

# Optimizations

## - Compilation for Embedded Processors -

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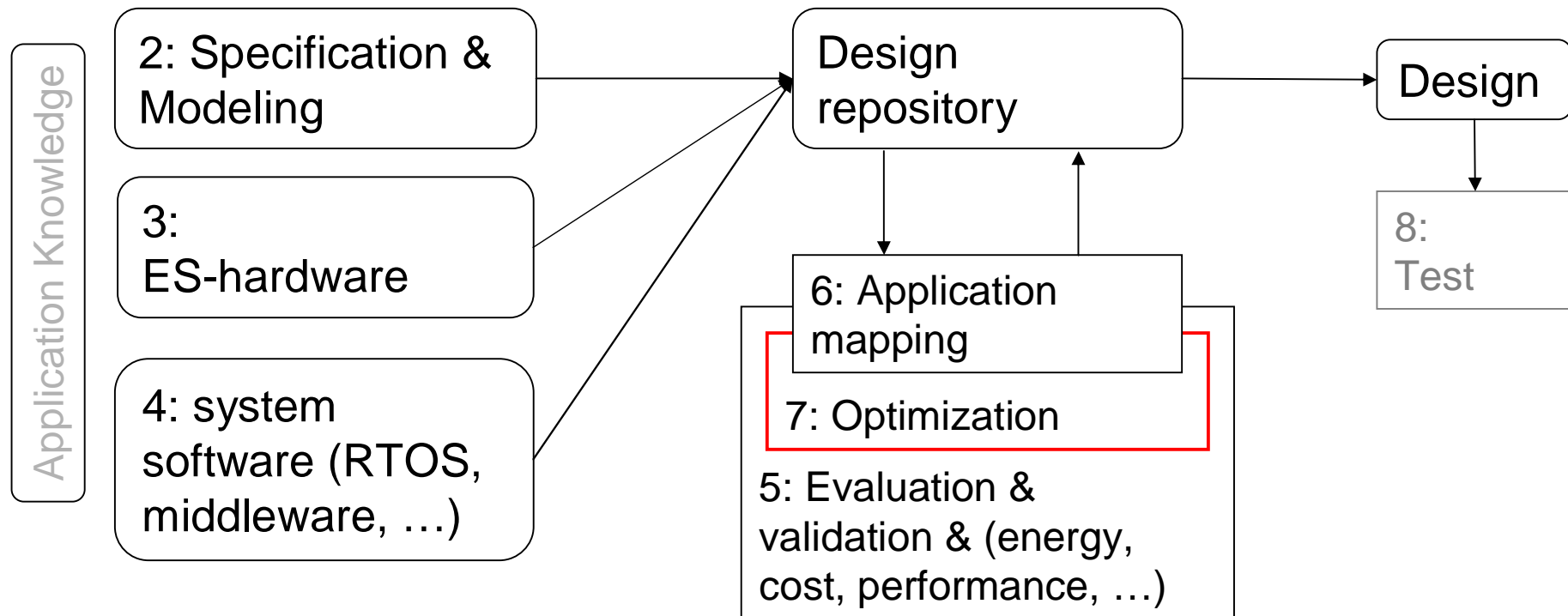


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# Structure of this course



Numbers denote sequence of chapters

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# Task-level concurrency management

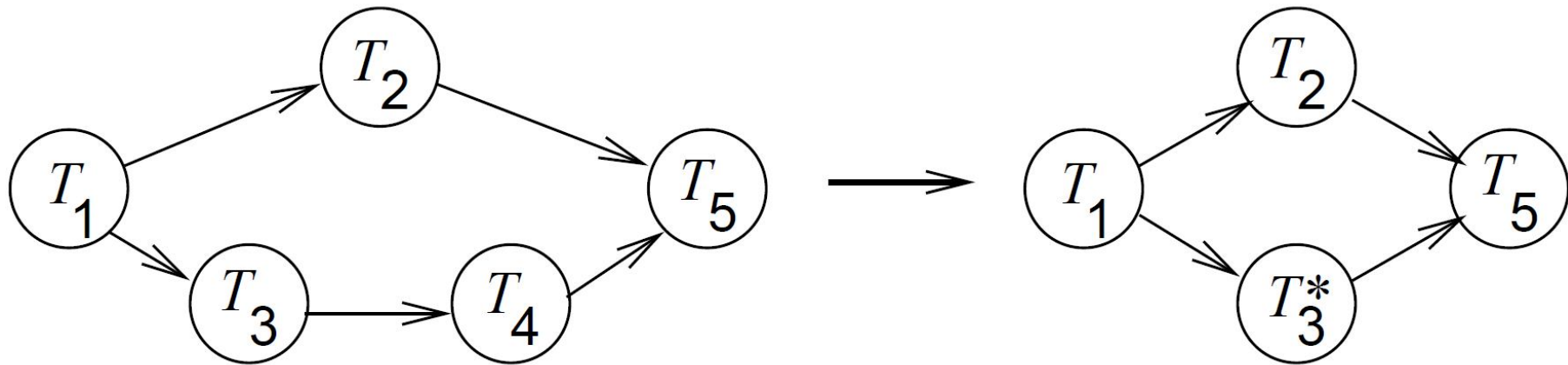
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*Granularity*: size of tasks (e.g. in instructions)

Readable specifications and efficient implementations can possibly require different task structures.

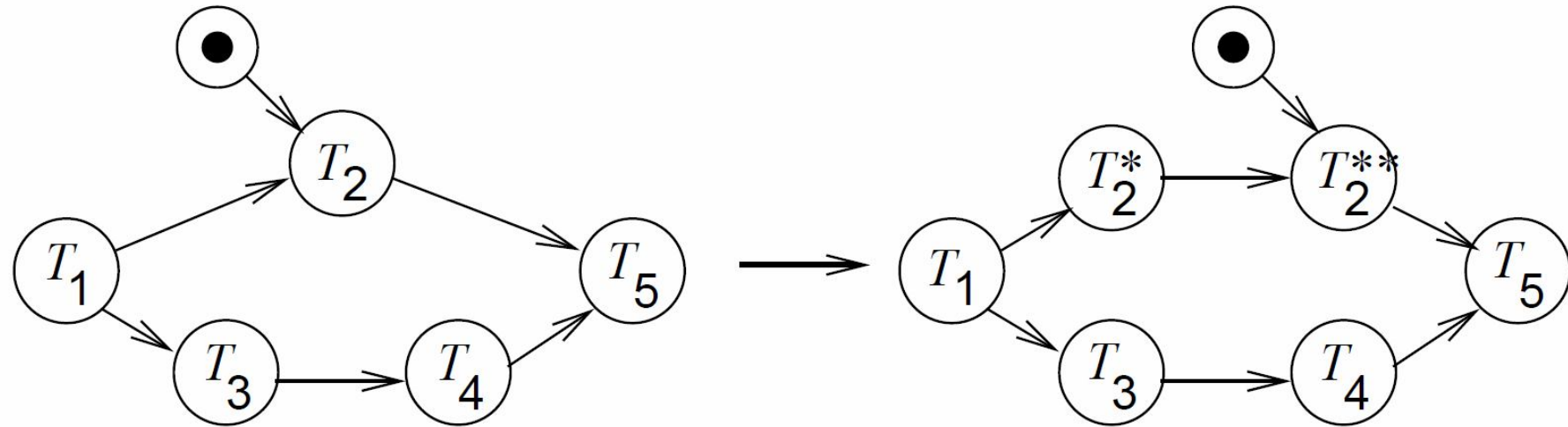
☞ Granularity changes

# Merging of tasks



Reduced overhead of context switches,  
More global optimization of machine code,  
Reduced overhead for inter-process/task communication.

# Splitting of tasks



No blocking of resources while waiting for input,  
more flexibility for scheduling, possibly improved result.

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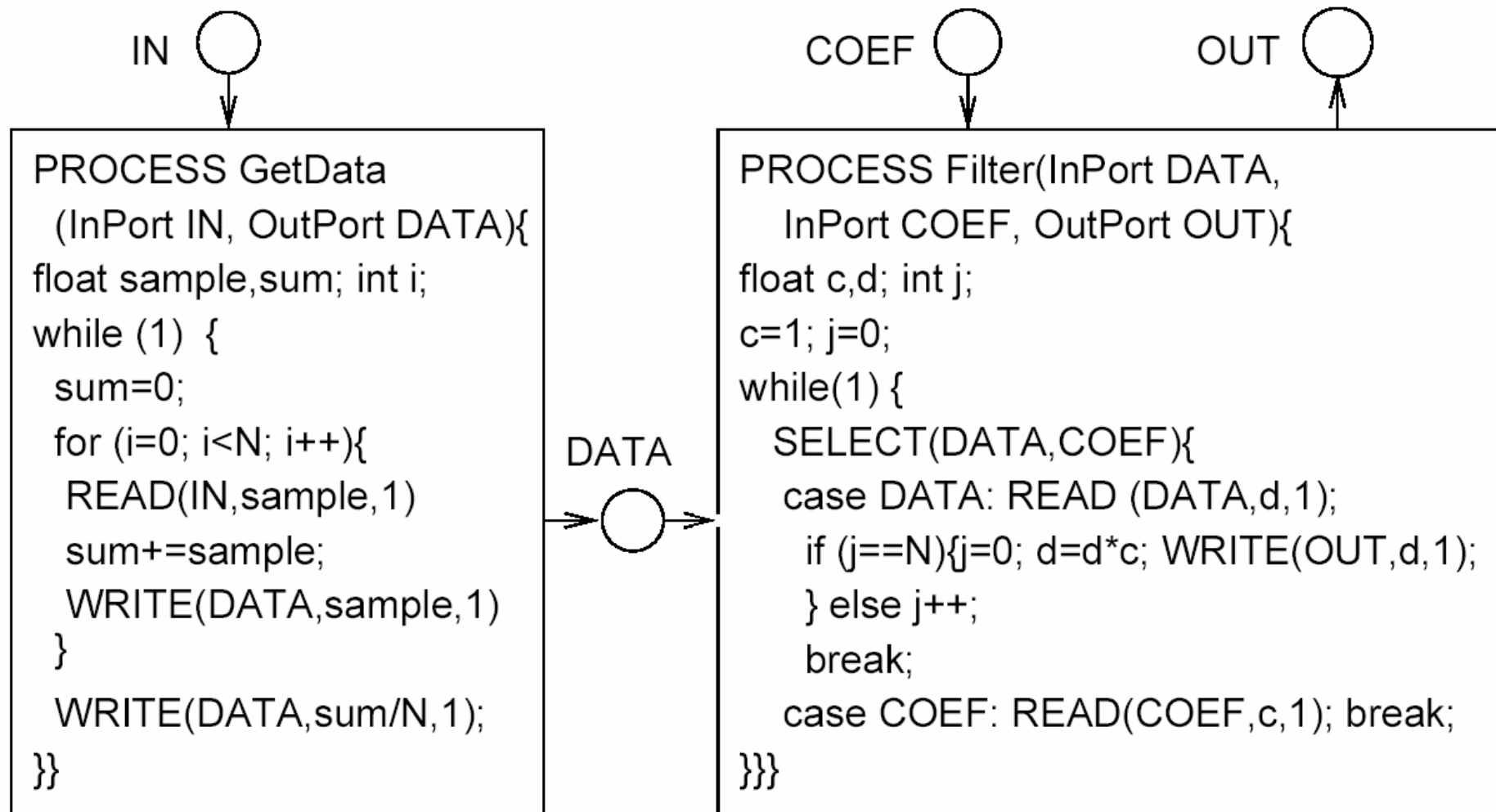
# Merging and splitting of tasks

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The most appropriate task graph granularity depends upon the context ➡ merging and splitting may be required.

