

Seminar Approximation Algorithms

Approximating Nash Social Welfare under Submodular Valuations through (Un)Matchings

Based on a paper of the same name by Garg, Kulkarni and Kulkarni

Zeno Adrian Weil

Supervised by Dr Giovanna Varricchio

8th July 2023 · Algorithms and Complexity (Prof. Dr Martin Hoefer)

What is the issue?

We need to distribute goods amongst recipients *fast*, *efficient* and *fairly*.

Where is this encountered?

- industrial procurement
- mobile edge computing
- satellites
- water withdrawal

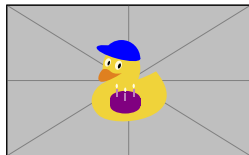
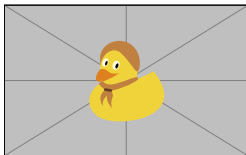
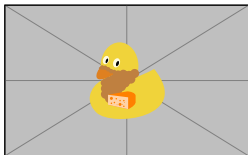
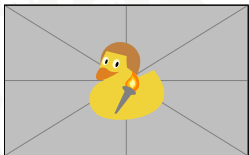


Table of Contents

1 Preliminaries

- Allocations
- Valuation Functions
- Maximum Nash Social Welfare Problem

2 RepReMatch

- Naïve Approach
- The Algorithm
- Analysing Phase II

1

Preliminaries



Setting:

- goods: set \mathcal{G} of m items
 - unsharable
 - indivisible
- recipients: set \mathcal{A} of n agents

Definition

An *allocation* is a tuple $\mathbf{x} = (\mathbf{x}_i)_{i \in \mathcal{A}}$ of bundles $\mathbf{x}_i \subset \mathcal{G}$ such that each item is element of precisely one bundle.

Item j is *assigned* to agent i if $j \in \mathbf{x}_i$.

But how to measure its efficiency and fairness?

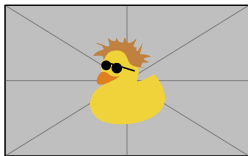
Valuation Functions

Requirements:

- monotonically non-decreasing: $v_i(\mathcal{S}_1) \leq v_i(\mathcal{S}_2) \quad \forall \mathcal{S}_1 \subset \mathcal{S}_2 \subset \mathcal{G}$
- normalised: $v_i(\emptyset) = 0$
- non-negative: $v_i(\mathcal{S}) \geq 0 \quad \forall \mathcal{S} \subset \mathcal{G}$

Types:

- additive: $v_i(\mathcal{S}) := \sum_{j \in \mathcal{S}} v_i(\{j\}) \quad \forall \mathcal{S} \subset \mathcal{G}$
- submodular: $v_i(\mathcal{S}_1 \mid \mathcal{S}_2) := v_i(\mathcal{S}_1 \cup \mathcal{S}_2) - v_i(\mathcal{S}_2) \quad \forall \mathcal{S}_1, \mathcal{S}_2 \subset \mathcal{G} \text{ with } \mathcal{S}_1, \mathcal{S}_2 \text{ disjoint}$
 - more general (encompasses additivity)
 - diminishing returns



Asymmetric Maximum Nash Social Welfare Problem

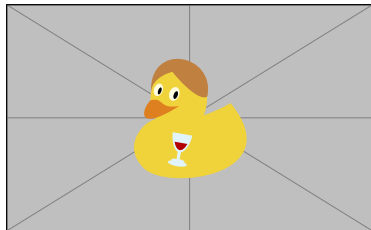
Definition

$$x^* \stackrel{!}{=} \arg \max_{x \in X_{\mathcal{A}}(\mathcal{G})} \{\text{NSW}(x)\} \quad \text{with } \text{NSW}(x) := \left(\prod_{i \in \mathcal{A}} v_i(x_i)^{\eta_i} \right)^{1 / \sum_{i \in \mathcal{A}} \eta_i}$$

- $X_{\mathcal{A}}(\mathcal{G})$: all possible allocations
- η_i : agent weight
- middle ground between efficiency and fairness

Challenge

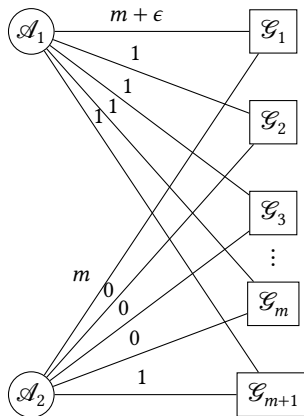
Algorithm with approximation factor *independent from m!*



2

RepReMatch

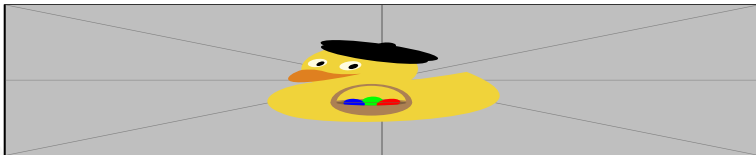




What are the low-value items?

