Singularities of tangent surfaces to directed curves

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Abstract

A directed curve is a possibly singular curve with well-defined tangent lines along the curve. Then the tangent surface to a directed curve is naturally defined as the ruled surface by tangent geodesics to the curve, whenever any affine connection is endowed with the ambient space. In this paper the local diffeomorphism classification is completed for generic directed curves. Then it turns out that the swallowtails and open swallowtails appear generically for the classification on singularities of tangent surfaces.

1 Introduction

Given a space curve, the ruled surface by its tangent lines is called a *tangent surface* or a *tangent developable* to the curve. Tangent surfaces appear in various geometric problems and applications (see for instance [2][8]). Even if the space curve is regular, its tangent surface has singularities at least along the original curve, so called "the curve of regression".

Let M be a general (semi-)Riemannian manifold, or more generally, a manifold M with an affine connection ∇ , of dimension $m \geq 3$, and let $\gamma: I \to M$ any regular curve in M. If we replace tangent lines by "tangent geodesics" in the definition of tangent surface, then we have the definition of the ∇ -tangent surface ∇ -Tan $(\gamma): (I \times \mathbf{R}, I \times \{0\}) \to M$ as a map-germ along $I \times \{0\}$.

Ordinarily we try to classify certain generic singularities in a *specific* space, say, in the Euclidian spaces, in the space forms, and so on. If we treat arbitrary spaces, it would become hopeless to classify singularities of tangent surfaces that appear far away. However, it is possible to find a local classification theorem which holds in general spaces. In the previous paper [9], actually we have shown the following result on the singularities of ∇ -tangent surfaces to generic curves for arbitrary affine connection ∇ :

Theorem 1.1 ([9]) The singularities of the ∇ -tangent surface to a generic immersed curve in M on a neighbourhood of the curve are only the cuspidal edges and the folded umbrellas if m=3, and the embedded cuspidal edges if $m \geq 4$.

The above theorem provides a rare but an ultimate *local* classification of singularities associated with *generic* immersed curves in *general* spaces. The explanation on singularities is coming later soon.

Now regarding the definition of general tangent surfaces, it seems to be very natural to consider the genericity in the space of curves, not only for regular (immersed) curves, but also for all singular curves with well-defined tangent directions, called *directed curves*, and to classify

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singularities of tangent surfaces for curves which is generic in such a class. In fact, as we show in this paper, it is possible and we have the following general result:

Theorem 1.2 (Singularities of tangent surfaces to generic directed curves.) Let ∇ be any affine connection on a manifold M of dimension $m \geq 3$. The singularities of the ∇ -tangent surface to a generic directed curve in M on a neighbourhood of the curve are only the cuspidal edges, the folded umbrellas and the swallowtails if m = 3, and the embedded cuspidal edges and open swallowtails if $m \geq 4$.

The genericity is exactly given using Whitney C^{∞} topology on an appropriate space of curves (see Proposition 4.1).

A map-germ $f: (\mathbf{R}^2, p) \to M$ is locally diffeomorphic at p to another map-germ $g: (\mathbf{R}^2, p') \to M'$ if there exist diffeomorphism-germs $\sigma: (\mathbf{R}^2, p) \to (\mathbf{R}^2, p')$ and $\tau: (M, f(p)) \to (M', g(p'))$ such that $\tau \circ f = g \circ \sigma: (\mathbf{R}^2, p) \to (M', g(p'))$.

The cuspidal edge is defined by the map-germ $(\mathbf{R}^2,0) \to (\mathbf{R}^m,0), m \geq 3$,

$$(t,s) \mapsto (t+s, t^2+2st, t^3+3st^2, 0, \dots, 0),$$

which is diffeomorphic to $(u, w) \mapsto (u, w^2, w^3, 0, \dots, 0)$. The cuspidal edge singularities are originally defined only in the three dimensional space. Here we are generalizing the notion of the cuspidal edge in higher dimensional space. In Theorem 1.2, we emphasize it by writing "embedded" cuspidal edge. In what follows, we call it just cuspidal edge for simplicity even in the case $m \geq 4$. The folded umbrella (or the cuspidal cross cap) is defined by the map-germ $(\mathbf{R}^2, 0) \to (\mathbf{R}^3, 0)$,

$$(t,s) \mapsto (t+s, t^2+2st, t^4+4st^3),$$

which is diffeomorphic to $(u,t) \mapsto (u,t^2+ut,t^4+\frac{2}{3}ut^3)$. The *swallowtail* is defined by the map-germ $(\mathbf{R}^2,0) \to (\mathbf{R}^3,0)$

$$(t,s) \mapsto (t^2 + s, t^3 + \frac{3}{2}st, t^4 + 2st^2),$$

which is diffeomorphic to $(u,t) \mapsto (u,t^3+ut,t^4+\frac{2}{3}ut^2)$. The open swallowtail is defined by the map-germ $(\mathbf{R}^2,0) \to (\mathbf{R}^m,0), m \ge 4$,

$$(t,s) \mapsto (t^2 + s, t^3 + \frac{3}{2}st, t^4 + 2st^2, t^5 + \frac{5}{2}st^3, 0, \dots, 0),$$

which is diffeomorphic to $(u,t) \mapsto (u,t^3+ut,t^4+\frac{2}{3}ut^2,t^5+\frac{5}{9}ut^3,0,\dots,0)$. The open swallow-tail singularity was introduced by Arnol'd (see [1]) as a singularity of Lagrangian varieties in symplectic geometry. Here we abstract its diffeomorphism class as the singularity of tangent surfaces (see [4][7]).

Swallowtails and open swallowtails appear as singularities of tangent surfaces to *singular* curves. It is observed that (open) swallowtails are destroyed by some perturbations of the original curves which induce big changes of their tangent directions, and however that they survive by any small perturbations which induce small changes of their tangent directions of the singular but directed curves.

