Seminar Approximation Algorithms

ANSWuSVþ(U)M

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Abstract

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Todo list

or rather 'allocated'?
less strict def of valuations; restriction for our case later on
agents without items assigned have valuation zero \rightarrow prevent
definition of approximation factor [def environment or in-text?]
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What is the factor?
what exactly did SF11 show?
something about this identifier ought to be done (also in algo)
u_i^*
decide on x or x^{III} ; discrepancies in orig paper in def of x^{III} !

1 Introduction

- problem introduction, motivation, applications
- formal problem definition (incl. why geometric mean?)
- short literature review: What is known, what not? New findings?
- content & structure of paper

Definition 1. Let $\mathcal{G} := \{1, \dots, m\}$ be a set of indivisible *items* and $\mathcal{A} := \{1, \dots, n\}$ be a set of *agents*. An *allocation* is a tuple $\boldsymbol{x} = (\boldsymbol{x}_1, \dots, \boldsymbol{x}_n) \in \mathcal{P}(G)^n$ of *bundles* \boldsymbol{x}_i such that each item is element of exactly one bundle, that is $\bigcup_{i \in \mathcal{A}} \boldsymbol{x}_i = \mathcal{G}$ and $\boldsymbol{x}_i \cap \boldsymbol{x}_{i'} = \emptyset$ for all $i \neq i'$. An item $j \in \mathcal{G}$ is *assigned* to agent $i \in \mathcal{A}$ if $j \in \boldsymbol{x}_i$ holds.

:

Definition 2. Given a set \mathcal{G} of items and a set \mathcal{A} of agents with valuations $v_i \colon \mathcal{P}(\mathcal{G}) \to \mathbb{R}$ and agent weights η_i for all agents $i \in \mathcal{A}$, the Nash Social Welfare problem (NSW) is to find an allocation maximising the weighted geometric mean of valuations, that is

$$\underset{\boldsymbol{x} \in \Pi_n(\mathcal{G})}{\operatorname{arg\,max}} \bigg\{ \bigg(\prod_{i \in \mathcal{A}} v_i(\boldsymbol{x}_i)^{\eta_i} \bigg)^{1/\sum_{i \in \mathcal{A}} \eta_i} \bigg\}$$

where $\Pi_n(\mathcal{G})$ is the set of all possible allocations of the items in \mathcal{G} amongst n agents. The problem is called *symmetric* if all agent weights η_i are equal, and *asymmetric* otherwise.

agents without items assigned have valuation zero \rightarrow prevent

:

In a slight abuse of notation, we omit curly braces delimiting a set in the arguments of a valuation function, so for example we write $v(j_1, j_2, ...)$ to denote $v(\{j_1, j_2, ...\})$.

definition of approximation factor [def environment or in-text?]

:

Garg, Kulkarni and Kulkarni [1] consider five different types of non-negative monotonically non-decreasing valuation functions of which we are going to consider only the following two due to space constraints:

Additive The valuation $v_i(\mathcal{S})$ of an agent i for a set $\mathcal{S} \subset \mathcal{G}$ of items j is the sum of individual valuations $v_i(j)$, that is $v_i(\mathcal{S}) = \sum_{j \in \mathcal{S}} v_i(j)$.

Submodular Let $v_i(\mathcal{S} \mid \mathcal{S}) \coloneqq v_i(\mathcal{S} \cup \mathcal{S}) - v_i(\mathcal{S})$ denote the marginal utility of agent i for a set $\mathcal{S} \subset \mathcal{G}$ of items over the disjoint set $\mathcal{S} \subset \mathcal{G}$. This valuation functions satisfies the submodularity constraint $v_i(j \mid \mathcal{S} \cup \mathcal{S}) \le v_i(j \mid \mathcal{S})$ for all agents $i \in \mathcal{A}$, items $j \in \mathcal{G}$ and sets $\mathcal{S}, \mathcal{S} \subset \mathcal{G}$ of items.

We use additive NSW and submodular NSW as shorthands for the Nash social welfare problems with additive and submodular valuation functions, respectively.