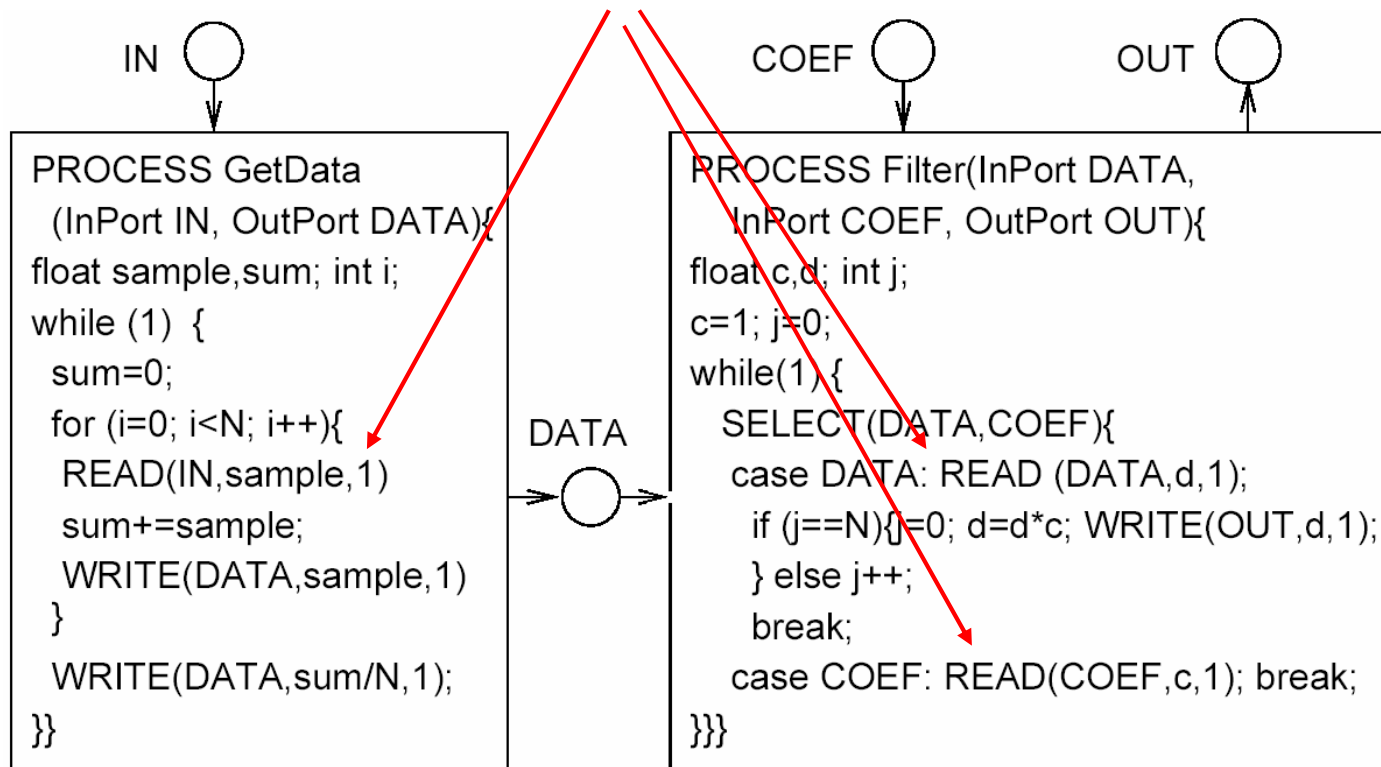
Merging and splitting of tasks should be done automatically, depending upon the context.

# Automated rewriting of the task system - Example -



# Attributes of a system that needs rewriting

Tasks blocking after they have already started running





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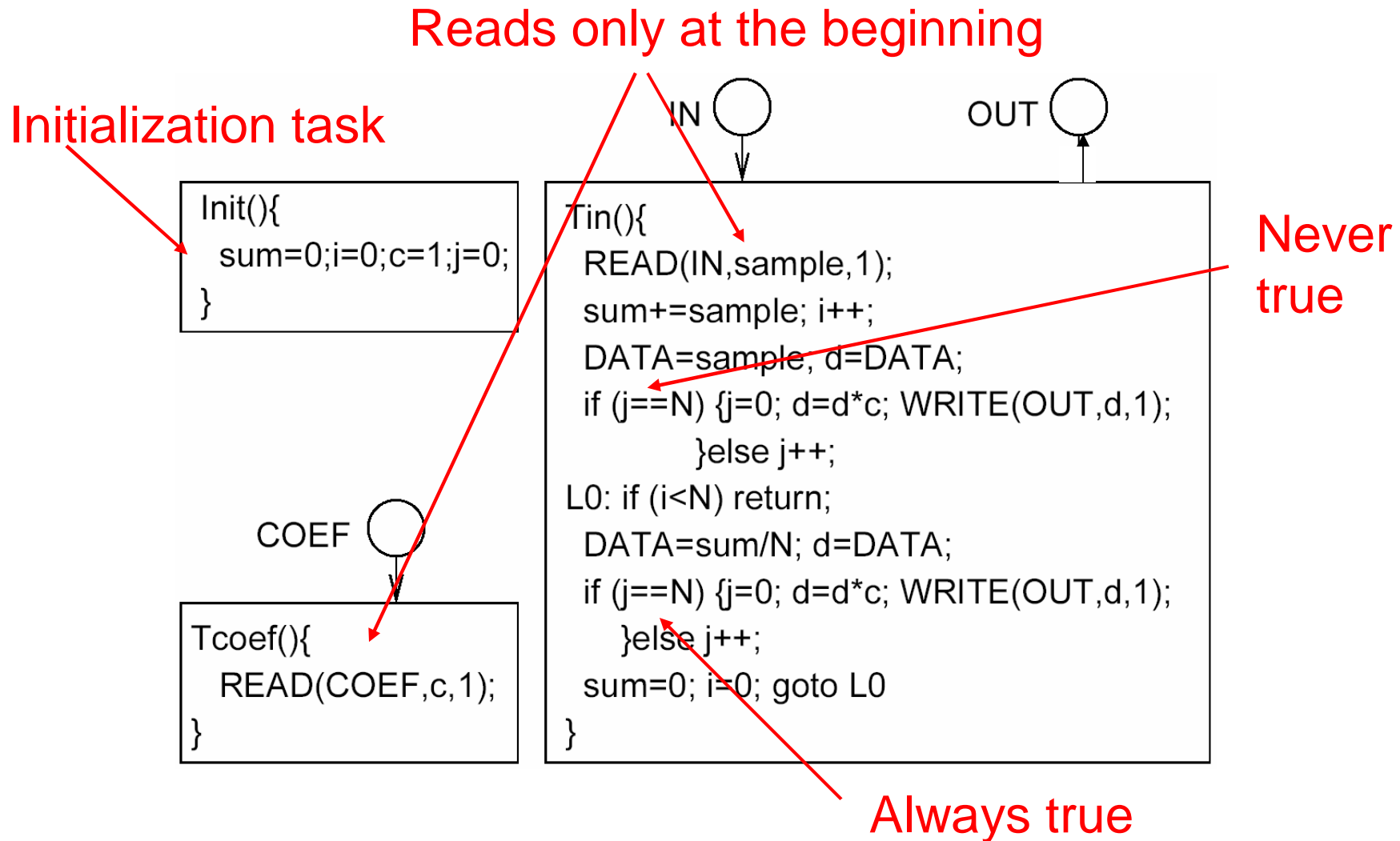
# Work by Cortadella et al.

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1. Transform each of the tasks into a Petri net,
2. Generate one global Petri net from the nets of the tasks,
3. Partition global net into “sequences of transitions”
4. Generate one task from each such sequence

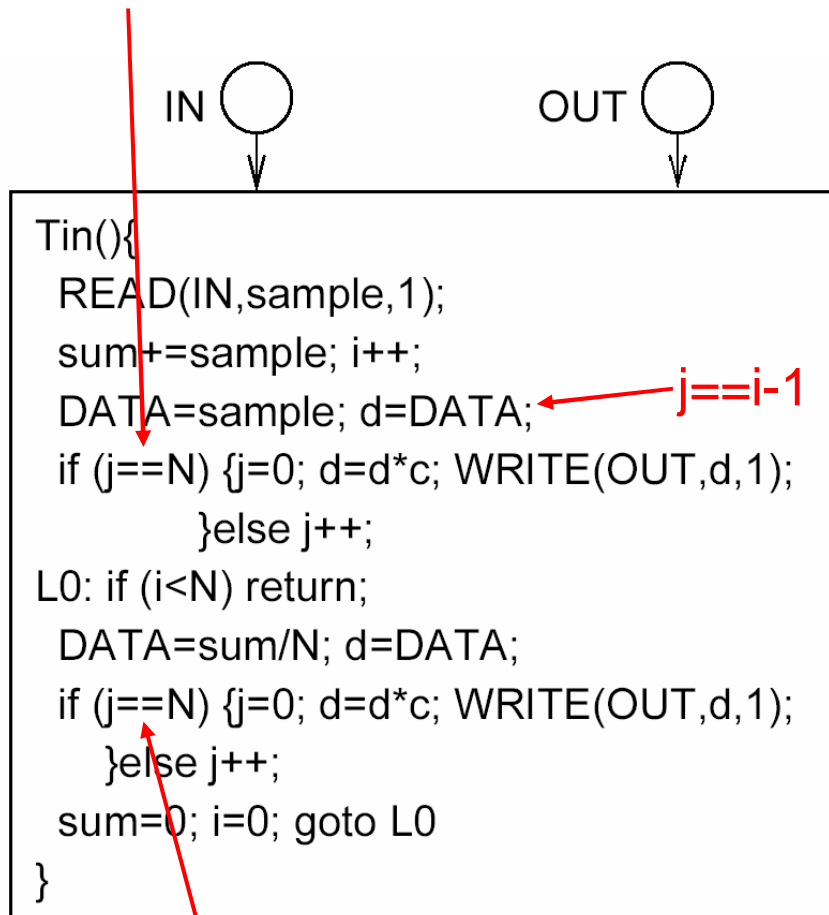
Mature, commercial approach not yet available

# Result, as published by Cortadella

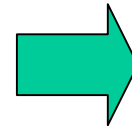


# Optimized version of Tin

Never true



j == i



```
Tin () {  
  READ (IN, sample, 1);  
  sum += sample; i++;  
  DATA = sample; d = DATA;  
L0: if (i < N) return;  
  DATA = sum/N; d = DATA;  
  d = d*c; WRITE(OUT,d,1);  
  sum = 0; i = 0;  
  return;  
}
```

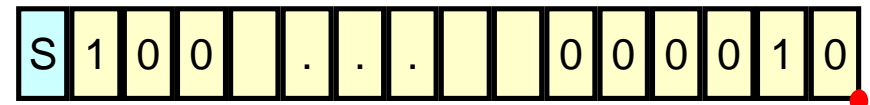
Always true

# Fixed-Point Data Format

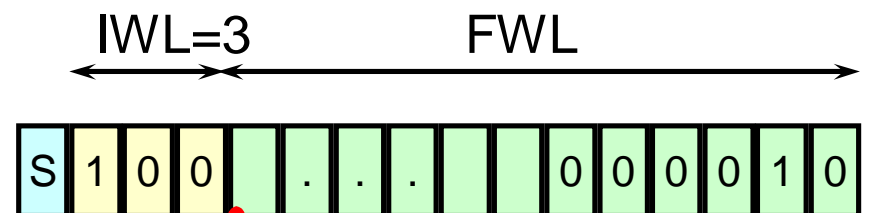
## • Floating-Point vs. Fixed-Point

- *exponent*, mantissa
- Floating-Point
  - automatic computation and update of each exponent at run-time
- Fixed-Point
  - implicit exponent
  - determined off-line

## • Integer vs. Fixed-Point



(a) Integer



hypothetical binary point

(b) Fixed-Point

© Ki-Il Kum, et al

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# Floating-point to fixed point conversion

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## Pros:

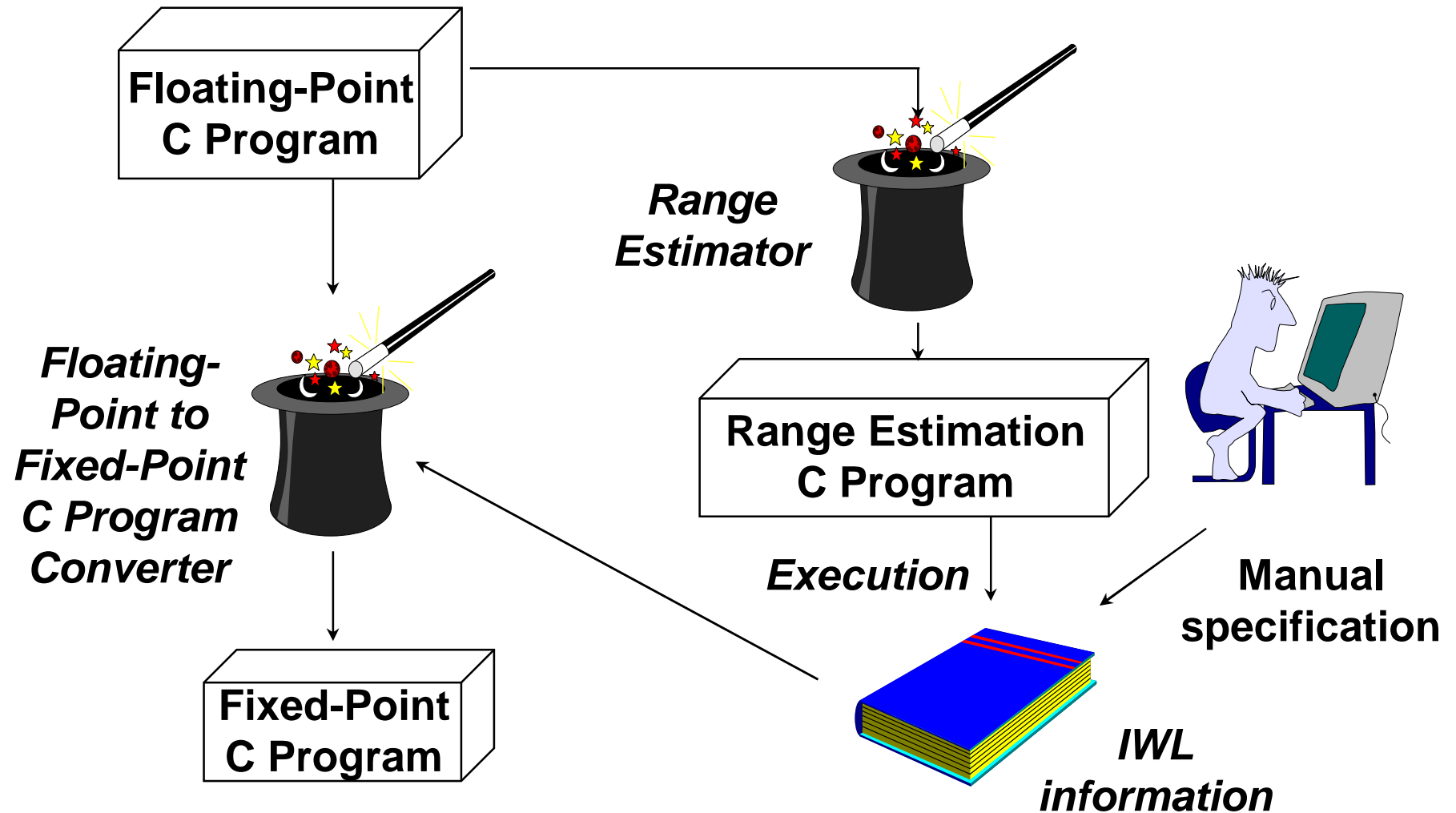
- Lower cost
- Faster
- Lower power consumption
- Sufficient SQNR, *if properly scaled*
- Suitable for portable applications