Let $\gamma: I \to M$ be any curve which is not necessarily a geodesic nor an immersed curve. The first derivative $(\nabla \gamma)(t)$ means just the velocity vector field $\gamma'(t)$. The second derivative $(\nabla^2 \gamma)(t)$ is defined, in terms of covariant derivative along the curve γ , by

$$(\nabla^2 \gamma)(t) := \nabla^{\gamma}_{\partial/\partial t}(\nabla \gamma)(t).$$

Note that γ is a ∇ -geodesic if and only if $\nabla^2 \gamma = 0$. In general, we define k-th covariant derivative of γ inductively by

$$(\nabla^k \gamma)(t) := \nabla_{\partial/\partial t}^{\gamma}(\nabla^{k-1} \gamma)(t), \ (k \ge 2).$$

Then we have:

Theorem 1.3 (Characterization.) Let ∇ be a torsion free affine connection on a manifold M. Let $\gamma: I \to M$ be a C^{∞} curve from an open interval I.

- (1) Let $\dim(M) = 3$. If $(\nabla \gamma)(t_0), (\nabla^2 \gamma)(t_0), (\nabla^3 \gamma)(t_0)$ are linearly independent, then the ∇ -tangent surface ∇ -Tan (γ) is locally diffeomorphic to the cuspidal edge at $(t_0, 0) \in I \times \mathbf{R}$. If $(\nabla \gamma)(t_0), (\nabla^2 \gamma)(t_0), (\nabla^3 \gamma)(t_0)$ are linearly dependent, and $(\nabla \gamma)(t_0), (\nabla^2 \gamma)(t_0), (\nabla^4 \gamma)(t_0)$ are linearly independent, then ∇ -Tan (γ) is locally diffeomorphic to the folded umbrella at $(t_0, 0) \in I \times \mathbf{R}$. If $(\nabla \gamma)(t_0) = 0$ and $(\nabla^2 \gamma)(t_0), (\nabla^3 \gamma)(t_0), (\nabla^4 \gamma)(t_0)$ are linearly independent, then ∇ -Tan (γ) is locally diffeomorphic to the swallowtail at $(t_0, 0) \in I \times \mathbf{R}$.
- (2) Let $\dim(M) \geq 4$. If $(\nabla \gamma)(t_0)$, $(\nabla^2 \gamma)(t_0)$, $(\nabla^3 \gamma)(t_0)$ are linearly independent, then the ∇ -tangent surface ∇ -Tan (γ) is locally diffeomorphic to the cuspidal edge at $(t_0, 0) \in I \times \mathbf{R}$. If $(\nabla \gamma)(t_0) = 0$ and $(\nabla^2 \gamma)(t_0)$, $(\nabla^3 \gamma)(t_0)$, $(\nabla^4 \gamma)(t_0)$, $(\nabla^5 \gamma)(t_0)$ are linearly independent, then ∇ -Tan (γ) is locally diffeomorphic to the open swallowtail at $(t_0, 0) \in I \times \mathbf{R}$.

Some of characterizations in Theorem 1.3 have been shown already in [9].

The intrinsic characterizations of singularities found in [11][3] are useful for our treatment of singularities in general ambient spaces. We apply to non-flat projective geometry the characterizations and their some generalization via the notion of openings introduced by the first author ([7], see also [6]).

In §2 we introduce the notion of directed curves and define their tangent surfaces. We recall the criteria of singularities in §3 and prove Theorem 1.3. In §4 we study on perturbations of directed curves and prove Theorem 1.2.

In this paper all manifolds and mappings are assumed to be of class C^{∞} unless otherwise stated.

This paper is a second half of the unpublished paper [10] which is divided into two shorter papers, the paper [9] and the present paper. We utilize in the present paper, as the sequel of [9], several detailed calculations performed in [9].

2 Directed curves and their tangent surfaces

Let PTM = Gr(1, TM) denote the projective tangent bundle over the manifold M, and $\pi : PTM \to M$ the natural projection. The fibre of π over $x \in M$ is the projective space $P(T_xM)$ of dimension m-1.

A curve $\gamma: I \to M$ from an open interval I, which is not necessarily an immersion, is called directed if there assigned a C^{∞} lifting $\tilde{\gamma}: I \to PTM$ of γ for π which satisfies the integrality condition $\gamma'(t) \in \tilde{\gamma}(t) \subset T_{\gamma(t)}M$ for any $t \in I$. Here $\tilde{\gamma}(t) \in P(T_{\gamma(t)}M)$ is regarded as a one-dimensional linear subspace of $T_{\gamma(t)}M$. Then we regard the direction $\tilde{\gamma}(t_0)$ is assigned to each point $\gamma(t_0)$ on γ . Note that if $\gamma'(t_0) \neq 0$, then $\tilde{\gamma}(t_0)$ is uniquely determined by the tangent line $\langle \gamma'(t_0) \rangle_{\mathbf{R}} \subset T_{\gamma(t_0)}M$. The notion of directed curves is nothing but the notion of frontal maps introduced in [9] in the case n=1 with assignment of an integral lifting when the immersion locus of γ is dense in I.

Let $\gamma: I \to M$ be a directed curve and $\widetilde{\gamma}$ its integral lifting. Then there exists a C^{∞} frame $u: I \to TM$ of $\widetilde{\gamma}$ which satisfies $\widetilde{\gamma}(t) = \langle u(t) \rangle_{\mathbf{R}}, u(t) \neq 0$ for any $t \in I$. Note that there exists a unique function a(t) such that $\gamma'(t) = a(t)u(t)$. Then define the ∇ -tangent surface $f = \nabla$ -Tan $(\gamma): V(\subset I \times \mathbf{R}) \to M$ by

$$f(t,s) := \varphi(\gamma(t), u(t), s),$$

using the family of ∇ -geodesics $\varphi = \varphi(x,v,s)$ and a frame u(t). Here $\varphi(x,v,s)$ gives the ∇ -geodesic parametrized by the parameter s through x with the velocity vector v at s=0, $\varphi(x,v,0)=x$ and $\frac{\partial \varphi}{\partial s}(x,v,0)=v$. In [9], the ∇ -tangent surface for an immersed curve γ was defined by the frame $u(t)=\gamma'(t)$ and studied with the detail analysis of ∇ -geodesics $\varphi=\varphi(x,v,s)$.

