

Seminar Approximation Algorithms

Approximating Nash Social Welfare under Submodular Valuations through (Un)Matchings

Based on the paper of the same name by Garg, Kulkarni and Kulkarni [\[14\]](#).

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Abstract

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1 Introduction

The study of distributing resources amongst one or more receivers is an interdisciplinary field and is interesting from both a computational (how to find an allocation) and a qualitative (what a good allocation makes) standpoint [8]. Its areas of application are manifold: industrial procurement, where the preferences of buyers and sellers need be appropriately captured and real-world constraints on goods and services be taken into account [8]; mobile edge computing, where computation and storage are taken on by physically close cloud systems but participation has to be incentivised [2, 11]; manufacturing processes, where tasks should be scheduled efficiently within and between many production sites and disturbances be quickly paid heed to [8]; water management, where hostile countries must come to mutual agreements on the withdrawal from contested rivers [10].

In this seminar paper, we focus on unsharable and indivisible resources, which we term *items*. The receivers of those items are called *agents*. The distributions of items amongst agents are modelled through allocations.

Definition 1. Let \mathcal{G} be a set of m items and \mathcal{A} be a set of n agents. An *allocation* is a tuple $\mathbf{x} = (\mathbf{x}_i)_{i \in \mathcal{A}}$ of *bundles* $\mathbf{x}_i \subset \mathcal{G}$ such that each item is element of exactly one bundle, that is, $\bigcup_{i \in \mathcal{A}} \mathbf{x}_i = \mathcal{G}$ and $\mathbf{x}_i \cap \mathbf{x}_{i'} = \emptyset$ for all $i \neq i'$. An item $j \in \mathcal{G}$ is *assigned* to agent $i \in \mathcal{A}$ if $j \in \mathbf{x}_i$ holds.

or rather
'alloc-
ated'?

The satisfaction of an agent i with her bundle \mathbf{x}_i is measured by her *valuation function* v_i , which assigns each set of items a real value. We always assume that valuation functions are non-negative, i. e., $v_i(\mathcal{S}) \geq 0 \ \forall \mathcal{S} \subset \mathcal{G}$, monotonically non-decreasing, i. e., $v_i(\mathcal{S}_1) \leq v_i(\mathcal{S}_2) \ \forall \mathcal{S}_1 \subset \mathcal{S}_2 \subset \mathcal{G}$, and normalised, i. e., $v_i(\emptyset) = 0$. Besides fulfilling these properties, the valuation functions can come from a plethora of function families. We will discuss additive and submodular functions in greater detail.

Additive The valuation $v_i(\mathcal{S})$ of an agent i for a set $\mathcal{S} \subset \mathcal{G}$ of items j is the sum of individual valuations $v_i(j)$, that is, $v_i(\mathcal{S}) = \sum_{j \in \mathcal{S}} v_i(j)$.

These are fairly simple but useful functions, and many expansions exist. [12, 14, p. 3]

Submodular Let $v_i(\mathcal{S}_1 \mid \mathcal{S}_2) := v_i(\mathcal{S}_1 \cup \mathcal{S}_2) - v_i(\mathcal{S}_2)$ denote the marginal valuation of agent i for a set $\mathcal{S}_1 \subset \mathcal{G}$ of items over a disjoint set $\mathcal{S}_2 \subset \mathcal{G}$. This valuation function satisfies the submodularity constraint $v_i(j \mid \mathcal{S}_1 \cup \mathcal{S}_2) \leq v_i(j \mid \mathcal{S}_1)$ for all agents $i \in \mathcal{A}$, items $j \in \mathcal{G}$ and sets $\mathcal{S}_1, \mathcal{S}_2 \subset \mathcal{G}$ of items.

or rather
utility?

Submodular valuation functions (which encompass additive ones) have the property that the gain from assigning new items is smaller, the bigger the bundles are. Diminishing returns are a common phenomenon in economics, making submodular functions worthwhile to study. [18]

In a slight abuse of notation, we sometimes omit curly braces delimiting a set, so we write $v_i(j_1, j_2, \dots)$ but mean $v_i(\{j_1, j_2, \dots\})$ for example.

In order to measure and maximise the overall satisfaction of all agents, one needs to combine their valuations. Several options arise here; common choices are the utilitarian social welfare (USW), that is the sum of all valuations [2, 8, 10, 14, 18], and the egalitarian social welfare (ESW), that is the minimum of all valuations [8, 14]. We consider a third one, the Nash social welfare (NSW).

Problem 1. Given a set \mathcal{G} of items and a set \mathcal{A} of agents with monotonically non-decreasing valuation functions $v_i: \mathcal{P}(\mathcal{G}) \rightarrow \mathbb{R}_0^+$ and agent weights $\eta_i \in \mathbb{R}^+$ for all agents $i \in \mathcal{A}$, the

Nash social welfare problem is to find an allocation \mathbf{x}^* maximising the weighted geometric mean of valuations, that is,

$$\mathbf{x}^* \stackrel{!}{=} \arg \max_{\mathbf{x} \in \mathbf{X}_{\mathcal{A}}(\mathcal{G})} \{\text{NSW}(\mathbf{x})\} \quad \text{with } \text{NSW}(\mathbf{x}) := \left(\prod_{i \in \mathcal{A}} v_i(\mathbf{x}_i)^{\eta_i} \right)^{1/\sum_{i \in \mathcal{A}} \eta_i}$$

where $\mathbf{X}_{\mathcal{A}}(\mathcal{G})$ is the set of all possible allocations. The problem is called *symmetric* if all agent weights η_i are equal, and *asymmetric* otherwise.

For the techniques employed in later sections, it is beneficial to consider the logarithmic NSW, that is,

$$\log \text{NSW}(\mathbf{x}) = \frac{1}{\sum_{i \in \mathcal{A}} \eta_i} \cdot \sum_{i \in \mathcal{A}} \eta_i \log v_i(\mathbf{x}_i), \quad (1)$$

which is a sum instead of a product. The NSW strikes as middle ground between the USW and the ESW, which focus on efficiency (height of overalls satisfaction) and fairness (how agents value other agents' bundles), respectively. In addition, it exhibits scale-freeness, that is invariance to the scales in which each valuation is expressed, rendering e. g. relative instead of absolute valuations unproblematic. Even though the NSW problem is \mathcal{NP} -hard and \mathcal{APX} -hard, approximate solutions largely keep the properties of optimal allocations. [3, 6, 9, 20, cf. remark 2] We use the following definition for the approximation factor.

Definition 2. An algorithm for a maximisation problem is α -approximative if, for every problem instance I and output $\text{ALG}(I)$, it holds $\text{ALG}(I) \geq \text{OPT}(I)/\alpha$, where $\text{OPT}(I)$ is the optimal value.

rephrase

As reference, a quick overview of the research situation¹ of the USW and ESW: For the submodular USW, a lower bound of $\frac{e}{e-1}$ on the approximation factor was proven [18] and an approximation algorithm achieving said factor shown [22] — the additive USW is trivially solvable through repeated maximum matchings. For the additive ESW, a randomised $(320\sqrt{n} \log^3 n)$ -approximative algorithm employing linear programming [1] and a hardness of 2 [5] are known. An $(2n-1)$ -approximative algorithm exists for the submodular ESW [17].

check if asymmetric

In contrast, the NSW is less well understood¹. A 1.45-approximative algorithm is known for the symmetric additive NSW [3]. For the symmetric submodular NSW, a $(m-n+1)$ -approximative algorithm has been devised [20]. Both approaches exploit the symmetry of the studied problem and fail to be extended to the asymmetric case. Moreover, an approximation factor dependant on the number of items is not desirable as the number of items vastly exceeds the number of agents in many applications.

