Q3 - Assignment 9 | ME7223

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In [1]:

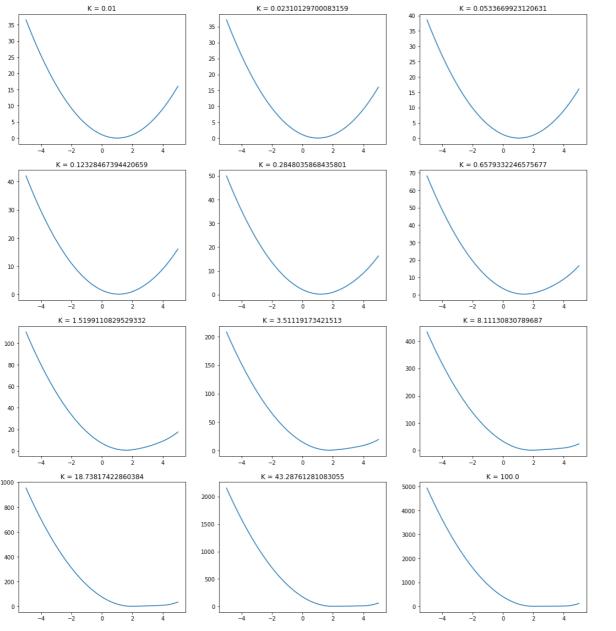
```
import numpy as np
import matplotlib.pyplot as plt
from sympy import symbols, solve
from scipy.optimize import minimize
import scipy
import math
import matplotlib.pyplot as plt
```

In [21]:

```
def f(x):
 2
        return (x-1)**2
 3
 4
   def g1(x):
 5
        return 2-x
 6
 7
   def g2(x):
 8
        return x-4
 9
   def diff f(x):
10
        return 2*(x-1)
11
12
13
   def penalty_ext(x, k):
        term = max(0, g1(x))**2 + max(0,g2(x))**2
14
15
        return f(x) + k*term
```

In [24]:

```
xmin = -5
 2
   xmax = 5
 3
   x = np.linspace(xmin, xmax, 600)
 5
   arr = np.linspace(-10, 10, 12)
   k_{arr} = 10**(0.2*arr)
 6
 7
   k_{arr} = np.reshape(k_{arr}, (4,3))
 8
9
   fig = plt.figure(figsize=(25, 20))
   for i in range(k_arr.shape[0]):
10
        for j in range(k_arr.shape[1]):
11
            y = np.array([penalty_ext(xi,k_arr[i,j]) for xi in x]).reshape(x.shape)
12
            fig.add_subplot(4, 4, 4*i + j + 1)
13
            plt.plot(x,y)
14
            plt.title('K = '+ str(k_arr[i,j]))
15
16
   plt.show()
```

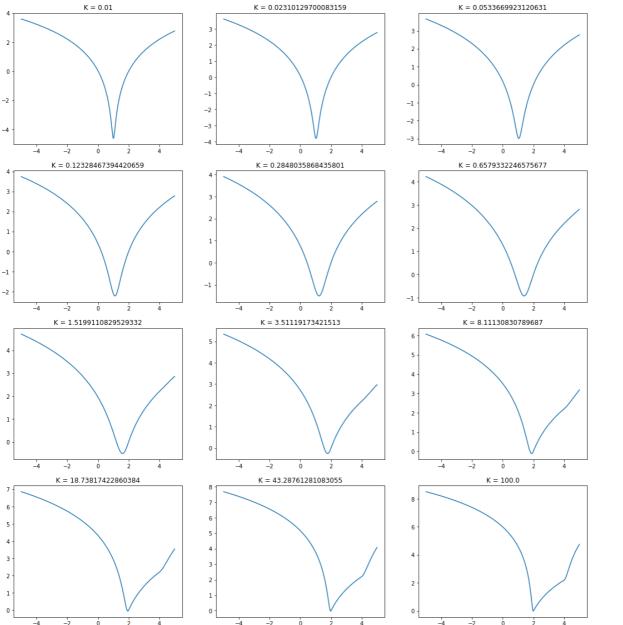


12/19/2020	Q3. ME17B162_Assign9_ME7223 - Jupyter Notebook
Normal graph doesn't give conclusive res understand the graphs, we take a semilog	cults as all of them converge finally with similar slop. To better g graph as shown below.

In [25]:

```
fig = plt.figure(figsize=(25, 20))
for i in range(k_arr.shape[0]):
    for j in range(k_arr.shape[1]):
        y = np.array([penalty_ext(xi,k_arr[i,j]) for xi in x]).reshape(x.shape)
        fig.add_subplot(4, 4, 4*i + j + 1)
        plt.plot(x,np.log(y))
        plt.title('K = '+ str(k_arr[i,j]))

plt.show()
```



From this we can see that, k=100 gives the sharpest change with steepest slope near the minimal and thus we take k=100 as the initial value. And we take k amp as 5.

In [30]:

```
x = 3
 2 print(0, '- Coordinate:', x, '- Objective Function:', f(x))
 4 max_iter = 10
 5
   eps = 2e-5
   err = abs(diff_f(x))
   k = 100
 7
 8 k_amp = 5
 9
   penalty_f = lambda x: penalty_ext(x, k)
10
11
   while err > eps and i<max_iter:</pre>
12
        residual = minimize(penalty_f, x)
13
       x_new = residual['x']
14
       x = x_new
        err = abs(diff_f(x))
15
16
        i = i+1
        k = k_amp * k
17
        print(i, '- Coordinate:', x, '- Objective Function:', f(x))
```

```
0 - Coordinate: 3 - Objective Function: 4
1 - Coordinate: [1.990099] - Objective Function: [0.98029604]
2 - Coordinate: [1.99800399] - Objective Function: [0.99601196]
3 - Coordinate: [1.99960015] - Objective Function: [0.99920047]
4 - Coordinate: [1.99992] - Objective Function: [0.99984]
5 - Coordinate: [1.99998399] - Objective Function: [0.99996799]
6 - Coordinate: [1.9999968] - Objective Function: [0.9999936]
7 - Coordinate: [1.99999936] - Objective Function: [0.999999872]
8 - Coordinate: [1.9999997] - Objective Function: [0.999999994]
9 - Coordinate: [1.9999997] - Objective Function: [0.999999999]
```