Lemma 2.1 If the immersion locus of a directed curve $\gamma: I \to M$ is dense in I, then the integral lifting $\widetilde{\gamma}$ is uniquely determined. The right equivalence class of the germ of ∇ -Tan (γ) : $(I \times \mathbf{R}, I \times \{0\}) \to M$ for a directed curve γ is independent of the choice of the frame u.

Proof: The first half is clear because $\tilde{\gamma}$ is C^{∞} , so is continuous. The second half is achieved by the diffeomorphism $(t,s) \to (t,c(t)s)$ for another choice $c(t)u(t),c(t)\neq 0$.

In [9] we have introduced the notions of frontals and non-degenerate singular points of frontals (§3 of [9]). Using those notions we have the following result:

Lemma 2.2 Let $\gamma: I \to M$ be a C^{∞} curve, $t_0 \in I$, and $k \ge 1$. Suppose that $(\nabla^i \gamma)(t_0) = 0, 1 \le i < k$ and that $(\nabla^k \gamma)(t_0), (\nabla^{k+1} \gamma)(t_0)$ are linearly independent. Then the germ of ∇ -Tan (γ) is a frontal with non-degenerate singular point at $(t_0, 0)$ and with the singular locus $S(\nabla$ -Tan (γ)) = $\{s = 0\}$.

To prove Lemma 2.2 we prepare

Lemma 2.3 Let $k \geq 2$. Suppose $(\nabla^i \gamma)(t_0) = 0, 1 \leq i < k$ and $(\nabla^k \gamma)(t_0) \neq 0$. Then we have:

- (1) For any coordinates of M around $\gamma(t_0)$, $\gamma^{(i)}(t_0) = 0, 1 \le i < k$ and $\gamma^{(k)}(t_0) = (\nabla^k \gamma)(t_0) \ne 0$. Moreover we have $\gamma^{(k+1)}(t_0) = (\nabla^{k+1} \gamma)(t_0)$.
 - (2) Set

$$u(t) = \frac{1}{k(t-t_0)^{k-1}} \gamma'(t).$$

Then u is a C^{∞} vector field along γ on a neighbourhood of t_0 . The curve γ is directed on a neighbourhood of t_0 by the frame u.

(3) For any frame u(t) of the directed curve γ around t_0 , and for any $\ell \geq 0$,

$$(\nabla^k \gamma)(t_0), \ (\nabla^{k+1} \gamma)(t_0), \ \dots, \ (\nabla^{k+\ell} \gamma)(t_0)$$

are linearly independent if and only if

$$u(t_0), \ (\nabla_{\partial/\partial t}^{\gamma} u)(t_0), \ \dots, \ ((\nabla_{\partial/\partial t}^{\gamma})^{\ell} u)(t_0)$$

are linearly independent. In particular, for the frame in (2), we have

$$u(t_0) = \frac{1}{k!} (\nabla^k \gamma)(t_0), \ (\nabla u)(t_0) = \frac{1}{k \cdot k!} (\nabla^{k+1} \gamma)(t_0), \ \dots, \ (\nabla^\ell u)(t_0) = \frac{\ell!}{k \cdot (k+\ell-1)!} (\nabla^{k+\ell} \gamma)(t_0).$$

where $\nabla^i u = (\nabla^{\gamma}_{\partial/\partial t})^i u$.

Proof: (1) Let k=2. Then $\gamma'(t_0)=(\nabla\gamma)(t_0)=0$. By Lemma 2.4 of [9], we have $\gamma''(t_0)=(\nabla^2\gamma)(t_0)\neq 0, \gamma'''(t_0)=(\nabla^3\gamma)(t_0)$. Let $k\geq 3$. Then $(\nabla^k\gamma)^{\lambda}$ is a sum of $(\gamma^{(k)})^{\lambda}$ and a polynomial of $\Gamma^{\lambda}_{\mu\nu}$, their partial derivatives and $\gamma^{(i)}, i< k$, each monomial of which contains a $\gamma^{(i)}$ with $i\leq k-2$ (cf. Lemma 2.4 of [9]). Thus we have $\gamma^{(i)}(t_0)=(\nabla^i\gamma)(t_0)=0, 1\leq i< k$. Moreover we have $0\neq (\nabla^k\gamma)(t_0)=\gamma^{(k)}(t_0)$ and $(\nabla^{k+1}\gamma)(t_0)=\gamma^{(k+1)}(t_0)$.

(3) We have that $c(t)u(t) = \gamma'(t)$ for some function c(t). If $k \geq 2$, then $c(t_0) = 0$. By operating $\nabla_{\partial/\partial t}^{\gamma}$ to both sides of $c(t)u(t) = \gamma'(t)$, we have

$$c'(t)u(t) + c(t)(\nabla_{\partial/\partial t}^{\gamma} u)(t) = (\nabla^2 \gamma)(t).$$

If $k \geq 3$, then $c(t_0) = 0$, $c'(t_0) = 0$. In general we have

$$c(t_0) = c'(t_0) = \dots = c^{(k-2)}(t_0) = 0, c^{(k-1)}(t_0) \neq 0,$$

and

(2) is clear.

$$\begin{array}{rcl} c^{(k-1)}(t)u(t) + (k-1)c^{(k-2)}(t)(\nabla u)(t) + {}_{k-1}C_2c^{(k-3)}(t)(\nabla^2 u)(t) + \cdots & = & (\nabla^k\gamma)(t) \\ c^{(k)}(t)u(t) + kc^{(k-1)}(t)(\nabla u)(t) + {}_kC_2c^{(k-2)}(t)(\nabla^2 u)(t) + \cdots & = & (\nabla^{k+1}\gamma)(t) \\ \vdots & & \vdots & & \vdots \\ c^{(k+\ell-1)}(t)u(t) + \cdots + {}_{k+\ell-1}C_{k-1}c^{(k-1)}(t)(\nabla^\ell u)(t) + \cdots & = & (\nabla^{k+\ell}\gamma)(t). \end{array}$$

Evaluating at t_0 , we have the result.