## Cons:

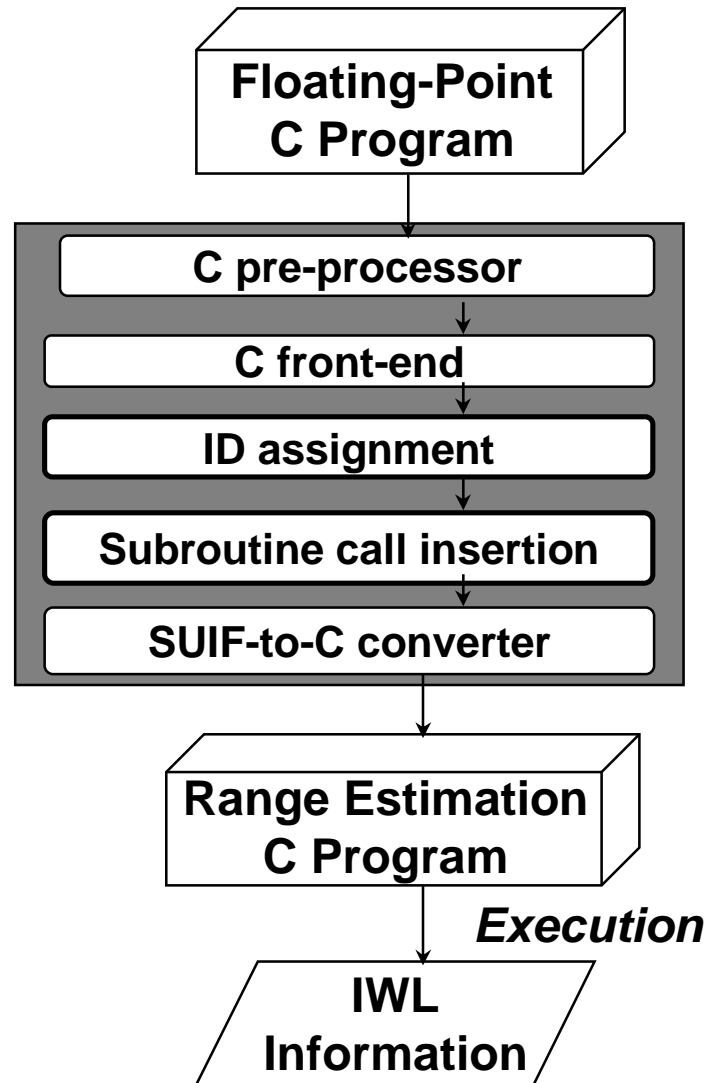
- Decreased dynamic range
- Finite word-length effect, *unless properly scaled*
  - Overflow and excessive quantization noise
- Extra programming effort

© Ki-Il Kum, et al. (Seoul National University): A Floating-point To Fixed-point C Converter For Fixed-point Digital Signal Processors, 2nd SUIF Workshop, 1996

# Development Procedure



# Range Estimator



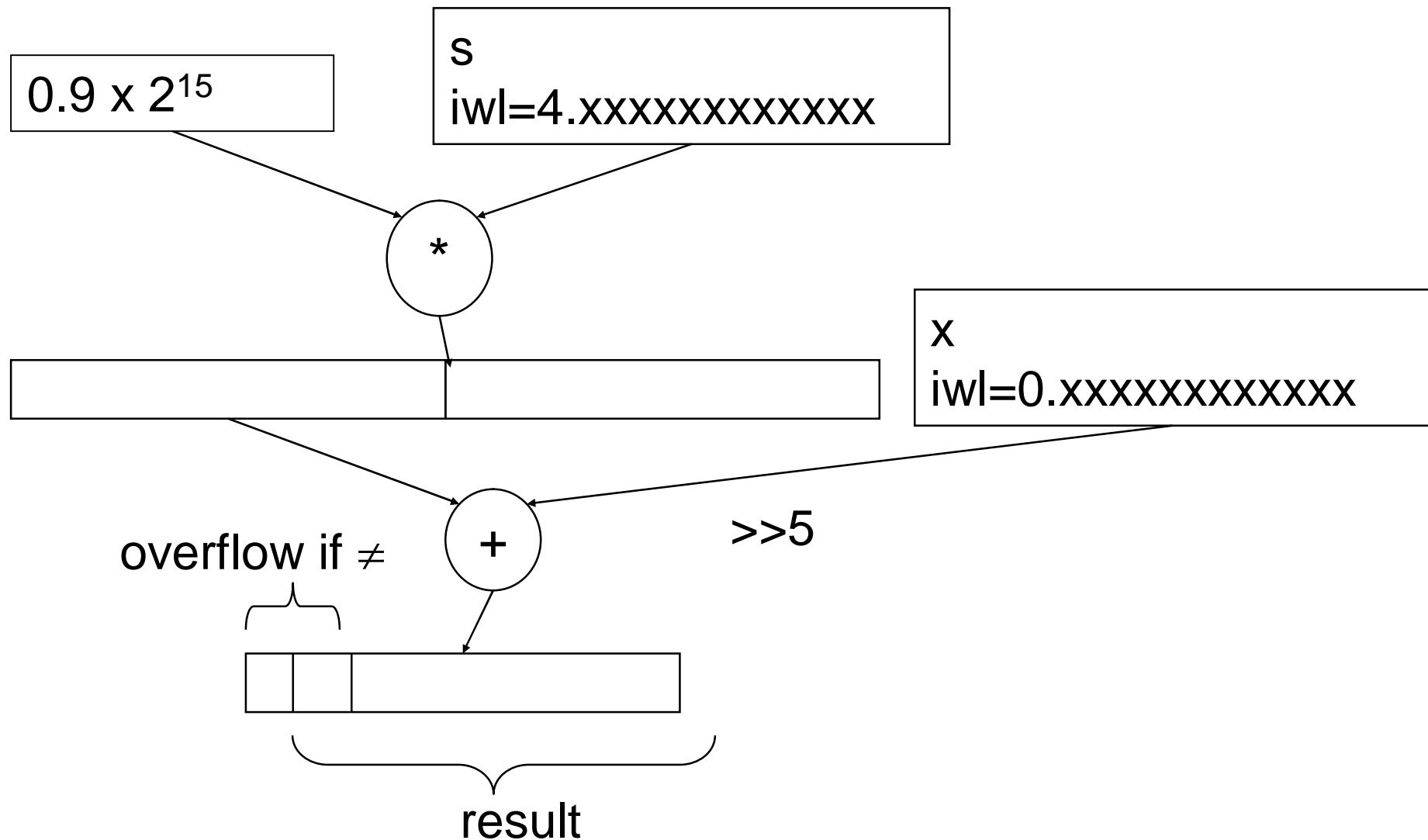
## Range Estimation C Program

```
float iir1(float x)
{
    static float s = 0;
    float y;

    y = 0.9 * s + x;
    range(y, 0);
    s = y;
    range(s, 1);

    return y;
}
```

# Operations in fixed point program





# Floating-Point to Fixed-Point Program Converter

## Fixed-Point C Program

```
int iir1(int x)
{
    static int s = 0;
    int y;
    y=sll(mulh(29491,s)+ (x>> 5), 1);
    s = y;
    return y;
}
```

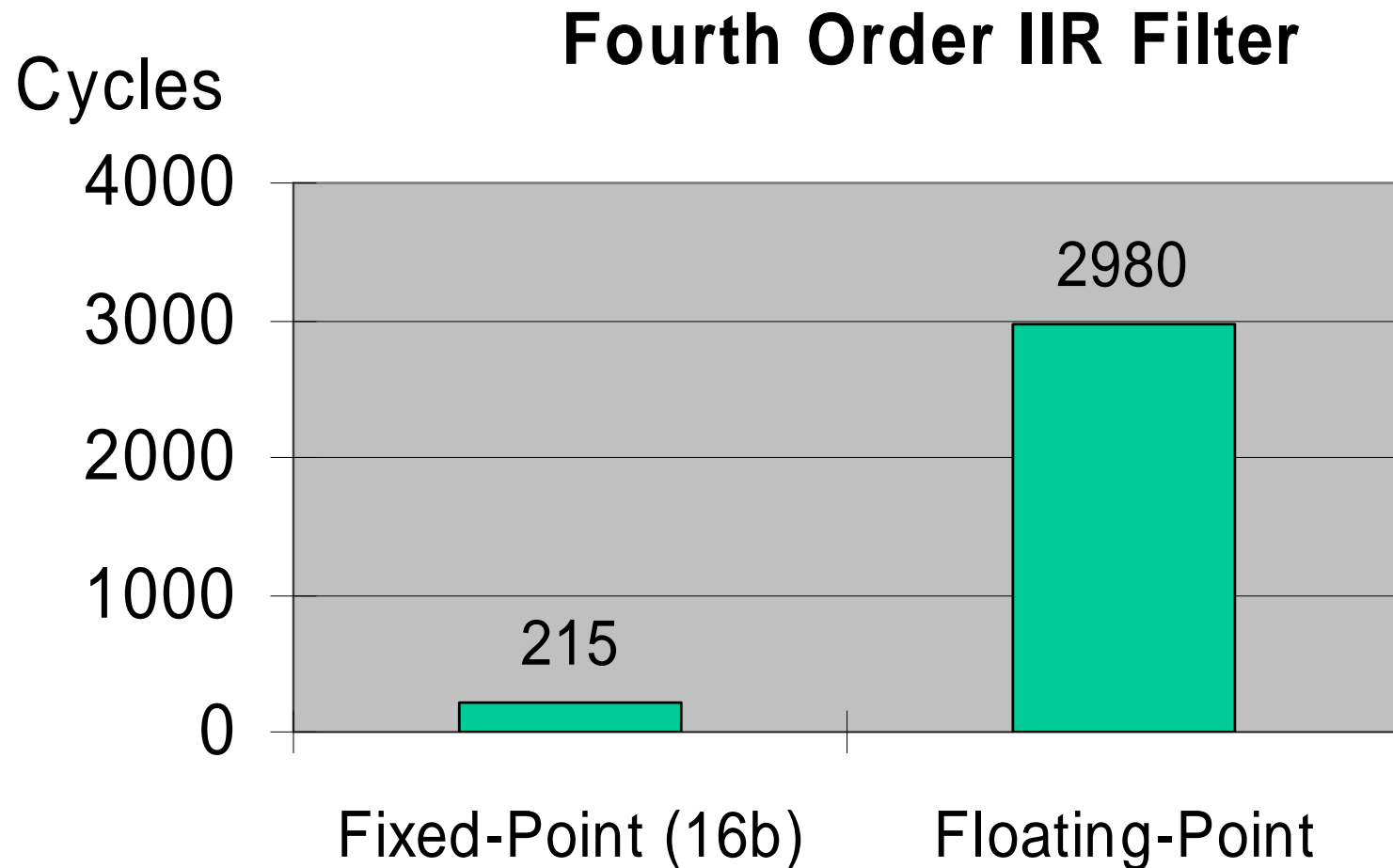
### *mulh*

- to access the upper half of the multiplied result
- target dependent implementation

