

$$z = f(x, y)$$

σ_x = error in variable x

σ_y = error in variable y

$$\sigma_z^2 = \left(\frac{\partial f}{\partial x} \right)^2 \sigma_x^2 + \left(\frac{\partial f}{\partial y} \right)^2 \sigma_y^2$$

↳ error in variable z

① $D_L = D_A (1+z)^2$ with σ_{D_A}, σ_z

$$D_L = f(D_A, z)$$

→

$$\sigma_{D_L}^2 = \left(\frac{\partial f}{\partial D_A} \right)^2 \sigma_{D_A}^2 + \left(\frac{\partial f}{\partial z} \right)^2 \sigma_z^2$$

$$= (1+z)^2 \sigma_{D_A}^2 + 2D_A(1+z) \sigma_z^2$$

② $L = 4\pi D_L^2 P_{\text{bol}}$ $L = f(D_L, P_{\text{bol}})$

→

$$\sigma_L^2 = \left(\frac{\partial f}{\partial D_L} \right)^2 \sigma_{D_L}^2 + \left(\frac{\partial f}{\partial P_{\text{bol}}} \right)^2 \sigma_{P_{\text{bol}}}^2$$

$$= 8\pi D_L P_{b010} \sigma_{D_L}^2 + 4\pi D_L^2 \sigma_{P_{b010}}^2$$

$$(3) \quad E_{ISO} = \frac{4\pi D_L^2 S_{b010}}{(1+z)}$$

$$E_{ISO} = f(D_L, S_{b010}, z)$$

$$\sigma_{E_{ISO}}^2 = \left(\frac{\partial f}{\partial D_L} \right)^2 \sigma_{D_L}^2 + \left(\frac{\partial f}{\partial S_{b010}} \right)^2 \sigma_{S_{b010}}^2 + \left(\frac{\partial f}{\partial z} \right)^2 \sigma_z^2$$

$$= \frac{8\pi D_L S_{b010}}{(1+z)} \sigma_{D_L}^2 + \frac{4\pi D_L^2}{(1+z)} \sigma_{S_{b010}}^2 - \frac{4\pi D_L^2 S_{b010}}{(1+z)^2} \sigma_z^2$$

④

$$E_r = E_{iso} \times F_{beam}$$

$$E_r = f(E_{iso}, F_{beam})$$

→

$$\sigma_{E_r}^2 = \left(\frac{\partial f}{\partial E_{iso}} \right)^2 \sigma_{E_{iso}}^2 + \left(\frac{\partial f}{\partial F_{beam}} \right)^2 \sigma_{F_{beam}}^2$$

$$= F_{beam} \sigma_{E_{iso}}^2 + E_{iso} \sigma_{F_{beam}}^2$$