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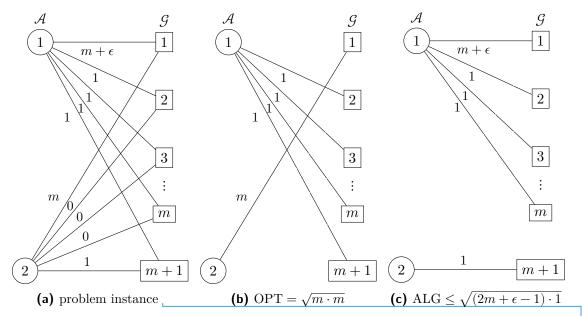


Figure 1: Agent 1 values item 1 at $m+\epsilon$ and all other items at 1. Agent 2 values item 1 at m, item m+1 at 1 and all other items at 0. In an optimal allocation, item 1 would be assigned to agent 2 and all other items to agent 1, resulting in a NSW of $\sqrt{m \cdot m} = m$. A repeated maximum matching algorithm would greedily assign item 1 to agent 1 and item m+1 to agent 2 in the first round. Even if all remaining items were going to be assigned to agent 1, the NSW will never surpass $\sqrt{(2m+\epsilon-1)\cdot 1} < \sqrt{2m}$. The approximation factor $\alpha \approx \sqrt{m/2}$ therefore depends on the number of items.

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2 SMatch

In the case of an equal number of agents and items, i. e. $|\mathcal{A}| = n = m = |\mathcal{G}|$, the additive NSW can be solved exactly by finding a maximum matching on a bipartite graph with the sets of agents and of items as its parts; as weight of the edge between agent i and item j, use $\eta_i \log v_i(j)$, that is the weighted valuation of item j by agent i in the logarithmic Nash social welfare. Should there be more items than agents, then it would be obvious to just repeatedly find a maximum matching and assign the items accordingly until all items are assigned. The flaw of this idea is that such a greedy algorithm only considers the valuations of items in the current matching and perhaps the valuations of items already assigned. As the example in fig. 1 demonstrates, this leads to an algorithm with an approximation factor dependent on the number m of items. The geometric mean of the NSW favours allocations with similarly valued bundles, wherefore it may be beneficial for an agent to leave items to other agents if those agents cannot expect many more valuable items in the future.

What is the factor?

The algorithm SMatch, described in algorithm 1, eliminates the flaw by first gaining foresight of the valuations of items assigned after the first matching, achieving an approximation factor of 2n (cf. theorem 1 later on). For a fixed agent i, order the items in descending order of the valuations by agent i and denote the j-th most liked item by \mathcal{G}_i^j . To obtain a well-defined order, items of equal rank are further ordered numerically. SMatch, too, does repeatedly match items. During the first matching, however, the edge weights are defined as $\eta_i \log(v_i(j) + u_i/n)$ for an edge between agent i and item j. The addend u_i serves as estimation of the valuation of items assigned after the first matching

Algorithm 1: SMatch for the Asymmetric Additive NSW problem

```
Input: set \mathcal{A} = \{1, ..., n\} of agents with weights \eta_i \forall i \in \mathcal{A}, set \mathcal{G} = \{1, ..., m\} of
                         indivisible items, additive valuations v_i \colon \mathcal{P}(\mathcal{G}) \to \mathbb{R}_0^+ where v_i(\mathcal{S}) is the
                         valuation of agent i \in \mathcal{A} for each set \mathcal{S} \subset \mathcal{G} of items
      Output: \frac{1}{2n}-approximation \boldsymbol{x}=(\boldsymbol{x}_1,\ldots,\boldsymbol{x}_n) of an optimal allocation
  1 \boldsymbol{x}_i \leftarrow \emptyset \quad \forall i \in \mathcal{A}
 \mathbf{2} \ u_i \leftarrow v_i(\mathcal{G}_i^{2n+1}, \dots, \mathcal{G}_i^{\,m}) \quad \forall i \in \mathcal{A}
                                                                                                             \triangleright est. valuations after the 1st matching
  3 \mathcal{W} \leftarrow \{ \eta_i \cdot \log(v_i(j) + u_i/n) \mid i \in \mathcal{A}, j \in \mathcal{G} \}
                                                                                                                                                                        \triangleright edge weights
  4 G \leftarrow (\mathcal{A}, \mathcal{G}, \mathcal{W})
                                                                                                                                                                   ⊳ bipartite graph
  5 \mathcal{M} \leftarrow \max_{\text{weight}} \text{matching}(G)
  6 \boldsymbol{x}_i \leftarrow \{j \mid (i,j) \in \mathcal{M}\} \quad \forall i \in \mathcal{A}
                                                                                                                                 ⊳ assign according to matching
  7 \mathcal{G}^{\text{rem}} \leftarrow \mathcal{G} \setminus \{ j \mid (i, j) \in \mathcal{M} \}
                                                                                                                                                \triangleright remove assigned items
  8 while \mathcal{G}^{\text{rem}} \neq \emptyset do
              \mathcal{W} \leftarrow \{ \stackrel{\cdot}{\eta_i} \cdot \log(v_i(j) + v_i(\boldsymbol{x}_i)) \mid i \in \mathcal{A}, j \in \mathcal{G}^{\text{rem}} \, \}
              G \leftarrow (\mathcal{A}, \mathcal{G}^{\text{rem}}, \mathcal{W})
10
               \mathcal{M} \leftarrow \max_{\text{weight}} \text{matching}(G)
               \begin{aligned} \boldsymbol{x}_i \leftarrow \boldsymbol{x}_i \cup \{\, j \mid (i,j) \in \mathcal{M} \,\} & \quad \forall i \in \mathcal{A} \\ \mathcal{G}^{\text{rem}} \leftarrow \mathcal{G}^{\text{rem}} \setminus \{\, j \mid (i,j) \in \mathcal{M} \,\} \end{aligned} 
14 end while
15 return x
```