Proof of Lemma 2.2. The case k=1 is proved in Lemma 3.1 of [9]. Therefor we suppose $k \geq 2$. Let u(t) be a frame around t_0 of the directed curve γ and $c(t)u(t) = \gamma'(t)$, $u(t_0) \neq 0$. (For instance $c(t) = k(t-t_0)^{k-1}$). Since $f(t,s) = \gamma(t) + su(t) + \frac{1}{2}s^2h(\gamma(t), u(t), s)$, we have

$$\begin{split} \frac{\partial f}{\partial t} &= \gamma' + su' + \frac{1}{2}s^2 (\gamma')^{\mu} \frac{\partial h}{\partial x^{\mu}} (\gamma, u, s) + \frac{1}{2}s^2 (u')^{\nu} \frac{\partial h}{\partial v^{\nu}} (\gamma, u, s), \\ \frac{\partial f}{\partial s} &= u + s h(\gamma, u, s) + \frac{1}{2}s^2 \frac{\partial h}{\partial s} (\gamma, u, s). \end{split}$$

Then we see that $S(f) \supseteq \{s = 0\}$ and the kernel field of f_* along $\{s = 0\}$ is given by $\eta = \frac{\partial}{\partial t} - c(t) \frac{\partial}{\partial s}$. Let $s \neq 0$. Then

$$\frac{1}{s}\left(\frac{\partial f}{\partial t} - c(t)\frac{\partial f}{\partial s}\right) = u' + \frac{1}{2}s\left(\gamma'\right)^{\mu}\frac{\partial h}{\partial x^{\mu}}(\gamma, u, s) + \frac{1}{2}s\left(u'\right)^{\nu}\frac{\partial h}{\partial v^{\nu}}(\gamma, u, s) - c(t)h(\gamma, u, s) - \frac{1}{2}sc(t)\frac{\partial h}{\partial s}(\gamma, u, s).$$

We define F(t,s) by the right hand side. Then $F(t,s) = \frac{1}{s}(\frac{\partial f}{\partial t} - c(t)\frac{\partial f}{\partial s})$ if $s \neq 0$. Moreover F is C^{∞} also on s = 0 and

$$F(t,0) = u'(t) - c(t)h(\gamma(t), u(t), 0).$$

By Lemmas 2.1 and 2.2 of [9],

$$F(t,0) = u'(t) + c(t)\Gamma^{\lambda}_{\mu\nu}(\gamma(t)) (u(t))^{\mu} (u(t))^{\nu} = (\nabla^{\gamma}_{\partial/\partial t} u)(t).$$

By Lemma 2.3 (3), if $(\nabla^k \gamma)(t_0)$, $(\nabla^{k+1} \gamma)(t_0)$ are linearly independent, then $\frac{\partial f}{\partial s}(t,s)$ and F(t,s) are linearly independent around $(t_0,0)$. Moreover they satisfies

$$(\frac{\partial f}{\partial t} \wedge \frac{\partial f}{\partial s})(t,s) = -s(\frac{\partial f}{\partial s} \wedge F)(t,s).$$

Therefore we see that $\frac{\partial f}{\partial s}(t,s)$ and F(t,s) define an integral lifting of f, f is frontal with non-degenerate singular point at $(t_0,0)$, and that $S(f)=\{s=0\}$.

3 Swallowtails and open swallowtails

Let $g: (\mathbf{R}^n, p) \to (\mathbf{R}^\ell, q)$ be a map-germ. A map germ $f: (\mathbf{R}^n, p) \to \mathbf{R}^{\ell+r}$ is called an *opening* of g if f is of form $f = (g, h_1, \ldots, h_r)$ for some functions $h_1, \ldots, h_r: (\mathbf{R}^n, p) \to \mathbf{R}$ satisfying

$$dh_i = \sum_{j=1}^{\ell} a_{ij} dg_j,$$

for some functions $a_{ij}: (\mathbf{R}^n, p) \to \mathbf{R}, (1 \leq i \leq r, 1 \leq j \leq \ell)$ (see for example [7]). If $\ell = n$, then the condition on h is equivalent to that f is frontal associated with an integral lifting $\widetilde{f}: (\mathbf{R}^n, p) \to \operatorname{Gr}(n, T\mathbf{R}^{n+r})$ having Grassmannian coordinates (a_{ij}) such that $\widetilde{f}(p)$ projects isomorphically to $T_{g(p)}\mathbf{R}^n$ by the projection $\mathbf{R}^{n+r} = \mathbf{R}^n \times \mathbf{R}^r \to \mathbf{R}^n$.

Based on results in [11] and [7], we summarize the characterization results on openings of the Whitney's cusp map-germ:

Theorem 3.1 Let $f: (\mathbf{R}^2, p) \to M^m, m \geq 2$ be a germ of frontal with a non-degenerate singular point at $p, V_1, V_2: (\mathbf{R}^2, p) \to TM$ an associated frame with \widetilde{f} with $V_2(p) \notin f_*(T_p\mathbf{R}^2)$, and $\eta: (\mathbf{R}^2, p) \to T\mathbf{R}^2$ an extension of a kernel field along of f_* . Let $c: (\mathbf{R}, t_0) \to (\mathbf{R}^2, p)$ be a parametrization of the singular locus of f. Set $\gamma = f \circ c: (\mathbf{R}, t_0) \to M$. Suppose $(\nabla \gamma)(t_0) = 0$ and $(\nabla^2 \gamma)(t_0) \neq 0$. Then f is diffeomorphic to an opening of Whitney's cusp, the germ defined by $(u, t) \mapsto (u, t^3 + ut)$. Moreover we have

- (0) Let m = 2. Then f is diffeomorphic to Whitney's cusp.
- (1) Let m = 3. Then f is diffeomorphic to the swallowtail if and only if

$$V_1(c(t_0)), \ V_2(c(t_0)), \ (\nabla_{\eta}^f V_2)(c(t_0))$$

are linearly independent in $T_{f(p)}M$.

