

Vacuum Cleaner

```
def vacuum-world():
```

```
    goal-state = {'A': '0', 'B': '0'}
```

```
    cost = 0
```

```
    location = input ("Enter location of vacuum")
```

```
    status = input ("Enter status of location :")
```

```
    status_complement = input ("Enter status of other room")
```

```
    print ("Initial location condition " + str(goal-state))
```

```
    if location == '1':
```

```
        print ("Location A is dirty")
```

```
        goal-state ['A'] = '0'
```

```
        cost += 1
```

```
        print ("Cost for cleaning A" + str(cost))
```

```
        print ("Location A has been cleaned")
```

```
        if status_complement == '1':
```

```
            print ("Location B is dirty")
```

```
            print ("Moving right to location B")
```

```
            cost += 1
```

```
            print ("Cost for moving right" + str(cost))
```

```
            goal-state ['B'] = '0'
```

```
            cost += 1
```

```
            print ("Cost for suck" + str(cost))
```

```
            print ("Location B has been cleaned")
```

```
        else:
```

```
            print ("No action" + str(cost))
```

```
            print ("Location B is already clean")
```

```
    if status == '0':
```

```
        print ("Location A is already clean")
```

if status-complement == '1':

print ("Location B is dirty")

print ("Moving right to location B")

cost += 1

print ("Cost for moving right" + str(cost))

goal-state['B'] = '0'

cost += 1

print ("Cost for suck" + cost)

print ("Location B has been cleaned")

else:

print ("No action" + str(cost))

~~print (cost)~~

print ("Location B is already clean")

else:

print ("Vacuum is placed in location B")

if status == '1':

print ("Location B is dirty")

goal-state['B'] = '0'

cost += 1

print ("Cost for cleaning" + str(cost))

print ("Location B has been cleaned")

if status-complement == '1':

print ("Location A is dirty")

print ("Moving left to location A")

cost += 1

print ("Cost for moving left" + str(cost))

goal-state['A'] = '0'

cost += 1

print ("Cost for suck" + cost)

print ("Location A has been cleaned")

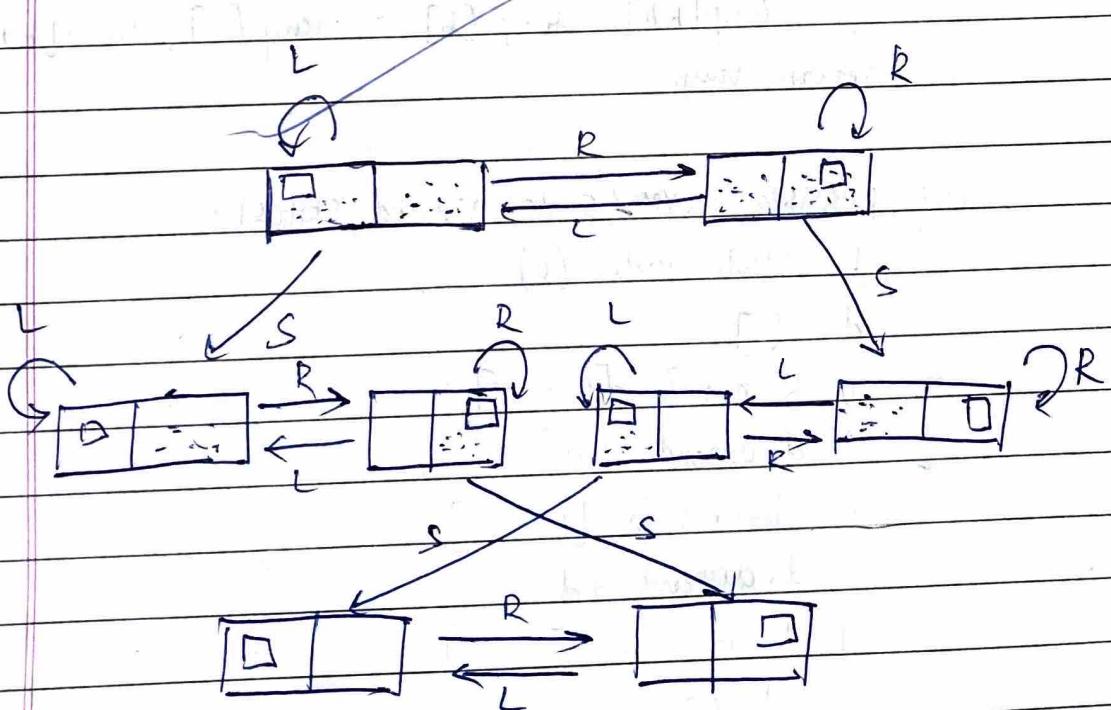
else

print (cost)

```

print (" location B is already clean")
if status-complement == '1':
    print (" location A is dirty")
    print (" Moving left to location A")
    cost += 1
    print (" Cost for moving left " + cost)
    goal-state ['A'] = '0'
    cost += 1
    print (" Cost for suck " + cost)
    print (" location A has been cleaned")
else
    print ("No action " + cost)
    print ("location A is already clean")
    print ("Goal state")
    print ("goal-state")
    print ("Performance measurement " + cost)

