Notes for Topology: Munkres

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Abstract

Welcome! This document will be used to create notes on Topology for the first 3 chapters of Munkres. Problems and exercises will be completed in a different document. All notes will be written by Saahil Sharma. Text Editor being used is Nvim with WSL 2022. Notes are first dated at 12/12/2023. Thank you.

0.1 Chapter 1

• Notation

If an object a belongs to a set A, we denote this by writing

$$a \in A$$

. If the converse is true - The element a does not belong to a set A, we denote this by writing

$$a \notin A$$

. We say that A is a subset of B if all of the elements of A are also in B, denoted by writing

$$A \subset B$$

. If A is not the same as B, we call A a proper subset of B, denoted with

$$A \subseteq B$$

. These relations are called inclusion and proper inclusion, respectively. It can be read as "B contains A".

How can one specify a set?

If a set is short, one can simply list the elements of the set:

$$A = \{a, b, c\}.$$

• Set Builder Notation:

If a set is too long, or possibly infintely long, we can use set builder notation to list the items within the set. To define the set B using set builder notation, we denote B as

$$B = \{x \mid x \text{ is an even integer }\}.$$

In this example, B would be the set of all even integers.

The union of two sets is defined as

$$A \cup B = \{x \mid x \in A \text{or} x \in B\}.$$

The intersection of two sets in defined as

$$A \cap B = \{x \mid x \in A \text{and} x \in B\}.$$

What if A and B have no elements in common? To denote this set, we use the empty set, which is written as

$$\varnothing = \{\}.$$

This fact can also be expressed by saying A and B are disjoint.

• The Difference of 2 Sets

Think about this as litterally subtracting out the terms that exist in A and B. To define this with rigor, we can write

$$A - B = \{ x \mid x \in A \text{ and } x \notin B \}.$$

This can sometimes be called the *complement* of B relative to A.

• Rules of Set Theory

- 1

$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$

This sort of resembles the distributive property.

- 2

$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$$

This also shares a resemblence to the distrubitive property.

- 3

$$A - (B \cup C) = (A - B) \cap (A - C)$$

-4

$$A - (B \cap C) = (A - B) \cup (A - C)$$

An efficient way to memorize this:

- * 1 The complement of the union equals the intersection of the complements.
- * 2 The complement of the intersection equals the union of the complements.
- Sets

A set can consist of anything, from other numbers to sets themselves. You can have a set of of all the subsets in a set:

$$A = \{ A \mid A \text{ is a subset of } B \}.$$

This is sometimes called the power set of B, denoted as \mathcal{B} . A set whose elements are set is commonly referred to as a collection of sets.

We now make a distinction in notation. To illustrate, if A is the set $\{1,2,3\}$, then the following are all equivalent.

$$a \in A, \{a\} \subset A, \text{and}\{a\} \in \mathcal{P}(A).$$

Given a collection of sets A, the **union** of A is defined by the equation

$$\bigcup_{x \in \mathcal{A}} A = \{ x \mid x \in A \text{ for at least one } A \in \mathcal{A} \}.$$

The intersection of the elements a is defined by the equation

$$\bigcap_{x \in \mathcal{A}} A = \{ x \mid x \in A \text{ for every } A \in \mathcal{A} \}.$$

This intersection is not defined when A is empty.

 \bullet Cartesian Products Given sets A and B, we can define their cartesian product to be

$$A \times B = \{(a, b) \mid a \in A \text{ and } b \in B\}$$

The cartesian product is the set of all ordered pairs, (a, b), such that a is an element of A and b is an element of B.

• Rule of Assignment

A Rule of Assignment r is of $C \times D$ is a rule of assignment if

$$[(c,d) \in r \text{ and } (c,d') \in r] \Longrightarrow [d=d'].$$

We think of r as a way of assigning, to the element c of C, the element d of D, for which $(c, d) \in r$.

Given a rule of assignment r, the **domain** of r is defined to be the subset of C consisting of all the first coordinates of elements of r, and the **image** set of r is defined as the subset of D consisting of all second coordinates of elements of r. Formally,

domain $r = \{c \mid \text{ there exists } d \in D \text{ such that } (c, d) \in r\}, \text{image } r = \{d \mid \text{ there exists } c \in C \text{ such that } (c, d) \in r\}$

• Function A function f is a rule of assignment r, together with a set B, that contains the image set of r. The domain A of the rule r is also called the domain of the function f; the image set of r is also called the **image set** of f; and the set B is called the **range** of f.

