

3 things to prove:

(i) red is poly time in the size of its input

here the size of the input is $\text{size}(G) (=|V| + |E|)$

(ii) if G has an HC then G' has a TSP tour of length $(\leq) k$ ✓

(iii) if G has no HC then G' has no TSP tour of length $(\leq) k$ ✓

Definition 20. A decision problem P is in (the complexity class) NP if there is a (deterministic) algorithm with runtime in $O(p(N))$, for some polyn. p , which, for any problem instance x of P and any "potential witness" y test whether or not y witnesses a "yes"-answer to x . Here N is the size of x .

S. Cook, 1971: There are hardest problems in NP !

Definition 21. A dec. problem is NP-complete if

(i) it is in NP and

(ii) every problem in NP is polynomially reducible to it.

Such problems seem intractable, since no poly-time alg. finding solutions to them are known.

NOTE

If P is NP-complete and

P' is in NP and

P is polyn. reducible to P'

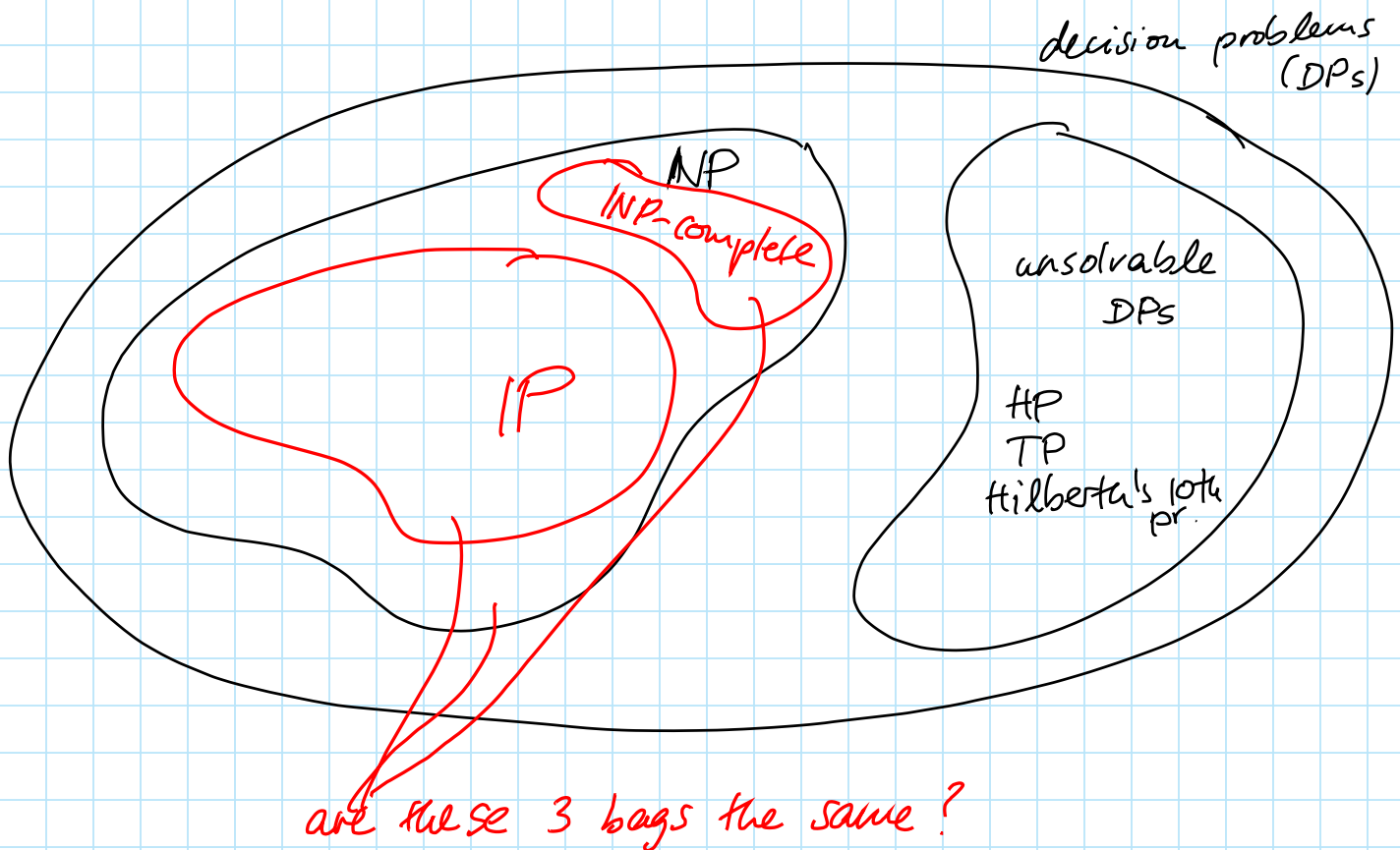
then P' is also NP-complete.

Example 53. HCP is NP-complete.

Since TSP is in NP (why?)

and HCP is polyn reducible to TSP,

thus also TSP is NP-complete.



open problem: is $IP = NP$?

so far, for all known NP-complete problems, we do know exponential-time algorithms, but not poly-time alg. \Rightarrow it seems $IP \neq NP \dots$?

6. ALGORITHM DESIGN TECHNIQUES

6.1. PARALLEL ALGORITHMS:

see posted notes

6.2. GREEDY ALGORITHMS

proceed in stages; in each stage make the choice that locally looks best

see e.g., Dijkstra, Kruskal, Prim

very natural, see e.g., giving change in coins

40 cents in fewest possible coins

NOT a good approach for every problem!