(2) Let $m \geq 4$. Then f is diffeomorphic to the open swallowtail if and only if

$$(V_1 \circ c)(t_0), \ (V_2 \circ c)(t_0), \ ((\nabla^f_{\eta} V_2) \circ c)(t_0), \ (\nabla^{\gamma}_{\partial/\partial t}((\nabla^f_{\eta} V_2) \circ c))(t_0)$$

are linearly independent in $T_{f(p)}M$.

Here ∇_{η}^{f} means the covariant derivative by a vector field η along a mapping f (see [9][10]).

Proof: The assertion (0) follows from Whitney's theorem (also see [14][13][12]). (1) follows from Proposition 1.3 of [11]. In general cases $m \geq 2$, we see that there exists a submersion $\pi: (M, f(p)) \to (\mathbf{R}^2, 0)$ such that $\pi^{-1}(0)$ is transverse to $\widetilde{f}(0) \subset T_{f(p)}M$, $\pi \circ f$ satisfies the same condition with f, namely, that $\pi \circ f$ is a frontal with the non-degenerate singular point at p and with the same singular locus with f and $f(c(t_0))$ and $f(t_0)$ are linearly independent, but $f(t_0)$ are linearly independent.

Let $f(u,t) = (u,t^3+ut,h_1(u,t),\ldots,h_r(u,t)), m=2+r$ and $dh_i = a_i du + b_i d(t^3+ut) = (a_i+tb_i)du + (3t^2+u)b_i dt$, for some functions $a_i = a_i(u,t), b_i = b_i(u,t), 1 \le i \le r$. Then we have

$$\frac{\partial f}{\partial u} = (1, t, a_1 + tb_1, \dots, a_r + tb_r), \quad \frac{\partial f}{\partial t} = (0, 3t^2 + u, (3t^2 + u)b_1, \dots, (3t^2 + u)b_r),$$

a frame $V_1 = \frac{\partial f}{\partial u}$, $V_2 = \frac{1}{3t^2 + u} \frac{\partial f}{\partial t} = (0, 1, b_1, \dots, b_r)$ of the frontal f, and a kernel field $\eta = \frac{\partial}{\partial t}$ of f_* . We have

$$V_1(0,0) = (1,0,a_1(0,0),\dots,a_r(0,0)), \quad V_2(0,0) = (0,1,b_1(0,0),\dots,b_r(0,0)),$$
$$(\nabla_{\eta}^f V_2)(0,0) = (0,0,\frac{\partial b_1}{\partial t}(0,0),\dots,\frac{\partial b_r}{\partial t}(0,0)).$$

Let $c(t) = (-3t^2, t)$. Then $\gamma(t) = f(c(t)) = (-3t^2, -2t^3, h_1(-3t^2, t), \dots, h_r(-3t^2, t))$ and

$$\nabla_{\eta}^{f} V_{2}(c(t)) = (0, 0, \frac{\partial b_{1}}{\partial t}(c(t)), \dots, \frac{\partial b_{r}}{\partial t}(c(t))).$$

Then we have

$$\nabla_{\partial/\partial t}^{\gamma}((\nabla_{\eta}^{f}V_{2})\circ c)|_{t=0}=(0,0,\frac{\partial^{2}b_{1}}{\partial t^{2}}(0,0),\dots,\frac{\partial^{2}b_{r}}{\partial t^{2}}(0,0)).$$

Thus the condition of (2) is equivalent, in our case, to that f is a versal opening of $\pi \circ f$ and then we see f is diffeomorphic to the open swallowtail (see Proposition 6.8 (3) $\ell = 3$ of [7]). Thus we have the characterization (2).

Proof of Theorem 1.3. Theorem 1.3 (1) is proved in [9] in regular case (§7 of [9]). Suppose that $\gamma: I \to M$ is not an immersion at t_0 , $\gamma'(t_0) = 0$, but $\gamma''(t_0) \neq 0$. Let $c(t)u(t) = \gamma'(t)$, $u(t_0) \neq 0$. Then the ∇ -tangent surface is defined by $f(t,s) = \varphi(\gamma(t), u(t), s)$ using the geodesics $\varphi(x, v, s)$ on TM. Then we have the frame

$$V_1(t,s) = \frac{\partial f}{\partial s}(t,s), \quad V_2(t,s) = F(t,s) = \frac{1}{s}(\frac{\partial f}{\partial t} - c(t)\frac{\partial f}{\partial s}).$$

We set $\eta = \frac{\partial}{\partial t} - c(t) \frac{\partial}{\partial s}$. Then, by Lemma 5.1 of [9], we have $(\nabla_{\eta}^f F)(t,0) = (\nabla_{\partial/\partial t}^{\gamma^2} u)(t)$. Therefore we have $\nabla_{\partial/\partial t}^{\gamma}((\nabla_{\eta}^f F)(t,0)) = (\nabla_{\partial/\partial t}^{\gamma^3} u)(t)$. Now, by Lemma 2.3,

$$V_1(t_0,0), V_2(t_0,0), (\nabla_{\eta}^f F)(t_0,0)$$

are linearly independent if and only if $u(t_0)$, $(\nabla_{\partial/\partial t}^{\gamma}u)(t_0)$, $(\nabla_{\partial/\partial t}^{\gamma}u)(t_0)$ are linearly independent, and the condition is equivalent to that $(\nabla^2\gamma)(t_0)$, $(\nabla^3\gamma)(t_0)$, $(\nabla^4\gamma)(t_0)$ are linearly independent. Then in the case m=3, by Theorem 3.1 (1), we have Theorem 1.3 (1) for non-regular case as well.