If f is a function having domain A and range B, we express this fact by writing

$$f:A\Longrightarrow B$$
,

which is read "f is a function from A to B, or "f is a mapping from A into B," or simply "f maps A into B." One sometimes visualizes f as a geometric transformation physically carrying the points of A to points of B.

If $f:A\Longrightarrow B$ and if a is an element of A, we denote by f(a) the unique element of B that the rule determining f assigns to a; it is called the textbfvalue of f at a, or sometimes the image of a under f. Formally, if r is the rule of the function f, then f(a) denotes the unique element of B such that $(a, f(a)) \in r$. Using this notation, one can go back to defining functions almost as one did before, with no lack of rigor. For instance, one can write (letting $\mathbb R$ denote the real numbers)

"Let f be the function whose rule is $\{(x, x^3+1) \mid x \in \mathbb{R} \text{ and whose range is } \mathbb{R}$ ",

or one can equally write

"Let
$$f: \mathbb{R} \to \mathbb{R}$$
 be the function such that $f(x) = x^3 + 1$."

The sentence let f be the function $f(x) = x^3 + 1$ is no longer adequate for specifying a function because it neither specifies the domain or range of f.

• Restriction IF $f: A \Rightarrow B$ and if A_0 is a subset of A, we define the restriction of f to A_0 to be the function mapping A_0 into B whose rule is

$$\{(a, f(a)) \mid a \in A_0\}.$$

It is denoted by $f/midA_0$, which is read "f restricted to A_0 .

• Composite Functions Given functions $f:A\longrightarrow B$ and $g:B\longrightarrow C$, we define the **composite** $g\circ f$ of f and g as the function $g\circ f:A\longrightarrow C$ defined by the equation $(g\circ f)(a)=g(f(a))$. Formally, $g\circ f:A\longrightarrow C$ is the function whose rule is

$$\{(a,c) \mid \text{For some } b \in B, f(a) = bandg(b) = c\}.$$

In your mind, you can picture this as the point a moving to the point f(a), and then to the point g(f(a)). Note that $g \circ f$ is only defined when the range of f equals the domain of g.

Bijective, Injective, and Surjective A function f: A

B is said to be injective (or one to one) if for each pair of distinct points of A, their images under f are distinct. It is said to be surjective (or f is said to map AontoB) if every element of B is the image of some element of A under the function f. IF f is both injective and surjective, it is said to be bijective (or is called a one to one correspondence). More formally, f is injective if

$$[f(a) = f(a')] \Longrightarrow [a = a'],$$

and f is surjective if

$$[b \in B] \Longrightarrow [b = f(a) \text{ for at least one } a \in A].$$

Injectivity of f depends only on the rule of f; surjectivity depends on the range of f as well. You can check that the composite of two injective functions is injective, and the composite of two sujective functions is surjective; it follows that the composite of two bijective functions is bijective.

If f is bijective, there exists a function from B to A called the **inverse** of f. IT is denoted by f^-1 , and is the standard inverse of f as you have learned. IF f is surjective, this implies there exists such an element in the domain that yields an inverse relationship, and if f is injective then there is *only one* such element that exists.

Lemma 2.1. Let $f: A \longrightarrow B$. If there are functions $g: B \longrightarrow A$ and $h: B \longrightarrow A$ such that g(f(a)) = a for every a in A and f(h(b)) = b for every b in B, then f is bijective and $g = h = f^{-1}$.

• Image Let $f: A \longrightarrow B$. If A_0 is a subset of A, we denote by $f(A_0)$ the set of all images of points of A_0 under the function f; this set is called the **image** of A_0 under f. Formally,

$$f(A_0) = \{b \mid b = f(a) \text{ for at least one } a \in A_0\}.$$

On the other hand, if B_0 is a subset of B, we denote by $f^{-1}(B_0)$ the set of all elements of A whose images under f lie in B_0 ; it is called the **preimage** of B_0 under f, also called the "counterimage" or the "inverse image". Formally,

$$f^{-1}(B_0) = \{ a \mid f(a) \in B_0 \}.$$