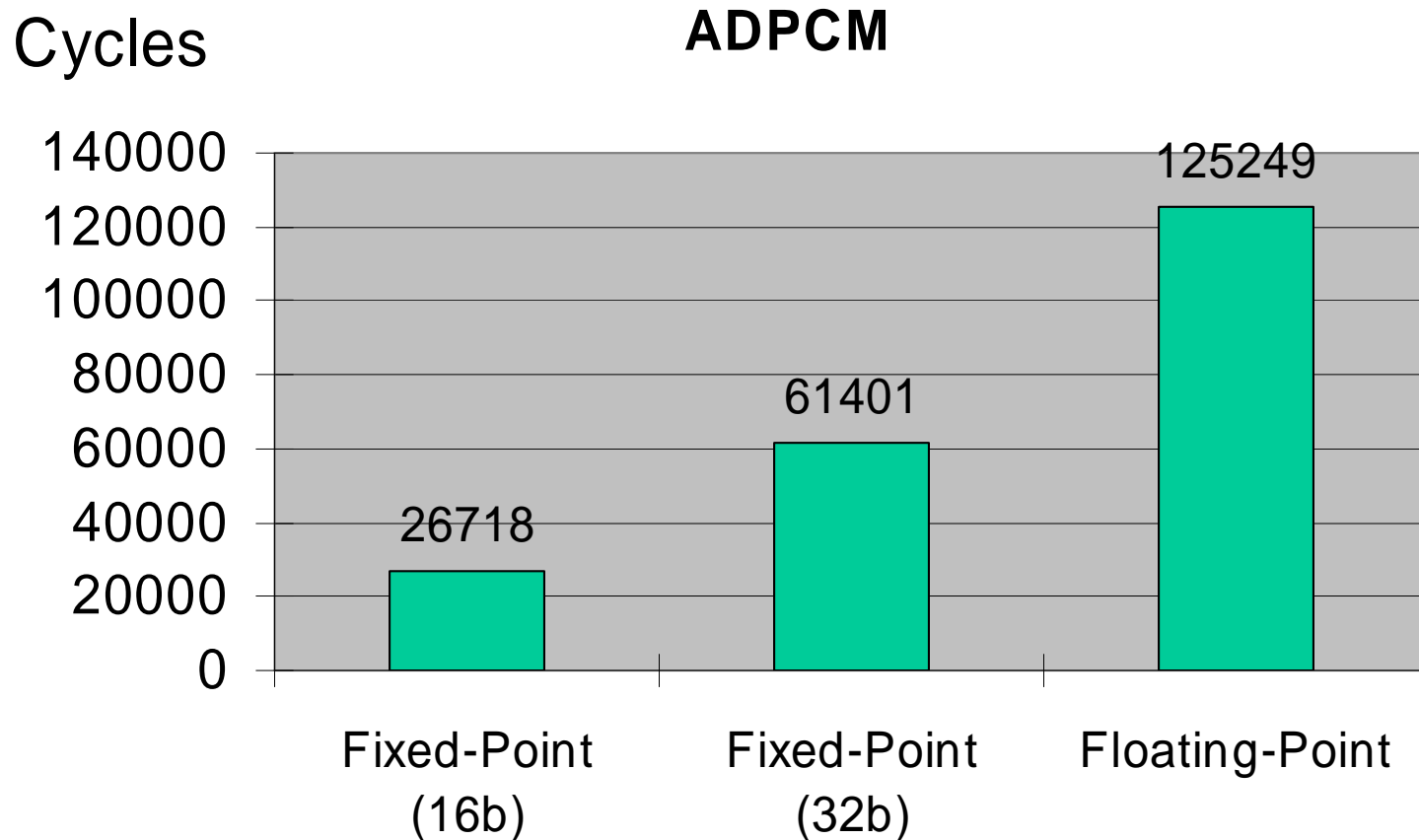
### *sll*

- to remove 2<sup>nd</sup> sign bit
- opt. overflow check

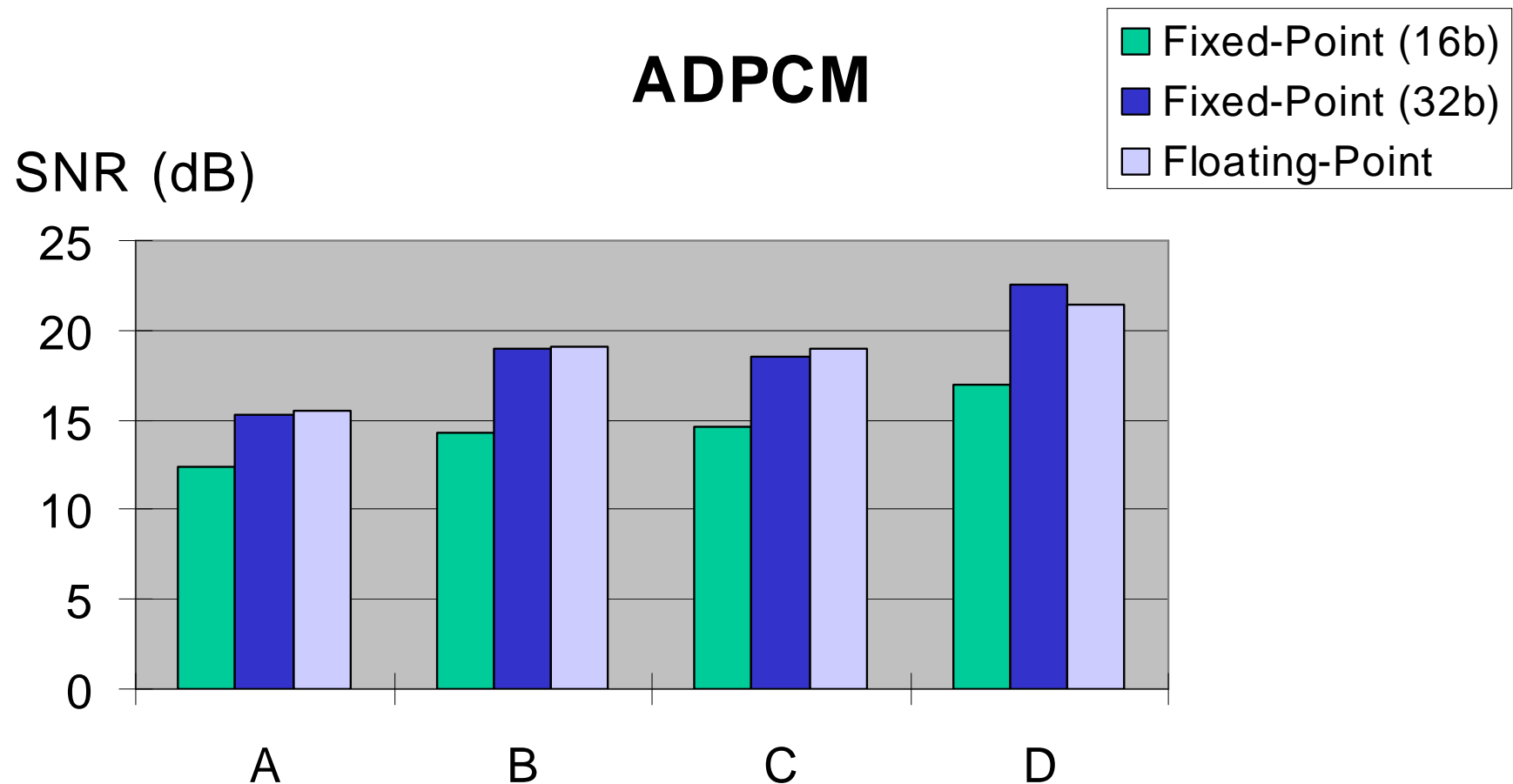
# Performance Comparison - Machine Cycles -



# Performance Comparison - Machine Cycles -



# Performance Comparison - SNR -



# High-level software transformations

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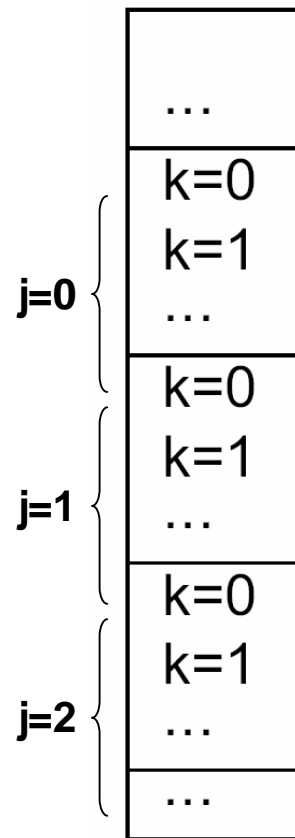
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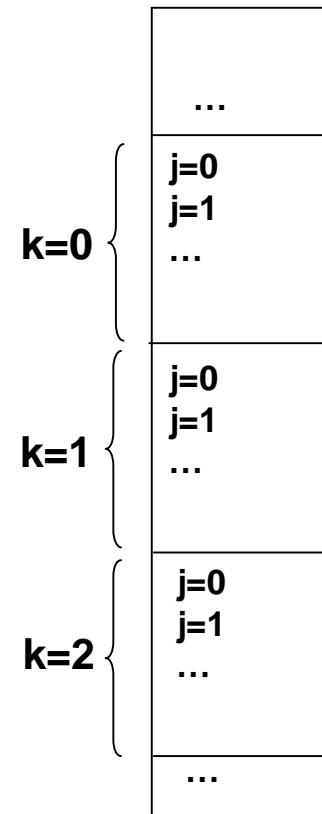
# Impact of memory allocation on efficiency

## Array $p[j][k]$

Row major order (C)



Column major order (FORTRAN)



# Best performance if innermost loop corresponds to rightmost array index

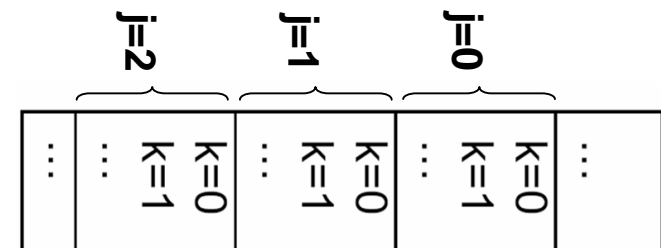
**Two loops, assuming row major order (C):**

```
for (k=0; k<=m; k++)  
  for (j=0; j<=n; j++) )  
    p[j][k] = ...
```

```
for (j=0; j<=n; j++)  
  for (k=0; k<=m; k++)  
    p[j][k] = ...
```

Same behavior for homogeneous memory access, but:

For row major order



↑ Poor cache behavior

Good cache behavior ↑

👉 memory architecture dependent optimization

# 👉 Program transformation “Loop interchange”

Example:

👉 Improved locality

```
...#define iter 400000
int a[20][20][20];
void computeijk() {int i,j,k;
    for (i = 0; i < 20; i++) {
        for (j = 0; j < 20; j++) {
            for (k = 0; k < 20; k++) {
                a[i][j][k] += a[i][j][k];}}}}
void computeikj() {int i,j,k;
    for (i = 0; i < 20; i++) {
        for (j = 0; j < 20; j++) {
            for (k = 0; k < 20; k++) {
                a[i][k][j] += a[i][k][j] ;}}}}...
start=time(&start);for(z=0;z<iter;z++)computeijk();
end=time(&end);
printf("ijk=%16.9f\n",1.0*difftime(end,start));
(SUIF interchanges array indexes instead of loops)
```



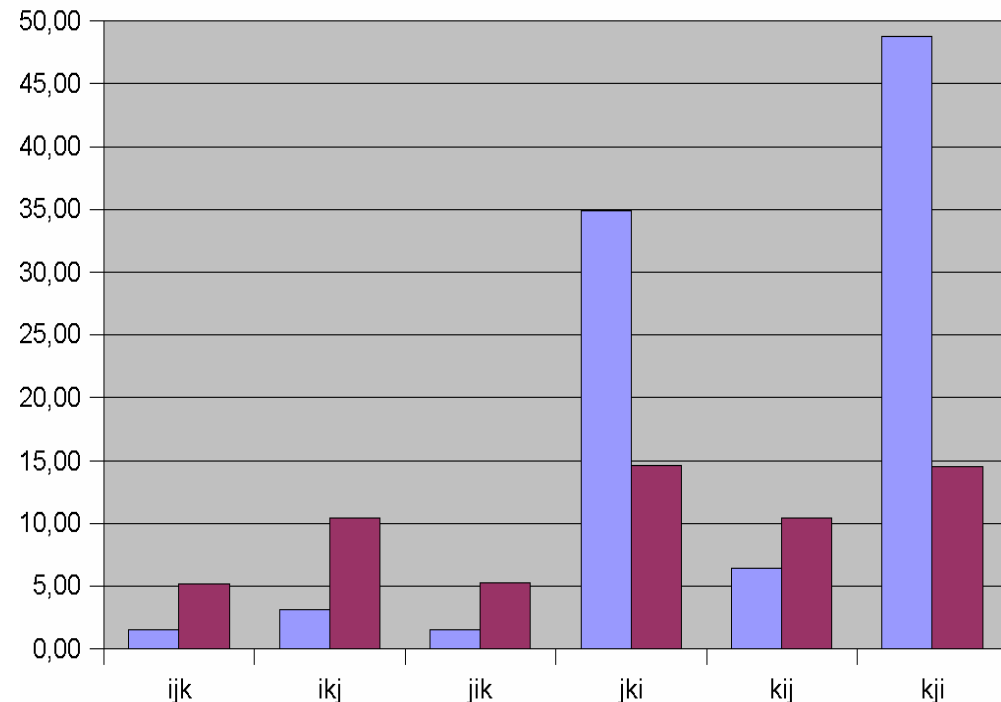
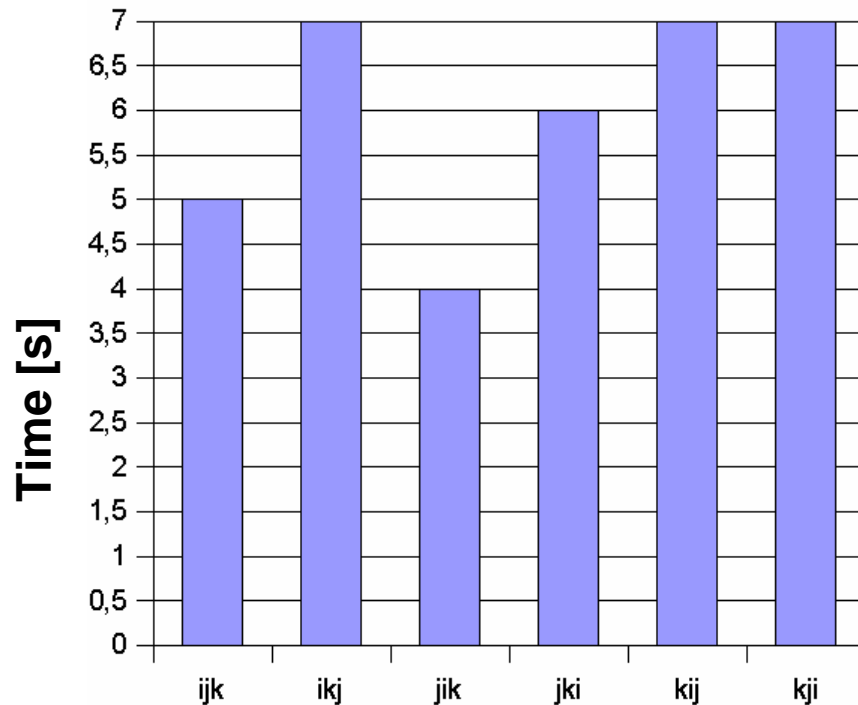
# Results:

## strong influence of the memory architecture

Loop structure: i j k

Dramatic impact of locality

Processor	Ti C6xx	Sun SPARC	Intel Pentium
reduction to [%]	~ 57%	35%	3.2 %



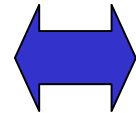
Not always the same impact ..

