

Introduction to Computer Vision



Taught by

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- Prof. Ender Konukoglu
- Guest starring by prof Orçun Göksel

The course comes with a course text that covers most – but not all ! – material.
Slide decks for all lectures will be made available on eDoz or similar

We got questions about which course to take

Computer Vision (D-INFK), or

Image Analysis and Computer vision (this course)

IN ANY CASE, DO NOT TAKE BOTH !

If you took the introductory course on CV at D-INFK,
then best take *Computer Vision*

If you did not take that course,
then best take *Image Analysis and Computer Vision*

... it is crucial ...

Vision is important

- ❑ half our brain is devoted to it
- ❑ developed many times during evolution
- ❑ it is non-contact
- ❑ it can be implemented with high resolution
- ❑ works with ambient E-M waves
- ❑ yields colour, texture, depth, motion, shape



The central take-home message:

For people vision is their most crucial sense, for good reason



Computer Vision

INTRO

perception
applications
light

... it is intriguing ...

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The perception of intensity

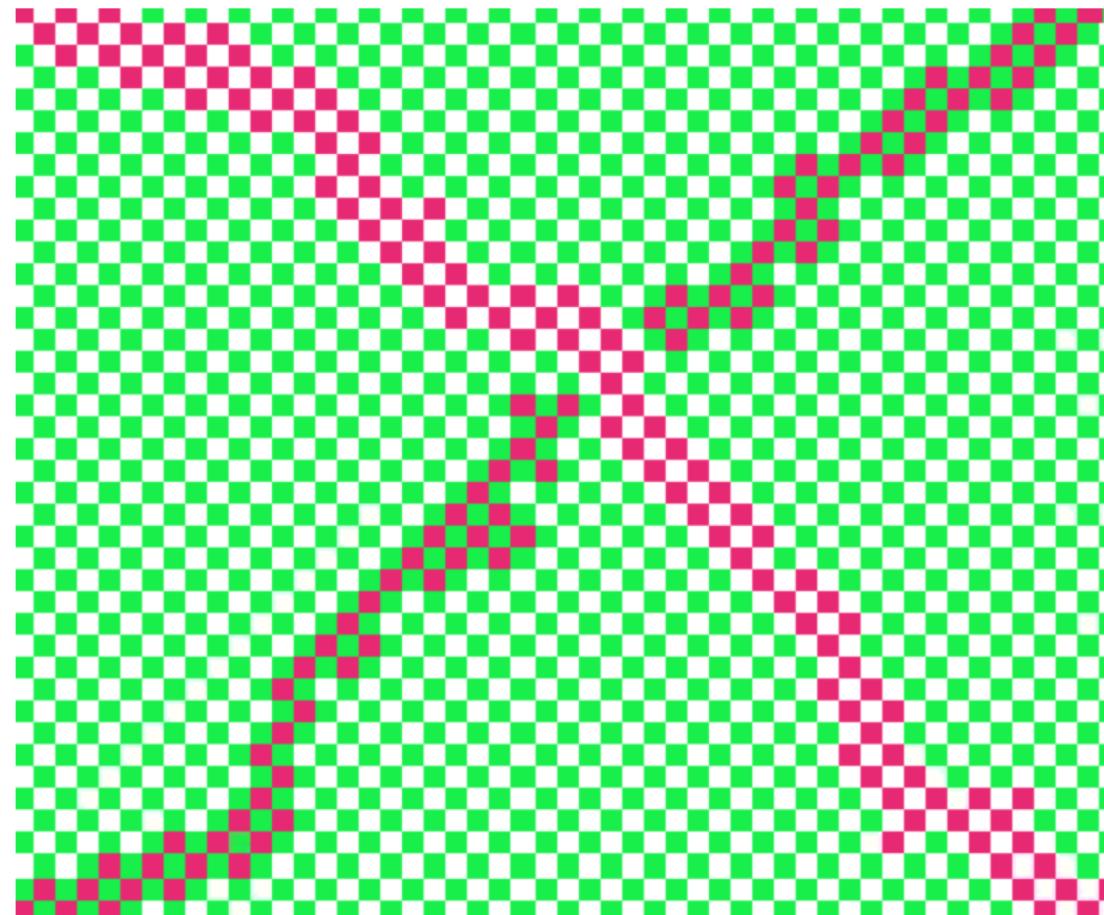


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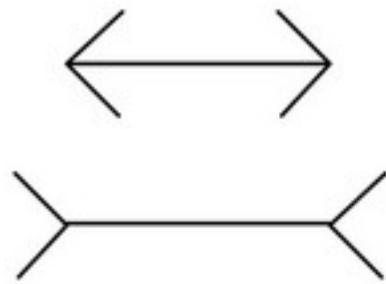
perception
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The perception of color

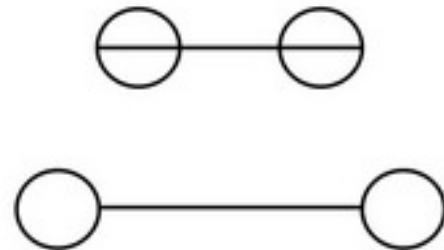


The red squares have equal color...

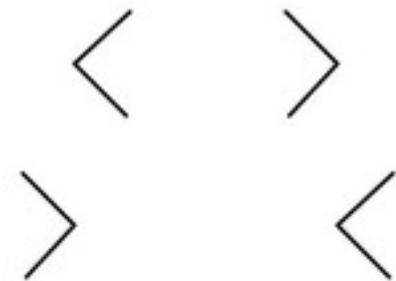
The perception of length



A



B



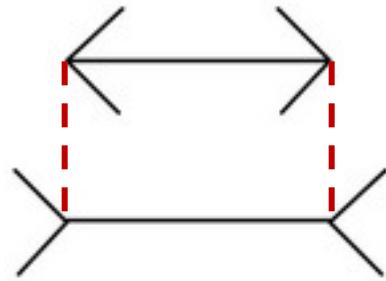
C

Computer Vision

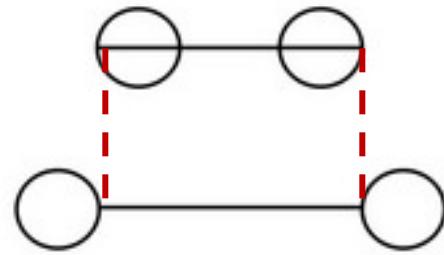
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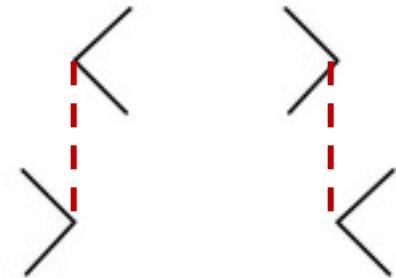
The perception of length



A



B



C

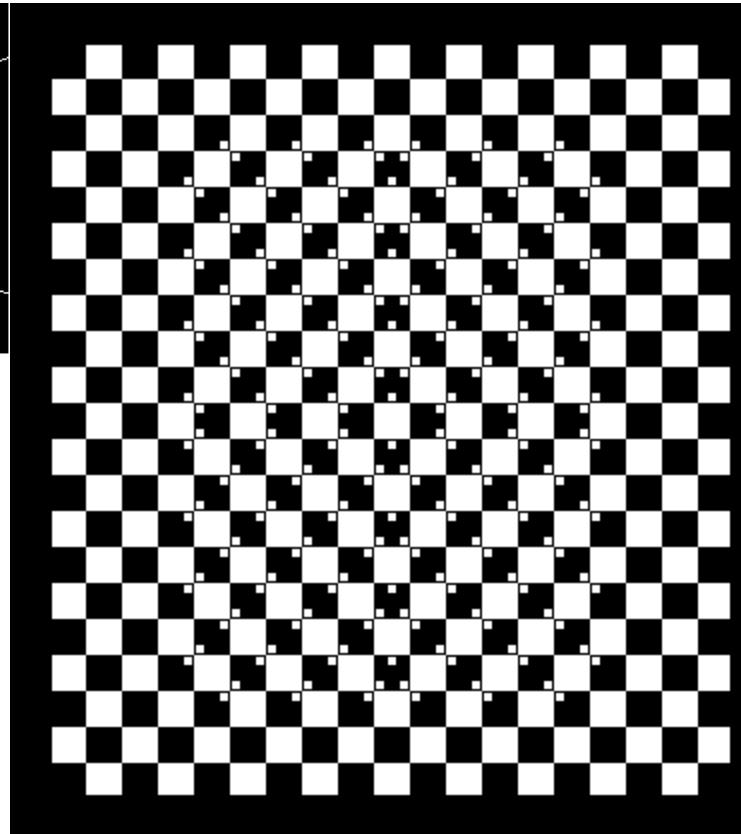
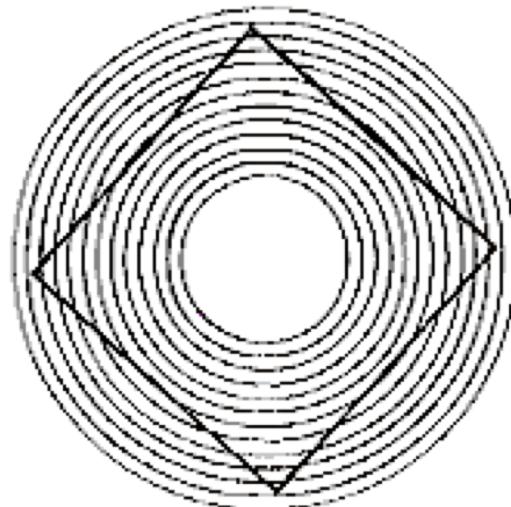
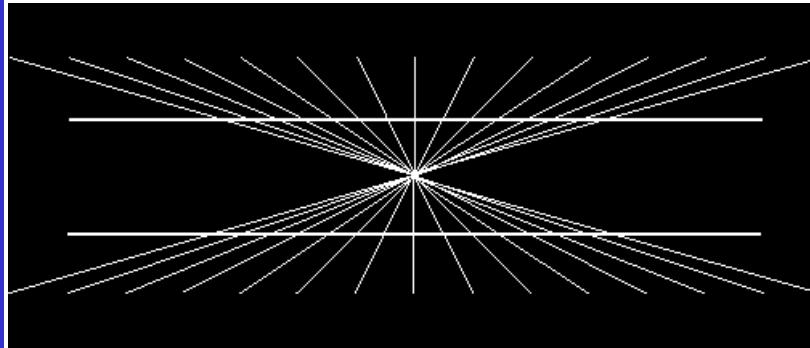
The horizontal lines are equally long...

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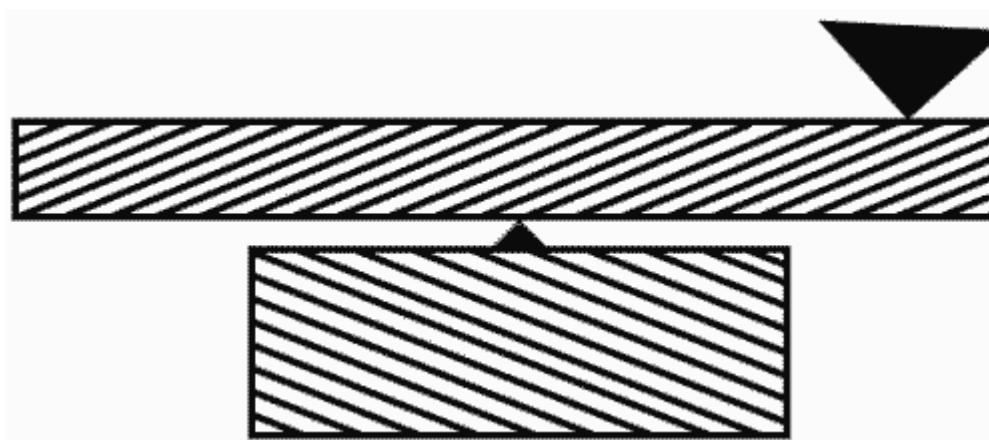
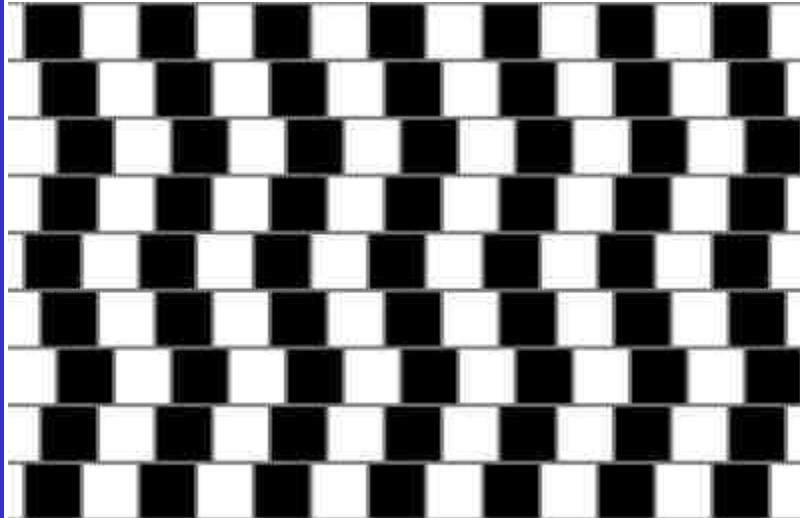
The perception of lines being straight



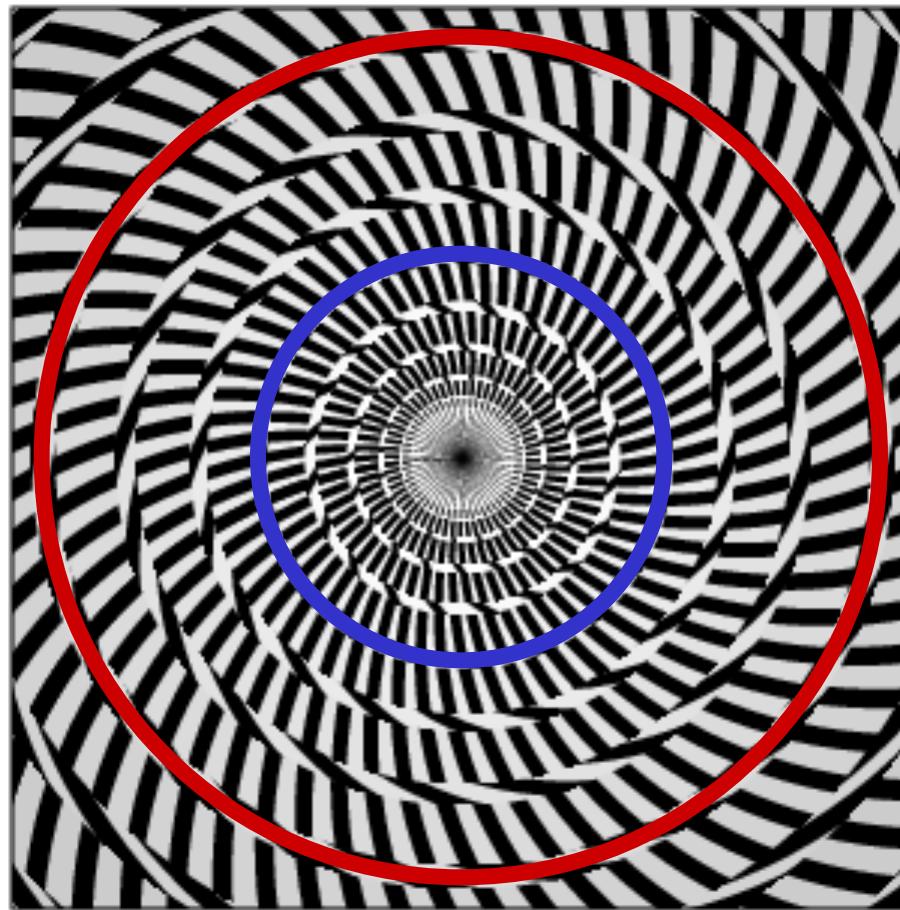
The perception of parallelism

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The perception of curvatures