Looking into the Future

- sort items by valuation in descending order
 - low-value items on the left



- use their valuations for edge weights in early matchings

A $2n$ -approximation is possible ... using SMatch.

This only works for additive valuation functions.

Changing the Past

Under submodular valuation, the set of lowest valuation is approximable only by $\Omega(\sqrt{m/\ln m})$.

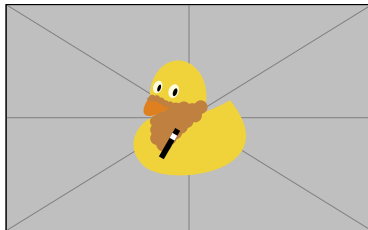


We can change the past in three phases:

Phase I Assign enough high-value items temporarily.

Phase II Assign the remaining items definitely.

Phase III Re-assign the items of phase I definitely.



A $2n(\log_2 n + 3)$ -approximation is possible!

The Algorithm

Phase I

- 1** repeat $\lceil \log_2 n \rceil + 1$ times or until $\mathcal{G} = \emptyset$
 - 1** create bipartite graph $G = (\mathcal{A}, \mathcal{G}, E)$ with edge weights $w(i, j) = \eta_i \log v_i(\{j\})$
 - 2** compute maximum weight matching \mathcal{M}
 - 3** update bundles \mathbf{x}_i^I according to matching \mathcal{M} & remove assigned items

Phase II

- 2** repeat until $\mathcal{G} = \emptyset$
 - 1** create bipartite graph $G = (\mathcal{A}, \mathcal{G}, E)$ with edge weights $w(i, j) = \eta_i \log(v_i(\mathbf{x}_i^I \cup \{j\}))$
 - 2** compute maximum weight matching \mathcal{M}
 - 3** update bundles \mathbf{x}_i^I according to matching \mathcal{M} & remove assigned items

Phase III

- 3** create bipartite graph $G = (\mathcal{A}, \bigcup_{i \in \mathcal{A}} \mathbf{x}_i^I, E)$ with edge weights $w(i, j) = \eta_i \log(v_i(\mathbf{x}_i^I \cup \{j\}))$
- 4** compute maximum weight matching \mathcal{M}
- 5** create bundles \mathbf{x}_i^I according to matching \mathcal{M} and previous bundles \mathbf{x}_i^I

Analysing Phase II (1/3)

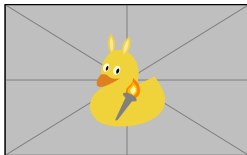
Definition

The set $\mathcal{L}_{i,r}$ of *lost items* is the set of all items $j \in \mathbf{x}_i^*$ assigned to other agents $i' \neq i$ in round r .

Definition

The set of *optimal and attainable items* is defined as

$$\bar{\mathbf{x}}_{i,r}^* := \begin{cases} \mathbf{x}_i^* \setminus \bigcup_{i' \in \mathcal{A}} \mathbf{x}_{i'}^I & \text{in round } r = 0, \\ \bar{\mathbf{x}}_{i,0}^* \setminus \mathcal{L}_{i,1} & \text{in round } r = 1, \\ \bar{\mathbf{x}}_{i,r-1}^* \setminus (\mathcal{L}_{i,r} \cup \{a_i^{r-1}\}) & \text{in round } r = 2, \dots, \tau_i^{\text{II}}. \end{cases}$$



Analysing Phase II (2/3)

Lemma

For each agent $i \in \mathcal{A}$ and her bundle $\mathbf{x}_i^\Pi = \{a_i^1, \dots, a_i^{\tau_i^\Pi}\}$ at the end of phase II, it holds in all rounds $r = 2, \dots, \tau_i^\Pi$ that

$$v_i(\bar{\mathbf{x}}_{i,r}^* \mid a_i^1, \dots, a_i^{r-1}) \geq v_i(\bar{\mathbf{x}}_{i,1}^*) - \sum_{r'=1}^{r-1} \ell_{i,r'+1} \cdot v_i(a_i^{r'} \mid a_i^1, \dots, a_i^{r'-1}) - v_i(a_i^1, \dots, a_i^{r-1}).$$