Garg, Kulkarni and Kulkarni [14] fill this knowledge gap by providing two algorithms. The first one, *SMatch*, computes an allocation for the asymmetric additive NSW and is $2n$ -approximative. It does so by smartly *matching* agents and items in a bipartite graph. The second one, *RepReMatch*, computes an allocation for the asymmetric submodular NSW and is $(2n(\log_2 n + 3))$ -approximative. It does so by *repeatedly* computing *matchings*, which then get partly annulled, so that items can be *rematched*. We present and analyse both algorithms in section 2 and section 3 of our seminar report, respectively. In section 4, we analyse the hardness of the submodular NSW. Section 5 comprises the conclusion, a summary of newly published work since 2020, and an outlook on open questions.

- matroids? preliminaries [13]

¹The overview is given as it was roughly at the end of the year 2019, when Garg, Kulkarni and Kulkarni wrote their paper [14] on which this seminar report is based.

- exponentially many subsets; additive vs. submodular?
- hardness; constant additive in 2015; $\mathcal{O}(n)$ for sym. subadditive but hard to improve for special cases; unbounded integrality gap [\[13\]](#)

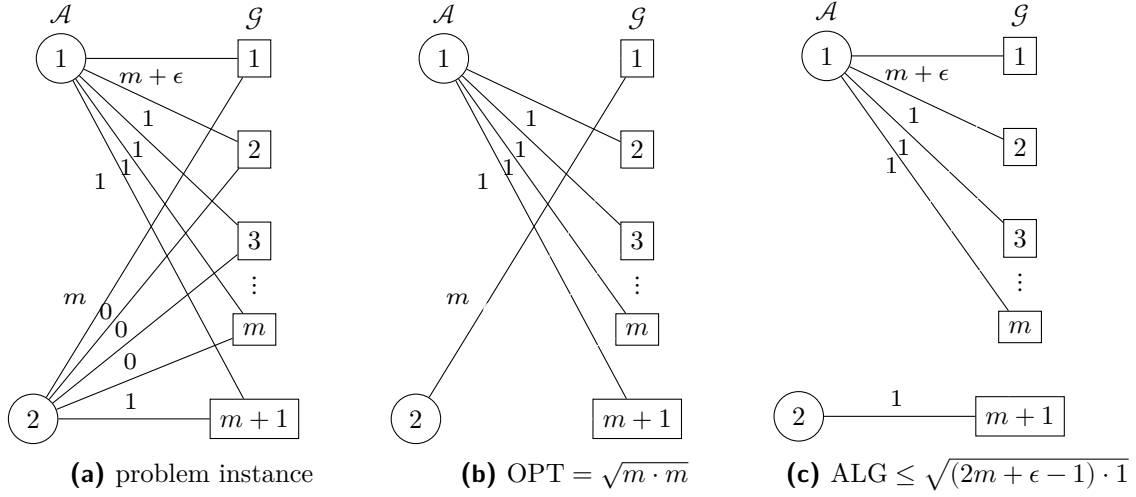


Figure 1: An example showing that simple repeated matching without consideration of the future leads to an approximation factor dependent on the number of items. Agent 1 values item 1 at $m + \epsilon$ and all other items at 1. Agent 2 values item 1 at m , item $m + 1$ at 1 and all other items at 0. In an optimal allocation, item 1 would be assigned to agent 2 and all other items to agent 1, resulting in a NSW of $\sqrt{m \cdot m} = m$. A repeated maximum matching algorithm would greedily assign item 1 to agent 1 and item $m + 1$ to agent 2 in the first round. Even if all remaining items were going to be assigned to agent 1, the NSW will never surpass $\sqrt{(2m + \epsilon - 1) \cdot 1} < \sqrt{2m}$. The approximation factor $\alpha \approx \sqrt{m/2}$ therefore depends on the number of items.

2 SMatch

In the case of an equal number of agents and items, i.e., $n = m$, the *additive* NSW can be solved exactly by finding a maximum matching on a bipartite graph with the sets of agents and of items as its parts; as weight of the edge between agent i and item j , use $\eta_i \log v_i(j)$, that is the weighted valuation of item j by agent i in the logarithmic Nash social welfare. Should there be more items than agents, then it would be obvious at first to just repeatedly find a maximum matching and assign the items accordingly until all items are assigned. The flaw of this idea is that such a greedy algorithm only considers the valuations of items in the current matching and perhaps the valuations of items already assigned. As the example in fig. 1 demonstrates, this leads to an algorithm with an approximation factor dependent on the number m of items. The geometric mean of the NSW favours allocations with similarly valued bundles, wherefore it may be beneficial to give items to agents who cannot expect many more valuable items in the future instead of to agents who value the item a bit more but do so for other items as well.

The algorithm SMatch, described in algorithm 1, eliminates the flaw by first gaining foresight of the valuations of items assigned after the first matching, achieving an approximation factor of $2n$ (cf. theorem 1 later on). For a fixed agent i , order the items in descending order of valuations and denote the j -th most liked item by \mathcal{G}_i^j . To obtain a well-defined order, items of equal rank are further ordered numerically. SMatch does in fact repeatedly match items. During the first matching, however, the edge weights are defined as $\eta_i \log(v_i(j) + u_i/n)$ for an edge between agent i and item j . The addend u_i serves as estimation of the valuation of items assigned after the first matching (cf. lemma 2) and is

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Algorithm 1: SMatch for the Asymmetric Additive NSW problem

Input : set \mathcal{G} of m items, set \mathcal{A} of n agents, additive valuation functions $v_i: \mathcal{P}(\mathcal{G}) \rightarrow \mathbb{R}_0^+$ and weights $\eta_i \in \mathbb{R}^+$ for all agents $i \in \mathcal{A}$

Output: $\frac{1}{2n}$ -approximation $\mathbf{x} = (\mathbf{x}_i)_{i \in \mathcal{A}}$ of an optimal allocation

- 1 $\mathbf{x}_i \leftarrow \emptyset \quad \forall i \in \mathcal{A}$
- 2 $u_i \leftarrow v_i(\mathcal{G}_i^{2n+1}, \dots, \mathcal{G}_i^m) \quad \forall i \in \mathcal{A}$ \triangleright estimation of future valuations
- 3 $\mathcal{W} \leftarrow \{\eta_i \cdot \log(v_i(j) + u_i/n) \mid i \in \mathcal{A}, j \in \mathcal{G}\}$ \triangleright edge weights
- 4 $G \leftarrow (\mathcal{A}, \mathcal{G}, \mathcal{W})$ \triangleright bipartite graph
- 5 $\mathcal{M} \leftarrow \text{max_weight_matching}(G)$
- 6 $\mathbf{x}_i \leftarrow \{j \mid (i, j) \in \mathcal{M}\} \quad \forall i \in \mathcal{A}$ \triangleright assign according to matching
- 7 $\mathcal{G}^{\text{rem}} \leftarrow \mathcal{G} \setminus \{j \mid (i, j) \in \mathcal{M}\}$ \triangleright remove assigned items
- 8 **while** $\mathcal{G}^{\text{rem}} \neq \emptyset$ **do**
- 9 $\mathcal{W} \leftarrow \{\eta_i \cdot \log(v_i(j) + v_i(\mathbf{x}_i)) \mid i \in \mathcal{A}, j \in \mathcal{G}^{\text{rem}}\}$
- 10 $G \leftarrow (\mathcal{A}, \mathcal{G}^{\text{rem}}, \mathcal{W})$
- 11 $\mathcal{M} \leftarrow \text{max_weight_matching}(G)$
- 12 $\mathbf{x}_i \leftarrow \mathbf{x}_i \cup \{j \mid (i, j) \in \mathcal{M}\} \quad \forall i \in \mathcal{A}$
- 13 $\mathcal{G}^{\text{rem}} \leftarrow \mathcal{G}^{\text{rem}} \setminus \{j \mid (i, j) \in \mathcal{M}\}$
- 14 **end while**
- 15 **return** \mathbf{x}

defined as

$$u_i := \min_{\substack{\mathcal{S} \subseteq \mathcal{G} \\ |\mathcal{S}| \leq 2n}} \{v_i(\mathcal{G} \setminus \mathcal{S})\} = v_i(\mathcal{G}_i^{2n+1}, \dots, \mathcal{G}_i^m). \quad (2)$$

The set \mathcal{S} has less than $2n$ elements only if there are less than $2n$ items in total. From the second matching onwards, the edge weights are defined as $\eta_i \log(v_i(j) + v_i(\mathbf{x}_i))$, where \mathbf{x}_i is the continuously updated bundle of agent i . The addend $v_i(\mathbf{x}_i)$ could lead to better allocations in applications, but does not improve the approximation factor asymptotically.