Illusions : interference of differently oriented patterns via adaptation

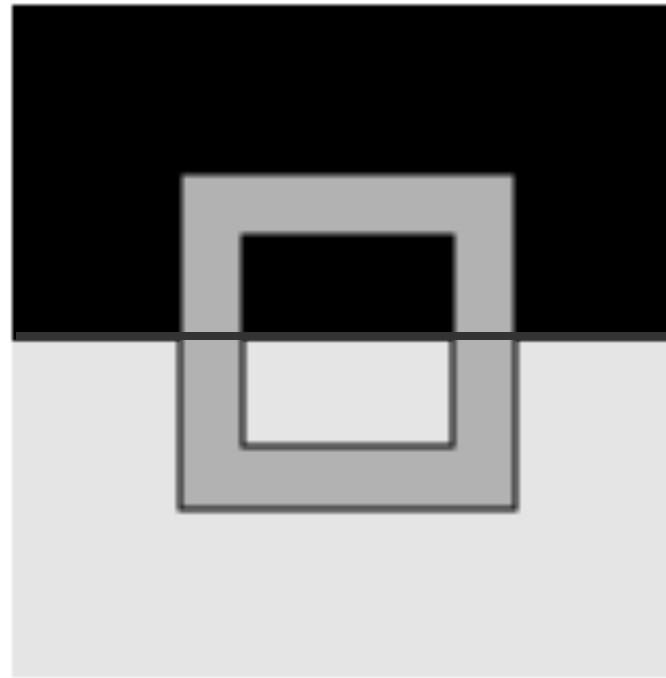
The perception of motion

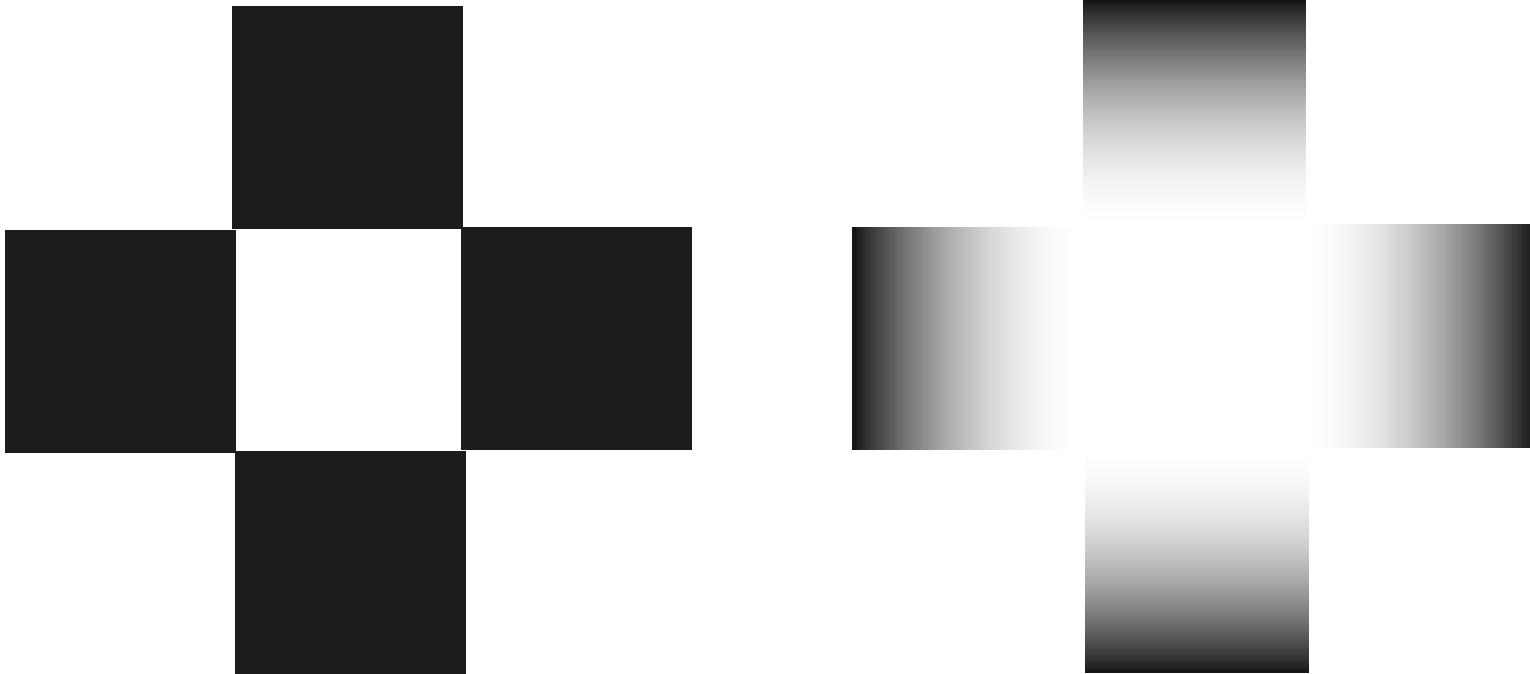


The 'barber pole' rotates about the vertical,
it does not translate vertically...

It's not that more context solves it all...

there is literally more than meets the eye,
i.e. a lot of massively parallel processing





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A

B

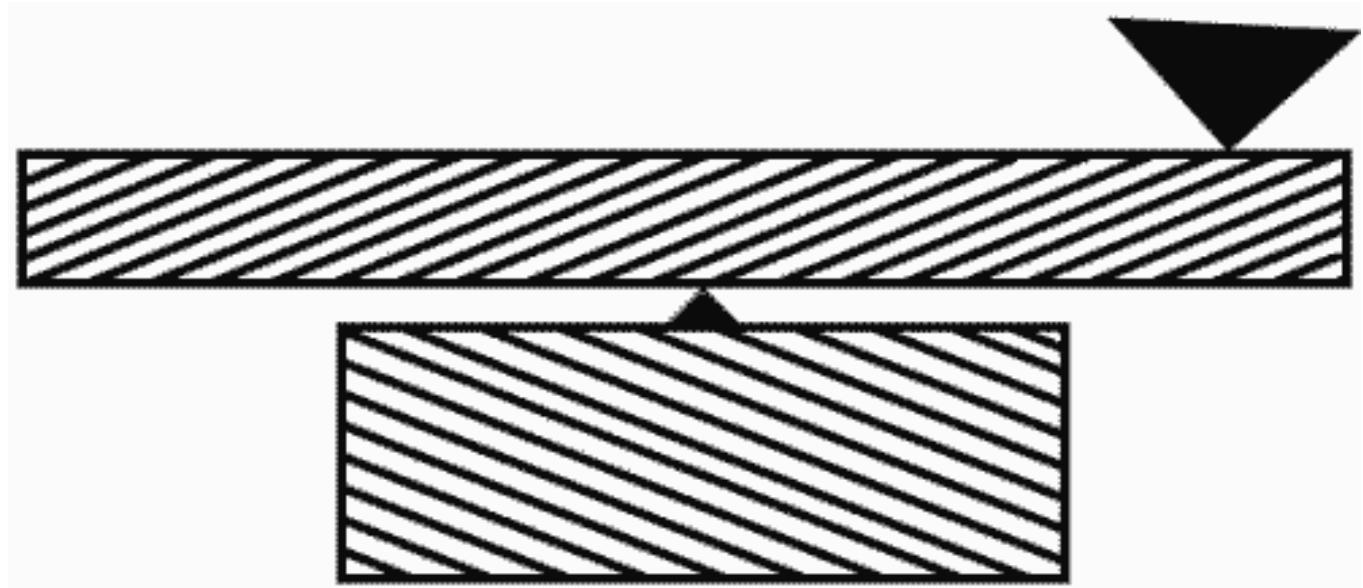


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Parallelism again...



Kanisza illusion

READ



Fill-in : averaging of perceived contrast at edges over regions possibly obtained via extrapolation of the edges... in any case *such illusion seems to help people to detect patterns in the world.*

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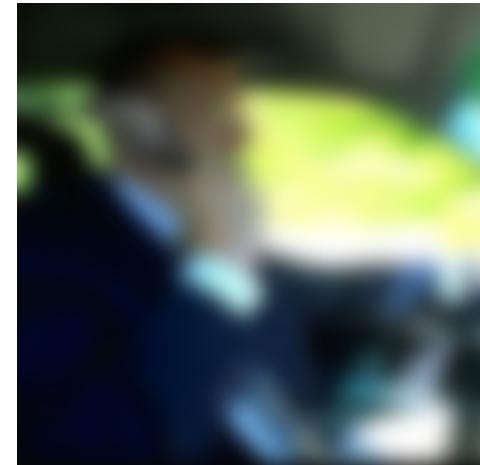
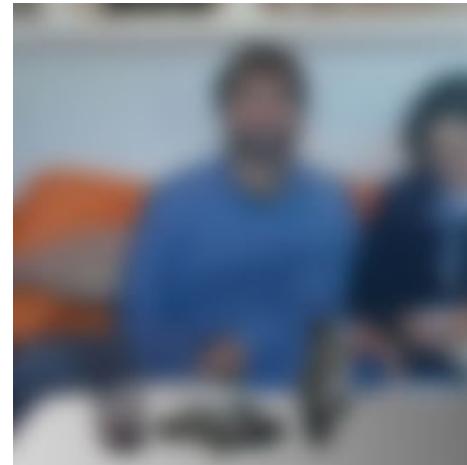
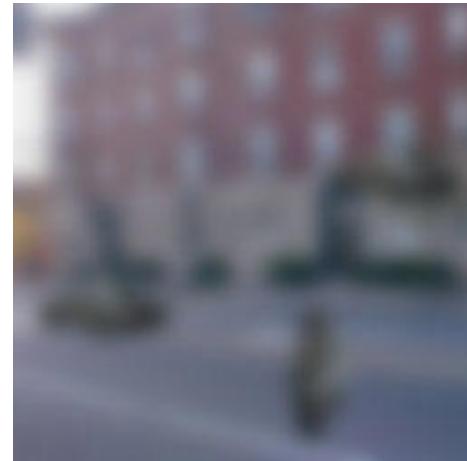


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Human vision:
Biederman, Bar &
Ullman, Palmer,
...



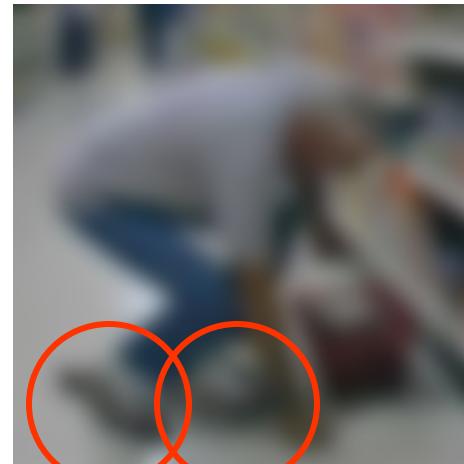
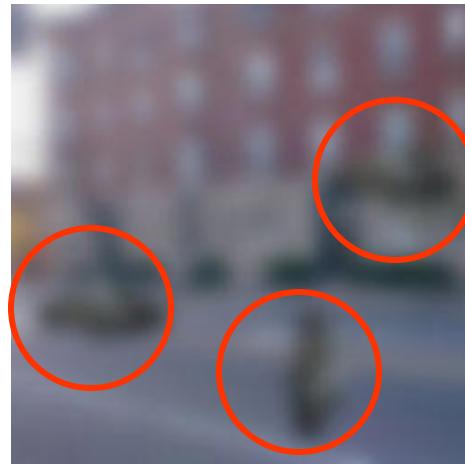
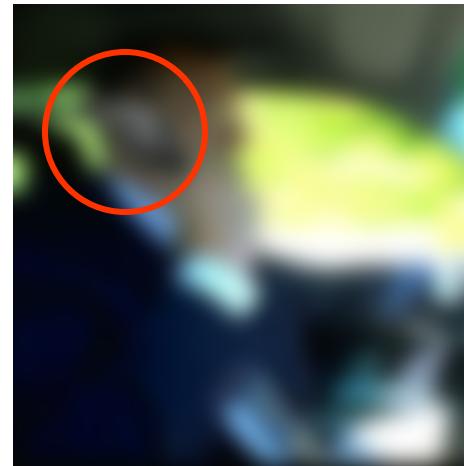
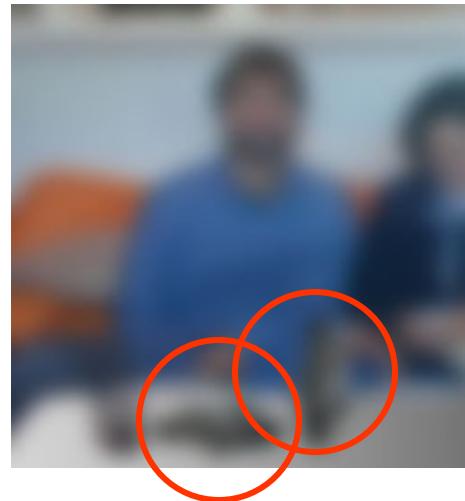
The role of context

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The role of context

All encircled
patterns
are identical:



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Person?

The role of context



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Person?

The role of context



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Person?

The role of context



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Person?

The role of context



Car?

The role of context

human vision is much more than a bottom-up process of subsequent signal processing steps.



