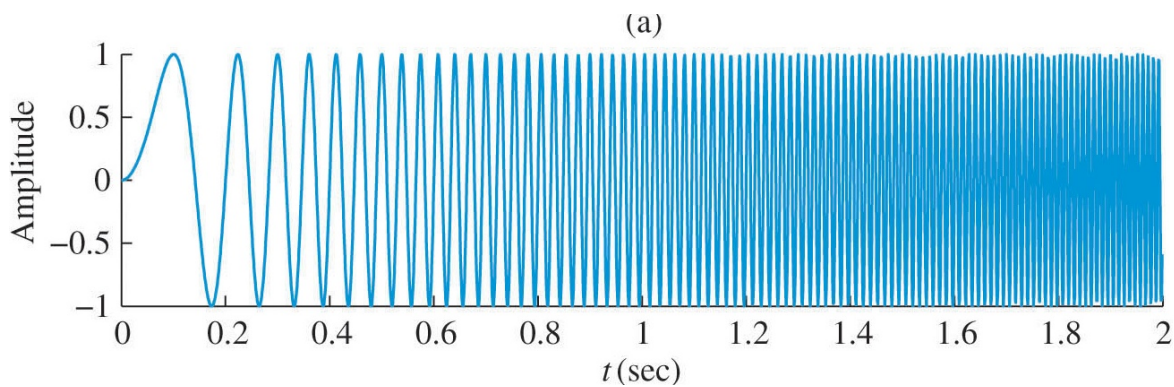


## Chap 7.6

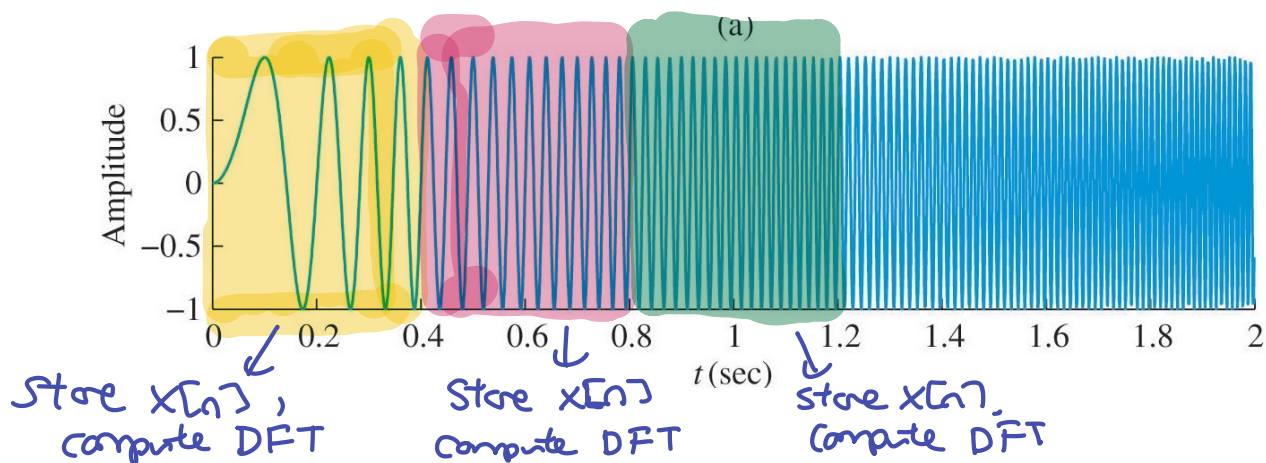
As we noted before, it is often not practical to collect all  $N$ -values of some signal  $x[n]$  before we do an  $N$ -point DFT

Another issue is that the frequency component may be changing over time

For example, the chirp signal, where the frequency is increasing over time



Since we don't know if a signal frequency changes or not, it's best to keep the sampling frequency the same but compute the DFT in chunks (i.e. window) (window may overlap)

