

# Curriculum Vitae

## Personal Details

**Full Name** Saar Cohen  
**ID Number** 318228178  
**Address** Kalisher 7, Holon  
**Telephone** 052-6617918  
**E-mail** saar30@gmail.com  
**Year of Birth** 1997 (Israel)

## Education and Academic Achievements

**2021 – present – Bar-Ilan University – Ph.D. candidate in Computer Science**  
“Coalition Formation in Sequential Decision-Making under Uncertainty”, under the supervision of Prof. Noa Agmon.

**2018 – 2021 – Bar-Ilan University – M.Sc. in Computer Science**  
“Spatial Consensus Prevention in Robotic Swarms”, under the supervision of Prof. Noa Agmon. Thesis grade: 98.

**2013-2017 – Tel-Aviv University – B.Sc. in Mathematics:**  
with specialization in Computer Science.

## Reviewing and Volunteering Activities

**2023 – Volunteer – AAAI'23 (Upcoming):** The 37th AAAI Conference on Artificial Intelligence, 2023.

**2022 – Reviewer – AAAI'23:** The 37th AAAI Conference on Artificial Intelligence, 2023.

**2022 – Reviewer – ICRA'23:** IEEE International Conference on Robotics and Automation, 2023.

**2021 – Reviewer – AAMAS'22:** The 21th International Conference on Autonomous Agents and Multiagent Systems, 2022.

**2021 – Reviewer – IEEE Transactions on Robotics (T-RO).**

**2021 – Volunteer – IJCAI '21:** Proceedings of the international Joint Conference on Artificial Intelligence, 2021.

**2021 – Volunteer – AAMAS'21:** Proceedings of the 20th International Conference on Autonomous Agents and Multiagent Systems, 2021.

## Publications

### Journals

Saar Cohen and Noa Agmon. *Recent Advances in Formations of Multiple Robots*. Current Robotics Reports 2, 159–175 (2021). (**Published**)

### Conferences

Saar Cohen and Noa Agmon. *Online Coalitional Skill Formation*. In AAMAS'23: the 22th International Conference on Autonomous Agents and Multiagent Systems, 2023. (**Accepted**)

Saar Cohen and Noa Agmon. *Complexity of Probabilistic Inference in Random Dichotomous Hedonic Games*. In AAAI '23: In Proceedings of the 37th AAAI Conference on Artificial Intelligence, 2023. (**Accepted**)

Saar Cohen and Noa Agmon. *Optimizing Multi-Agent Coordination via Hierarchical Graph Probabilistic Recursive Reasoning*. In AAMAS'22: the 21th

International Conference on Autonomous Agents and Multiagent Systems, 2022.  
(Published)

Saar Cohen and Noa Agmon. *Convexified Graph Neural Networks for Distributed Control in Robotic Swarms*. In IJCAI '21: Proceedings of the international Joint Conference on Artificial Intelligence, 2021. (Published)

Saar Cohen and Noa Agmon. *On The (Im)possibility of Leading a Swarm to a Desired Consensus in Static and Dynamic Settings*. In DARS/SWARM '21: Proceedings of the 4th International Symposium on Swarm Behavior and Bio-Inspired Robotics, 2021. (Published)

Saar Cohen and Noa Agmon. *Spatial Consensus-Prevention in Robotic Swarms*. In AAMAS'21: Proceedings of the 20th International Conference on Autonomous Agents and Multiagent Systems, 2021. (Published)

#### Languages

- Hebrew
- English