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The central take-home message:

**Effective vision needs more than
sheer filtering and measuring**

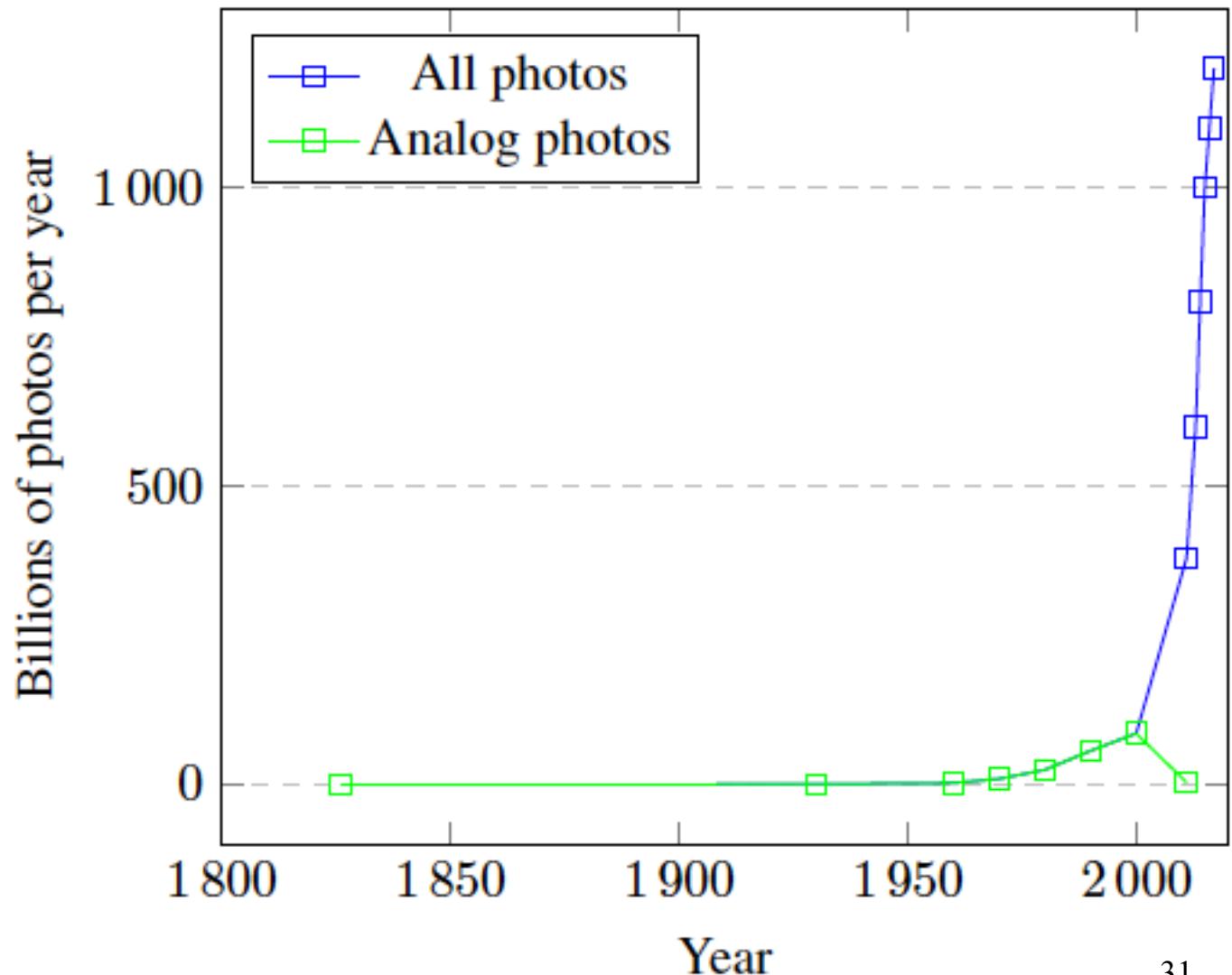
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... it is hot ...

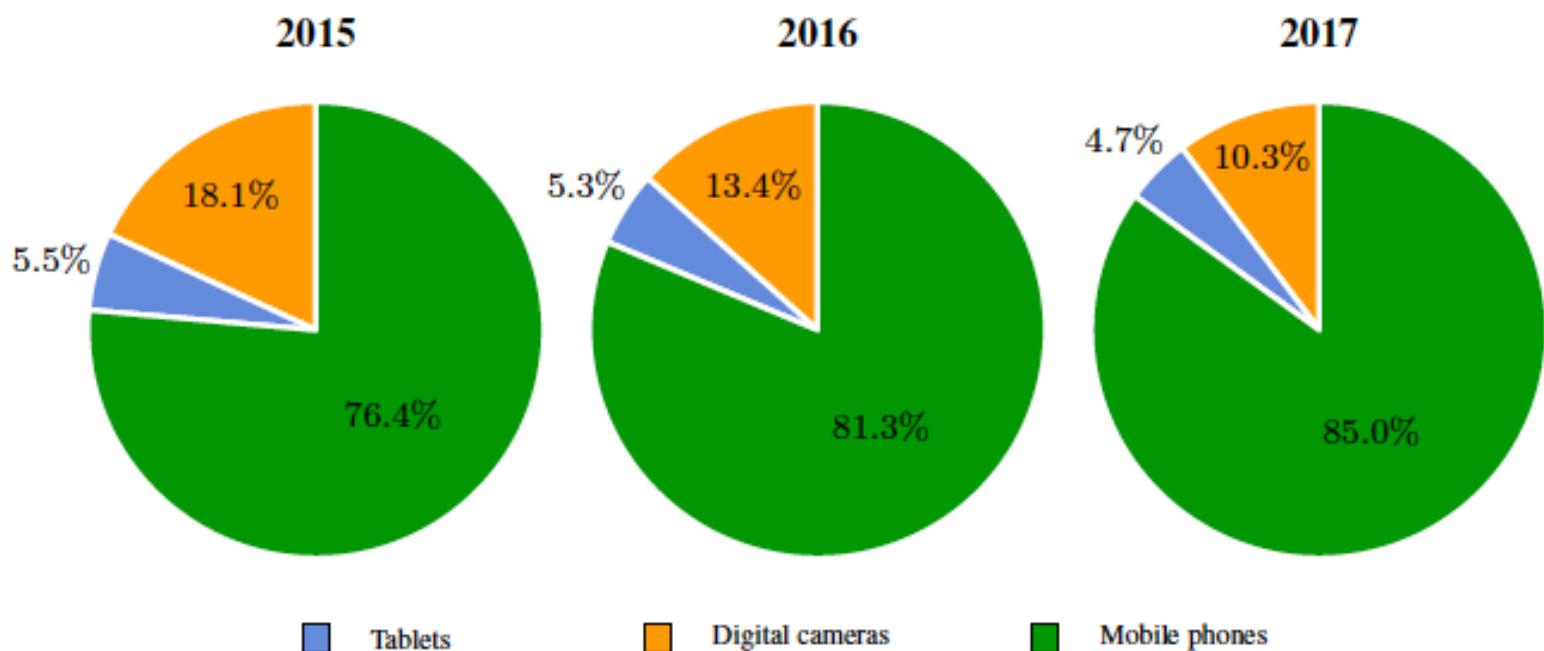
The explosion of photography



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The explosion of photography



Easier than ever to take a photo
The cost is extremely low (cheap memory)
Most people carry a camera most of the time 32

The development of computer vision apps

Most early applications were found in production environments, as these *allow for controlled conditions* and *have little uncertainty*

some areas do not allow for much control:
medical IP, remote sensing, surveillance, etc.

currently CV is *conquering the less controllable areas by storm*

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Ex App: image enhancement: mobile -> DSLR



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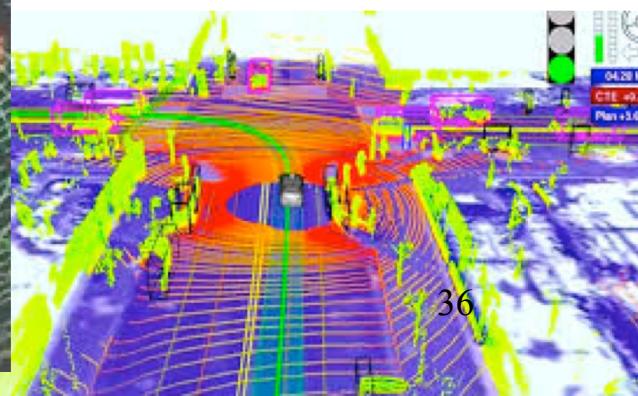
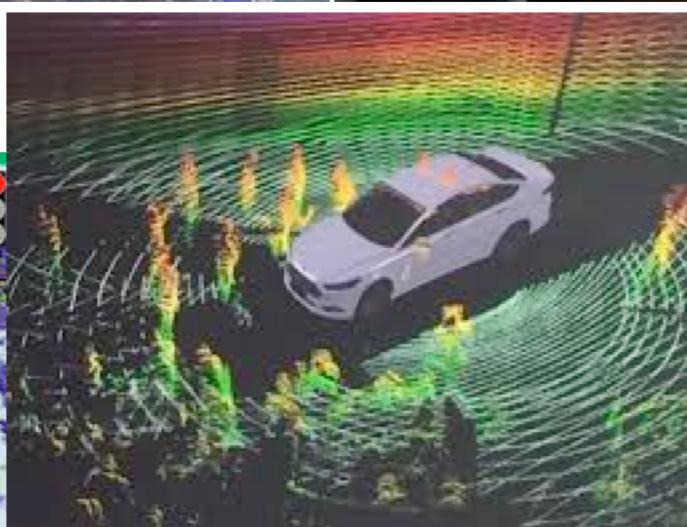
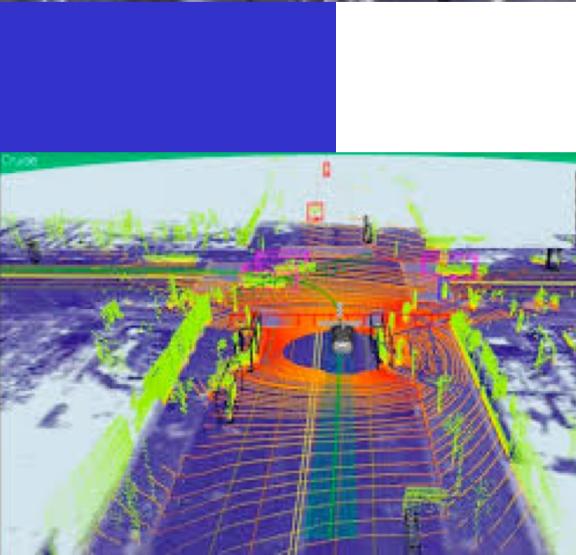
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Ex App: synthetic face generation



https://miro.medium.com/max/1176/1*LZp9nkzbSk8v6cpwp8CD8g.gif

Ex App: autonomous vehicles



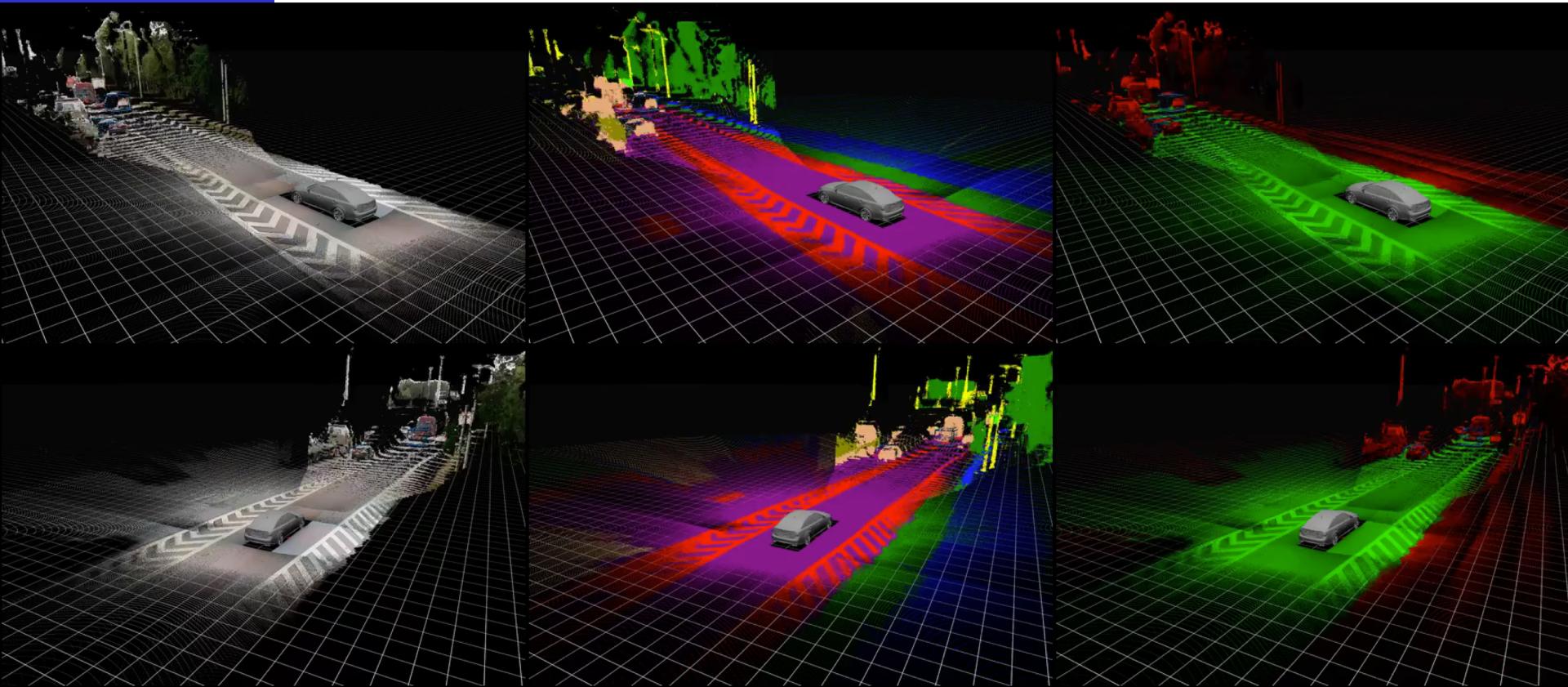
Ex App: autonomous vehicles

car detection:

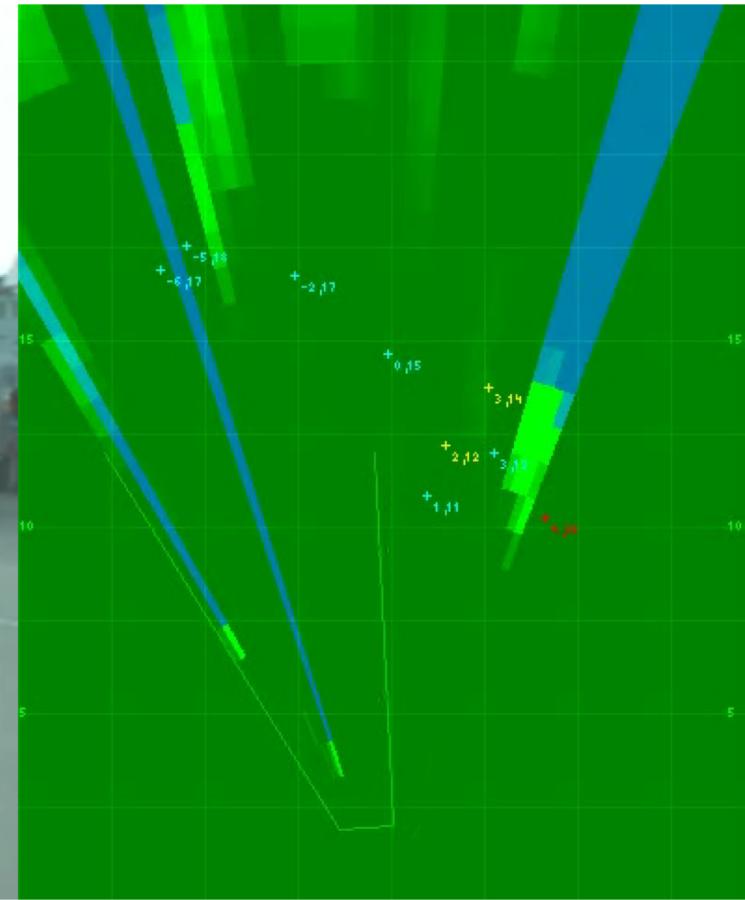


Ex App: autonomous vehicles

putting vision modalities together:



Ex: autonomous mobile platform



Ex App: image retrieval, captioning, ...

