# Motion in two and three dimensions Chapter 4 Textbook

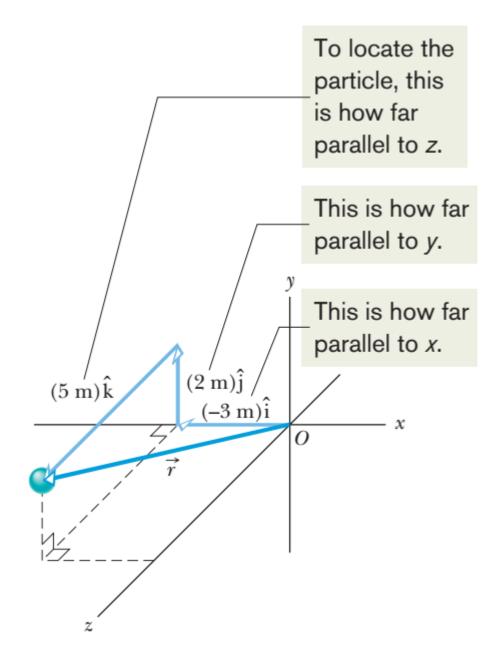
# Position and Displacement

### **Position Vector:**

• A vector that extends from a reference point (usually origin) to the particle.

### Position Vector in 3-D

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$



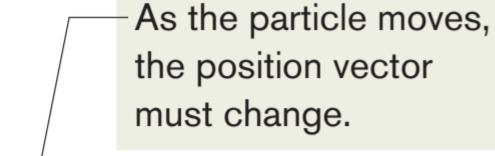
# Displacement vector

As a particle moves, its position vector changes in such a way that the vector always extends to the particle from the reference point (the origin). If the position vector changes—say, from  $\vec{r}_1$  to  $\vec{r}_2$  during a certain time interval—then the particle's **displacement**  $\Delta \vec{r}$  during that time interval is

$$\Delta \vec{r} = \vec{r}_2 - \vec{r}_1.$$

Using the unit-vector notation we can rewrite this displacement as

$$\Delta \vec{r} = (x_2 \hat{i} + y_2 \hat{j} + z_2 \hat{k}) - (x_1 \hat{i} + y_1 \hat{j} + z_1 \hat{k}) 
\Delta \vec{r} = (x_2 - x_1) \hat{i} + (y_2 - y_1) \hat{j} + (z_2 - z_1) \hat{k}, 
\Delta \vec{r} = \Delta x \hat{i} + \Delta y \hat{j} + \Delta z \hat{k}.$$



$$\overrightarrow{r_2} = \overrightarrow{r_1} + \Delta \overrightarrow{r}$$

Tangent

This is the displacement.

$$\vec{r_1}$$
 $\vec{r_2}$ 

Path

$$\Delta \vec{r} = \Delta x \hat{i} + \Delta y \hat{j} + \Delta z \hat{k}$$

### Avg. Velocity in 3-Dimensions

$$\vec{v}_{\text{avg}} = \frac{\Delta \vec{r}}{\Delta t}$$
.

$$\Delta \vec{r} = \Delta x \hat{i} + \Delta y \hat{j} + \Delta z \hat{k}.$$

Put in the formula of average velocity we'll get

$$\vec{v}_{\text{avg}} = \frac{\Delta x \hat{\mathbf{i}} + \Delta y \hat{\mathbf{j}} + \Delta z \hat{\mathbf{k}}}{\Delta t} = \frac{\Delta x}{\Delta t} \hat{\mathbf{i}} + \frac{\Delta y}{\Delta t} \hat{\mathbf{j}} + \frac{\Delta z}{\Delta t} \hat{\mathbf{k}}.$$

### Instantaneous Velocity in 3-D

When we speak of the **velocity** of a particle, we usually mean the particle's **instantaneous velocity**  $\vec{v}$  at some instant. This  $\vec{v}$  is the value that  $\vec{v}_{avg}$  approaches in the limit as we shrink the time interval  $\Delta t$  to 0 about that instant. Using the language of calculus, we may write  $\vec{v}$  as the derivative

$$\overrightarrow{v} = \frac{d\overrightarrow{r}}{dt}.$$

• Substitute the value of unit vector

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k},$$

$$\vec{v} = \frac{d}{dt}(x\hat{i} + y\hat{j} + z\hat{k}) = \frac{dx}{dt}\hat{i} + \frac{dy}{dt}\hat{j} + \frac{dz}{dt}\hat{k}.$$