[Till Buchwald, Diploma thesis, Univ. Dortmund, Informatik 12, 12/2004]

# Transformations

## “Loop fusion” (merging), “loop fission”

```
for(j=0; j<=n; j++)  
  p[j]= ... ;  
for (j=0; j<=n; j++) ,  
  p[j]= p[j] + ...
```



```
for (j=0; j<=n; j++)  
  {p[j]= ... ;  
   p[j]= p[j] + ...}
```

Loops small enough to  
allow zero overhead  
Loops

**Better locality** for  
access to p.  
Better chances for  
parallel execution.

Which of the two versions is best?

Architecture-aware compiler should select best version.

# Example: simple loops

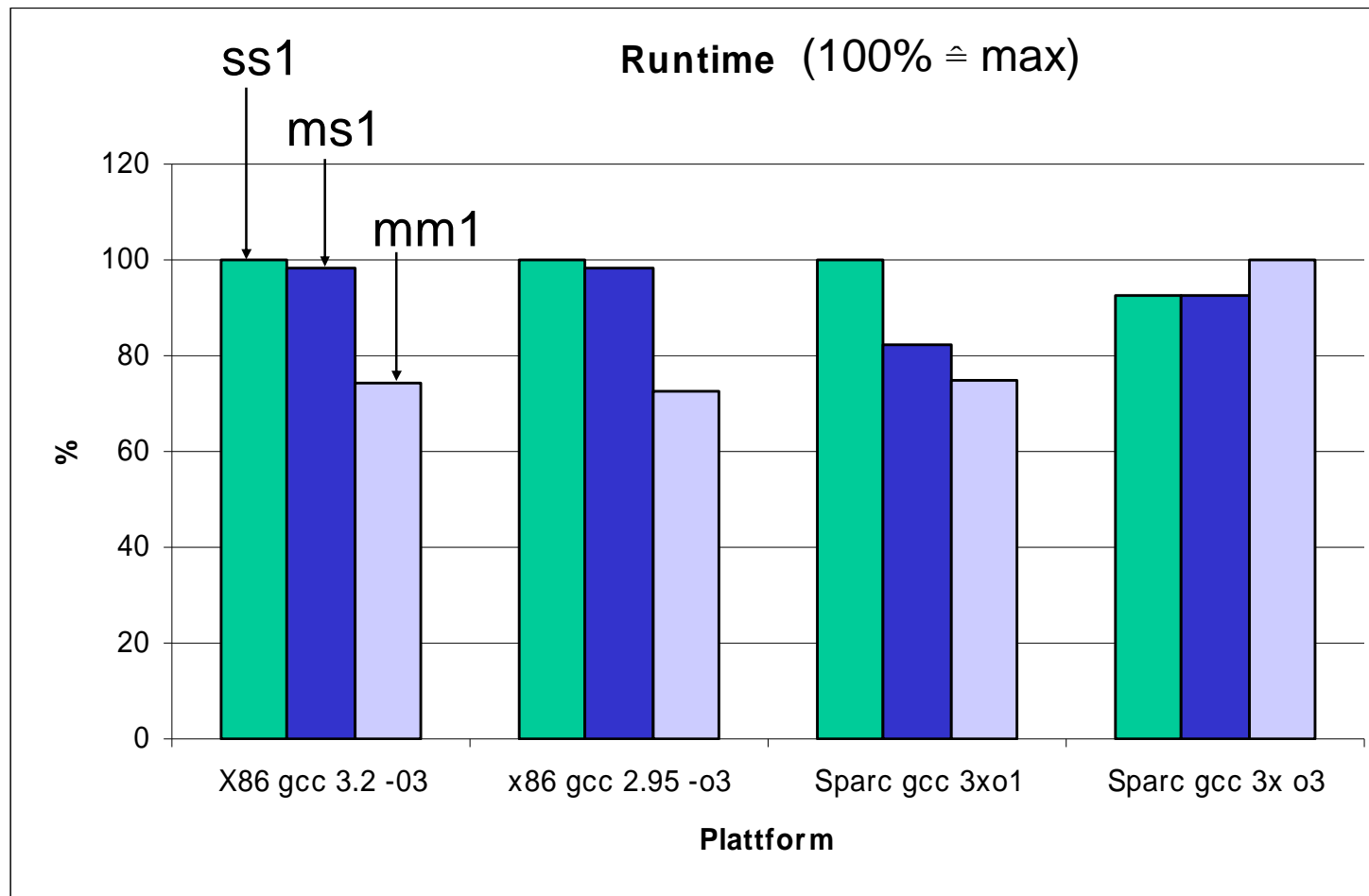
```
#define size 30
#define iter 40000
int a[size][size];
float b[size][size];
```

```
void ss1() {int i,j;
  for (i=0;i<size;i++){
    for (j=0;j<size;j++){
      a[i][j]+= 17;}}
  for(i=0;i<size;i++){
    for (j=0;j<size;j++){
      b[i][j]-=13;}}}
```

```
void ms1() {int i,j;
  for (i=0;i< size;i++){
    for (j=0;j<size;j++){
      a[i][j]+=17;    }
    for (j=0;j<size;j++){
      b[i][j]-=13;  }}}}
```

```
void mm1() {int i,j;
  for(i=0;i<size;i++){
    for(j=0;j<size;j++){
      a[i][j] += 17;
      b[i][j] -= 13;}}}}
```

# Results: simple loops



Merged loops superior; except Sparc with -o3

# Loop unrolling

```
for (j=0; j<=n; j++)  
  p[j]= ... ;
```



```
for (j=0; j<=n; j+=2)  
  {p[j]= ... ; p[j+1]= ... }
```

factor = 2

**Better locality** for access to p.  
Less branches per execution  
of the loop. More opportunities  
for optimizations.

Tradeoff between code size  
and improvement.

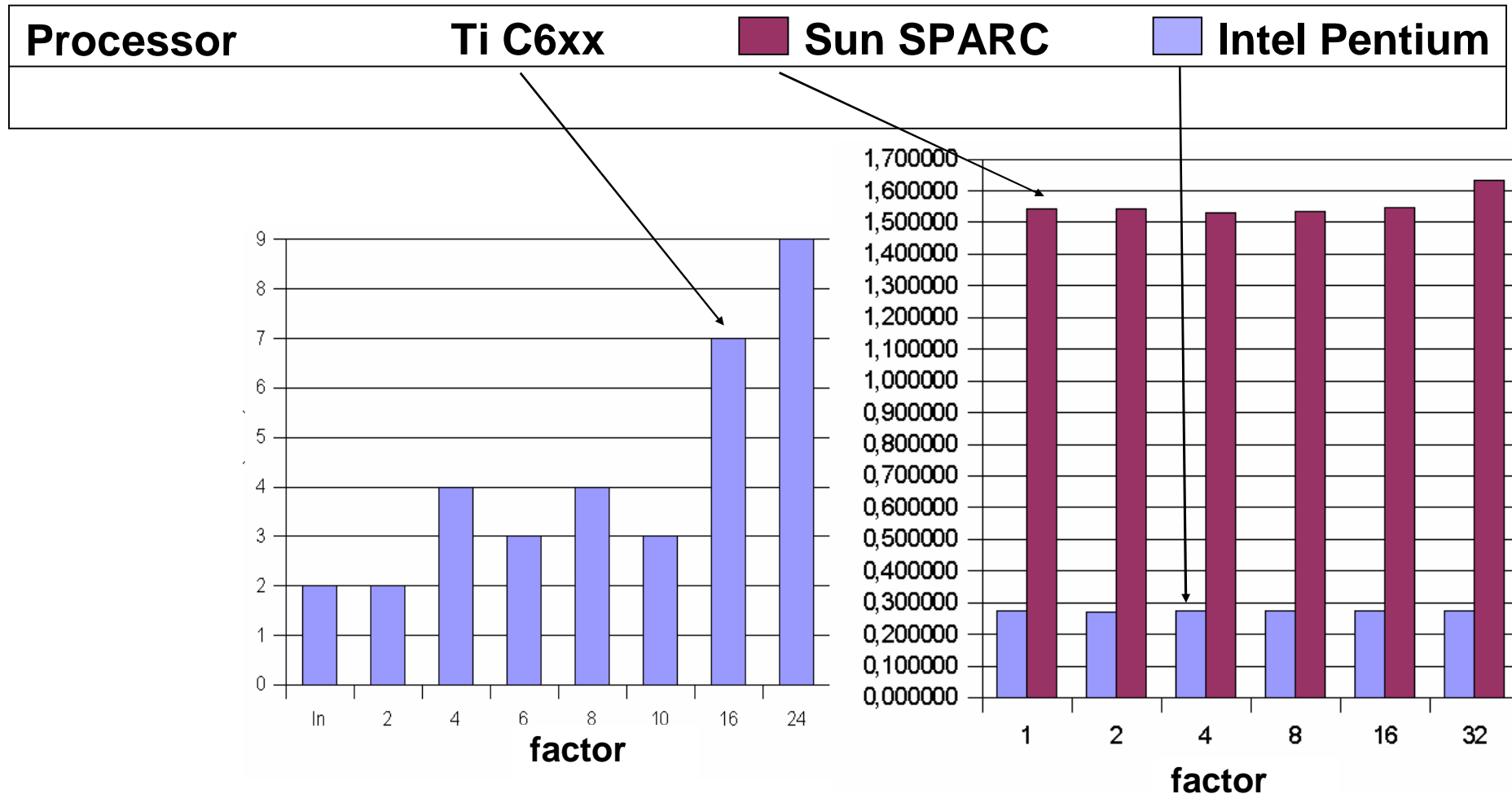
Extreme case: completely  
unrolled loop (no branch).