Let $m \geq 4$. Then $V_1(t_0,0), V_2(t_0,0), (\nabla_{\eta}^f F)(t_0,0), \nabla_{\partial/\partial t}^{\gamma}((\nabla_{\eta}^f F)(t,0))|_{t=t_0}$ are linearly independent if and only if $u(t_0), (\nabla_{\partial/\partial t}^{\gamma} u)(t_0), (\nabla_{\partial/\partial t}^{\gamma^2} u)(t_0), (\nabla_{\partial/\partial t}^{\gamma^3} u)(t_0)$ are linearly independent, and the condition is equivalent to that $(\nabla^2 \gamma)(t_0), (\nabla^3 \gamma)(t_0), (\nabla^4 \gamma)(t_0), (\nabla^5 \gamma)(t_0)$ are linearly independent. By Theorem 3.1 (2), we have Theorem 1.3 (2).

4 Perturbations of directed curves

To treat directed curves (see §2), we consider PTM = Gr(1,TM) with the natural projection $\pi: PTM \to M$ and the tautological subbundle $D \subset TPTM$ on the tangent bundle of PTM: For any $(x,\ell) \in PTM$ and for any $v \in T_{(x,\ell)}PTM$, $v \in D_{(x,\ell)}$ if and only if $\pi_*(v) \in \ell \subset T_xM$. A curve $\widetilde{\gamma}: I \to PTM$ is called integral if $\widetilde{\gamma}_*(\partial/\partial t) \in D_{\widetilde{\gamma}(t)}$, for any $t \in I$. Recall that $\gamma = \pi \circ \widetilde{\gamma}$ with the lifting $\widetilde{\gamma}$ is called a directed curve.

Let $u: I \to TM$ be a vector field along a curve $\gamma: I \to M$. For $t_0 \in I$, we set

$$b_i := \inf \left\{ k \mid \operatorname{rank} \left(u(t_0), (\nabla_{\partial/\partial t}^{\gamma} u)(t_0), \dots, ((\nabla_{\partial/\partial t}^{\gamma})^{k-1} u)(t_0) \right) = i \right\}.$$

We have $1 \le b_1 < b_2 < \dots < b_m$, if each $b_i < \infty$. Then we call the strictly increasing sequence (b_1, b_2, \dots, b_m) of natural numbers the ∇ -type of u at t_0 .

Moreover the ∇ -type of a curve $\gamma: I \to M$ itself is defined by the ∇ -type of the velocity vector field $\gamma': I \to TM$ along γ .

Let $\gamma: (\mathbf{R}, t_0) \to M$ be a germ of directed curve with an integral lifting $\widetilde{\gamma}: (\mathbf{R}, t_0) \to PTM$ generated by a frame $u: (\mathbf{R}, t_0) \to TM$, $u(t_0) \neq 0$. Then $b_1 = 1$ for u, since $u(t_0) \neq 0$.

Then we have

Proposition 4.1 Let M be a manifold of dimension m with an affine connection ∇ . Then there exists an open dense subset \mathcal{O} in the space of C^{∞} integral curves $I \to PTM$ with Whitney C^{∞} topology such that for any $\widetilde{\gamma} \in \mathcal{O}$ and for any $t_0 \in I$, $\gamma = \pi \circ \widetilde{\gamma} : I \to M$ is of ∇ -type

$$(1,2,3),(1,2,4), \text{ or } (2,3,4),$$

if $m = \dim(M) = 3$, and

$$(1, 2, 3, 4, \dots, m-1, m), (1, 2, 3, 4, \dots, m-1, m+1), \text{ or } (2, 3, 4, 5, \dots, m, m+1).$$

if m > 4, at t_0 .

To show Proposition 4.1, we use the following generalization of Lemma 2.3 (3):

Lemma 4.2 If ∇ -type of u is $(1, b_2, \dots, b_m)$ and the order of c at t_0 is ℓ , that is, $c(t_0) = \dots = c^{(\ell-1)}(t_0) = 0$, $c^{(\ell)}(t_0) \neq 0$, then γ is of ∇ -type $(a_1, a_2, \dots, a_m) = (1 + \ell, b_2 + \ell, \dots, b_m + \ell)$.

Proof: By taking covariant derivative ∇ ℓ -times of the both sides of $c(t)u(t) = \gamma'(t)$, we have $(\nabla \gamma)(t_0) = \cdots = (\nabla^{\ell} \gamma)(t_0) = 0, (\nabla^{\ell+1} \gamma)(t_0) = c^{(\ell)}(t_0)u(t_0) \neq 0$. Then

$$\operatorname{rank}\left((\nabla\gamma)(t_0),\dots,(\nabla^{\ell}\gamma)(t_0),(\nabla^{\ell+1}\gamma)(t_0)\right)=\operatorname{rank}\left(c^{(\ell)}(t_0)u(t_0)\right)=1,$$

and we have $a_1 = 1 + \ell$. Moreover we have

$$\operatorname{rank}\left((\nabla \gamma)(t_0), \dots, (\nabla^{\ell} \gamma)(t_0), (\nabla^{\ell+1} \gamma)(t_0), (\nabla^{\ell+2} \gamma)(t_0)\right) = \operatorname{rank}\left((\nabla^{\ell+1} \gamma)(t_0), (\nabla^{\ell+2} \gamma)(t_0)\right)$$

$$= \operatorname{rank}\left(c^{(\ell)}(t_0)u(t_0), c^{(\ell+1)}(t_0)u(t_0) + (\ell+1)c^{(\ell)}(t_0)\nabla u(t_0)\right) = \operatorname{rank}\left(u(t_0), \nabla u(t_0)\right).$$

In general, we have inductively

$$\operatorname{rank}\left((\nabla\gamma)(t_0),(\nabla^2\gamma)(t_0),\ldots,(\nabla^k\gamma)(t_0)\right) = \operatorname{rank}\left(u(t_0),(\nabla u)(t_0),\ldots,(\nabla^{k-\ell-1}u)(t_0)\right),$$

for any $k \geq 1 + \ell$. Therefore we have $a_i = b_i + \ell, 1 \leq i \leq m$.

We need also the following lemma on local perturbations of integral curves.