Describes without errors



A person riding a motorcycle on a dirt road.

Describes with minor errors



Two dogs play in the grass.

Somewhat related to the image



A skateboarder does a trick on a ramp.

Unrelated to the image



A dog is jumping to catch a frisbee.



A group of young people playing a game of frisbee.



Two hockey players are fighting over the puck.



A little girl in a pink hat is blowing bubbles.



A refrigerator filled with lots of food and drinks.



A herd of elephants walking across a dry grass field.



A close up of a cat laying on a couch.

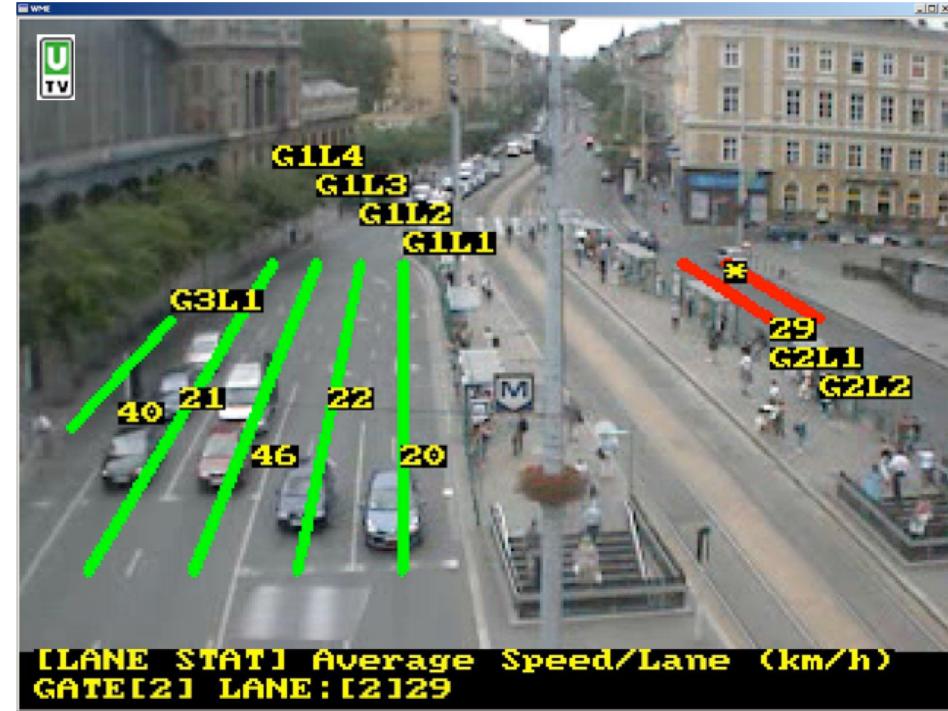


A red motorcycle parked on the side of the road.



A yellow school bus parked in a parking lot.

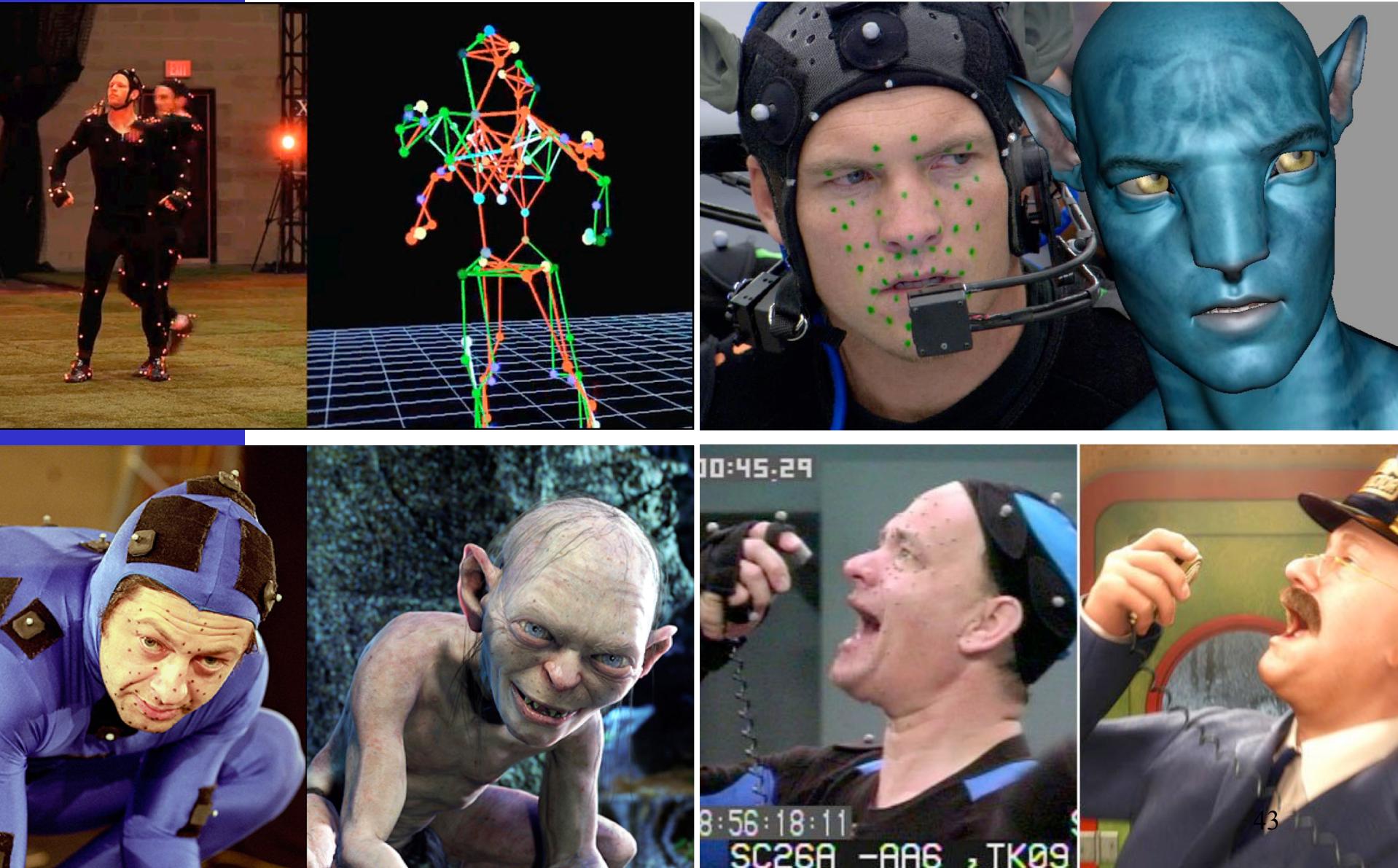
Ex App: visual surveillance



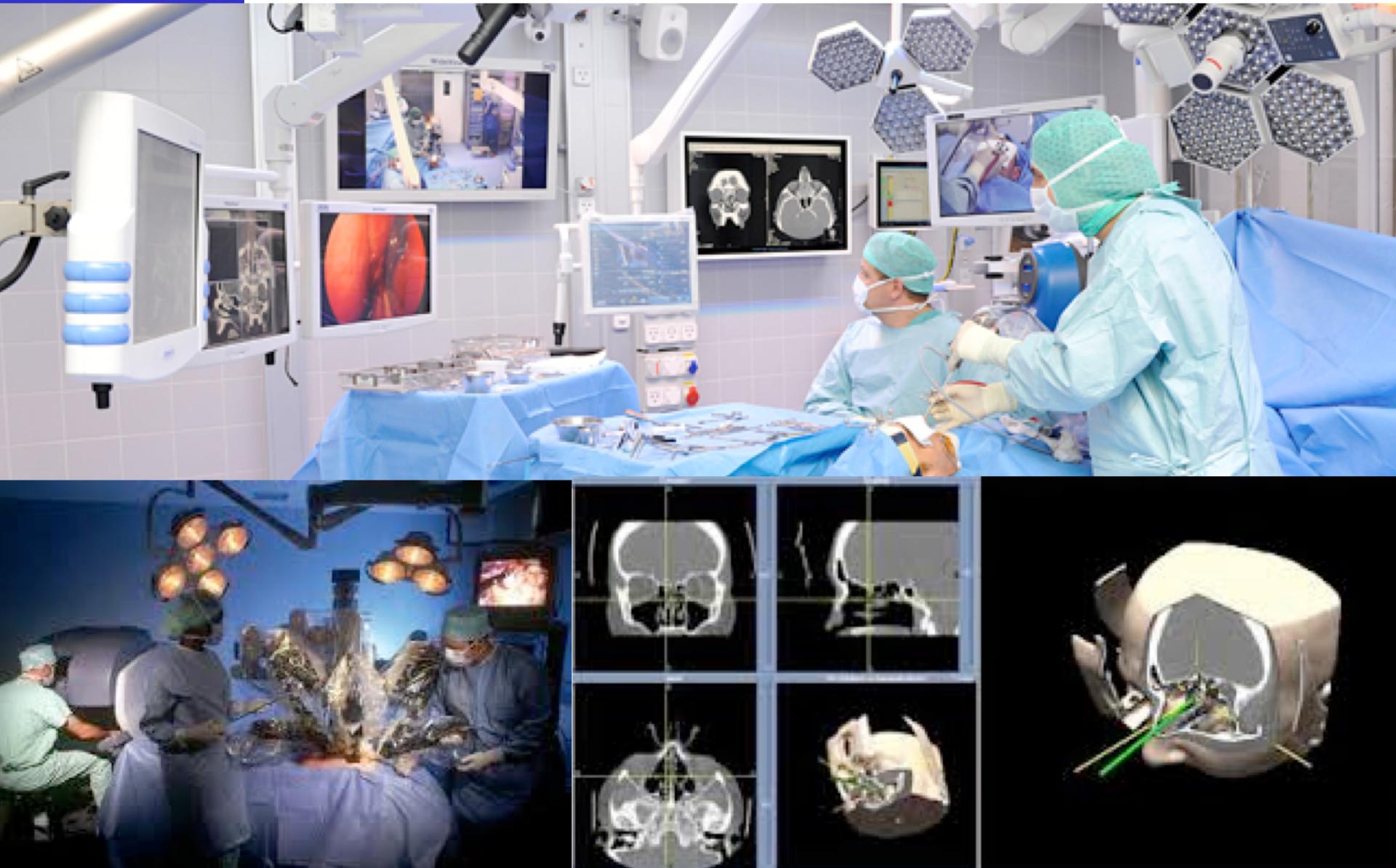
Ex App: Augm. Reality, eg sports



Ex App: motion capture for movies/games



Ex App: computer-assisted surgery



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Ex App: mobile mapping



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The central take-home message:

**It is feasible now to let most
things see and interpret
their environment**

Computer Vision

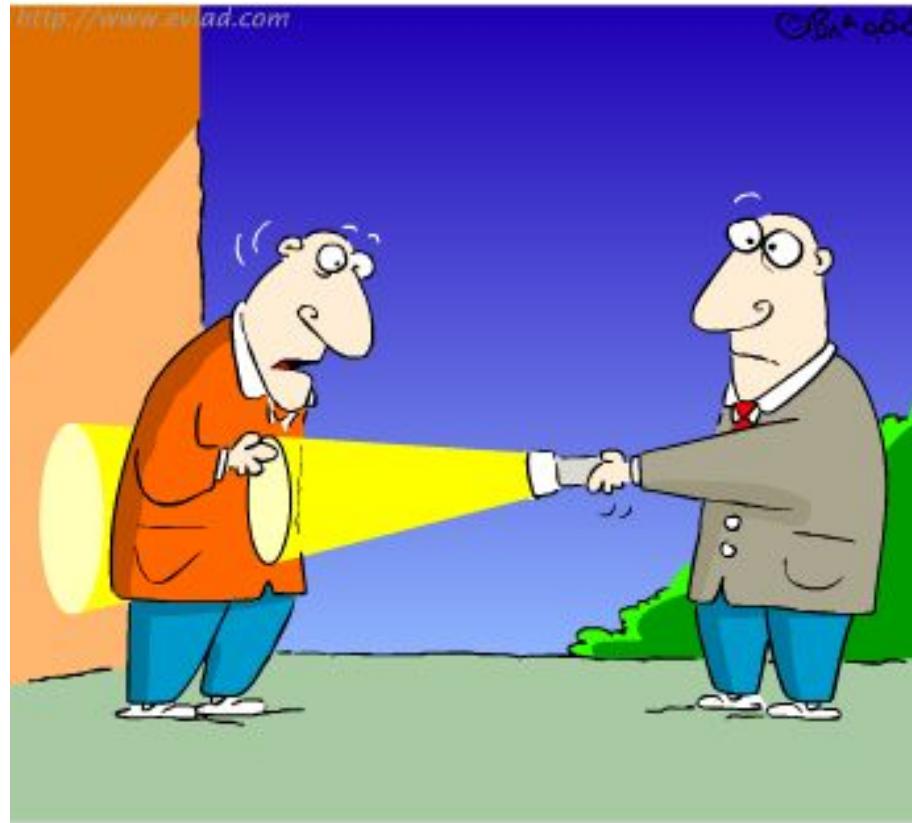
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... it needs light ...