and is defined as

$$u_i \coloneqq \min_{\substack{\mathcal{S} \subset \mathcal{G} \\ |\mathcal{S}| \leq 2n}} \{v_i(\mathcal{G} \setminus \mathcal{S})\} = v_i(\mathcal{G}_i^{2n+1}, \dots, \mathcal{G}_i^m). \tag{1}$$

The set \mathcal{S} has less than 2n elements only if there are less than 2n items in total. From the second matching onwards, the edge weights are defined as $\eta_i \log(v_i(j) + v_i(\boldsymbol{x}_i))$, where \boldsymbol{x}_i is the continuously updated set of items assigned to agent i in previous matchings. The addend $v_i(\boldsymbol{x}_i)$ could lead to better allocations in applications, but does not improve the approximation factor asymptotically.

For convenience, we order the items in the final bundle $\mathbf{x}_i = \{h_i^1, \dots, h_i^{\tau_i}\}$ of agent i by the order in which they were assigned, so that item h_i^t is assigned according to the t-th matching. To calculate the approximation factor of SMatch, we first need to establish a lower bound on the valuation of single items.

Lemma 1. For each agent $i \in \mathcal{A}$ and her final bundle $\mathbf{x}_i = \{h_i^1, \dots, h_i^{\tau_i}\}$, the item h_i^t is worth at least as much as the overall tn-th most highly valued item \mathcal{G}_i^{tn} , i. e. $v_i(h_i^t) \geq v_i(\mathcal{G}_i^{tn})$, for all $t = 1, \dots, \tau_i$.

Proof. At the start of the t-th iteration, no more than (t-1)n items out of the tn most highly valued items $\mathcal{G}_i^1,\dots,\mathcal{G}_i^{tn}$ have been assigned in previous iterations since at most n items are assigned in each iteration. During the t-th iteration, at most n-1 more of those highly valued items could be assigned to all other agents $i'\neq i$, leaving at least one item in $\mathcal{G}_i^1,\dots,\mathcal{G}_i^{tn}$ unassigned. Since $v_i(\mathcal{G}_i^k)\geq v_i(\mathcal{G}_i^{tn})$ for all $k\leq tn$ by definition of \mathcal{G}_i^n , the lemma follows.

We can now establish $u_i/n = v_i(\mathcal{G}_i^{2n+1}, \dots, \mathcal{G}_i^m)/n$ as lower bound on the valuations of items assigned after the first matching.

Lemma 2. For each agent $i \in \mathcal{A}$ and her final bundle $\mathbf{x}_i = \{h_i^1, \dots, h_i^{\tau_i}\}$, it holds $v_i(h_i^2, \dots, h_i^{\tau_i}) \geq u_i/n$, where n is the number of items and $u_i = v_i(\mathcal{G}_i^{2n+1}, \dots, \mathcal{G}_i^m)$.