To calculate the approximation factor of SMatch, we first need to establish a lower bound on the valuation of single items. For convenience, we order the items in the final bundle $\mathbf{x}_i = \{h_i^1, \dots, h_i^{\tau_i}\}$ of agent i by the order in which they were assigned, so that item h_i^t is assigned according to the t -th matching. Note that it holds $v_i(h_i^t) \geq v_i(h_i^{t'})$ for all $t' \geq t$.

Lemma 1. *For each agent $i \in \mathcal{A}$, her final bundle $\mathbf{x}_i = \{h_i^1, \dots, h_i^{\tau_i}\}$, and her tn -th most highly valued item \mathcal{G}_i^{tn} , it holds $v_i(h_i^t) \geq v_i(\mathcal{G}_i^{tn})$ for all $t = 1, \dots, \tau_i$.*

Proof. Before the t -th matching, no more than $(t-1)n$ items out of the tn most highly valued items $\mathcal{G}_i^1, \dots, \mathcal{G}_i^{tn}$ have been assigned in previous matchings since at most n many out of those items are assigned each time. Because of the t -th matching, at most $n-1$ more could be assigned to all other agents $i' \neq i$, leaving at least one item of $\mathcal{G}_i^1, \dots, \mathcal{G}_i^{tn}$ unassigned. Since $v_i(\mathcal{G}_i^k) \geq v_i(\mathcal{G}_i^{tn})$ for all $k \leq tn$ by definition of \mathcal{G}_i , the lemma follows. \square

We can now establish $u_i/n = v_i(\mathcal{G}_i^{2n+1}, \dots, \mathcal{G}_i^m)/n$ as lower bound on the valuations of items assigned after the first matching.

Lemma 2. *For each agent $i \in \mathcal{A}$ and her final bundle $\mathbf{x}_i = \{h_i^1, \dots, h_i^{\tau_i}\}$, it holds $v_i(h_i^2, \dots, h_i^{\tau_i}) \geq u_i/n$.*

Proof. By lemma 1 and definition of \mathcal{G}_i , every item h_i^t is worth at least as much as each item \mathcal{G}_i^{tn+k} with $k \in \{1, \dots, n\}$ and, consequently, its valuation $v_i(h_i^t)$ is at least as high

as the mean valuation $\frac{1}{n}v_i(\mathcal{G}_i^{tn+1}, \dots, \mathcal{G}_i^{tn+n})$. Further, it holds $\tau_i n + n \geq m$ since agent i gets assigned $\tau_i \geq \lfloor \frac{m}{n} \rfloor \geq \frac{m}{n} - 1$ many items. Together, this yields

$$v_i(h_i^2, \dots, h_i^{\tau_i}) = \sum_{t=2}^{\tau_i} v_i(h_i^t) \geq \sum_{t=2}^{\tau_i} \frac{1}{n} v_i(\mathcal{G}_i^{tn+1}, \dots, \mathcal{G}_i^{tn+n}) \geq \frac{1}{n} v_i(\mathcal{G}_i^{2n+1}, \dots, \mathcal{G}_i^m) = \frac{u_i}{n}. \quad (3)$$

i: I do not get the reason for the extra step in the original paper.

□

Remark 1. In lemma 2, we assumed non-zero valuations for all items, hence the bundle lengths of $\tau_i \geq \lfloor \frac{m}{n} \rfloor$. Of course in an actual program, one would not assign items to agents who value them at zero. Nevertheless, lemma 2 still holds inasmuch as additional zero valuations in eq. (3) do not change the sum.

This allows us to calculate an approximation factor for SMatch by comparing its output with an optimal allocation \mathbf{x}^* .

Theorem 1. *SMatch is 2n-approximative.*

Proof. Lemma 2 can be plugged into the logarithmic NSW:

$$\log \text{NSW}(\mathbf{x}) = \frac{1}{\sum_{i \in \mathcal{A}} \eta_i} \cdot \sum_{i \in \mathcal{A}} \eta_i \log v_i(h_i^1, \dots, h_i^{\tau_i}) \quad (4)$$

$$= \frac{1}{\sum_{i \in \mathcal{A}} \eta_i} \cdot \sum_{i \in \mathcal{A}} \eta_i \log(v_i(h_i^1) + v_i(h_i^2, \dots, h_i^{\tau_i})) \quad (5)$$

$$\geq \frac{1}{\sum_{i \in \mathcal{A}} \eta_i} \cdot \sum_{i \in \mathcal{A}} \eta_i \log(v_i(h_i^1) + u_i/n) \quad (6)$$

Notice that the first matching of SMatch maximises the sum in eq. (6). Thus, assigning all agents i their respective most highly valued item g_i^1 in an optimal bundle $\mathbf{x}_i^* = \{g_i^1, \dots, g_i^{\tau_i^*}\}$ yields the even lower bound

$$\log \text{NSW}(\mathbf{x}) \geq \frac{1}{\sum_{i \in \mathcal{A}} \eta_i} \cdot \sum_{i \in \mathcal{A}} \eta_i \log(v_i(g_i^1) + u_i/n). \quad (7)$$

Recall the definition of u_i from eq. (2). Consider a slightly modified variant:

$$u_i = v_i(\mathcal{G} \setminus \mathcal{S}_i) \text{ with } \mathcal{S}_i := \arg \min_{\substack{\mathcal{S} \subset \mathcal{G} \\ |\mathcal{S}| \leq 2n}} \{v_i(\mathcal{G} \setminus \mathcal{S})\} \quad (8)$$

Moreover, consider the set \mathcal{S}_i^* of the (at most) $2n$ most highly valued items in the optimal bundle \mathbf{x}_i^* , i. e.

$$\mathcal{S}_i^* := \arg \min_{\substack{\mathcal{S} \subset \mathcal{G} \\ |\mathcal{S}| \leq 2n}} \{v_i(\mathbf{x}_i^* \setminus \mathcal{S})\}. \quad (9)$$

It holds $v_i(g_i^1) \geq \frac{1}{2n} v_i(\mathcal{S}_i^*)$ because of $v_i(g_i^1) \geq v_i(j)$ for all $j \in \mathcal{S}_i^*$. Furthermore, it holds $u_i = v_i(\mathcal{G} \setminus \mathcal{S}_i) \geq v_i(\mathbf{x}_i^* \setminus \mathcal{S}_i) \geq v_i(\mathbf{x}_i^* \setminus \mathcal{S}_i^*)$. We can insert these two inequalities into eq. (7) and prove the theorem thereby:

$$\log \text{NSW}(\mathbf{x}) \geq \frac{1}{\sum_{i \in \mathcal{A}} \eta_i} \cdot \sum_{i \in \mathcal{A}} \eta_i \log \left(\frac{v_i(\mathcal{S}_i^*)}{2n} + \frac{v_i(\mathbf{x}_i^* \setminus \mathcal{S}_i^*)}{n} \right) \quad (10)$$

$$\geq \frac{1}{\sum_{i \in \mathcal{A}} \eta_i} \cdot \sum_{i \in \mathcal{A}} \eta_i \log \left(\frac{v_i(\mathbf{x}_i^*)}{2n} \right) \quad (11)$$

$$= \log \left(\frac{\text{NSW}(\mathbf{x}^*)}{2n} \right) \quad (12)$$

□

The analysis is asymptotically tight. It is possible to design an instance for the asymmetric NSW such that SMatch achieves an approximation ratio approaching $2/n$. It remains to be shown whether the symmetric NSW is equally hard. [14, Section 6.3]

Remark 2. SMatch produces *fair* allocations which are *envy-free up to one item* (EF1). An allocation \mathbf{x} is EF1 if, for every pair $(i_1, i_2) \in \mathcal{A}^2$ of agents, one needs to remove at most one item from the bundle \mathbf{x}_{i_2} of agent i_2 so that agent i_1 does not want to swap bundles. In other words, either it holds $v_{i_1}(\mathbf{x}_{i_1}) \geq v_{i_2}(\mathbf{x}_{i_2})$ or there is an item $j \in \mathbf{x}_{i_2}$ such that $v_{i_1}(\mathbf{x}_{i_1}) \geq v_{i_2}(\mathbf{x}_{i_2} \setminus \{j\})$. [14, Section 5.2]

Pigou-Dalton-Prinzip?