# Instantaneous Velocity in 3-D

• Simply we can
$$\vec{v} = \frac{dx}{dt}\hat{i} + \frac{dy}{dt}\hat{j} + \frac{dz}{dt}\hat{k}.$$

$$\vec{v} = v_x\hat{i} + v_y\hat{j} + v_z\hat{k},$$

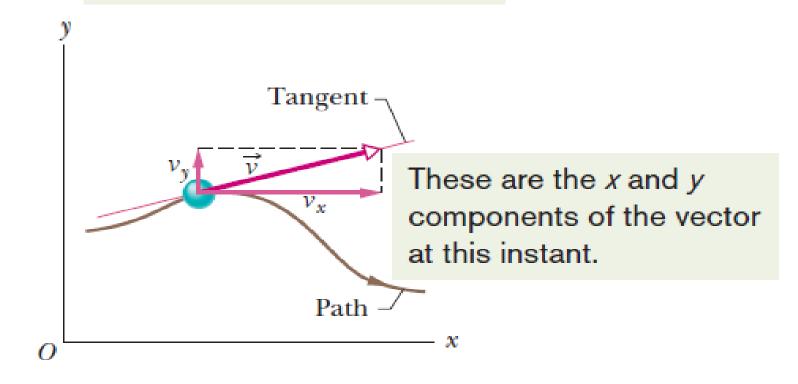
where the scalar components of  $\vec{v}$  are

$$v_x = \frac{dx}{dt}$$
,  $v_y = \frac{dy}{dt}$ , and  $v_z = \frac{dz}{dt}$ .

The direction of the instantaneous velocity of a particle is always tangent to the particle's path at the particle's position

# Instantaneous Velocity in 3-D

The velocity vector is always tangent to the path.



### Instantaneous acceleration in 3-D

### instantaneous acceleration

$$\vec{a} = \frac{d\vec{v}}{dt}.$$

$$\vec{v} = v_x \hat{i} + v_y \hat{j} + v_z \hat{k},$$

$$\vec{a} = \frac{d}{dt} (v_x \hat{i} + v_y \hat{j} + v_z \hat{k})$$

$$= \frac{dv_x}{dt} \hat{i} + \frac{dv_y}{dt} \hat{j} + \frac{dv_z}{dt} \hat{k}$$

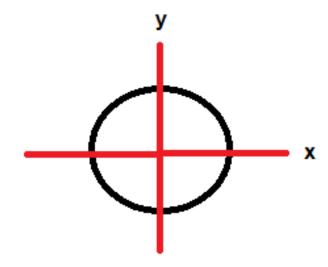
$$\vec{a} = a_x \hat{i} + a_y \hat{j} + a_z \hat{k},$$

where the scalar components of  $\vec{a}$  are

$$\overrightarrow{a} = \frac{d\overrightarrow{v}}{dt}.$$
where the scalar components of  $a$  are
$$a_x = \frac{dv_x}{dt}, \quad a_y = \frac{dv_y}{dt}, \quad \text{and} \quad a_z = \frac{dv_z}{dt}.$$

### Checkpoint 1:

The figure shows a circular path taken by a particle. If the instantaneous velocity of the particle is  $\vec{v} = (2 \text{ m/s})\hat{i} - (2 \text{ m/s})\hat{j}$ , through which quadrant is the particle moving at that instant if it is traveling (a) clockwise and (b) counterclockwise around the circle? For both cases, draw  $\vec{v}$  on the figure.



# Checkpoint 2

Here are four descriptions of the position (in meters) of a puck as it moves in an xy plane:

(1) 
$$x = -3t^2 + 4t - 2$$
 and  $y = 6t^2 - 4t$  (3)  $\vec{r} = 2t^2\hat{i} - (4t + 3)\hat{j}$ 

(2) 
$$x = -3t^3 - 4t$$
 and  $y = -5t^2 + 6$  (4)  $\vec{r} = (4t^3 - 2t)\hat{i} + 3\hat{j}$ 

Are the x and y acceleration components constant? Is acceleration  $\vec{a}$  constant?

### Sample Problem 4.01

A rabbit runs across a parking lot on which a set of coordin7ate axes has, strangely enough, been drawn. The coordinates (meters) of the rabbit's position as functions of time t (seconds) are given by

$$x = -0.31t^2 + 7.2t + 28$$
$$y = 0.22t^2 - 9.1t + 30.$$

At t =15 s, what is the rabbit's position vector  $\vec{r}$  in unit-vector notation and in magnitude-angle notation?

### **Answers:**

$$\vec{r} = (66m)\hat{\imath} - (57m)\hat{j}$$
  
 $r \text{ (magnitude)} = 87 \text{ m}$   
 $\theta = -41^{\circ}$ 

# Sample Problem 4.02

For the rabbit in the preceding sample problem, find the velocity  $\vec{v}$  at time t = 15 s.

### **Answers:**

```
\vec{v} = (-2.1 \, m/s)\hat{\imath} + (-2.5 \, m/s)\hat{\jmath}
v (magnitude) = 3.3 m/s
\theta = -130^{\circ}
```

# Sample Problem 4.03

For the rabbit in the preceding two sample problems, find the acceleration  $\vec{a}$  at time t = 15 s.

### **Answers:**

```
\vec{a} = (-0.62 \ m/s^2)\hat{\imath} + (0.44 \ m/s^2)\hat{\jmath}

a \text{ (magnitude)} = 0.76 \ m/s^2

\theta = -35^\circ
```

### Homework questions:

- Practice problems:
- End of chapter 4 textbook "Fundamentals of Physics" by Halliday & Resnick Jearl Walker 10<sup>th</sup> Edition"

Problem 17

# Adapted from:

Book:

Fundamentals of Physics by Halliday Resnick & Jearl Walker 10<sup>th</sup> edition