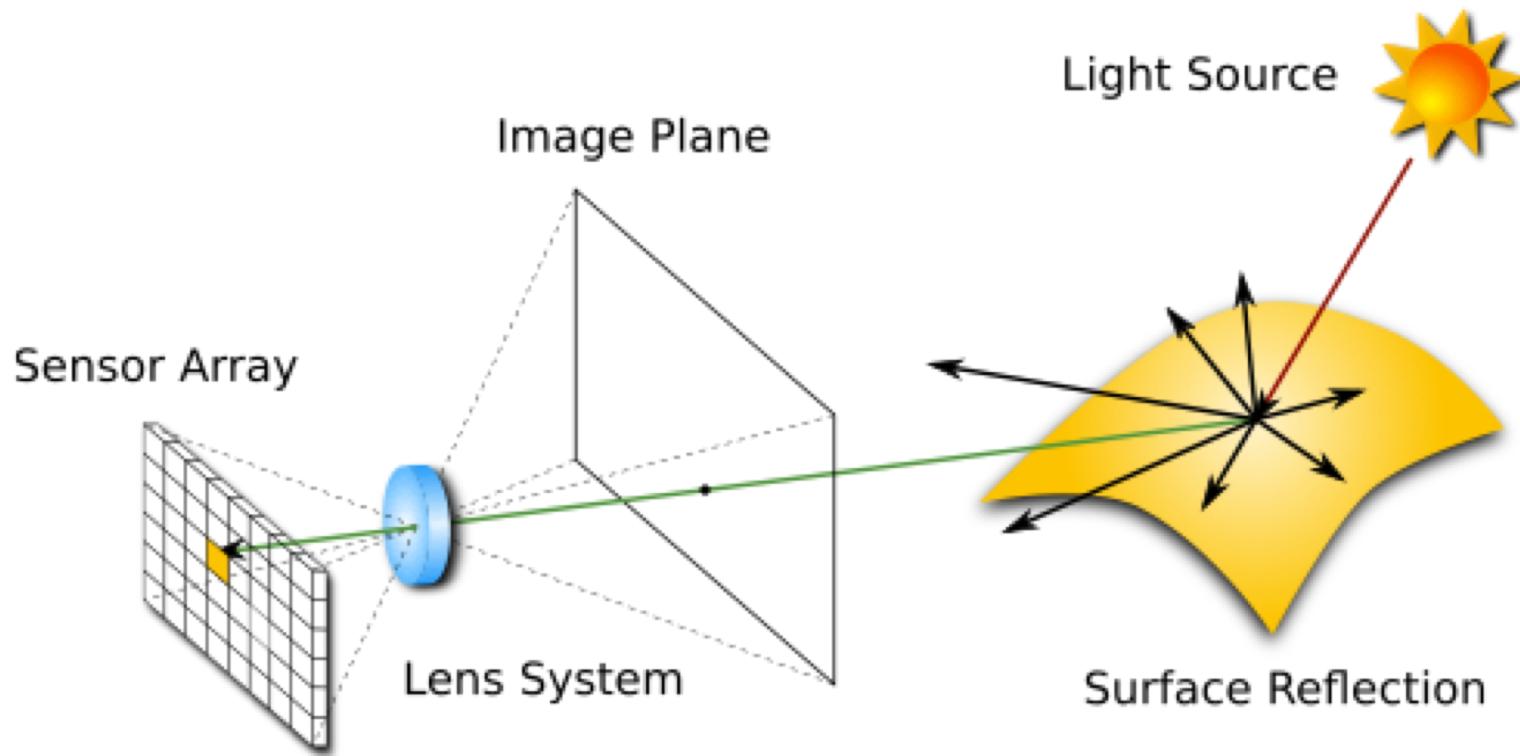
And then there was Light...

- no vision without light...
- ... because it is influenced by objects

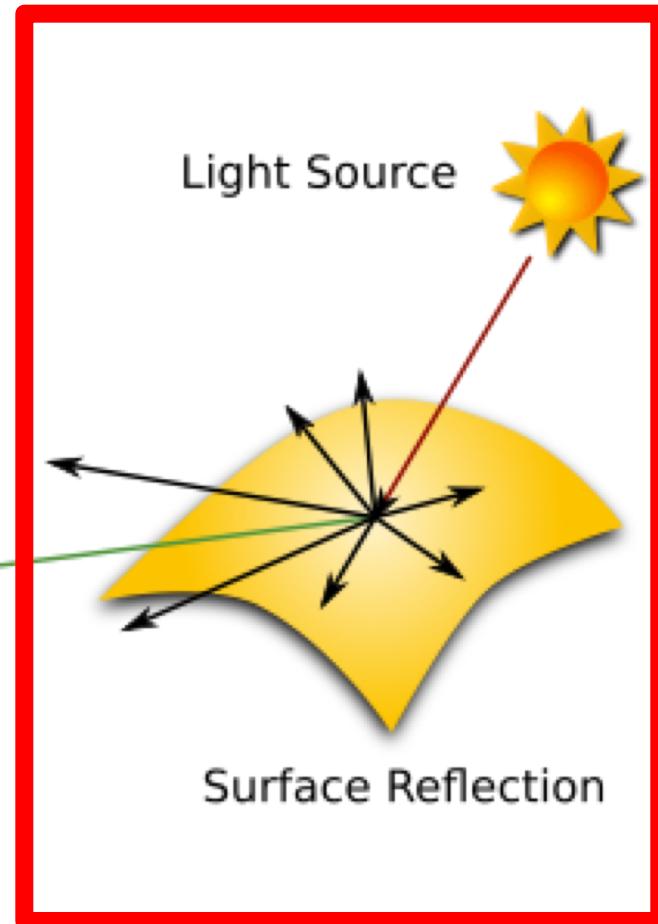
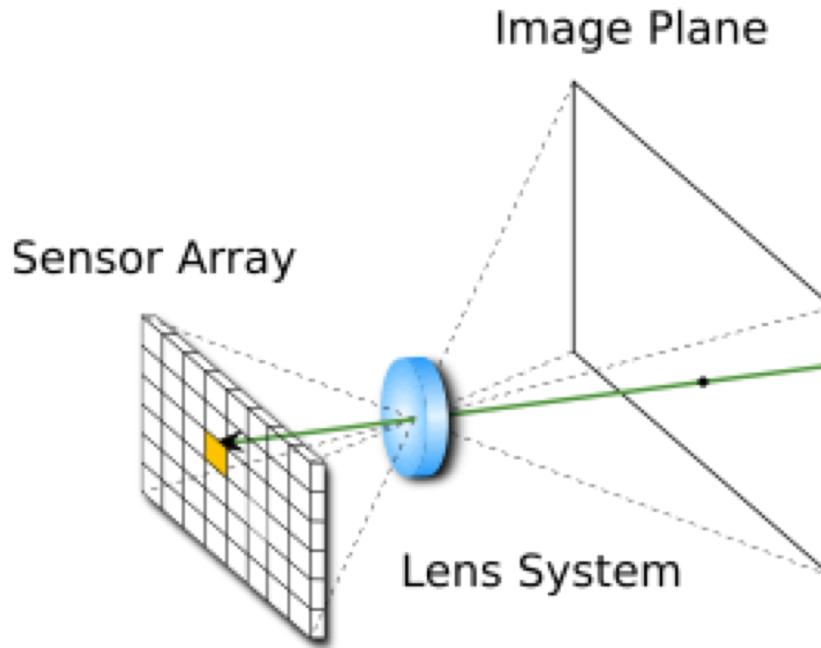


"What the...?"

Kickoff: the light, surface, lens & cam



Kickoff: the light, surface, lens & cam



topics

- ❑ the nature of light
- ❑ interactions with matter

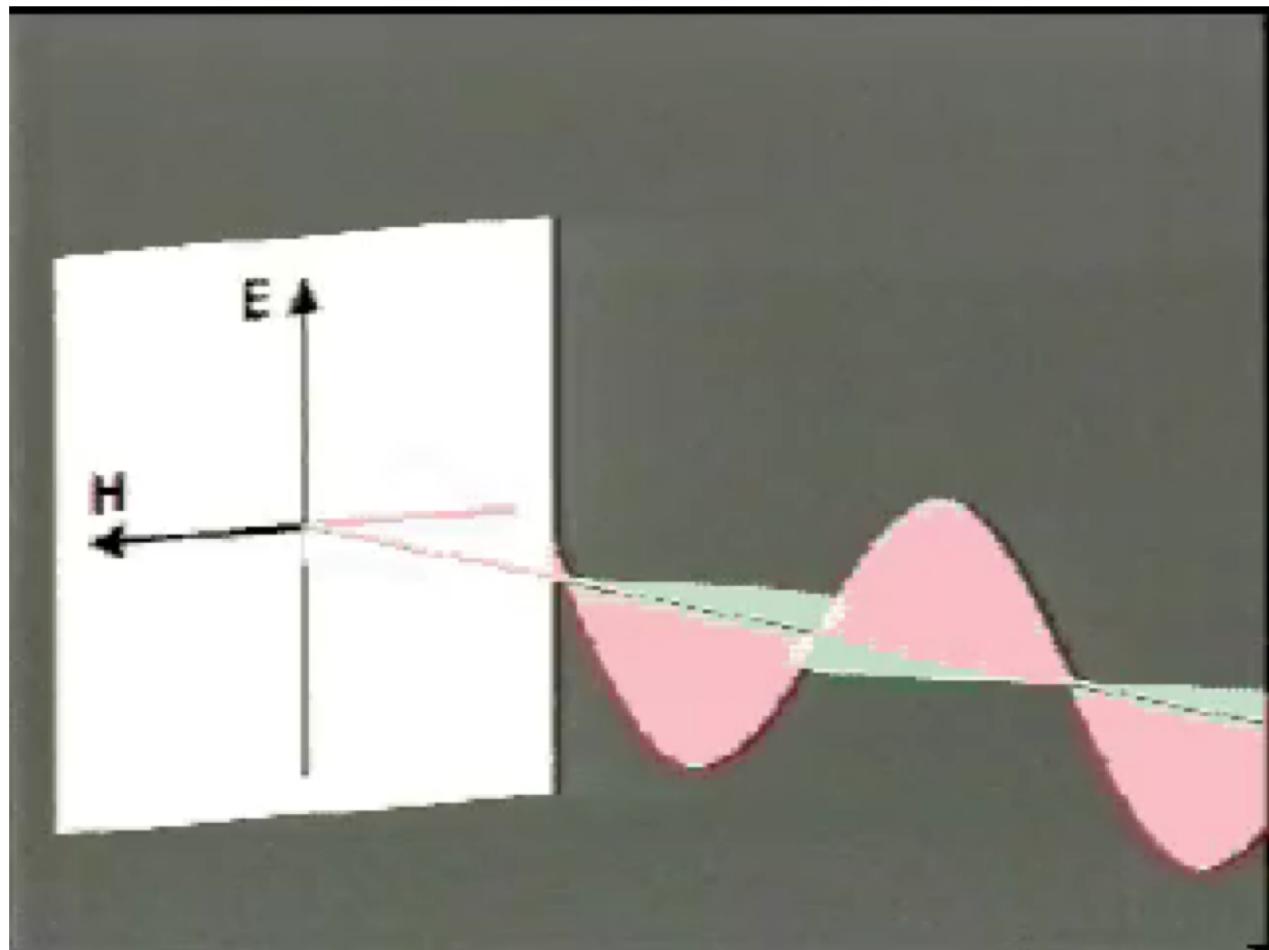


An option on optics

1. Geometrical optics
2. Physical optics, or
3. Quantum-mechanical optics

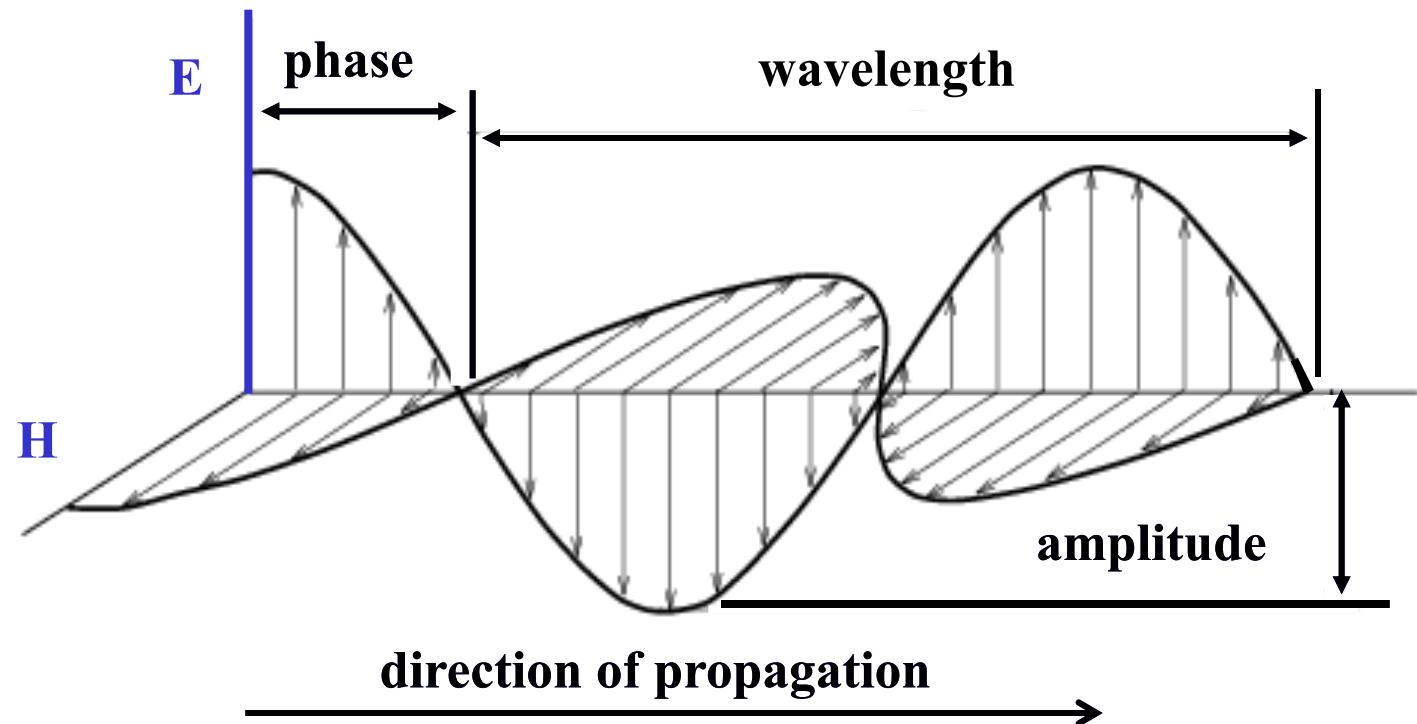
→ **wave character**

Light as electromagnetic waves



Light as electromagnetic waves

Self-sustaining exchange of electric and magnetic fields



1. wavelength
2. direction
3. amplitude E
4. phase
5. direction of polarisation

The spectrum

Normal ambient light is a mixture of wavelengths,
polarisation directions, and phases

