: Normal Operation, Compressor
 Degradation, Turbine Blade Damage, Sensor Malfunction,
 Fuel System Anomaly, and Excessive Vibration Fault.



Project Pipeline

1. Data Ingestion & Setup

Import necessary libraries and load the turboshaft dataset.

3. Label Encoding

Encode multiclass fault labels into numerical format.

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5. Model Training

Train a Random Forest
Classifier on the prepared
data.

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7. Model Persistence

Save the trained model for future inference and testing.

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2. Preprocessing &

Clean, preprocess, and scale features for optimal model performance.

Scaling

4. Data Balancing

Address class imbalance
using SMOTE for
oversampling and
RandomUnderSampler for
downsampling.

6. Model Evaluation

Evaluate performance using a Confusion Matrix and key metrics.

8. Deployment & App

Build an interactive Streamlit application for real-time fault prediction.

* Data Preprocessing

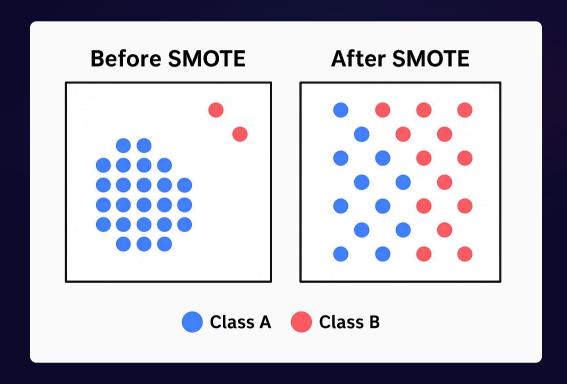
Data Cleaning & Preparation

Column Management Drop irrelevant columns like 'Timestamp' to streamline data. Label Encoding Convert categorical 'Fault_Label' into numerical representations for ML compatibility. Feature Scaling 3 Apply StandardScaler to normalize numerical features, preventing dominance by larger values. Train-Test Split Partition the dataset into 80% training and 20% testing sets to ensure unbiased evaluation. Handling Class Imbalance 5 Used **SMOTE** (Synthetic Minority Oversampling Technique) to balance class distribution.



Resampling Strategy

Addressing the challenge of imbalanced classes, where 'Normal' operational data significantly outweighs 'Fault' instances.



SMOTE (Synthetic Minority Over-sampling Technique)

This clever technique generates brand new synthetic samples for the underrepresented fault types. By boosting their numbers, we ensure the model gets to learn from a more balanced distribution of fault patterns.

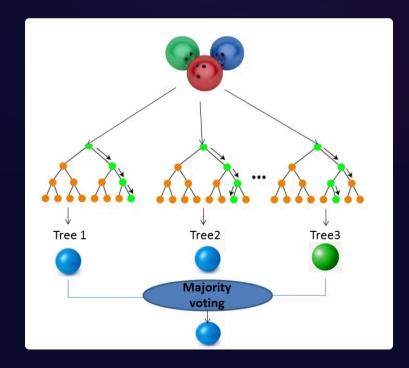
New Sample = Original Sample - Factor * (Original Sample - Neighbour)



Random Forest Classifier

The Random Forest Classifier is selected for its robust performance on tabular datasets and ability to handle complex feature interactions. Random forest Classifier works on the Bagging (Bootstrap Aggregation) principle.

• **Training Data:** Model is trained exclusively on the resampled dataset to ensure unbiased learning from both common and rare fault conditions.



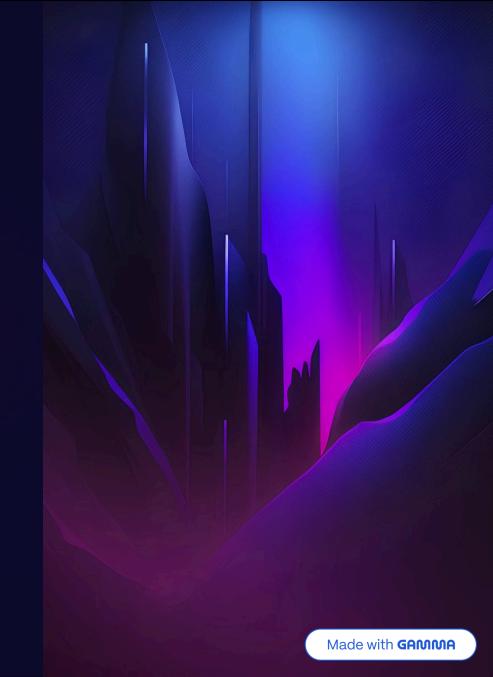




Evaluation

Performance Metrics:

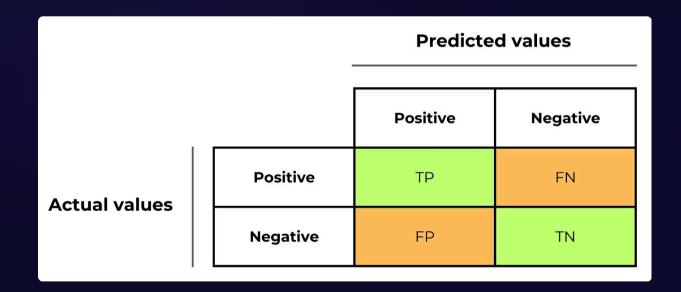
- Accuracy: Overall correctness of predictions.
- Precision, Recall, F1-score: Detailed metrics for each fault class, crucial for evaluating performance on minority classes.
- **Confusion Matrix:** Provides a visual breakdown of true positives, false positives, true negatives, and false negatives.





Confusion Matrix

The Confusion Matrix is a critical tool for visualizing the performance of our classification model, particularly in safety-critical applications like aviation.



It helps us understand which fault types are correctly identified and which are misclassified, ensuring reliability in critical systems.

Sample Prediction

To perform an instant fault prediction, the model requires 9 specific sensor values from the turboshaft engine.

Temperature: e.g., 850.5 °C

Pressure: e.g., 150.2 kPa

Speed: e.g., 25000 RPM

Vibration: e.g., 0.85 mm/s

Altitude: e.g., 1000 m

Fuel Flow: e.g., 0.7 kg/s

Ambient Temp: e.g., 25.0 °C

Other relevant sensor readings (2 additional)



Instant Output:

Compressor Degradation

The model processes these inputs and delivers a precise fault type, such as "Compressor Degradation" or "Normal Operation", in real-time.



Deployment Ready

Ensuring the fault detection model is easily accessible and reusable without the need for repetitive retraining.



Model Persistence

The trained Random Forest model is efficiently saved using **joblib**, a lightweight library for serializing Python objects.



Seamless Loading

The saved model can be loaded into any Python environment, facilitating quick setup for predictions in new applications.



Reduced Overhead

Eliminates the need for retraining the model from scratch for every new prediction task or deployment instance.

Reference

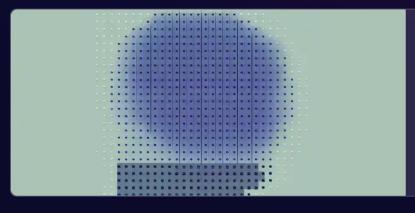


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Random Forest Algorithm in Machine Learning

Explore the Random Forest algorithm: its applications, key features, differences from decision trees, important hyperparameters. Read Now!



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SMOTE for Imbalanced Classification with Python

SMOTE is an oversampling technique where the synthetic samples are generated for the minority class. Handle imbalanced data using SMOTE.

Thank You