PO?

3 RepReMatch

The algorithm SMatch estimates the valuation of the lowest-value items by determining the set of highest-value items and then valuing the remaining items. Unfortunately, this approach does not work for general submodular valuation functions because taking the set of highest-value items away does not necessarily leave a set of lowest-value items. In fact, it can be shown [21] that determining the set of lowest-value items is approximable only within a factor of $\Omega(\sqrt{m/\ln m})$.

For this reason, the algorithm RepReMatch, described in algorithm 2, relies on an approach with three phases, achieving an approximation factor of $2n(\log_2 n + 3)$ (cf. theorem 2). In phase I, a sufficiently big set of high-value items is determined through repeated matchings. This phase serves merely to determine this set, so items are assigned

Algorithm 2: RepReMatch for the Asymmetric Submodular NSW problem

Input : set \mathcal{G} of m items, set \mathcal{A} of n agents, additive valuation functions

$v_i: \mathcal{P}(\mathcal{G}) \rightarrow \mathbb{R}_0^+$ and weights $\eta_i \in \mathbb{R}^+$ for all agents $i \in \mathcal{A}$

Output: $\frac{1}{2n(\log_2 n + 3)}$ -approximation $\mathbf{x}^{\text{III}} = (\mathbf{x}_i^{\text{III}})_{i \in \mathcal{A}}$ of an optimal allocation

Phase I:

```

1  $\mathbf{x}_i^{\text{I}} \leftarrow \emptyset$ 
2  $\mathcal{G}^{\text{rem}} \leftarrow \mathcal{G}$ 
3 for  $t \leftarrow 1, \dots, \lceil \log_2 n \rceil + 1$  do
4   if  $\mathcal{G}^{\text{rem}} \neq \emptyset$  then
5      $\mathcal{W} \leftarrow \{ \eta_i \cdot \log(v_i(j)) \mid i \in \mathcal{A}, j \in \mathcal{G}^{\text{rem}} \}$   $\triangleright$  valuation of single item
6      $G \leftarrow (\mathcal{A}, \mathcal{G}^{\text{rem}}, \mathcal{W})$ 
7      $\mathcal{M} \leftarrow \text{max\_weight\_matching}(G)$ 
8      $\mathbf{x}_i^{\text{I}} \leftarrow \mathbf{x}_i^{\text{I}} \cup \{j\} \quad \forall (i, j) \in \mathcal{M}$ 
9      $\mathcal{G}^{\text{rem}} \leftarrow \mathcal{G}^{\text{rem}} \setminus \{j \mid (i, j) \in \mathcal{M}\}$ 
10  end if
11 end for
```

Phase II:

```

12  $\mathbf{x}_i^{\text{II}} \leftarrow \emptyset \quad \forall i \in \mathcal{A}$   $\triangleright$  put allocation  $\mathbf{x}^{\text{I}}$  away and start a new one
13 while  $\mathcal{G}^{\text{rem}} \neq \emptyset$  do
14    $\mathcal{W} \leftarrow \{ \eta_i \cdot \log(v_i(\mathbf{x}_i^{\text{II}} \cup \{j\})) \mid i \in \mathcal{A}, j \in \mathcal{G}^{\text{rem}} \}$   $\triangleright$  val. of item & cur. bundle
15    $G \leftarrow (\mathcal{A}, \mathcal{G}^{\text{rem}}, \mathcal{W})$ 
16    $\mathcal{M} \leftarrow \text{max\_weight\_matching}(G)$ 
17    $\mathbf{x}_i^{\text{II}} \leftarrow \mathbf{x}_i^{\text{II}} \cup \{j\} \quad \forall (i, j) \in \mathcal{M}$ 
18    $\mathcal{G}^{\text{rem}} \leftarrow \mathcal{G}^{\text{rem}} \setminus \{j \mid (i, j) \in \mathcal{M}\}$ 
19 end while
```

Phase III:

```

20  $\mathcal{G}^{\text{rem}} \leftarrow \bigcup_{i \in \mathcal{A}} \mathbf{x}_i^{\text{I}}$   $\triangleright$  release items assigned in phase I
21  $\mathcal{W} \leftarrow \{ \eta_i \cdot \log(v_i(\mathbf{x}_i^{\text{II}} \cup \{j\})) \mid i \in \mathcal{A}, j \in \mathcal{G}^{\text{rem}} \}$   $\triangleright$  val. of item & cur. bundle
22  $G \leftarrow (\mathcal{A}, \mathcal{G}^{\text{rem}}, \mathcal{W})$ 
23  $\mathcal{M} \leftarrow \text{max\_weight\_matching}(G)$ 
24  $\mathbf{x}_i^{\text{III}} \leftarrow \mathbf{x}_i^{\text{II}} \cup \{j\} \quad \forall (i, j) \in \mathcal{M}$ 
25  $\mathcal{G}^{\text{rem}} \leftarrow \mathcal{G}^{\text{rem}} \setminus \{j \mid (i, j) \in \mathcal{M}\}$ 
26  $\mathbf{x}^{\text{III}} \leftarrow \text{arbitrary\_allocation}(\mathcal{A}, \mathcal{G}^{\text{rem}}, \mathbf{x}^{\text{III}}, (v_i)_{i \in \mathcal{A}})$ 
27 return  $\mathbf{x}^{\text{III}}$ 
```

temporarily only. The edge weights reflect this by taking the valuations of just single items into account.

In phase II, the remaining items are assigned normally through repeated matchings. Consequently, each edge weight is updated in each round to be the weighted logarithm of the valuation of both the respective item and the items assigned so far.

In phase III, the high-value items assigned in phase I are released. With the knowledge of items assigned in phase II, one maximum weight matching is calculated, and the matched items are assigned accordingly. Again each edge weight is the weighted logarithm of the valuation of both the respective item and the respective agent's bundle from phase II. The remaining released items are assigned arbitrarily.

We start by analysing phase II as it is the first phase with definitive assignments. To this end, we introduce two types of item sets. Note that we use the term *round* to refer to the iterations of the loops in the phases I and II. For ease of notation, we refer to the moment right before the first iteration in phase II as round 0.

Definition 3. Let \mathbf{x}_i^* be an optimal bundle of some agent $i \in \mathcal{A}$. For any round $r \geq 1$ in phase II, the set $\mathcal{L}_{i,r} \subset \mathbf{x}_i^*$ of *lost* items is the set of all items $j \in \mathbf{x}_i^*$ assigned to other agents $i' \neq i$ in that round.

Definition 4. Let \mathbf{x}_i^* be an optimal bundle of some agent $i \in \mathcal{A}$ and $\mathbf{x}_i^{\text{II}} = \{h_i^1, \dots, h_i^{\tau_i^{\text{II}}}\}$ be her bundle in phase II. The set $\bar{\mathbf{x}}_{i,r}^*$ of *optimal and attainable* items is defined as $\bar{\mathbf{x}}_{i,0}^* := \mathbf{x}_i^* \setminus \bigcup_{i' \in \mathcal{A}} \mathbf{x}_{i'}^{\text{I}}$ in round 0 and as $\bar{\mathbf{x}}_{i,r}^* := \bar{\mathbf{x}}_{i,r-1}^* \setminus (\mathcal{L}_{i,r} \cup \{h_i^{r-1}\})$ in round $r \in [1, \tau_i^{\text{II}}]$.