Lemma 4.3 Let $a < t_1 < t_2 < b$ and $\widetilde{\gamma}, \widetilde{\alpha} : (a,b) \to PT\mathbf{R}^m$ be integral curves. Then there exists an integral curve $\widetilde{\beta} : (a,b) \to PT\mathbf{R}^m$ such that $\widetilde{\beta}(t) = \widetilde{\alpha}(t), a < t \le t_1$ and $\widetilde{\beta}(t) = \widetilde{\gamma}(t), t_2 \le t < b$. If $\widetilde{\alpha}$ is sufficiently close to $\widetilde{\gamma}$ on $[t_1, t_2]$ in Whitney C^{∞} topology, then $\widetilde{\beta}$ can be taken to be close to $\widetilde{\gamma}$ on (a,b) in Whitney C^{∞} topology.

Proof: Let $x = (x^{\lambda})$ be a system of coordinates of \mathbf{R}^m and $(x, \xi) = (x^{\lambda}, \xi_{\lambda})$ be the associated system of coordinates of $T\mathbf{R}^m$. Let $(x \circ \widetilde{\gamma})'(t) = c(t)u(t)$, $(x \circ \widetilde{\alpha})'(t) = e(t)v(t)$, for some $c, e : (a, b) \to \mathbf{R}$ and $u, v : (a, b) \to \mathbf{R}^m \setminus \{0\}$. Then we take a function $f : (a, b) \to \mathbf{R}$ and $w : (a, b) \to \mathbf{R}^m$ such that f(t) = e(t) on $(a, t_1]$, f(t) = c(t) on $[t_2, b)$, w(t) = v(t) on $[a, t_1]$, w(t) = u(t) on $[t_2, b)$ and

$$\int_{t_1}^{t_2} f(t)w(t)dt = (x \circ \widetilde{\gamma})(t_1) - (x \circ \widetilde{\alpha})(t_1) + \int_{t_1}^{t_2} c(t)u(t)dt.$$

Then we have the required $\widetilde{\beta}$ by $(\xi \circ \widetilde{\beta})(t) = w(t)$ and

$$(x \circ \widetilde{\beta})(t) = (x \circ \widetilde{\alpha})(t_1) + \int_{t_1}^t f(t)w(t)dt, \quad (a < t < b).$$

Proof of Proposition 4.1. Let $\tilde{\gamma}: (\mathbf{R}, t_0) \to PTM$ be a germ of integral curve with $\gamma = \pi \circ \tilde{\gamma}$. Let $c(t)u(t) = \gamma'(t)$ for some frame $u: (\mathbf{R}, t_0) \to TM$ along $\gamma, u(t_0) \neq 0$, and for some function $c: (\mathbf{R}, t_0) \to \mathbf{R}$. Note that $\tilde{\gamma}$ is determined by the frame u. The frame u is determined up to the multiplication of functions b(t) with $b(t_0) \neq 0$. Given the initial point $q = \gamma(t_0)$, the pair (u, c) determines the directed curve γ uniquely. Moreover $(\nabla^k u)(t_0) = u^{(k)}(t_0) + Q$, by a polynomial Q of $u^{(i)}(t_0), c^{(i)}(t_0), 0 \leq i < k$ and $(\partial^{\alpha}\Gamma^{\lambda}_{\mu\nu}/\partial x^{\alpha})(q), |\alpha| \leq k-1$. In particular $(\nabla^k u)(t_0)$ depends only on k-jet of (c, u) and just on the position $q = \gamma(t_0)$.

Let us consider the r-jet bundle $J^r(I, \mathbf{R} \times (TM \setminus \zeta))$ over $I \times \mathbf{R} \times (TM \setminus \zeta)$, where ζ is the zero-section. For the projection $I \times \mathbf{R} \times (TM \setminus \zeta) \to I \times M$, take the fibre $J^r(I, \mathbf{R} \times (TM \setminus \zeta))_{(t_0,q)}$ over a $(t_0, q) \in I \times M$, and consider the set

$$S_{\nabla} := \{ j^{r}(c, u)(t_{0}) \mid u(t_{0}), (\nabla u)(t_{0}), \dots, (\nabla^{m-1}u)(t_{0}) \text{ are linearly dependent}$$
 and $u(t_{0}), (\nabla u)(t_{0}), \dots, (\nabla^{m-2}u)(t_{0}), (\nabla^{m}u)(t_{0}) \text{ are linearly dependent} \}.$

$$S_{\nabla}' := \{ j^{r}(c, u)(t_{0}) \mid u(t_{0}), (\nabla u)(t_{0}), \dots, (\nabla^{m-1}u)(t_{0}) \text{ are linearly dependent}$$
 and $c(t_{0}) = 0 \}.$

$$S_{\nabla}'' := \{ j^{r}(c, u)(t_{0}) \mid c(t_{0}) = c'(t_{0}) = 0 \}.$$

Then, for any but fixed system of local coordinates around q of M, $S_{\nabla}, S'_{\nabla}, S''_{\nabla}$ are algebraic sets of codimension ≥ 2 . Let $S_{\nabla}(I, M), S'_{\nabla}(I, M), S''_{\nabla}(I, M)$ be the corresponding subbundle of $J^r(I, \mathbf{R} \times (TM \setminus \zeta))$ over $I \times M$. For any subinterval $J \subset I$, we set

$$\widetilde{\mathcal{O}}_J := \{ (c, u) : I \to \mathbf{R} \times (TM \setminus \zeta) \mid j^r(c, u) : I \to J^r(I, \mathbf{R} \times (TM \setminus \zeta))$$
 is transverse to $S_{\nabla}(I, M), S'_{\nabla}(I, M), S''_{\nabla}(I, M)$ over $J \}.$