# Example: matrixmult

```
#define s 30
#define iter 4000
int
a[s][s],b[s][s],c[s]
[s];
void compute(){int
i,j,k;
  for(i=0;i<s;i++){
    for(j=0;j<s;j++){
      for(k=0;k<s;k++){
        c[i][k]+=
        a[i][j]*b[j][k];
      }}}
}}}

extern void compute2()
{int i, j, k;
  for (i = 0; i < 30; i++) {
    for (j = 0; j < 30; j++) {
      for (k = 0; k <= 28; k += 2)
        {{int *suif_tmp;
          suif_tmp = &c[i][k];
          *suif_tmp=
          *suif_tmp+a[i][j]*b[j][k];}
        {int *suif_tmp;
          suif_tmp=&c[i][k+1];
          *suif_tmp=*suif_tmp
          +a[i][j]*b[j][k+1];
        }}}
    }}}
  return;}
```

# Results



Benefits quite small; penalties may be large

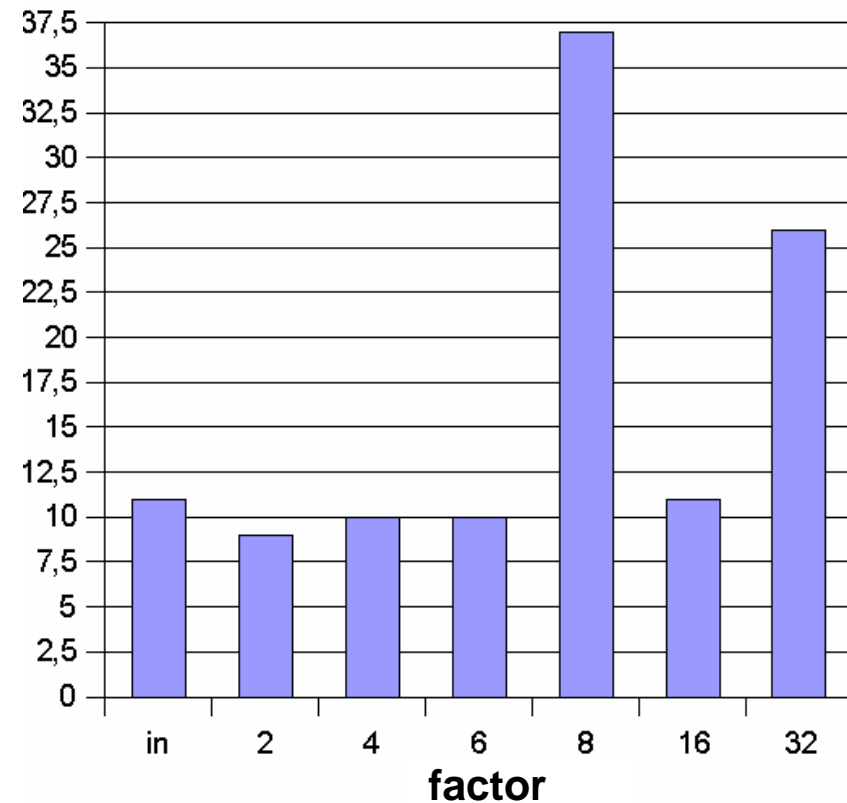
[Till Buchwald, Diploma thesis, Univ. Dortmund, Informatik 12, 12/2004]

# Results: benefits for loop dependences

Processor	Ti C6xx
reduction to [%]	

```
#define s 50
#define iter 150000
int a[s][s], b[s][s];
void compute() {
    int i,k;
    for (i = 0; i < s; i++) {
        for (k = 1; k < s; k++) {
            a[i][k] = b[i][k];
            b[i][k] = a[i][k-1];
        }
    }
}
```

Small benefits;



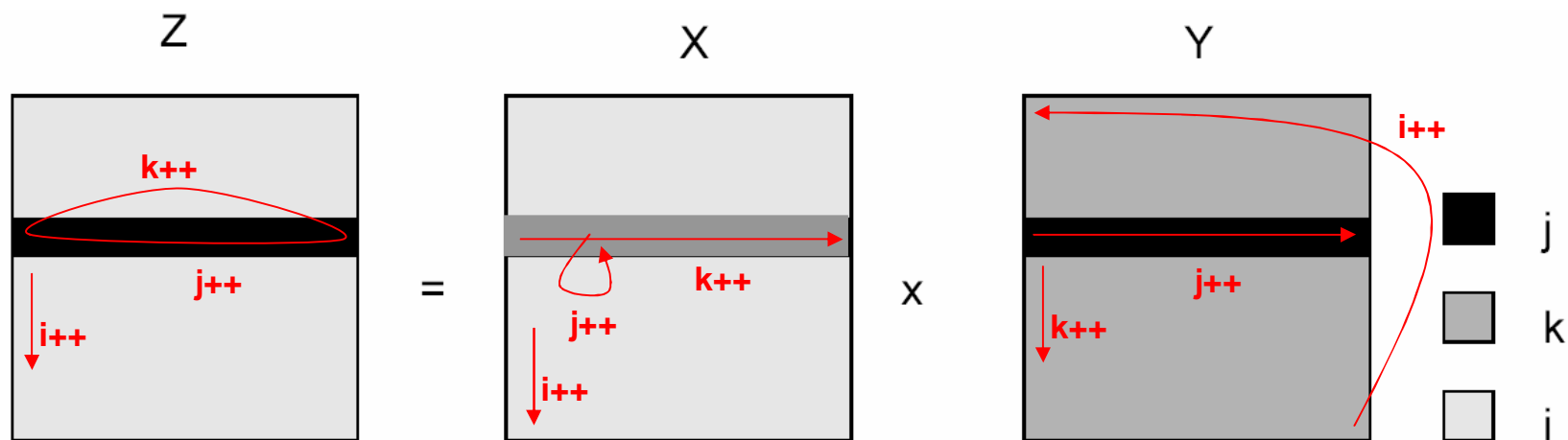
[Till Buchwald, Diploma thesis, Univ. Dortmund, Informatik 12, 12/2004]



# Program transformation

## Loop tiling/loop blocking: - Original version -

```
for (i=1; i<=N; i++)  
  for(k=1; k<=N; k++){  
    r=X[i,k]; /* to be allocated to a register*/  
    for (j=1; j<=N; j++)  
      Z[i,j] += r* Y[k,j]  
  } % Never reusing information in the cache for Y and Z if N  
    is large or cache is small (2 N3 references for Z).
```



# Loop tiling/loop blocking

## - tiled version -

```

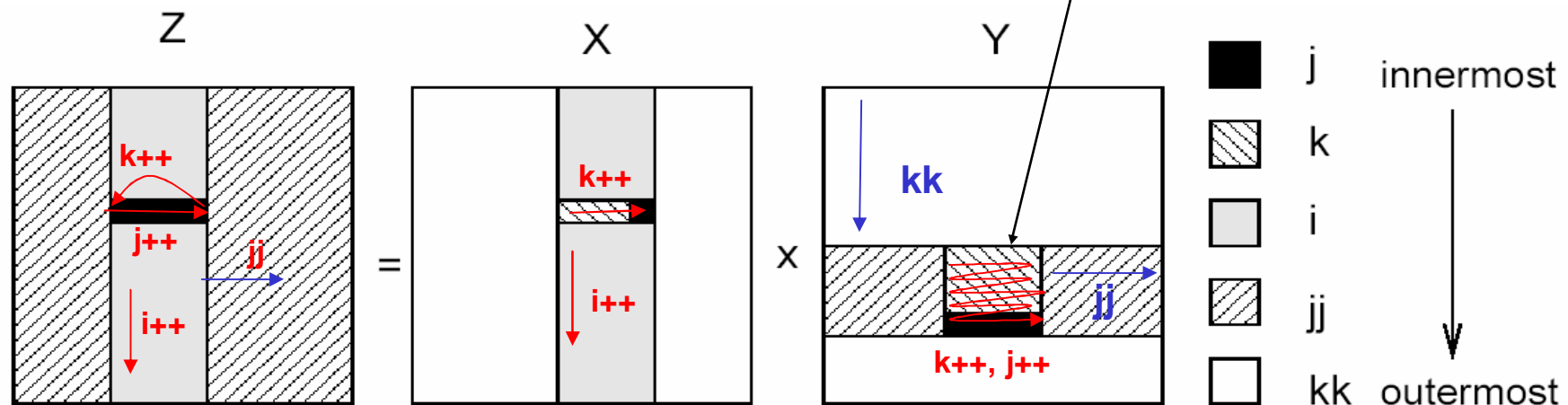
for (kk=1; kk<= N; kk+=B)
  for (jj=1; jj<= N; jj+=B)
    for (i=1; i<= N; i++)
      for (k=kk; k<= min(kk+B-1,N); k++){
        r=X[i][k]; /* to be allocated to a register*/
        for (j=jj; j<= min(jj+B-1, N); j++)
          Z[i][j] += r* Y[k][j]
      }
  
```

Reuse factor of  
B for Z, N for Y

$O(N^3/B)$   
accesses to  
main memory

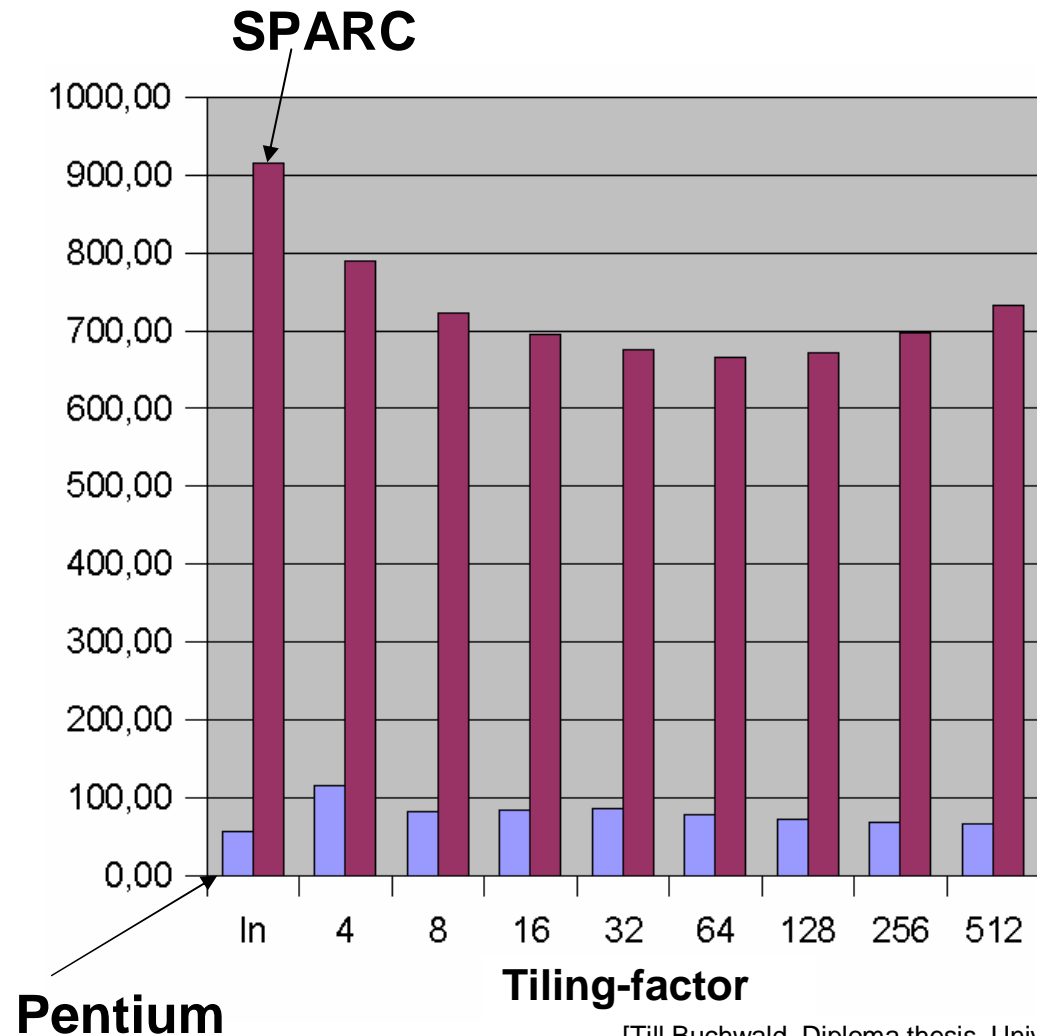
*Compiler  
should select  
best option*

*Same elements for  
next iteration of i*



# Example

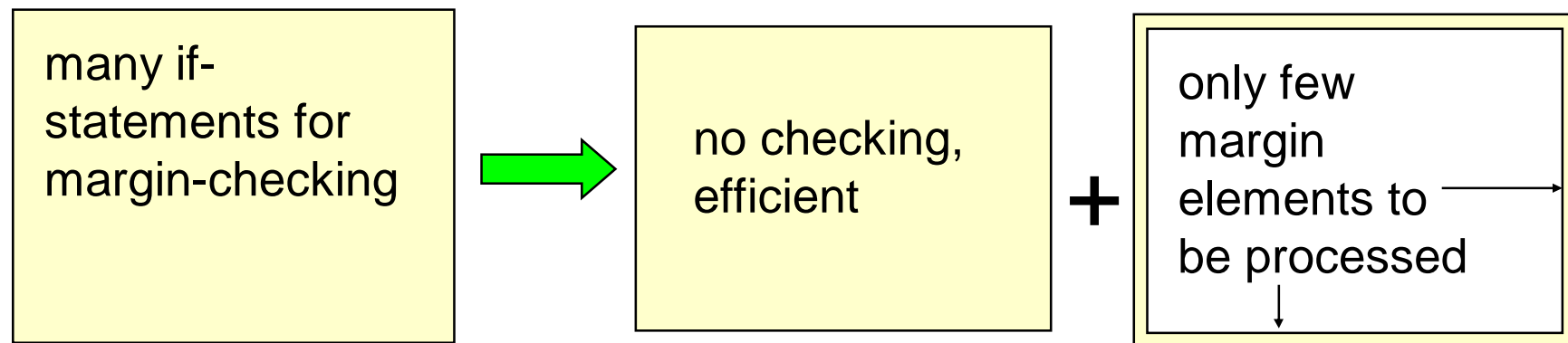
**In practice, results by Buchwald are disappointing. One of the few cases where an improvement was achieved:  
Source: similar to matrix mult.**



[Till Buchwald, Diploma thesis, Univ. Dortmund, Informatik 12, 12/2004]