We denote their sizes by $\ell_{i,r} := |\mathcal{L}_{i,r}|$ and $\bar{\tau}_{i,r}^* := |\bar{\mathbf{x}}_{i,r}^*|$, respectively. First, we give a lower bound on the valuations of optimal and attainable items.

Lemma 3. For each agent $i \in \mathcal{A}$ and her bundle $\mathbf{x}_i^{\text{II}} = \{h_i^1, \dots, h_i^{\tau_i^{\text{II}}}\}$, it holds in all rounds $r = 2, \dots, \tau_i^{\text{II}}$ of phase II that

$$v_i(\bar{\mathbf{x}}_{i,r}^* \mid h_i^1, \dots, h_i^{r-1}) \geq v_i(\bar{\mathbf{x}}_{i,1}^*) - \ell_{i,2} \cdot v_i(h_i^1) - \sum_{r'=2}^{r-1} \ell_{i,r'+1} \cdot v_i(h_i^{r'}) - v_i(h_i^1, \dots, h_i^{r-1}).$$

i: Would it be 'dirty' to include notation in the definitions?

Proof. We prove the lemma by induction on the number r of rounds. In the beginning of the base case $r = 2$, agent i has already been assigned item h_i^1 . For each of the optimal and attainable items $j \in \bar{\mathbf{x}}_{i,1}^*$ in round 1, the marginal valuation $v_i(j \mid \emptyset)$ over the empty set was at most $v_i(h_i^1 \mid \emptyset)$, as otherwise item h_i^1 would not have been assigned first. The marginal valuation $v_i(j \mid h_i^1)$ over $\{h_i^1\}$ is upper-bounded by $v_i(h_i^1 \mid \emptyset)$, too, due to the submodularity of valuations. During round 2, a further $\ell_{i,2}$ of these items j are assigned to other agents, and item h_i^2 is assigned to agent i . We can bound the marginal valuation of the remaining optimal and attainable items in round 2 in the following way:

Case 1— $h_i^1 \in \bar{\mathbf{x}}_{i,1}^*$: It holds $v_i(\bar{\mathbf{x}}_{i,2}^* \mid h_i^1) = v_i(\bar{\mathbf{x}}_{i,2}^* \cup \{h_i^1\}) - v_i(h_i^1) = v_i(\bar{\mathbf{x}}_{i,1}^* \setminus \mathcal{L}_{i,2}) - v_i(h_i^1)$.

Case 2— $h_i^1 \notin \bar{\mathbf{x}}_{i,1}^*$: Due to the monotonicity of the valuation functions, it holds $v_i(\bar{\mathbf{x}}_{i,2}^* \cup \{h_i^1\}) \geq v_i(\bar{\mathbf{x}}_{i,2}^*)$ and, therefore, $v_i(\bar{\mathbf{x}}_{i,2}^* \mid h_i^1) \geq v_i(\bar{\mathbf{x}}_{i,2}^*) - v_i(h_i^1) = v_i(\bar{\mathbf{x}}_{i,1}^* \setminus \mathcal{L}_{i,2}) - v_i(h_i^1)$.

In both cases, the base case is proven because

$$v_i(\bar{\mathbf{x}}_{i,2}^* \mid h_i^1) \geq v_i(\bar{\mathbf{x}}_{i,1}^* \setminus \mathcal{L}_{i,2}) - v_i(h_i^1) \quad (13)$$

$$\geq v_i(\bar{\mathbf{x}}_{i,1}^*) - v_i(\mathcal{L}_{i,2}) - v_i(h_i^1) \quad (14)$$

$$\geq v_i(\bar{\mathbf{x}}_{i,1}^*) - \ell_{i,2} \cdot v_i(h_i^1) - v_i(h_i^1), \quad (15)$$

where the second inequality is shown easily using an alternative definition of submodularity ($v_i(\mathcal{S}_1 \cup \mathcal{S}_2) + v_i(\mathcal{S}_1 \cap \mathcal{S}_2) \leq v_i(\mathcal{S}_1) + v_i(\mathcal{S}_2)$ with $\mathcal{S}_1 = \bar{\mathbf{x}}_{i,1}^* \setminus \mathcal{L}_{i,2}$ and $\mathcal{S}_2 = \mathcal{L}_{i,2}$ [18]), and

the third inequality is due all $\ell_{i,2}$ items j in set $\mathcal{L}_{i,2}$ not being assigned in round 1 although attainable, implying $v_i(j) \leq v_i(h_i^1)$.

For the induction hypothesis, we assume that the lemma holds true for all rounds up to some r . In the induction step $r \rightarrow r+1$, we differentiate the same two cases again:

Case 1— $h_i^r \in \bar{\mathbf{x}}_{i,r}^*$: Again we exploit the submodularity of the valuation functions to obtain a lower bound on the marginal valuation of $\bar{\mathbf{x}}_{i,r+1}^*$.

$$v_i(\bar{\mathbf{x}}_{i,r+1}^* \mid h_i^1, \dots, h_i^r) = v_i(\bar{\mathbf{x}}_{i,r+1}^* \cup \{h_i^r\} \mid h_i^1, \dots, h_i^{r-1}) - v_i(h_i^r \mid h_i^1, \dots, h_i^{r-1}) \quad (16)$$

$$= v_i(\bar{\mathbf{x}}_{i,r}^* \setminus \mathcal{L}_{i,r+1} \mid h_i^1, \dots, h_i^{r-1}) - v_i(h_i^r \mid h_i^1, \dots, h_i^{r-1}) \quad (17)$$

$$\geq v_i(\bar{\mathbf{x}}_{i,r}^* \mid h_i^1, \dots, h_i^{r-1}) - v_i(h_i^r \mid h_i^1, \dots, h_i^{r-1}) \quad (18)$$

$$- v_i(\mathcal{L}_{i,r+1} \mid h_i^1, \dots, h_i^{r-1})$$

Case 2— $h_i^r \notin \bar{\mathbf{x}}_{i,r}^*$: At first, we use the monotonicity of the valuation functions to get the inequality

$$v_i(\bar{\mathbf{x}}_{i,r}^* \mid h_i^1, \dots, h_i^r) = v_i(\bar{\mathbf{x}}_{i,r}^* \cup \{h_i^1, \dots, h_i^r\}) - v_i(h_i^1, \dots, h_i^r) \quad (19)$$

$$\geq v_i(\bar{\mathbf{x}}_{i,r}^* \cup \{h_i^1, \dots, h_i^{r-1}\}) - v_i(h_i^1, \dots, h_i^r) \quad (20)$$

$$= (v_i(\bar{\mathbf{x}}_{i,r}^* \cup \{h_i^1, \dots, h_i^{r-1}\}) - v_i(h_i^1, \dots, h_i^{r-1})) \quad (21)$$

$$- (v_i(h_i^1, \dots, h_i^r) - v_i(h_i^1, \dots, h_i^{r-1}))$$

$$= v_i(\bar{\mathbf{x}}_{i,r}^* \mid h_i^1, \dots, h_i^{r-1}) - v_i(h_i^r \mid h_i^1, \dots, h_i^{r-1}). \quad (22)$$