Proof. By lemma 1 and definition of \mathcal{G}_i , every item h_i^t is worth at least as much as each item \mathcal{G}_i^{tn+k} with $k \in \{0,\dots,n-1\}$ and, consequently, its valuation $v_i(h_i^t)$ is at least as high as the mean valuation $\frac{1}{n}v_i(\mathcal{G}_i^{tn},\dots,\mathcal{G}_i^{tn+n-1})$. Further, it holds $\tau_i n+n \geq m$ since each agent receives items for at least $\lfloor \frac{m}{n} \rfloor \geq \frac{m}{n}-1$ rounds. Together, this yields

$$v_i(h_i^2, \dots, h_i^{\tau_i}) = \sum_{t=2}^{\tau_i} v_i(h_i^t) \ge \sum_{t=2}^{\tau_i} \frac{1}{n} v_i(\mathcal{G}_i^{tn}, \dots, \mathcal{G}_i^{tn+n-1}) \tag{2}$$

$$\geq \frac{1}{n}v_i(\mathcal{G}_i^{\,2n},\ldots,\mathcal{G}_i^{\,m-1}) \geq \frac{1}{n}v_i(\mathcal{G}_i^{\,2n+1},\ldots,\mathcal{G}_i^{\,m}) = \frac{u_i}{n} \tag{3}$$

with the last inequality stemming from $v_i(\mathcal{G}_i^{2n}) \geq v_i(\mathcal{G}_i^m)$.

Remark 1. In lemma 2, we assumed non-zero valuations for all items, hence the bundle lengths of $\tau_i \geq \lfloor \frac{m}{n} \rfloor$. Of course in an actual program, one would not assign items to agents who value these with zero. Nevertheless, lemma 2 still holds as additional zeros in the sum of eq. (3) do not change it.

This allows us to calculate an approximation factor for SMatch by comparing its output with an optimal allocation x^* .

Theorem 1. SMatch has an approximation factor of 2n.

Proof. Lemma 2 can be plugged into the logarithmic NSW:

$$\log \text{NSW}(\boldsymbol{x}) = \frac{1}{\sum_{i=1}^{n} \eta_i} \cdot \sum_{i=1}^{n} \eta_i \log v_i(h_i^1, \dots, h_i^{\tau_i}) \tag{4}$$

$$= \frac{1}{\sum_{i=1}^{n} \eta_{i}} \cdot \sum_{i=1}^{n} \eta_{i} \log (v_{i}(h_{i}^{1}) + v_{i}(h_{i}^{2}, \dots, h_{i}^{\tau_{i}}))$$
 (5)

$$\geq \frac{1}{\sum_{i=1}^{n} \eta_i} \cdot \sum_{i=1}^{n} \eta_i \log(v_i(h_i^1) + u_i/n)$$
 (6)

Notice that the first matching of SMatch maximises the sum in eq. (6). Thus, assigning all agents i their respective most highly valued item g_i^1 in an optimal bundle $\boldsymbol{x}_i^* = \{g_i^1, \dots, g_i^{\tau_i^*}\}$ yields the even lower bound

$$\log \text{NSW}(\boldsymbol{x}) \ge \frac{1}{\sum_{i=1}^{n} \eta_i} \cdot \sum_{i=1}^{n} \eta_i \log(v_i(g_i^1) + u_i/n). \tag{7}$$

Recall the definition of u_i from eq. (1). Consider a slightly modified variant:

$$u_i = \min_{\substack{\mathcal{S} \subset \mathcal{G} \\ |\mathcal{S}| \leq 2n}} \{v_i(\mathcal{G} \smallsetminus \mathcal{S})\} \quad \text{or, alternatively,} \quad u_i = v_i(\mathcal{G} \smallsetminus \mathcal{S}) \text{ with } \mathcal{S} \coloneqq \underset{\substack{\mathcal{S} \subset \mathcal{G} \\ |\mathcal{S}| \leq 2n}}{\arg\min} \{v_i(\mathcal{G} \smallsetminus \mathcal{S})\} \ \ (8)$$

Moreover, consider the set \mathcal{S}^* of the (at most) 2n most highly valued items in the optimal bundle \boldsymbol{x}_i^* , i. e.

