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物理…原理井16 1913*
                                                                                   ① 6<sub>KV</sub> ③ SO(n) ⑤ 前由後
一般化學能
                                                           | Total | Tota
                                                                 E-1
② Thank 29 21 連7 12 12 22 2
~~> 運動力学表現性
                                                                                                                                               RXIAN-TA
D(カ)、- {A(GL(カ) | A:Vエの過去分換 }
                                                                                               通父女操!
                                                                                                     \begin{array}{c} O(a):=\left\{\begin{array}{ll} \left\{\left\{\left(L_{1}^{2}\right)\right\}^{\frac{1}{2}}Y-Y^{-\frac{1}{2}}\right\} \\ A:z(a) \rightarrow T_{A}:Y-Y_{A}: O(Y) \\ & \downarrow i \mapsto T_{A}(x):=Ax \\ & \in I_{A}(x):=Ax \\ & \in I_{A}(x):=Ax \\ & \downarrow i \mapsto T_{A}(x):=Ax \\
                                                                                                                                   VIAD較存
SO(V):= {A+O(V) | det A-1 }
使用的用意。例如《 (p.SF)
                                                                                                                                   4.13. A+SO(Y).
F:A-B.对、今 L(A) S<sub>Y</sub>(I) = S<sub>y</sub>(Y).
www.NB.A-N35. 26。段数对对
                                                                                         4.几6.空间超过对称性(4.100)
                                                                                                                                                                                               \begin{split} \widetilde{F}(E^{n}, \underline{x}) & = \widetilde{F}(E^{n}, \underline{x}) \\ \widetilde{F}: & = \widetilde{F}(E^{n}, \underline{x}) + \widetilde{F}(E^{n}, \underline{x}) \\ & \Rightarrow \widetilde{F}_{n}(E^{n}, \underline{x}) + \widetilde{F}_{n}(E^{n}, \underline{x}) \\ & \times \underbrace{\widetilde{F}_{n}(E^{n}, \underline{x})}_{\underline{x}} + \underbrace{\widetilde{F}_{n}(E^{n}, \underline{x})}_{\underline{x}} + \underbrace{\widetilde{F}_{n}(E^{n}, \underline{x})}_{\underline{x}} \\ & \times \underbrace{\widetilde{F}_{n}(E^{n}, \underline{x})}_{\underline{x}} + \underbrace{\underline{F}_{n}(E^{n}, \underline{x})}_{\underline{x}} + \underbrace{\underline{F}_{n}(E^{n}, \underline{x})}_{\underline{x}} + \underbrace{\underline{F}_{n}(E^{n}, \underline{
                                                                                                                                                                                                                                                                                                                                         \begin{cases} S_{k} & J_{k}, \ Y_{k} & J_{k} \\ \vdots & \vdots & \vdots \\ \left\{ (Y_{j}(k_{j}), Y_{j}^{-1}) \right\}_{j \in L_{k}} : S_{k}^{1} \land s \not= ks \end{cases}.
                                                                                                                                                                                                     例 5.5.
R<sup>3</sup>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                f = 3 + 2 = 5
                                                                                                                                                                                                                                                                                                     自由模3
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