Together with the submodularity of valuation, we obtain the same lower bound again:

$$v_i(\bar{\mathbf{x}}_{i,r+1}^* \mid h_i^1, \dots, h_i^r) = v_i(\bar{\mathbf{x}}_{i,r}^* \setminus \mathcal{L}_{i,r+1} \mid h_i^1, \dots, h_i^r) \quad (23)$$

$$\geq v_i(\bar{\mathbf{x}}_{i,r}^* \mid h_i^1, \dots, h_i^r) - v_i(\mathcal{L}_{i,r+1} \mid h_i^1, \dots, h_i^r) \quad (24)$$

$$\geq v_i(\bar{\mathbf{x}}_{i,r}^* \mid h_i^1, \dots, h_i^r) - v_i(\mathcal{L}_{i,r+1} \mid h_i^1, \dots, h_i^{r-1}) \quad (25)$$

$$\geq v_i(\bar{\mathbf{x}}_{i,r}^* \mid h_i^1, \dots, h_i^{r-1}) - v_i(h_i^r \mid h_i^1, \dots, h_i^{r-1}) \quad (26)$$

$$- v_i(\mathcal{L}_{i,r+1} \mid h_i^1, \dots, h_i^{r-1})$$

In both cases, we can replace $v_i(\bar{\mathbf{x}}_{i,r}^* \mid h_i^1, \dots, h_i^{r-1})$ by the induction hypothesis and $v_i(\mathcal{L}_{i,r+1} \mid h_i^1, \dots, h_i^{r-1})$ by $\ell_{i,r+1} \cdot v_i(h_i^r \mid h_i^1, \dots, h_i^{r-1})$ to prove the lemma. For a detailed calculation we refer to Garg, Kulkarni and Kulkarni [14, p. 14]. \square

The lemma can be used to find a lower bound on the marginal valuation of the items assigned in each round r .

Corollary 1. *From lemma 3 follows*

$$v_i(h_i^r \mid h_i^1, \dots, h_i^{r-1}) \geq \left(v_i(\bar{\mathbf{x}}_{i,1}^*) - \ell_{i,2} \cdot v_i(h_i^1) - \sum_{r'=2}^{r-1} \ell_{i,r'+1} \cdot v_i(h_i^{r'} \mid h_i^1, \dots, h_i^{r'-1}) \right. \\ \left. - v_i(h_i^1, \dots, h_i^{r-1}) \right) / \bar{\tau}_{i,r}^*.$$

Proof. Remember that valuation functions are monotonic if $v_i(\mathcal{S}_1) \leq v_i(\mathcal{S}_2)$ holds for all sets $\mathcal{S}_1 \subset \mathcal{S}_2 \subset \mathcal{G}$. Induction shows that there must be an item $j \in \mathcal{S}_2$ with valuation $v_i(j) \geq v_i(\mathcal{S}_2)/|\mathcal{S}_2|$, otherwise it would hold $v_i(\emptyset) > 0$. Applied to lemma 3, this means that there must be an item $j \in \bar{\mathbf{x}}_{i,r}^*$ with a marginal valuation of at least $v_i(\bar{\mathbf{x}}_{i,r}^* \mid h_i^1, \dots, h_i^{r-1})/\bar{\tau}_{i,r}^*$. As item h_i^r was the one to be assigned, its marginal valuation cannot be smaller. \square

This, finally, enables us to give a lower bound on the valuation of the bundles \mathbf{x}_i^{II} .

Lemma 4. For each agent $i \in \mathcal{A}$ and her bundle $\mathbf{x}_i^\Pi = \{h_i^1, \dots, h_i^{\tau_i^\Pi}\}$, it holds

$$v_i(h_i^1, \dots, h_i^{\tau_i^\Pi}) \geq v_i(\bar{\mathbf{x}}_{i,1}^*)/n.$$

Proof. In each round $r = 1, \dots, \tau_i^\Pi$, $\ell_{i,r}$ optimal and attainable items of agent i are assigned to other agents. As there are n agents in total, $n-1$ is an upper bound on $\ell_{i,r}$. Furthermore, after τ_i^Π rounds, the number $\bar{\tau}_{i,\tau_i^\Pi}^*$ of optimal and attainable items is at most $n-1 \leq n$ elsewise agent i would have been assigned yet another item. Together with corollary 1, this proves the lemma:

$$v_i(h_i^1, \dots, h_i^{\tau_i^\Pi}) = v_i(h_i^{\tau_i^\Pi} \mid h_i^1, \dots, h_i^{\tau_i^\Pi}) + v_i(h_i^1, \dots, h_i^{\tau_i^\Pi-1}) \quad (27)$$

$$\begin{aligned} &\geq \left(v_i(\bar{\mathbf{x}}_{i,1}^*) - \ell_{i,2} \cdot v_i(h_i^1) - \sum_{r'=2}^{\tau_i^\Pi-1} \ell_{i,r'+1} \cdot v_i(h_i^{r'} \mid h_i^1, \dots, h_i^{r'-1}) \right. \\ &\quad \left. - v_i(h_i^1, \dots, h_i^{\tau_i^\Pi-1}) \right) / \bar{\tau}_{i,r}^* + v_i(h_i^1, \dots, h_i^{\tau_i^\Pi-1}) \end{aligned} \quad (28)$$

$$\begin{aligned} &\geq \left(v_i(\bar{\mathbf{x}}_{i,1}^*) - (n-1)v_i(h_i^1) - \sum_{r'=2}^{\tau_i^\Pi-1} (n-1)v_i(h_i^{r'} \mid h_i^1, \dots, h_i^{r'-1}) \right. \\ &\quad \left. - v_i(h_i^1, \dots, h_i^{\tau_i^\Pi-1}) \right) / n + v_i(h_i^1, \dots, h_i^{\tau_i^\Pi-1}) \end{aligned} \quad (29)$$

$$\begin{aligned} &\geq (v_i(\bar{\mathbf{x}}_{i,1}^*) - (n-1)v_i(h_i^1, \dots, h_i^{\tau_i^\Pi-1}) - v_i(h_i^1, \dots, h_i^{\tau_i^\Pi-1})) / n \\ &\quad + v_i(h_i^1, \dots, h_i^{\tau_i^\Pi-1}) \end{aligned} \quad (30)$$

$$= v_i(\bar{\mathbf{x}}_{i,1}^*)/n \quad (31)$$

□

After having obtained a lower bound on the valuation of items assigned in phase II, we need a lower bound for phase III as well. Therefor we introduce a third type of item set.

Definition 5. Let $\mathbf{x}_i^* = \{g_i^1, \dots, h_i^{\tau_i^*}\}$ be an optimal bundle of some agent $i \in \mathcal{A}$. The set \mathcal{G}_i^+ of *overly good* items is defined as $\mathcal{G}_i^+ := \{j \in \mathcal{G} \mid v_i(j) \geq v_i(g_i^1)\}$.

Lemma 5. In phase III, there exists a matching such that each agent $i \in \mathcal{A}$ is matched to one of her overly good items in the set $\bigcup_{i' \in \mathcal{A}} \mathbf{x}_{i'}^I$ of released items.

Proof. If all items were matched in phase I, i.e., $\bigcup_{i' \in \mathcal{A}} \mathbf{x}_{i'}^I = \mathcal{G}$, then all optimal items are released in phase III and each agent can be matched to one; the lemma is proven immediately. If not, imagine for some t that only the items assigned in the first t rounds of phase I were released. Now choose some matching \mathcal{M}_t with the following properties:

1. If for an agent i all overly good items were amongst the released items, she gets matched with an overly good item $j \in \mathcal{G}_i^+$.
2. The number of agents matched with one of their overly good items is maximal amongst all matchings fulfilling property 1.

Property 1 is always satisfiable as the union of k many sets \mathcal{G}_i^+ contains k different items g_i^1 , which can be matched with agents i . Property 2 leads to all agents being matched with an overly good item for $t = \lceil \log_2 n \rceil + 1$, i.e. the number of rounds in phase I, whence the lemma follows. To prove this, we denote by \mathcal{A}_t^- the set of agents who are *not* matched with one of their overly good items, and show by induction on t that it holds $|\mathcal{A}_t^-| \leq n/2^t$.

In the base case $t = 1$, none of the items are assigned initially. Denote by α the number of agents who were not assigned an overly good item in the first round of phase I. If $\alpha \leq n/2$, then a matching \mathcal{M}_1 obviously exists and the base case is immediately proven. Otherwise,

all items from at least α many sets \mathcal{G}_i^+ got assigned to someone. Again: Each set \mathcal{G}_i^+ is the only one containing the item g_i^1 , so the union of these sets contains at least α items which can be matched with at least α agents upon release. This then leaves at most $n - \alpha < n/2$ agents not matched with an overly good item.