# Transformation “Loop nest splitting”

## Example: Separation of margin handling



# Loop nest splitting at University of Dortmund

## Loop nest from MPEG-4 full search motion estimation

```
for (z=0; z<20; z++)
  for (x=0; x<36; x++) {x1=4*x;
    for (y=0; y<49; y++) {y1=4*y;
      for (k=0; k<9; k++) {x2=x1+k-4;
        for (l=0; l<9; ) {y2=y1+l-4;
          for (i=0; i<4; i++) {x3=x1+i; x4=x2+i;
            for (j=0; j<4;j++) {y3=y1+j; y4=y2+j;
              if (x3<0 || 35<x3||y3<0||48<y3)
                then_block_1; else else_block_1;
              if (x4<0|| 35<x4||y4<0||48<y4)
                then_block_2; else else_block_2;
            }}}}}}
```



analysis of polyhedral domains,  
selection with genetic algorithm

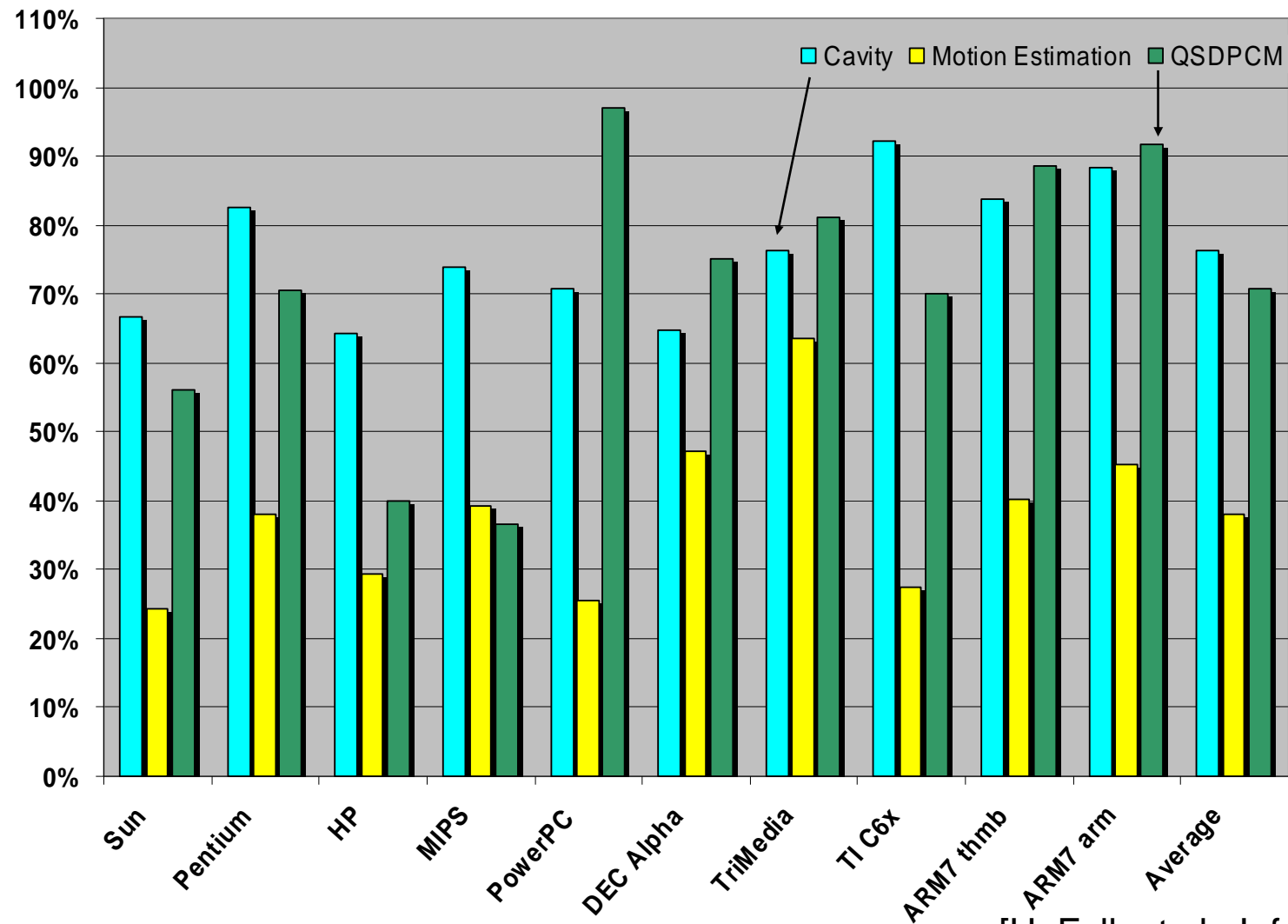
```
for (z=0; z<20; z++)
  for (x=0; x<36; x++) {x1=4*x;
    for (y=0; y<49; y++)
```

```
      if (x>=10||y>=14)
        for (; y<49; y++)
          for (k=0; k<9; k++)
            for (l=0; l<9;l++ )
              for (i=0; i<4; i++)
                for (j=0; j<4;j++) {
                  then_block_1; then_block_2}
      else {y1=4*y;
        for (k=0; k<9; k++) {x2=x1+k-4;
          for (l=0; l<9; ) {y2=y1+l-4;
            for (i=0; i<4; i++) {x3=x1+i; x4=x2+i;
              for (j=0; j<4;j++) {y3=y1+j; y4=y2+j;
                if (0 || 35<x3 ||0 || 48<y3)
                  then-block-1; else else-block-1;
                if (x4<0|| 35<x4||y4<0||48<y4)
                  then_block_2; else else_block_2;
                }}}}}}
```

[H. Falk et al., Inf 12, UniDo, 2002]

# Results for loop nest splitting

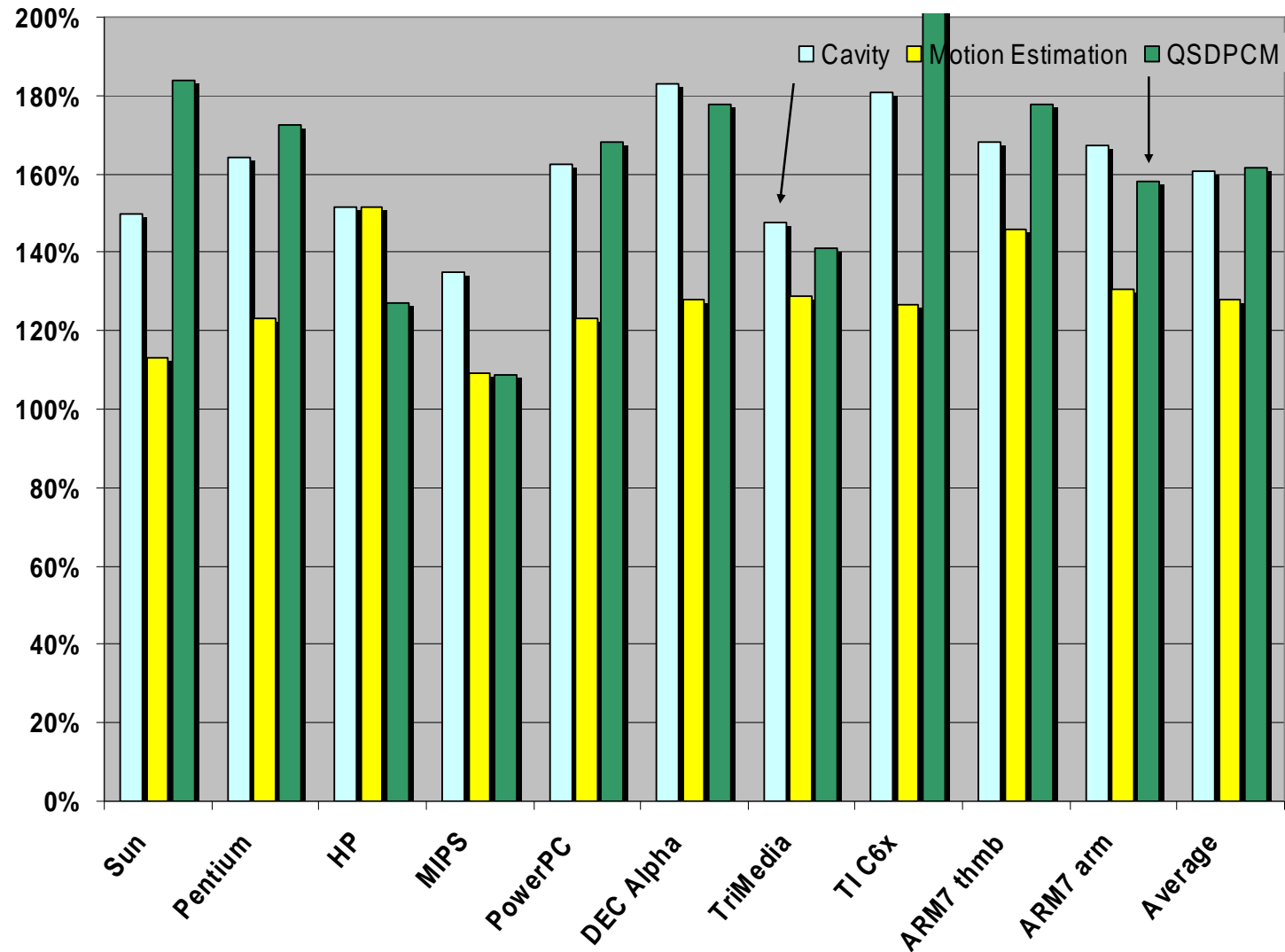
## - Execution times -



[H. Falk et al., Inf 12, UniDo, 2002]

# Results for loop nest splitting

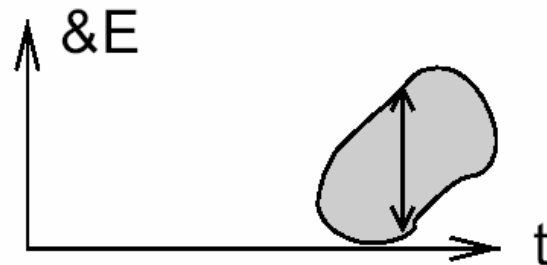
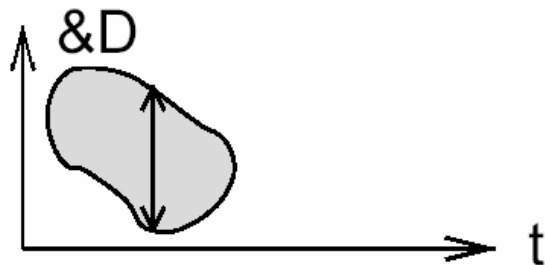
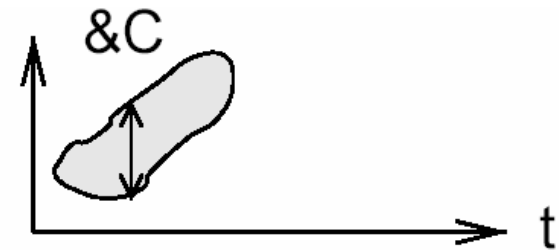
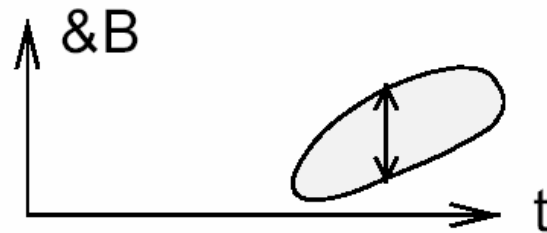
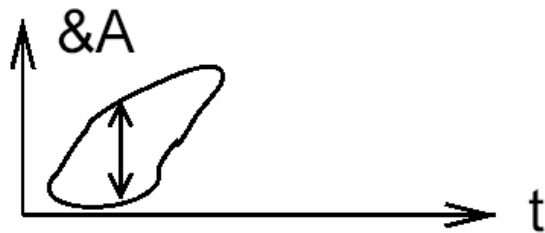
## - Code sizes -



[Falk, 2002]