Then $\widetilde{\mathcal{O}} = \widetilde{\mathcal{O}}_I$ is open dense in Whitney C^{∞} topology. Let $(c,u) \in \widetilde{\mathcal{O}}$ and $t_0 \in I$. Then $j^r(c,u)(t_0) \notin S_{\nabla} \cup S'_{\nabla} \cup S''_{\nabla}$. Since $j^r(c,u)(t_0) \notin S_{\nabla}$, we have that the ∇ -type of u is $(1,2,\ldots,m-1,m)$ or $(1,2,\ldots,m-1,m+1)$. Since $j^r(c,u)(t_0) \notin S'_{\nabla}$, if $c(t_0) = 0$ then ∇ -type of u must

be (1, 2, ..., m - 1, m). On the other hand, since $j^r(c, u)(t_0) \notin S_{\nabla}''$, we have that $c(t_0) \neq 0$ or $c(t_0) = 0, c'(t_0) \neq 0$, i.e. the order of c at t_0 is 0 or 1. We set

$$\mathcal{O}_J := \{ \widetilde{\gamma} : I \to PTM \text{ integral } | \exists (c, u) \in \widetilde{\mathcal{O}}_J, \ \widetilde{\gamma}(t) = \langle u(t) \rangle_{\mathbf{R}}, (\pi \circ \widetilde{\gamma})'(t) = c(t)u(t) \}.$$

We will show, for any compact subinterval $J \subset I$, that \mathcal{O}_J is open dense and $\mathcal{O} = \mathcal{O}_I$ is open dense in the space of integral curves with Whitney C^{∞} topology.

That \mathcal{O}_J and \mathcal{O} are open is clear, since \mathcal{O} is open.

We will show \mathcal{O}_J is dense. Let $\widetilde{\gamma}: I \to PTM$ be any integral curve and \mathcal{I} be any open neighbourhood of $\widetilde{\gamma}$. We will show $\mathcal{O}_J \cap \mathcal{I} \neq \emptyset$. Set $\gamma = \pi \circ \widetilde{\gamma} : I \to M$. Take any frame uassociated to $\widetilde{\gamma}$. Then there exists uniquely $c: I \to \mathbf{R}$ which satisfies $c(t)u(t) = \gamma'(t), t \in I$. Take a compact subinterval $J' \subset I$ such that $J \subseteq J'$. We approximate (c, u) by some $(e, v) \in \mathcal{O}_J$ and that (e,v)=(c,u) outside of J'. Then v generates a curve $\rho:I\to PTM, \rho(t)=\langle v(t)\rangle_{\mathbf{R}}$, which approximates $\tilde{\gamma}$, however ρ may not be an integral curve. Consider the vector field $(\frac{\partial}{\partial t}, ev)$ along the graph of $\pi \circ \rho$ in $I \times M$. Extend $(\frac{\partial}{\partial t}, v(t))$ to a vector field $(\frac{\partial}{\partial t}, V(t, x))$ over $I \times M$ with a support contained in $I \times K$ for some compact $K \subset M$. Take $t_0 \in J$. Take the integral curve $\alpha: I \to M$ of the vector field $(\frac{\partial}{\partial t}, e(t)V(t, x))$ through $(t_0, \alpha(t_0))$. Then $\alpha'(t) = e(t)V(t, \alpha(t))$. Define the vector field $w: I \to TM$ over α by $w(t) = V(t, \alpha(t))$. Then we have $\alpha'(t) = e(t)w(t)$. If we choose (e,v) sufficiently close to (c,u), then $w(t) \neq 0$ and $(e,w) \in \mathcal{O}_J$. However the integral curve $\widetilde{\alpha}$ defined by w may not belong to \mathcal{I} , which is an open set for Whitney C^{∞} topology. Further we modify the perturbation (e, v) over $J' \setminus J$ and the extension V over $(J' \setminus J) \times M$ to obtain an integral curve β such that $\beta = \widetilde{\alpha}$ on J and $\beta = \widetilde{\gamma}$ outside of J', using the method of Lemma 4.3. Then the integral curve β approximates $\tilde{\gamma}$ and belongs to \mathcal{I} , while $(e,w)\in\mathcal{O}_J$. Since $\beta(t)=\langle w(t)\rangle_{\mathbf{R}}$ and $(\pi\circ\beta)'(t)=e(t)w(t)$, we have $\beta\in\mathcal{O}_J\cap\mathcal{I}$. Thus we have seen that \mathcal{O}_J is dense, for any compact subinterval $J \subset I$.

Since $\mathcal{O} = \cap_{J \subset I} \mathcal{O}_J$, the intersection over compact subintervals $J \subset I$, we have that \mathcal{O} is residual, and therefore that \mathcal{O} is dense in Whitney C^{∞} topology [5].

Thus we have that \mathcal{O} is open dense in Whitney C^{∞} topology. Then, using Lemma 4.2, we have the required result.

Remark 4.4 By the same method as above, we have that the codimension of jets of integral curves such that the projections are of ∇ -type (a_1, a_2, \ldots, a_m) is given by

$$\ell + \sum_{i=1}^{m} (b_i - i) = a_1 - 1 + \sum_{i=2}^{m} (a_i - a_1 - i + 1),$$

for any affine connection ∇ . Note that the codimension is calculated in Theorem 5.6 of [7] in the flat case (cf. Theorem 5.8, Theorem 3.3 of [7]).

Proof of Theorem 1.2. We observe that the equation on geodesics

$$\frac{\partial^2 \varphi}{\partial s^2}^{\lambda}(x, v, s) + \Gamma^{\lambda}_{\mu\nu}(\varphi(x, v, s)) \frac{\partial \varphi}{\partial s}^{\mu}(x, v, s) \frac{\partial \varphi}{\partial s}^{\nu}(x, v, s) = 0,$$

is symmetric on the indices μ, ν . Therefore the geodesics $\varphi(x, v, s)$ and the tangent surfaces ∇ -Tan (γ) remain same if the connection $\Gamma^{\lambda}_{\mu\nu}$ is replaced by the torsion free connection $\frac{1}{2}(\Gamma^{\lambda}_{\mu\nu} + \Gamma^{\lambda}_{\nu\mu})$, in other word, if ∇ is replaced by the torsion free connection $\widetilde{\nabla}$, defined by $\widetilde{\nabla}_X Y = \nabla_X Y - \frac{1}{2}T(X,Y)$. Thus we may suppose ∇ is torsion free. Then Theorem 1.3 and Proposition 4.1 imply Theorem 1.2.

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