$$\mathcal{S}^* := \underset{\substack{\mathcal{S} \subset \mathcal{G} \\ |\mathcal{S}| \leq 2n}}{\min} \{ v_i(\boldsymbol{x}_i^* \setminus \mathcal{S}) \}. \tag{9}$$

We get the lower bound $v_i(g_i^1) \geq \frac{1}{2n}v_i(\mathcal{S}^*)$ from a similar argument as in the proof of lemma 2. Further, it holds $u_i = v_i(\mathcal{G} \setminus \mathcal{S}) \geq v_i(\boldsymbol{x}_i^* \setminus \mathcal{S}) \geq v_i(\boldsymbol{x}_i^* \setminus \mathcal{S}^*)$. We can substitute these two inequalities into eq. (7) and prove the theorem thereby:

$$\log \text{NSW}(\boldsymbol{x}) \ge \frac{1}{\sum_{i=1}^{n} \eta_i} \cdot \sum_{i=1}^{n} \eta_i \log \left(\frac{v_i(\mathcal{S}^*)}{2n} + \frac{v_i(\boldsymbol{x}_i^* \setminus \mathcal{S}^*)}{n} \right)$$
(10)

$$\geq \frac{1}{\sum_{i=1}^{n} \eta_i} \cdot \sum_{i=1}^{n} \eta_i \log \left(\frac{v_i(\boldsymbol{x}_i^*)}{2n} \right) = \log \left(\frac{\text{OPT}}{2n} \right)$$
 (11)

3 RepReMatch

• SMatch does not work for general submodular valuations since we need to detect the set of lowest valuation. This is not possible independent of m [SF11].

Lemma 3. During phase II, each agent $i \in \mathcal{A}$ gets assigned a set $\boldsymbol{x}_i^{\mathrm{II}} = \{h_i^1, \dots, h_i^{\tau_i^{\mathrm{II}}}\}$ of items. For all iterations $t = 1, \dots, \tau_i^{\mathrm{II}} - 1$, the following inequality about her set $\bar{\boldsymbol{x}}_{i,t}^*$ of optimal and attainable items holds true:

what exactly did SF11 show?

$$v_i(\bar{\boldsymbol{x}}_{i,t+1}^* \mid h_i^1, \dots, h_i^t) \geq u_i^* - \ell_{i,2} v_i(h_i^1) - \sum_{t'=2}^t \ell_{i,t'+1} v_i(h_i^{t'} \mid h_i^1, \dots, h_i^{t'-1}) - v_i(h_i^1, \dots, h_i^t),$$

where $\ell_{i,t}$ is the size of the set $\mathcal{L}_{i,t} \subset \bar{x}_{i,t-1}^*$ of optimal items that were attainable in iteration t-1 and assigned to other agents in iteration t.

Corollary 1. From lemma 3 follows

$$\begin{aligned} v_i(h_i^{t+1} \mid h_i^1, \dots, h_i^t) & \geq \frac{1}{\tau_i^* - \sum_{t'=1}^{t+1} \ell_{i,t'}} \Big(u_i^* - \ell_{i,2} v_i(h_i^1) - \sum_{t'=2}^t \ell_{i,t'+1} v_i(h_i^{t'} \mid h_i^1, \dots, h_i^{t'-1}) \\ & - v_i(h_i^1, \dots, h_i^t) \Big) \end{aligned}$$

about this
identifier
ought to be
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Lemma 4.

$$v_i(h_i^1,\dots,h_i^{\tau_i^{\mathrm{II}}}) \ge u_i^*/n$$

Lemma 5. about phase I

Theorem 2. RepReMatch has an approximation factor of $2n(\log n + 2)$.