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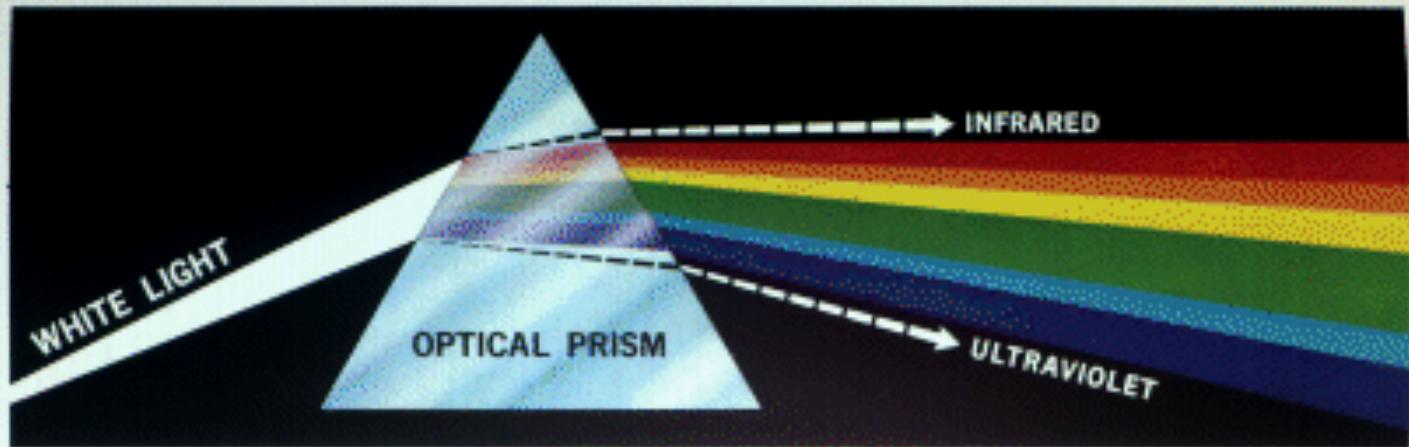
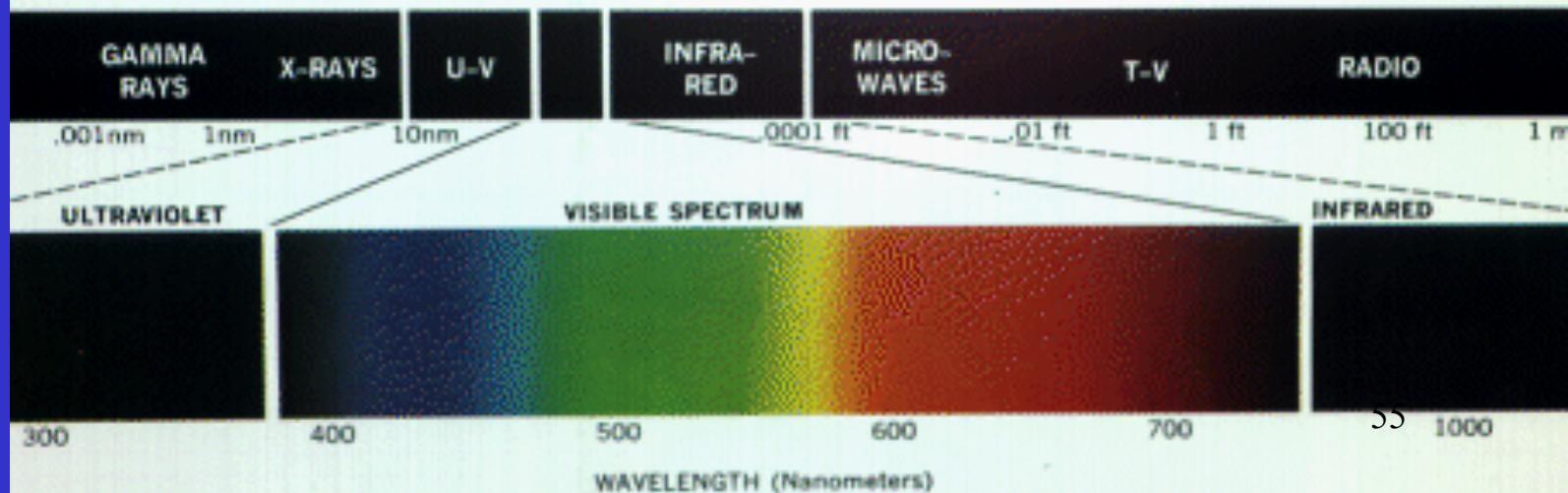


Plate I. Color spectrum seen by passing white light through a prism. (Courtesy of General Electric Co., Lamp Business Division.)

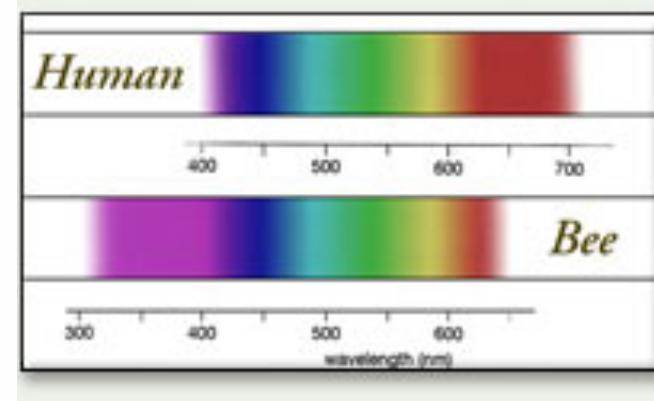
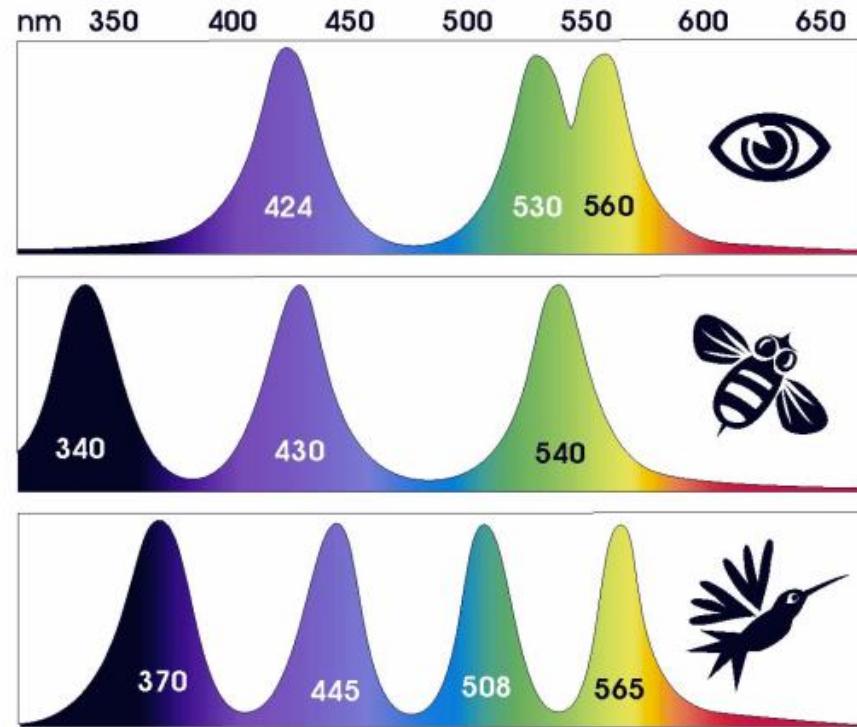


The visible range

Wavelength (in nm)	Colour
380 - 450	violet
450 - 490	blue
490 - 560	green
560 - 590	yellow
590 - 630	orange
630 - 760	red

NOTE : Cameras may have different spectral sensitivities
(i.e. also different from human vision)

The visible range



NOTE : animals may have different spectral sensitivities (i.e. different from human vision), and may also have a Different number of cone types, like 4 in most birds.

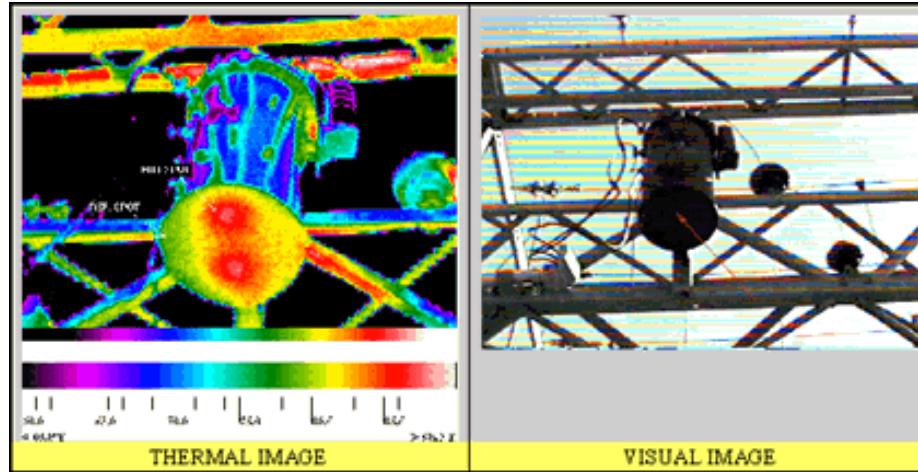


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Also cams for non-visible 'light', e.g. infrared



Overheating of transformer coils, with far IR



Near infra-red
(NIR) space image

NRG -> RGB for
visualization (notice
the strong reflection in
the NIR for vegetation)

Interactions with matter

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four types :

phenomenon

absorption

scattering

reflection

refraction

example

blue water

blue sky, red sunset

coloured ink

dispersion by a prism

+ diffraction

Interactions with matter

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four types :

phenomenon	example
absorption	blue water
<u>scattering</u>	blue sky, red sunset
reflection	coloured ink
refraction	dispersion by a prism

+ diffraction



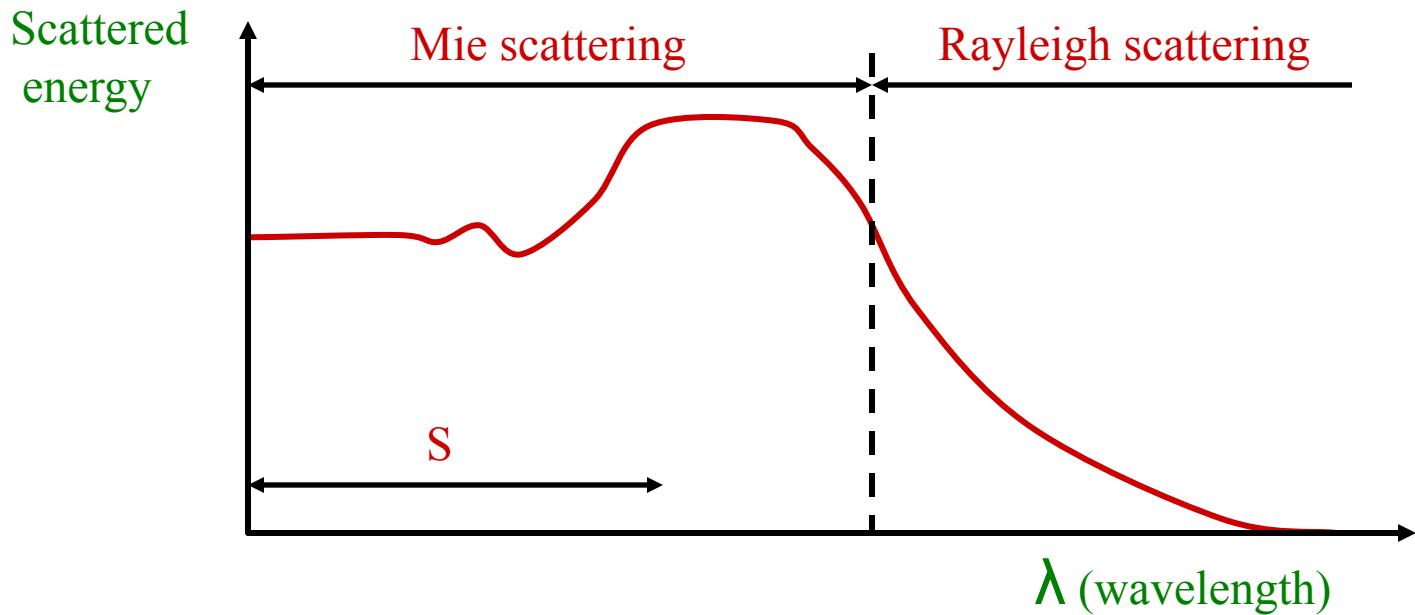
Scattering

3 types depending on relative sizes of particles and wavelengths:

1. small particles: *Rayleigh* (strongly wavelength dependent)
2. comparable sizes: *Mie* (weakly wavelength dependent)
3. Large particles: *non-selective* (wavelength independent)



Wavelength dependence



Less haze in the infrared (long wavelengths -> little scatter)
Looking through clouds by radar (even longer wavelengths)
NOTE: without scatter we would wander mainly in the dark



Atmospheric showcase



Rayleigh:

Tyndall effect (blue sky)

Red, setting sun

Non-selective:

Grey clouds



Mie:

Coloured cloud
from volcanic
eruption

Interactions with matter

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four types :

phenomenon	example
absorption	blue water
scattering	blue sky, red sunset
<u>reflection</u>	coloured ink
refraction	dispersion by a prism