For the induction hypothesis, we assume that the statement holds true for all rounds up to some t . In the induction step $t \rightarrow t+1$, by property 1, there is at least one unassigned item in each set $\mathcal{G}_{i'}^+$ for all agents $i' \in \mathcal{A}_t^-$ at the start of round $t+1$. Analogously to the base case, for at least half of those agents i' these unassigned items will be assigned to them or someone else and it can be argued accordingly. By the induction hypothesis, it holds $|\mathcal{A}_{t+1}^-| \leq |\mathcal{A}_t^-|/2 \leq (n/2^t)/2 = n/2^{t+1}$. \square

This allows us to calculate an approximation factor for RepReMatch by comparing its output with an optimal allocation \mathbf{x}^* .

Theorem 2. *RepReMatch is $(2n(\log_2 n + 3))$ -approximative.*

Proof. By lemma 5, we can assign each agent i an overly good item $j_i^+ \in \mathcal{G}_i^+$ in the beginning of phase III. RepReMatch maximises the logarithmic Nash social welfare, so

$$\log \text{NSW}(\mathbf{x}^{\text{III}}) \geq \frac{1}{\sum_{i \in \mathcal{A}} \eta_i} \cdot \sum_{i \in \mathcal{A}} \eta_i \log v_i(j_i^+, h_i^1, \dots, h_i^{\tau_i^{\text{II}}}) \quad (32)$$

is a lower bound on the logarithmic NSW after the first matching in phase III, whereby $\mathbf{x}_i^{\text{II}} = \{h_i^1, \dots, h_i^{\tau_i^{\text{II}}}\}$ is the bundle of agent i from phase II.

Item j_i^+ was released in phase III, which means it was assigned in phase I, implying $j_i^+ \in \mathbf{x}_i^* \setminus \bar{\mathbf{x}}_{i,0}^*$ and, subsequently, $j_i^+ \in (\mathbf{x}_i^* \setminus \bar{\mathbf{x}}_{i,0}^*) \cup \mathcal{L}_{i,1}$. Phase I runs for at most $\lceil \log_2 n \rceil + 1$ rounds, and at most n items are assigned in each iteration. Therefore, at most $n(\log_2 n + 2)$ optimal items are assigned in that phase, i. e., $|\mathbf{x}_i^* \setminus \bar{\mathbf{x}}_{i,0}^*| \leq n(\log_2 n + 2)$. Furthermore, it holds $n \geq \ell_{i,1} = |\mathcal{L}_{i,1}|$ as in lemma 4. Together with the monotonicity of the valuation functions, this yields

$$v_i(j_i^+, h_i^1, \dots, h_i^{\tau_i^{\text{II}}}) \geq v_i(j_i^+) \geq \frac{v_i((\mathbf{x}_i^* \setminus \bar{\mathbf{x}}_{i,0}^*) \cup \mathcal{L}_{i,1})}{n(\log_2 n + 3)} \quad (33)$$

as lower bound on the valuations of bundles. Moreover, lemma 2 and the monotonicity of the valuation functions yield

$$v_i(j_i^+, h_i^1, \dots, h_i^{\tau_i^{\text{II}}}) \geq v_i(h_i^1, \dots, h_i^{\tau_i^{\text{II}}}) \geq \frac{v_i(\bar{\mathbf{x}}_{i,1}^*)}{n} \geq \frac{v_i(\bar{\mathbf{x}}_{i,1}^*)}{n(\log_2 n + 3)} = \frac{v_i(\bar{\mathbf{x}}_{i,0}^* \setminus \mathcal{L}_{i,1})}{n(\log_2 n + 3)} \quad (34)$$

as yet another lower bound. The mean of eqs. (33) to (34) and the monotonicity of the valuation functions give the concise lower bound

$$v_i(j_i^+, h_i^1, \dots, h_i^{\tau_i^{\text{II}}}) \geq \frac{1}{2} \left(\frac{v_i((\mathbf{x}_i^* \setminus \bar{\mathbf{x}}_{i,0}^*) \cup \mathcal{L}_{i,1})}{n(\log_2 n + 3)} + \frac{v_i(\bar{\mathbf{x}}_{i,0}^* \setminus \mathcal{L}_{i,1})}{n(\log_2 n + 3)} \right) \quad (35)$$

$$\geq \frac{1}{2} \cdot \frac{v_i(((\mathbf{x}_i^* \setminus \bar{\mathbf{x}}_{i,0}^*) \cup \mathcal{L}_{i,1}) \cup (\bar{\mathbf{x}}_{i,0}^* \setminus \mathcal{L}_{i,1}))}{n(\log_2 n + 3)} \quad (36)$$

$$= \frac{v_i(\mathbf{x}_i^*)}{2n(\log_2 n + 3)}. \quad (37)$$

We can insert this lower bound into eq. (32) and prove the theorem thereby:

$$\log \text{NSW}(\mathbf{x}^{\text{III}}) \geq \frac{1}{\sum_{i \in \mathcal{A}} \eta_i} \cdot \sum_{i \in \mathcal{A}} \eta_i \log \left(\frac{v_i(\mathbf{x}_i^*)}{2n(\log_2 n + 3)} \right) = \log \left(\frac{\text{NSW}(\mathbf{x}^*)}{2n(\log_2 n + 3)} \right) \quad (38)$$

\square

i: Error in paper? see also lemma 5

overly good -> outstanding?

4 Hardness of Approximation

Garg, Kulkarni and Kulkarni [14, Section 4] provide the following hardness result.

Theorem 3. *The submodular NSW is not approximable within a factor of $\frac{e}{e-1}$ in polynomial time unless $\mathcal{P} = \mathcal{NP}$, even when the agents have equal weights and valuation functions.*

i: Should it not be $\frac{e}{e-1} - \epsilon$?

Proof. Consider the related USW problem¹.

Problem 2. Given a set \mathcal{G} of indivisible items and a set \mathcal{A} of agents with monotonic, submodular valuation functions $v_i: \mathcal{P}(\mathcal{G}) \rightarrow \mathbb{R}$ for all agents $i \in \mathcal{A}$, the *symmetric submodular utilitarian social welfare problem* is to find an allocation \mathbf{x}^* maximising the sum of valuations, that is,

$$\mathbf{x}^* \stackrel{!}{=} \arg \max_{\mathbf{x} \in \mathbf{X}_{\mathcal{A}}(\mathcal{G})} \{\text{USW}(\mathbf{x})\} \quad \text{with } \text{USW}(\mathbf{x}) := \sum_{i \in \mathcal{A}} v_i(\mathbf{x}_i)$$

where $\mathbf{X}_{\mathcal{A}}(\mathcal{G})$ is the set of all possible allocations of the items in \mathcal{G} amongst n agents.

Note that this problem is identical to the symmetric submodular NSW except for the sum in the target function instead of a product. We will exploit this fact to calculate the NSW of instances for USW. Khot et al. [18] supply a polynomial-time reduction of USW from the following problem:

Problem 3. Given a graph $G = (V, E)$ and a constant $c \leq 1$, the *c-Gap-Max-3-Colouring problem* is to decide whether, for any 3-colouring of graph G which maximises the number of edges with different coloured endpoints, the number of such edges is $|E|$ (*Yes instance*) or $c|E|$ and below (*No instance*).

Proposition 1. *There exists a constant $c \leq 1$ such that the c-Gap-Max-3-Colouring problem is \mathcal{NP} -hard.*

Reducing an instance of the c-Gap-Max-3-Colouring problem yields an instance of the symmetric submodular USW problem with identical valuation functions. Its properties are as follows:

Yes instance The USW is nC because every agent values her bundle at n , whereby C is a constant depending on the input graph. The NSW of the instance would be C .