# Array folding

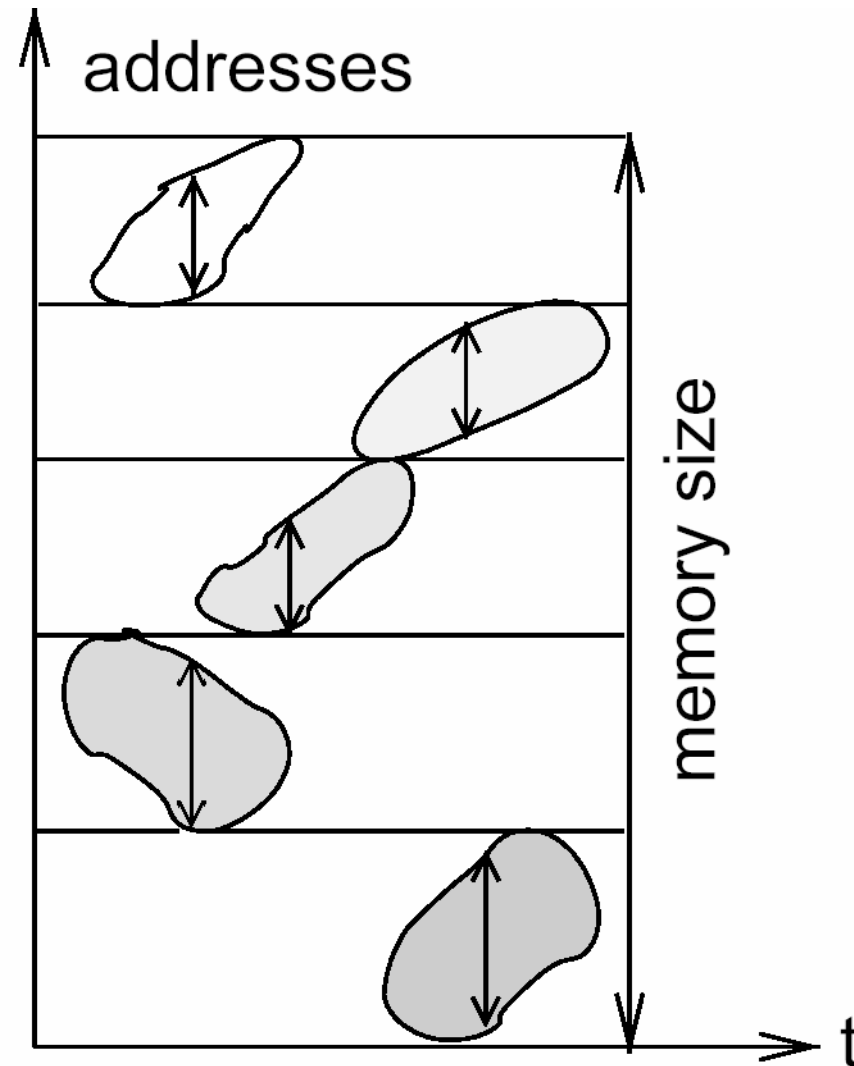
## Initial arrays





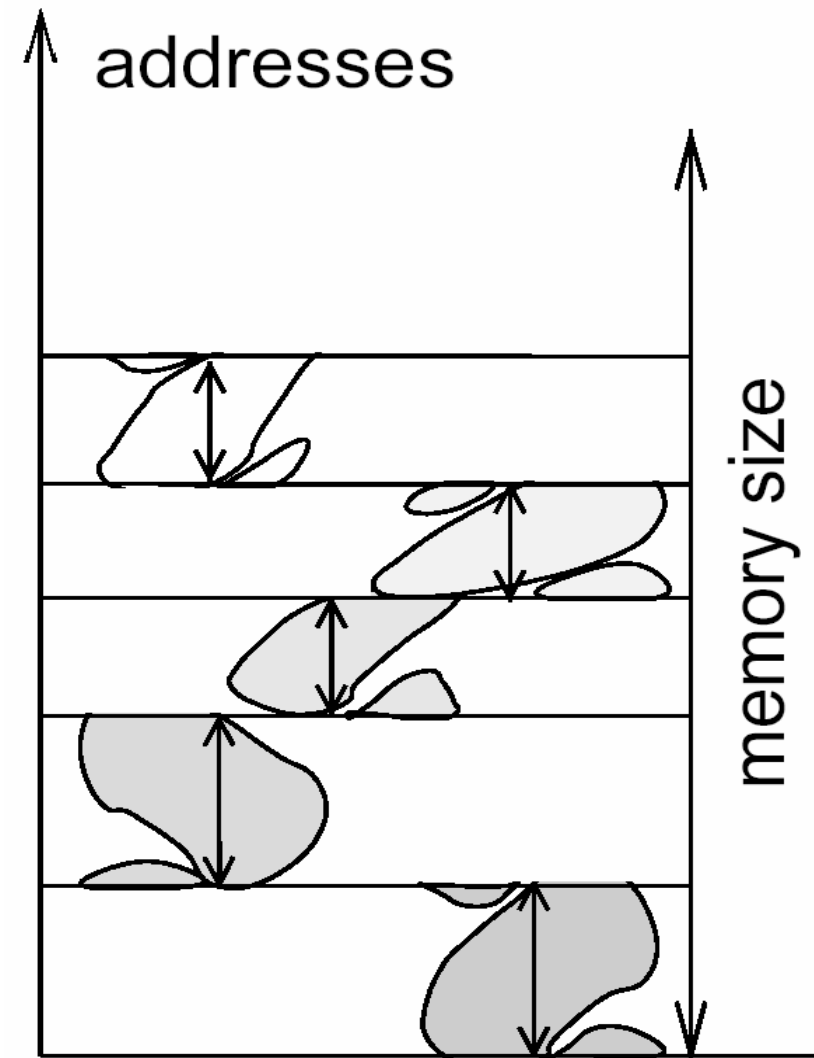
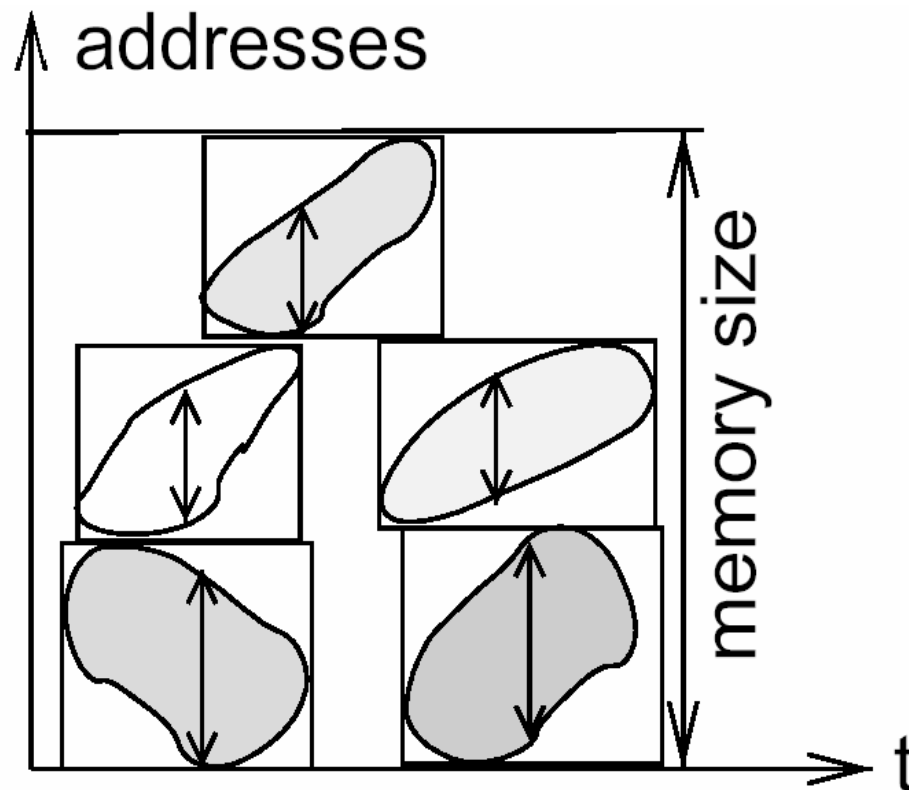
# Array folding

Unfolded  
arrays



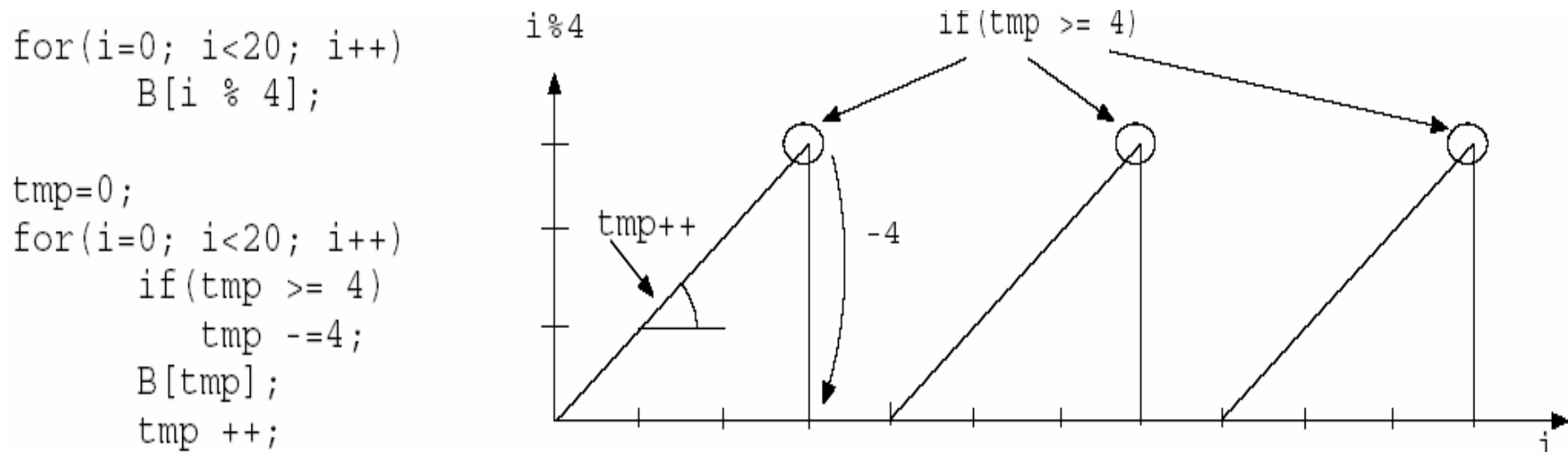
# Intra-array folding

## Inter-array folding

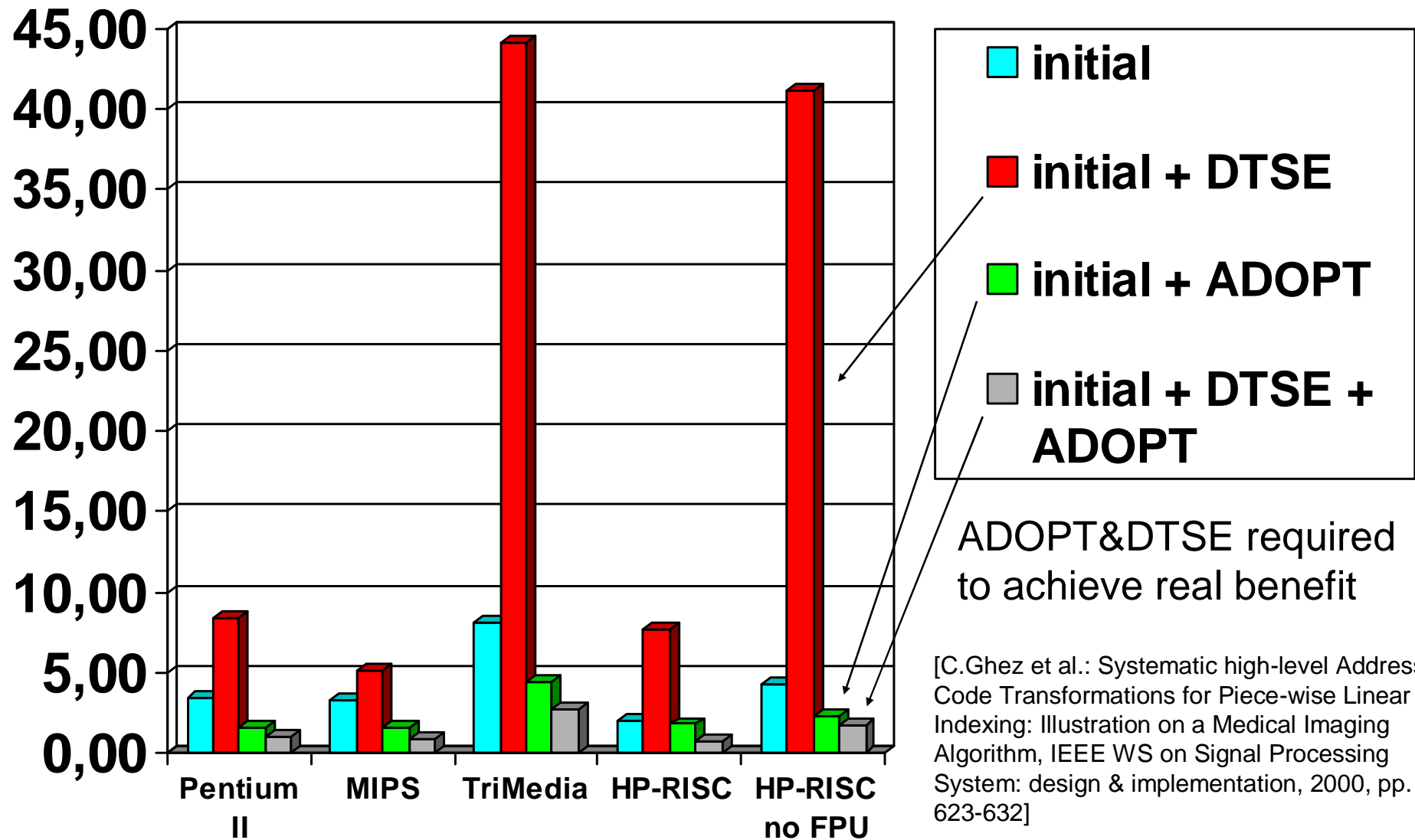


# Application

- Array folding is implemented in the DTSE optimization proposed by IMEC. Array folding adds div and mod ops. Optimizations required to remove these costly operations.
- At IMEC, ADOPT address optimizations perform this task. For example, modulo operations are replaced by pointers (indexes) which are incremented and reset.



# Results (Mcycles for cavity benchmark)



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# Summary

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- Task concurrency management
  - Re-partitioning of computations into tasks
- Floating-point to fixed point conversion
  - Range estimation
  - Conversion
  - Analysis of the results
- High-level loop transformations
  - Fusion
  - Unrolling
  - Tiling
  - Loop nest splitting
  - Array folding