+ diffraction

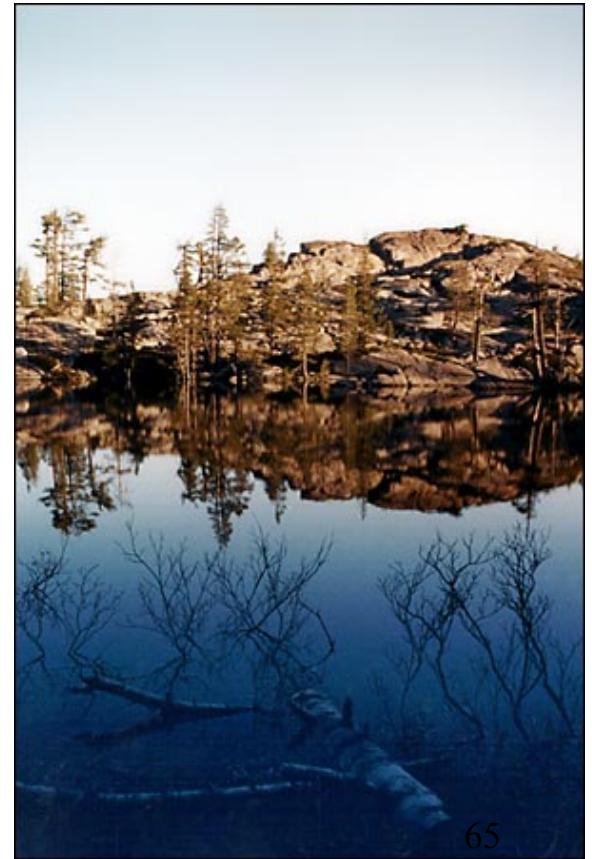
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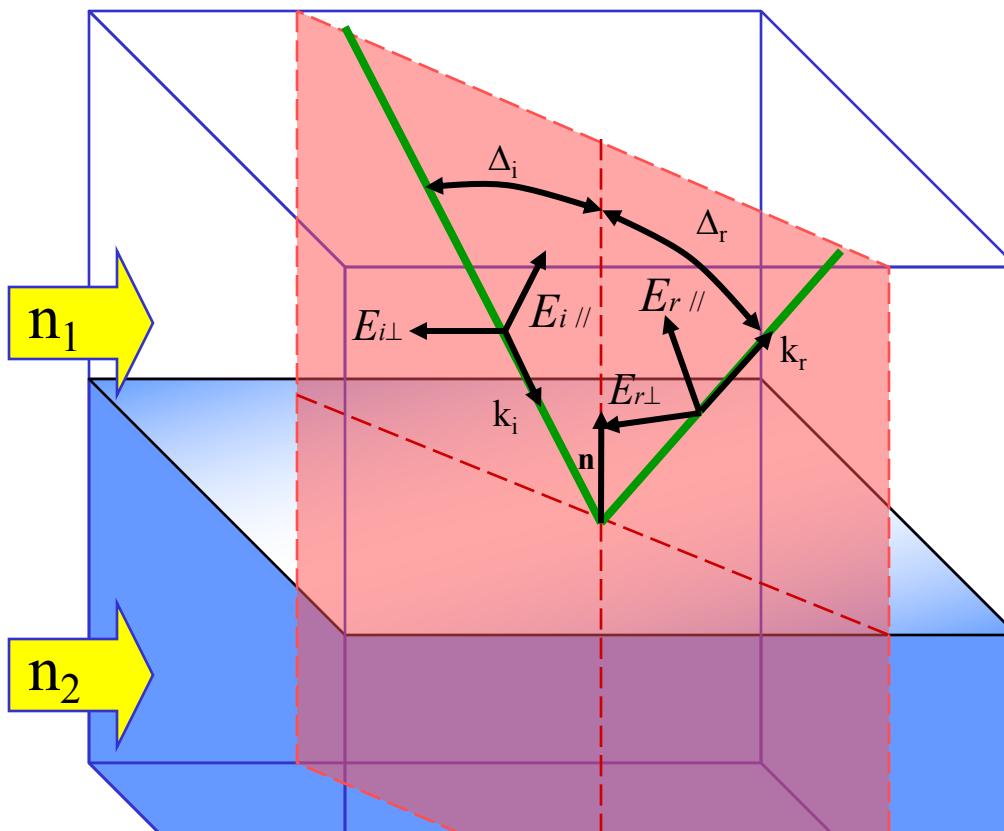
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Mirror reflection

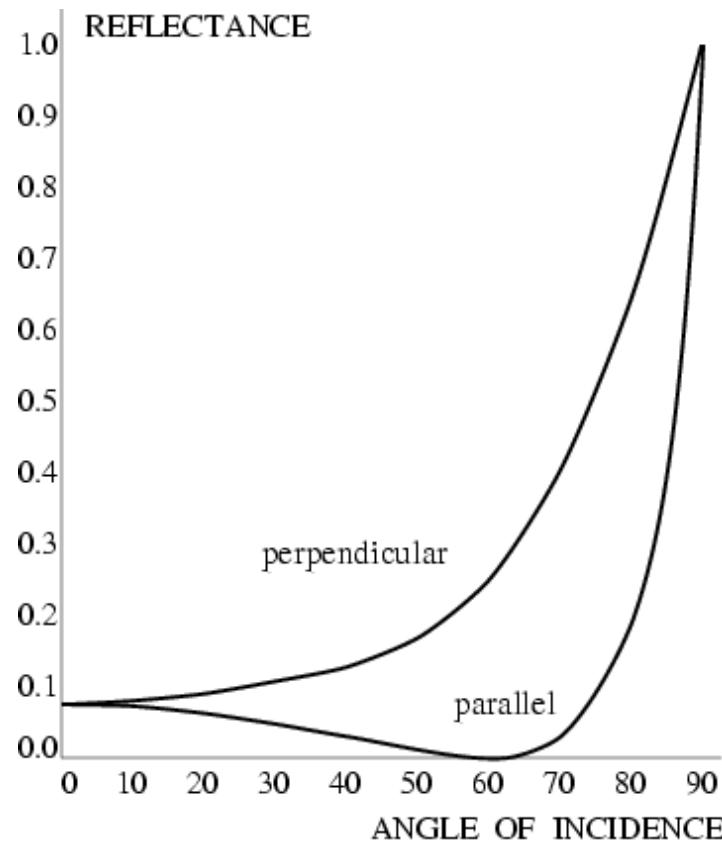


Mirror reflection



Angle of reflection = angle of incidence

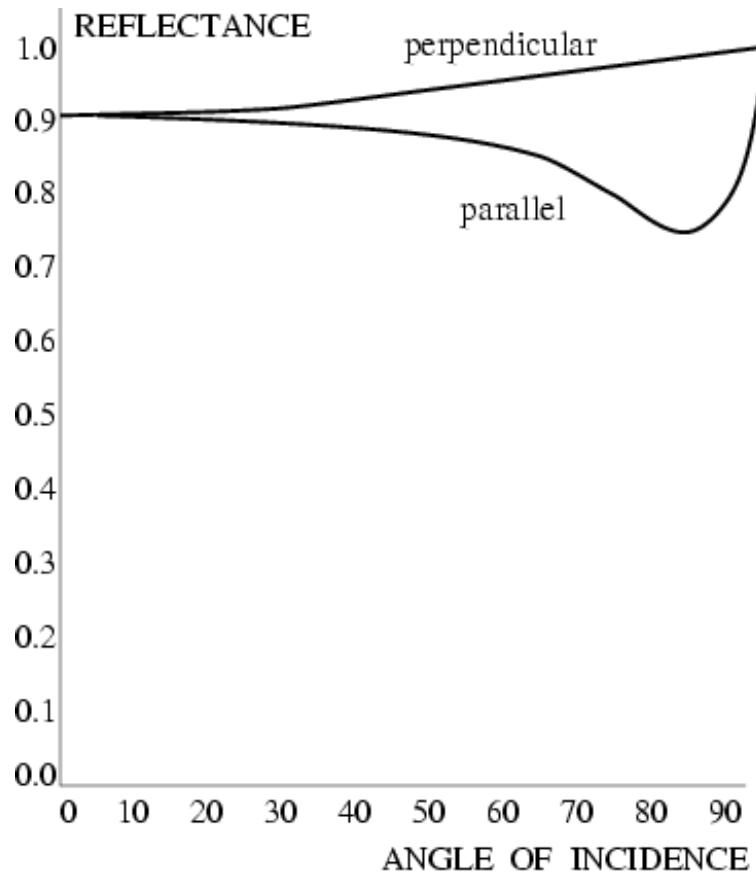
Mirror reflection : dielectric



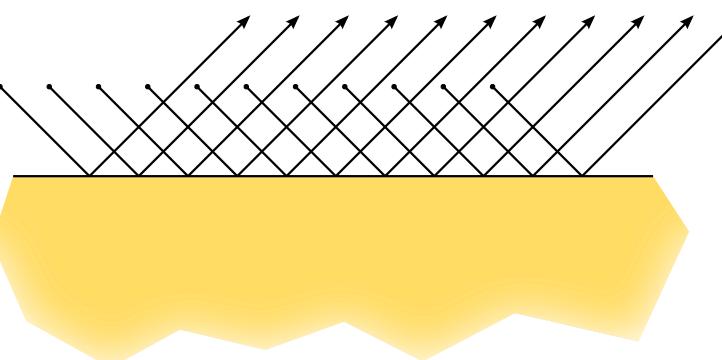
Polarizer at *Brewster angle*

Full reflection at grazing angles

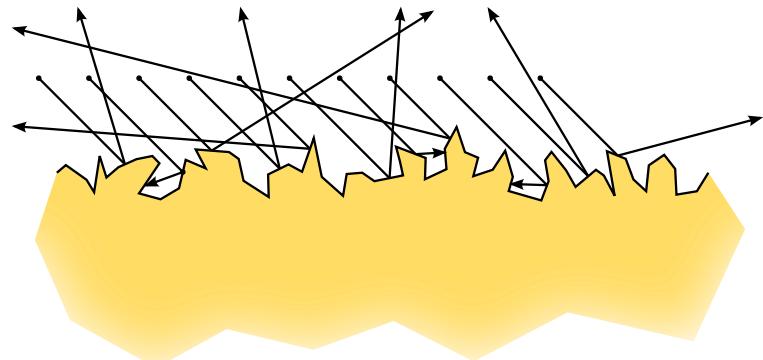
Mirror reflection : conductor



strong reflectors (under all angles)
more or less preserve polarization



(a)

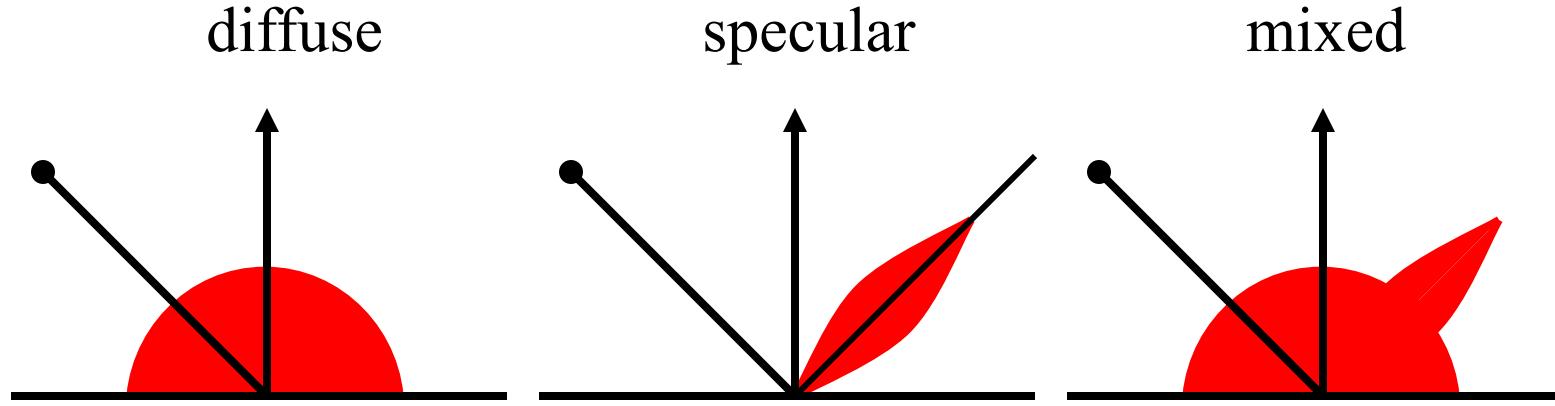


(b)

(a) Mirror or 'specular' reflection, (b) diffuse reflection

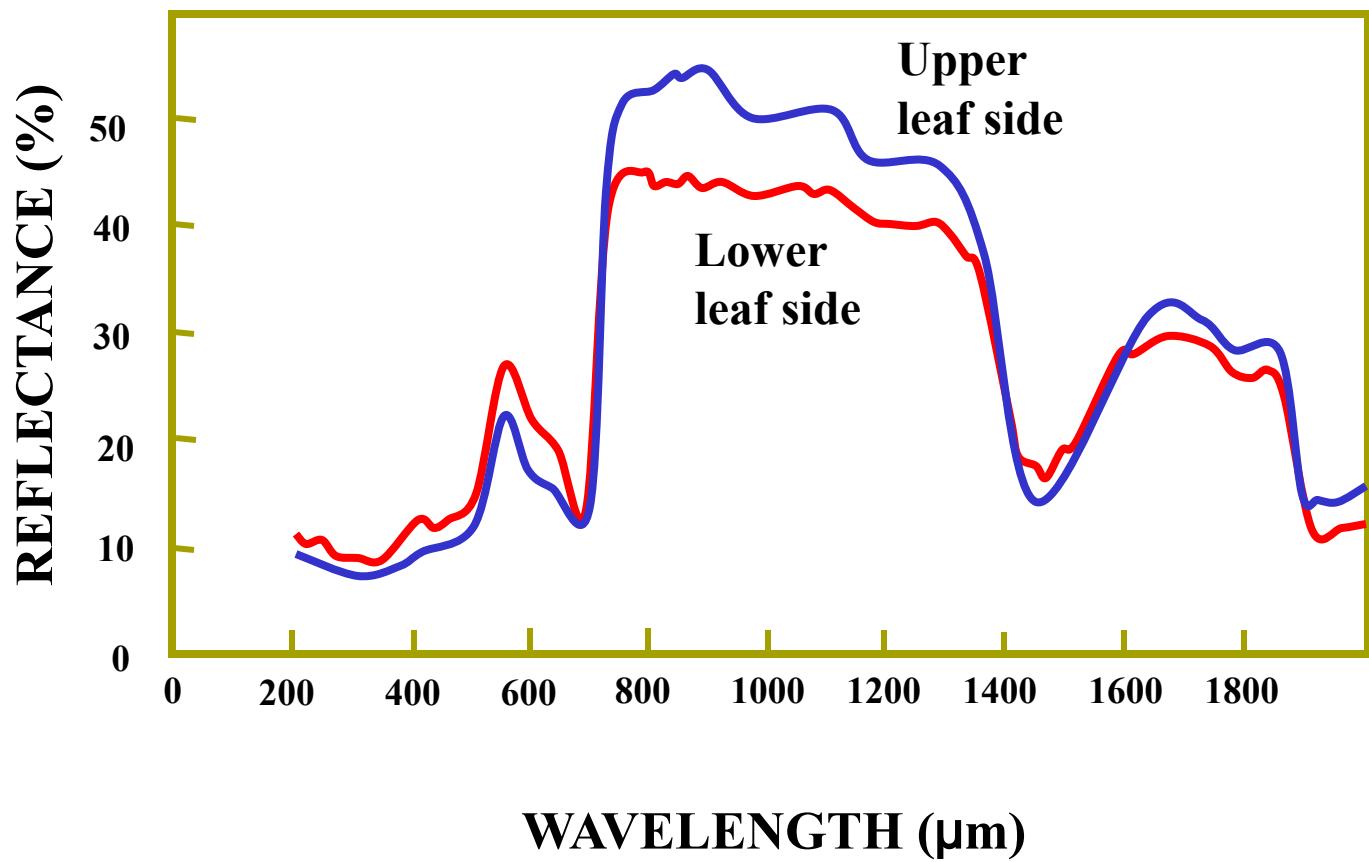
... and to mixed reflection for most real surfaces

three types of reflection :



