

CSE330: Numerical Methods

Topic: Hermite Polynomial,
Numerical Differentiation,
Central Difference

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☆ so far we have learned three methods of polynomial interpolation.

method-1: Vandermonde's method

reason: PC does not save function as function. It saves them as polynomial.

So we started guessing the function.

method-2: Lagrange polynomial

reason: In method-1, inversion of matrix needs to be done. But it is an inefficient operation for

P.C. so we learn lagrange, where no inversion of matrix is involved.

method-3: Newton's Polynomial

extra node add કરો newton's polynomial નો reusability નો ઉપયોગ reuse કરી શકો,

કરો Lagrange method દ્વારા મોંઘ

બાંધી શકો છો.

Today we learn method-4 (Hermite Interpolation) because it gives more accurate polynomial in same degree since it adds more terms.

Hermite Interpolation

$(n+1)$ points nodes \rightarrow degree n

$(n+1)$ points nodes $\rightarrow (n+1)$ equation/conditions

$(n+1)$ " nodes $\rightarrow (n+1)$ equations
 \hookrightarrow reason: derivative

$$\text{total number of equations} = \underbrace{2n+2}$$

$$(2n+2)-1 \text{ degree}$$

$$= 2n+1 \text{ degree}$$

so we will get P_{2n+1} and not P_n

So,

$$P_{2n+1}(x) = \sum_{k=0}^n \left\{ \underbrace{f(x_k) h_k(x)} + \underbrace{f'(x_k) \hat{h}_k(x)} \right\}$$

↓
hermite basis 2^{ζ}

where,

$$h_k(x) = \left[1 - 2(x - x_k) l'_k(x_k) \right] l_k^2(x)$$

and

$$\hat{h}_k(x) = (x - x_k) l_k^2(x)$$

$$P_{2n+1}(x) = \sum_{k=0}^n \left\{ f(x_k) h_k(x) + f'(x_k) \hat{h}_k(x) \right\}$$

$$\# f(x) = \sin x$$

$$x_0 = 0$$

$$x_1 = \frac{\pi}{2}$$

$$f(x_0) = 0$$

$$f(x_1) = 1$$

interpolate the polynomial using hermite polynomial.

solⁿ:

$$P_3(x) = f(x_0) h_0(x) + f'(x_0) \hat{h}_0(x) +$$

$\xrightarrow{2n+1}$

$$f(x_1) h_1(x) + f'(x_1) \hat{h}_1(x)$$

line $\frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) dx \Rightarrow$

$$= 0 + 1 \times \hat{h}_0(x) + 1 \times h_1(x) + 0$$

$$= \hat{h}_0(x) + h_1(x)$$

$$\text{so, } p_3(x) = x \left(1 - \frac{2x}{\pi}\right)^2 + \frac{4x^2}{\pi^2} \times \left(3 - \frac{4x}{\pi}\right)$$

now,

$$h_1(x) = \left[1 - 2(x - x_1) l_1'(x_1)\right] l_1^2(x)$$

here $l_1(x) = \frac{x - x_0}{x_1 - x_0}$

$$= \frac{x - 0}{\frac{\pi}{2} - 0}$$

$$= \frac{2x}{\pi}$$

$$l_1'(x) = \frac{2}{\pi} \quad ; \quad l_1'(\pi/2) = \frac{2}{\pi}$$

$$h_1(x) = \left[1 - 2\left(x - \frac{\pi}{2}\right) \times \frac{2}{\pi}\right] \times \frac{4x^2}{\pi^2}$$

not necessary $\rightarrow h_1(x) = \frac{4}{\pi^2} x^2 \left(3 - \frac{4x}{\pi}\right)$

now, $\hat{h}_0(x) = (x - x_k) l_k^2(x)$

again, $L_0(x) = \frac{x - x_1}{x_0 - x_1}$

$$= \frac{x - \pi/2}{0 - \frac{\pi}{2}}$$
$$= 1 - \frac{2x}{\pi}$$

$$\hat{h}_0(x) = (x - 0) \left(1 - \frac{2x}{\pi}\right)^2$$

Ans:

$$p_3(x) = x \left(1 - \frac{2x}{\pi}\right)^2 + \frac{4x^2}{\pi^2} \left(3 - \frac{4x}{\pi}\right)$$

previous question $\hookrightarrow P_3(10)=?$

— X —

End of chapter 2

Ch-3: Numerical

easy marks

Differentiation

$$f'(x) = \frac{f(x+h) - f(x)}{h} \quad \text{forward difference}$$

$$y = mx + c$$

↓
m / derivative



Backward difference

$$f'(x) = \frac{f(x) - f(x-h)}{h}$$

Que: $f(x) = x^3 - 4x + 1;$

$f'(x)$ ज्ञात करें using backward difference.

soln:

$$f'(x) = \frac{f(2) - f(2 - 0.1)}{0.1}$$

↑
numeric

derivative

$$= 7.41$$

error how?

$$\Rightarrow f'(x) = 3x^2 - 4$$

$$\begin{aligned} f'(2) &= 3(2)^2 - 4 \\ &= 8 \end{aligned}$$

$$\begin{aligned} \therefore \text{error} &= 8 - 7.41 \\ &= 0.59 \end{aligned}$$

relative error how?

Central Difference

$x, x+h, x-h$ ଓ h point use କରାଯାଏ

derivative of Accuracy total.

$$f'(x) = \frac{f(x+h) - f(x-h)}{2h}$$

$$\# f(x) = \ln(x) \quad , \quad x = 2$$

$$h = 1, 0.1, 0.01, 0.001$$

forward difference ज्ञात करें

derivative লস্ট error তেও কমে।

$$f'(x) = \frac{1}{x}$$

solⁿ: $f'(2) = 0.5$

also called
truncation error

h	$f'(x)$	error
1	0.405465	$ 0.5 - 0.4055 $ $= 0.09453$
0.1	0.4870	0.01209
0.01	0.4987	0.001245
0.001	0.499875	0.00012

forward / backward \rightarrow Error $\propto h$

central \rightarrow Error $\propto h^2$