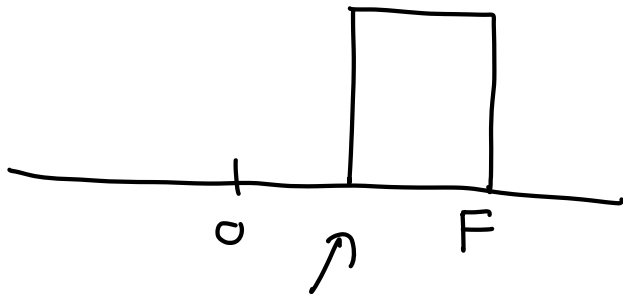


We pay a price for this windowing method

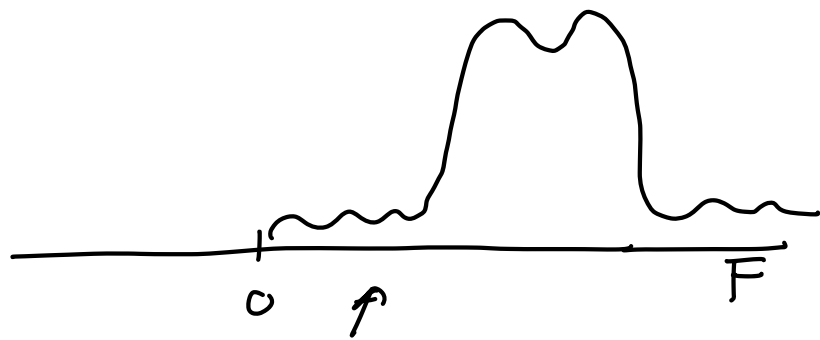
1) more computation

2) we have to choose a windowing function  
(rectangular, hamming, hann, etc.)

All windowing function will cause  
smearing and leakage in the frequency domain



No smearing  
and leakage



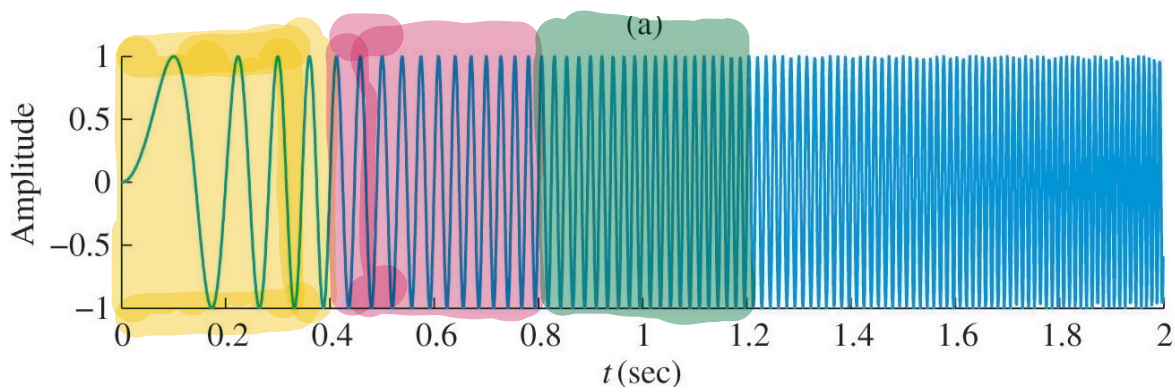
with smearing  
and leakage

The idea of breaking a long signal into small  
segments and analyze each one with the DFT is  
called time-dependent or short-time DFT

$$X[k, n] \equiv \sum_{m=0}^{L-1} w[m] x[n+m] e^{-j\left(\frac{2\pi k}{N}\right)m}$$

↑ time                      ↑ window function

$L$  = length of each window, we compute an  $N$ -point DFT, so  $N \geq L$



The windows may overlap by  $m$ , so  $m \leq L$

Unlike classic DFT, the short-time DFT,  $X[k, n]$  is 2-dimensional

$$X[k, n]$$

↑ frequency
↑ time

Component

$$\omega_k = \frac{2\pi k}{N} \text{ at time index } n$$

The 2-D picture is called a spectrogram. Usually  $|X[k, n]|$  or  $\log |X[k, n]|$  is visualized by color