Note : Lambertian example of diffuse reflection

Spectral reflectance e.g. vegetation



Ideally: spectral BRDF at all points known



BRDF = bidirectional reflectance distribution function

Interactions with matter

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scattering

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example

blue water

blue sky, red sunset

coloured ink

dispersion by a prism

+ diffraction

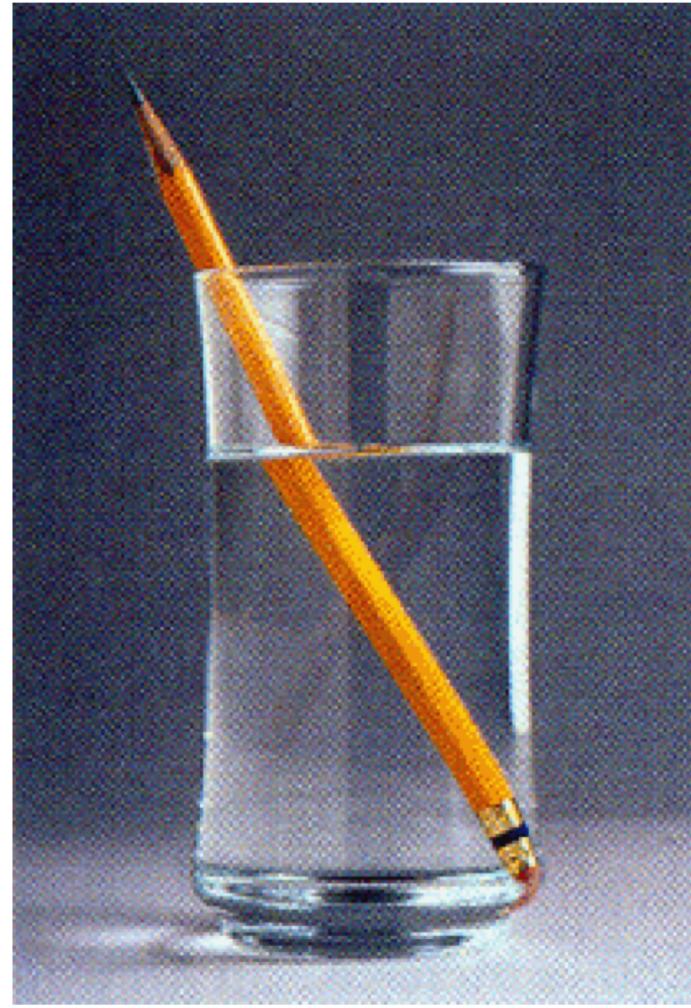


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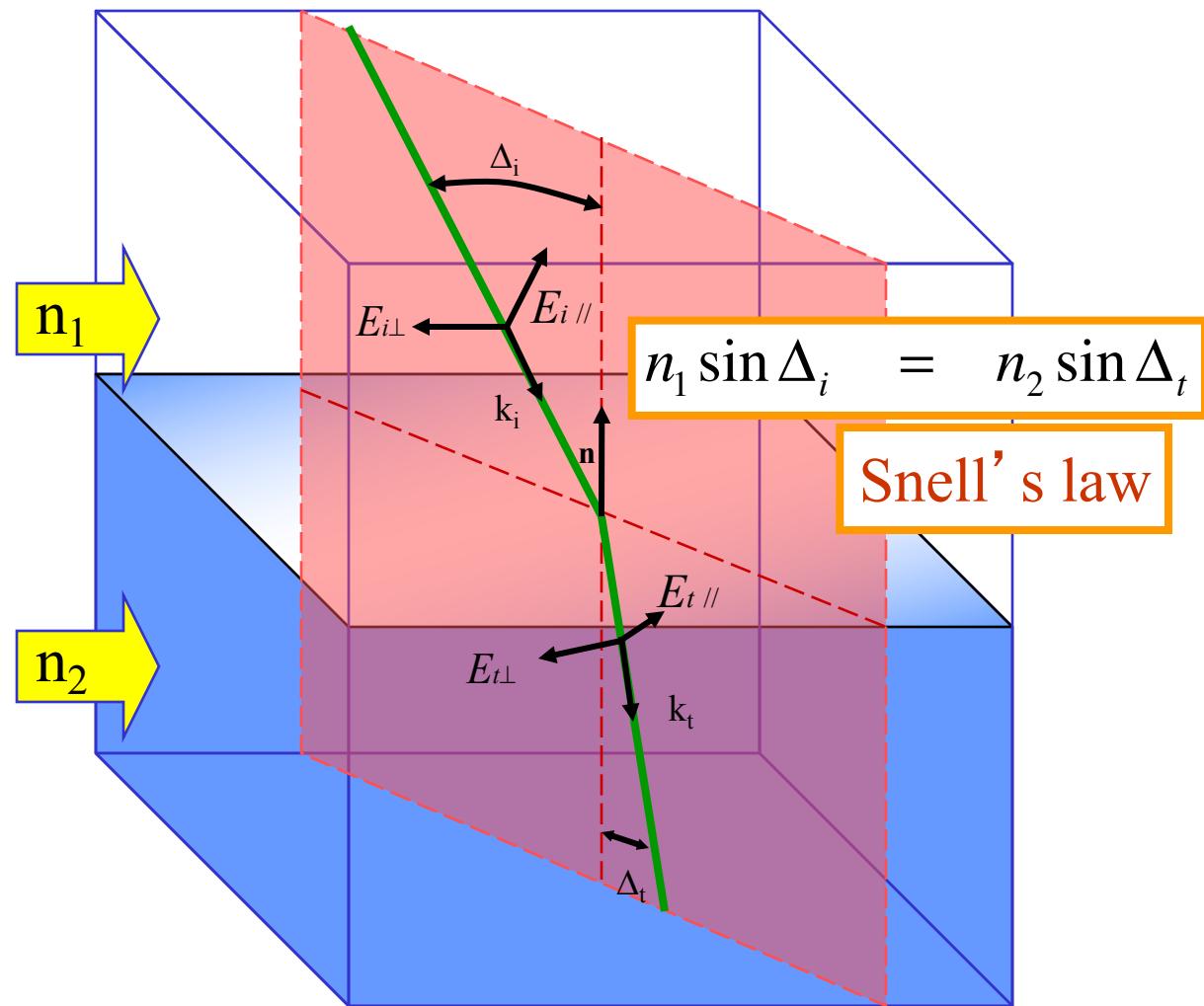
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Refraction



Refraction



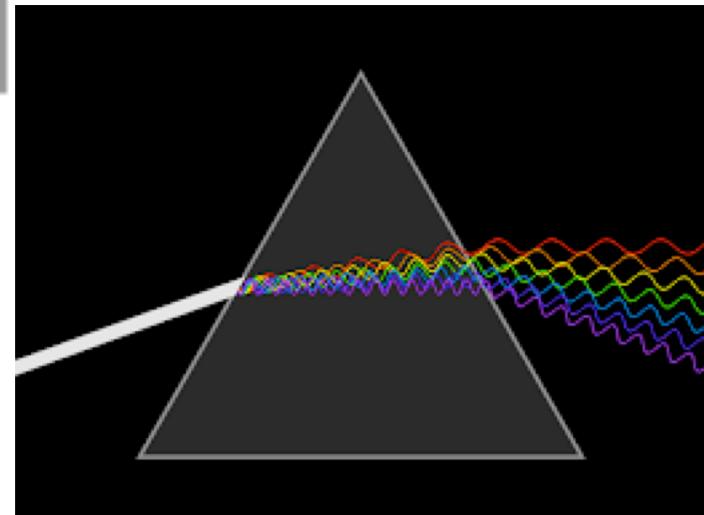
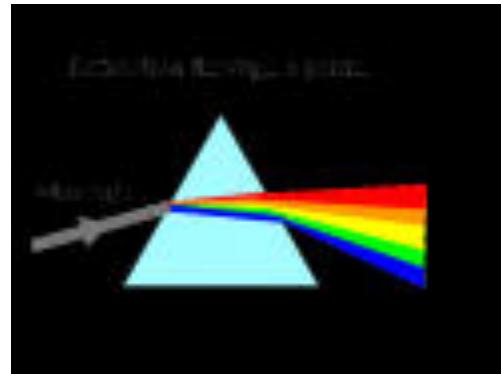
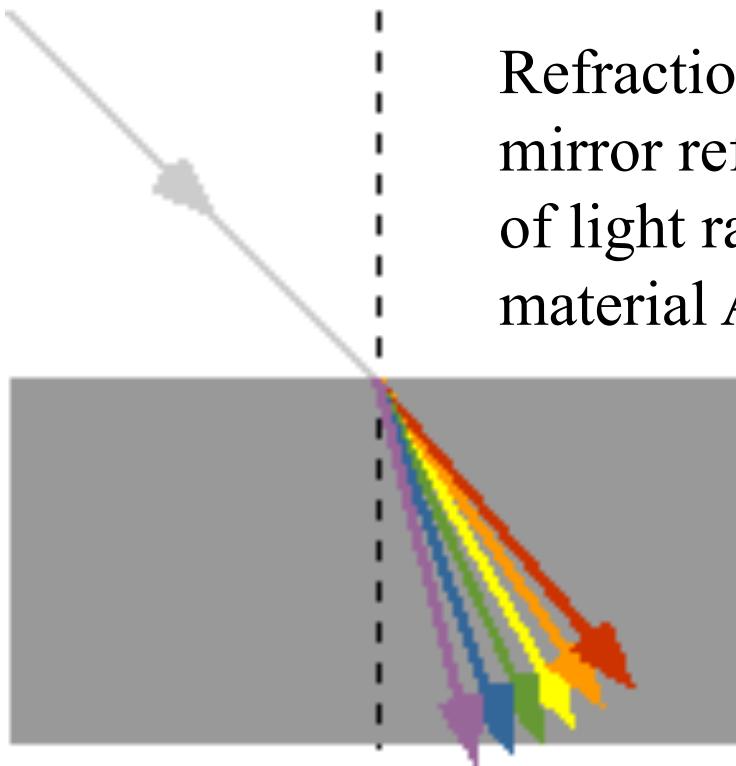
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Dispersion

Refraction is more complicated than mirror reflection: the path orientation of light rays is changed depending on material AND wavelength !!!



Interactions with matter

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four types :

phenomenon

example

absorption

blue water

scattering

blue sky, red sunset

reflection

coloured ink

refraction

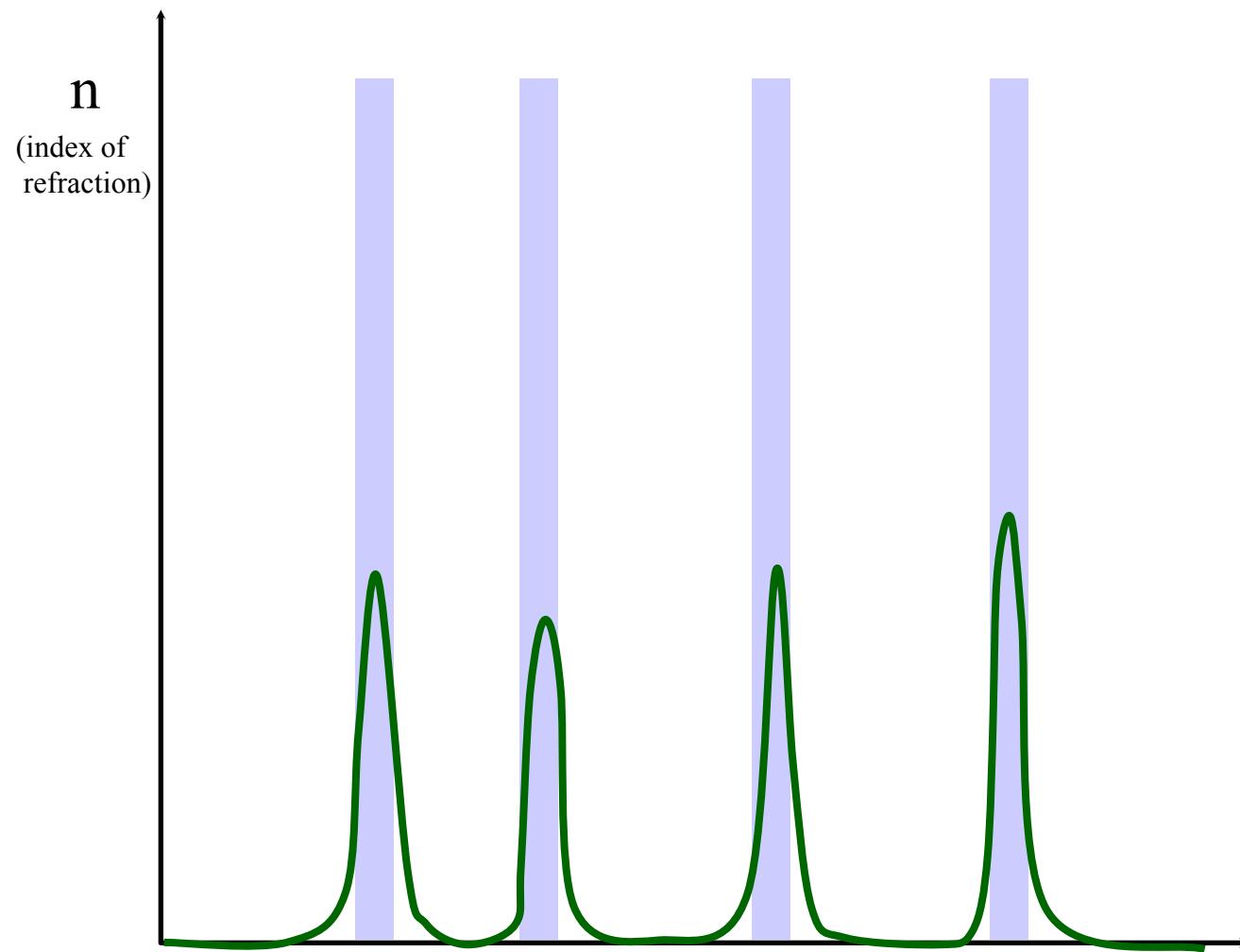
dispersion by a prism

+ diffraction



Absorption

Dissipation of wavelengths specific for the medium



Based on resonance frequencies of molecules -> peaks
Holes in sky light spectrum observed by Fraunhofer

The solar spectrum

Peaks around 500nm, hence human sensitivity for that part of the spectrum