No instance The USW is $\frac{e-1}{e}nC$. Applying the inequality of arithmetic and geometric means, i.e., $(x_1 + \dots + x_n)/n \geq \sqrt[n]{x_1 \dots x_n}$ for all nonnegative numbers $x_1, \dots, x_n \in \mathbb{R}_0^+$, reveals that the NSW of the instance is at most $\frac{e-1}{e}C$.

Thereout follows that the submodular NSW problem, even when symmetric and with identical valuation functions, cannot be approximated within a factor better than $\frac{e}{e-1}$; otherwise one could decide the c-Gap-Max-3-Colouring problem in polynomial time by checking whether the corresponding NSW instance has a value above $\frac{e-1}{e}C$. \square

For a constant number of agents, Garg, Kulkarni and Kulkarni [14, Section 5.1] describe a family $(A_\epsilon)_{\epsilon > 0}$ of algorithms for the asymmetric submodular NSW problem where each algorithm A_ϵ achieves an approximation factor of $\frac{e}{e-1} + \epsilon$.

¹Garg, Kulkarni and Kulkarni (and many others) call problem 2 the ‘Allocation problem’. We changed the name to match the naming scheme of the NSW problem and to avoid confusion, as both problems are about finding allocations.

5 Conclusion and Outlook

In this seminar report, we presented two algorithms for the asymmetric Nash social welfare problem (NSW), based on a paper by Garg, Kulkarni and Kulkarni [14]. The asymmetric NSW asks to find an allocation of unsharable and indivisible items amongst agents such that the weighted geometric mean of their valuations is maximised. The novelty lies in both algorithms having an approximation factor dependant on the number n of agents but not on the number m of items.

The first algorithm, SMatch, finds a $2n$ -approximative allocation if the valuation functions are additive. It does so by repeatedly matching agents with items within a weighted bipartite graph. For the very first matching, the edge weights incorporate an estimation of the valuation of future items.

The second algorithm, RepReMatch, finds a $\frac{1}{2n(\log_2 n + 3)}$ -approximative allocation if the valuation functions are submodular. In phase I, a set of high-value items is determined through repeated matchings and then put away. In phase II, agents are repeatedly matched with the remaining items. In phase III, the high-value items are finally assigned to the agents.

Lastly, it was shown that any polynomial-time algorithm for the submodular NSW must have an approximation factor of at least $\frac{e}{e-1}$ unless $\mathcal{P} = \mathcal{NP}$. This holds even when the problem is symmetric and the valuation functions equal.

The research on the NSW gained pace in the last years. Since the publication of the paper of Garg, Kulkarni and Kulkarni at the start of 2020, quite a few new papers advancing the topic have been published.

- Rado valuations are a special class of submodular functions and stem from a generalisation of OXS valuations. Garg, Kulkarni and Kulkarni emphatically mentioned the lack of research into the OXS NSW. Garg, Husic and Vegh [13] developed an algorithm for the Rado NSW, which is independent from both the number of items and the number of agents. For the symmetric Rado NSW, their algorithm achieves an approximation factor of $256e^{3/e} \approx 772$. For the asymmetric Rado NSW, the approximation factor is $256\gamma^3$ with $\gamma := \max_{i \in \mathcal{A}} \{\eta_i\} / \min_{i \in \mathcal{A}} \{\eta_i\}$. Interestingly, the algorithm is 16γ -approximative in case of the asymmetric additive NSW, so it outperforms SMatch in many instances. Remarkably enough, the algorithm is divided into five phases, and the first phase serves to determine a set of high-value items.
- Li and Vondrák [19] introduced a randomised, 380-approximative algorithm for the symmetric submodular NSW. Later, Garg et al. [15] devised a family of deterministic algorithms any $\epsilon > 0$. They are $(4 + \epsilon)$ -approximative in the symmetric case and $e(n \cdot \max_{i \in \mathcal{A}} \{\eta_i\} + 2 + \epsilon)$ -approximative in the asymmetric one.
- XOS functions are a superclass of submodular functions, for which the approximation factor of RepReMatch is not independent of the number of items anymore. Barman et al. [4] used both RepReMatch and the discrete moving-knife method to get an $\mathcal{O}(n^{53/54})$ -approximative algorithm for the symmetric XOS NSW. However, the algorithm uses demand and XOS queries, whereas RepReMatch needs only the weaker value queries.
- CASC (also known as SPLC) functions are a superclass of additive functions, which can model diminishing returns. Chaudhury et al. [7] came up with an $e^{1/e}$ -approximative algorithm for the symmetric CASC NSW. For SMatch, only an approximation factor of $2n$ for the symmetric CASC NSW could be shown by Garg, Kulkarni and Kulkarni, although they suspect a better one.

Besides efficiency, fairness is also a property towards which algorithm can be designed. Especially RepReMatch with no fairness guarantees is unsatisfactory in that regard. Re-

search is made complex because of the myriad of notions of fairness. A selection of new developments:

- Garg et al. guarantee $1/2$ -EFX and an approximation factor of $8 + \epsilon$.
[24] improved efficiency
- The algorithm of Chaudhury et al. computes an allocation which is $1/2$ -EF1 and approximately Pareto optimal.

- conclusion of [20]
- cf. [20]: do not only approximate efficiency but also fairness
 - [15]: ‘Prior work on EFX and related notions The existence of EFX allocations has not been settled despite significant efforts [14,17,43,44]. This problem is open for more than two agents with general monotone valuations (including submodular), and for more than three agents with additive valuations. This necessitated the study of its relaxations α -EFX for $\alpha \in (0, 1)$ and partial EFX allocations. For the notion of α -EFX, the best-known α is 0.618 for additive [1] and 0.5 for general monotone valuations (including submodular) [43]. For the notion of partial EFX allocations, the existence is known for general monotone valuations if we do not allocate at most $n - 2$ items [9, 19, 40], albeit without any efficiency guarantees. For additive valuations, although $n - 2$ is still the best bound known, there exist partial EFX allocations with 2-approximation to the NSW problem [13].

A well-studied weaker notion is envy-freeness up to one item (EF1), where no agent envies another agent after the removal of some item from the envied agent’s bundle. EF1 allocations are known to exist for general monotone valuations and can also be computed in polynomial-time [39]. However, an EF1 allocation alone is not desirable because it might be highly inefficient in terms of any welfare objective. For additive valuations, the allocations maximizing NSW are EF1 [14]. Although the NSW problem is APX-hard [36], there exists a pseudopolynomial time algorithm to find an allocation that is EF1 and 1.45-approximation to the NSW problem under additive valuations [8]. For capped-SPLC valuations, [16] shows the existence of an allocation that is $1/2$ -EF1 and 1.45-approximation to the NSW problem. The existence of an EF1 allocation with high NSW is open for submodular valuations. Subsequent to our work, [24] improves Theorem 1.2 to show the existence of an allocation T that is $1/2$ -EFX and $\text{NSW}(T) \geq 2/3 \text{NSW}(S)$ for a given allocation S .

- [16]: Best of Both Worlds = combining randomisation and relaxation; asym add NSW; extendable to more general NSW like asym XOS NSW though ; eg. weighted proportional up to one good (WPROP1) $:= v_i(\mathbf{x}_i \cup \{j\}) \geq \eta_i v_i(\mathcal{G})$, weighted envy-free $:= \eta_j v_i(\mathbf{x}_i) \geq \eta_i v_i(\mathbf{x}_j)$; invoke the image of agents eating their goods proportional speed to weights

many notions of fairness actually exist

- gap between hardness of add NSW and SMatch
- is approx factor for sym add NSW equally bad?
- RepReMatch does not extend to XOS or subadditive
- <https://www.semanticscholar.org/reader/bef4514574543720bc45ea235df4c4556e97efe0>

- [7]: ‘There is a considerable gap in the lower bound (1.069) on the approximation factor that is hard to achieve (see Garg et al.(2019)) and the approximation factor of 1.445, even for the additive valuations. It will be interesting to close this gap.’

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