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```
Algorithm 2: RepReMatch for the Asymmetric Submodular NSW problem
        Input: set \mathcal{A} = \{1, ..., n\} of agents with weights \eta_i \forall i \in \mathcal{A}, set \mathcal{G} = \{1, ..., m\} of
                             indivisible items, additive valuations v_i \colon \mathcal{P}(\mathcal{G}) \to \mathbb{R}_0^+ where v_i(\mathcal{S}) is the
                             valuation of agent i \in \mathcal{A} for each set \mathcal{S} \subset \mathcal{G} of items
       Output: \frac{1}{2n(\log n+2)}-approximation \boldsymbol{x}^{\mathrm{III}}=(\boldsymbol{x}_1^{\mathrm{III}},\ldots,\boldsymbol{x}_n^{\mathrm{III}}) of an optimal allocation
        Phase I:
  1 \boldsymbol{x}_i^{\mathrm{I}} \leftarrow \emptyset \quad \forall i \in \mathcal{A}
  \mathbf{2} \mathcal{G}^{\text{rem}} \leftarrow \mathcal{G}
  3 for t \leftarrow 0, ..., \lceil \log n \rceil - 1 do
                if \mathcal{G}^{\mathrm{rem}} \neq \emptyset then
                          \mathcal{W} \leftarrow \{ \, \eta_i \cdot \log(v_i(j)) \mid i \in \mathcal{A}, j \in \mathcal{G} \, \}
  \mathbf{5}
                          G \leftarrow (\mathcal{A}, \mathcal{G}, \mathcal{W})
   6
                          \mathcal{M} \leftarrow \max_{\text{weight}} \text{matching}(G)
   7
                          \begin{aligned} \boldsymbol{x}_{i}^{\mathrm{I}} \leftarrow \boldsymbol{x}_{i}^{\mathrm{I}} \cup \{j\} & \forall (i,j) \in \mathcal{M} \\ \mathcal{G}^{\mathrm{rem}} \leftarrow \mathcal{G}^{\mathrm{rem}} \setminus \{j \mid (i,j) \in \mathcal{M} \} \end{aligned}
   8
                end if
10
11 end for
        Phase II:
12 x_i^{\text{II}} \leftarrow \emptyset \quad \forall i \in \mathcal{A}
                                                                                                            \triangleright put allocation \boldsymbol{x}_i^{\mathrm{I}} aside and start a new one
13 while \mathcal{G}^{\text{rem}} \neq \emptyset do
                 \mathcal{W} \leftarrow \{\, \eta_i \cdot \log(v_i(\boldsymbol{x}_i^{\mathrm{II}} \cup \{j\})) \mid i \in \mathcal{A}, j \in \mathcal{G} \,\}
                 G \leftarrow (\mathcal{A}, \mathcal{G}, \mathcal{W})
15
                 \mathcal{M} \leftarrow \max_{\text{weight}} \text{matching}(G)
                 \begin{aligned} \boldsymbol{x}_i^{\text{II}} \leftarrow \boldsymbol{x}_i^{\text{II}} \cup \left\{ j \right\} & \forall (i,j) \in \mathcal{M} \\ \mathcal{G}^{\text{rem}} \leftarrow \mathcal{G}^{\text{rem}} \setminus \left\{ \left. j \mid (i,j) \in \mathcal{M} \right. \right\} \end{aligned} 
19 end while
        Phase III:
20 \mathcal{G}^{\mathrm{rem}} \leftarrow \bigcup_{i \in \mathcal{A}} oldsymbol{x}_i^{\mathrm{I}}
                                                                                                                                         \triangleright release items assigned in phase I
21 \mathcal{W} \leftarrow \{ \eta_i \cdot \log(v_i(\boldsymbol{x}_i^{\mathrm{II}} \cup \{j\})) \mid i \in \mathcal{A}, j \in \mathcal{G} \}
22 G \leftarrow (\mathcal{A}, \mathcal{G}, \mathcal{W})
23 \mathcal{M} \leftarrow \max_{\text{weight}} \text{matching}(G)
24 \boldsymbol{x}_i^{\mathrm{III}} \leftarrow \boldsymbol{x}_i^{\mathrm{II}} \cup \{j\} \forall (i,j) \in \mathcal{M}
25 \mathcal{G}^{\text{rem}} \leftarrow \mathcal{G}^{\text{rem}} \setminus \{j \mid (i,j) \in \mathcal{M}\}\
26 \boldsymbol{x}_i^{\text{III}} \leftarrow \text{arbitrary\_allocation}(\mathcal{A}, \mathcal{G}^{\text{rem}}, \boldsymbol{x}_i^{\text{III}}, (v_i)_{i \in \mathcal{A}})
28 return x^{\rm III}
```

decide on x or x^{III} ; discrepancies in orig paper in def of x^{III} !