```



Program-2

8 puzzle using BFS

```
import numpy as np  
import pandas as pd  
import os
```

```
def gen(state, m, b):  
    temp = state.copy()
```

```
    if m == 'd':
```

```
        temp[b+3], temp[b] = temp[b], temp[b+3]
```

```
    elif m == 'u':
```

```
        temp[b-3], temp[b] = temp[b], temp[b-3]
```

```
    elif m == 'l':
```

```
        temp[b-1], temp[b] = temp[b], temp[b-1]
```

```
    elif m == 'r':
```

```
        temp[b+1], temp[b] = temp[b], temp[b+1]
```

```
    return temp
```

```
def possible_moves(state, visited_states):
```

```
    b = state.index(0)
```

```
    d = []
```

```
    if b not in [0, 1, 2]:
```

```
        d.append('u')
```

```
    if b not in [6, 7, 8]:
```

```
        d.append('d')
```

```
    if b not in [0, 3, 6]:
```

```
        d.append('l')
```

```
    if b not in [2, 5, 8]:
```

```
        d.append('r')
```

pos-moves = []

for i in d :

pos-moves.append(gen(state, i, b))

return [move for move in pos-moves if move not in visited-states]

def bfs(src, target)

queue = []

queue.append(src)

cost = 0

exp = []

while len(queue) > 0 :

source = queue.pop(0)

exp.append(source)

print("queue [n", source)

cost = cost + 1

if source == target :

print("Success")

print("path cost", cost)

return

~~moves = possible_moves(source, exp)~~

for move in moves :

~~if move not in exp and move not in queue :~~

~~queue.append(move)~~

src = [1, 2, 3, 4, 5, 6, 0, 7, 8]

target = [1, 2, 3, 4, 0, 5, 6, 7, 8, 0]

bfs(src, target)

OUTPUT

queue :

$[0, 2, 3, 1, 5, 6, 4, 7, 8]$

$[1, 2, 3, 5, 0, 6, 4, 7, 8]$

1 | 2 | 3

4 | 5 | 6

7 | 0 | 8

queue :

$[1, 2, 3, 5, 0, 6, 4, 7, 8]$

$[1, 2, 3, 4, 0, 6, 7, 5, 8]$

$[1, 2, 3, 4, 5, 6, 7, 8, 0]$

0 | 2 | 3

1 | 5 | 6

4 | 7 | 8

queue :

$[2, 0, 3, 1, 5, 6, 4, 7, 8]$

$[1, 0, 3, 5, 2, 6, 4, 7, 8]$

~~0 0 0 0 0~~ 1 | 2 | 3

~~0 0 0 0~~ 4 | 0 | 6

7 | 5 | 8

queue :

$[1, 2, 3, 4, 6, 0, 7, 5, 8]$

1 | 2 | 3

4 | 5 | 6

7 | 8 | 0

Program-3

Tic Tac Toe

~~board~~

~~board~~ = $\begin{bmatrix} "", "", "" \\ "", "", "" \\ "", "", "" \end{bmatrix}$

def print_board():

for row in board:

print ("|", join(row))

print (" - " * 5)

def check_winner (player):

for i in range(3):

if all ([board[i][j] == player for j in range(3)])
or

all ([board[j][i] == player for j in range(3)])

return True

if all ([board[i][i] == player for i in range(3)])

or

all ([board[i][2-i] == player for i in range(3)]):

return True

return False

def is_full ():

return all ([cell != " " for row in board for cell in row])

def minimax (depth, is_maximizing):

if check_winner ("X"):

return -1

if check_winner ("O"):

return 1

```
if is-full()
    return 0

if is-maximizing:
    max-eval = float("-inf")
    for i in range(3):
        for j in range(3):
            if board[i][j] == " ":
                board[i][j] = "O"
                eval = minimax(depth+1, False)
                board[i][j] = " "
            max-eval = max(max-eval, eval)
    return max-eval

else:
    min-eval = float("inf")
    for i in range(3):
        for j in range(3):
            if board[i][j] == " ":
                board[i][j] = "X"
                eval = minimax(depth+1, True)
                board[i][j] = " "
            min-eval = min(min-eval, eval)
    return min-eval.
```

```
def ai-move():
    best-move = None
    best-eval = float("-inf")
    for i in range(3):
        for j in range(3):
            if board[i][j] == " ":
                board[i][j] = "O"
                eval = minimax(0, False)
                board[i][j] = " "
            if eval > best-eval:
                best-move = (i, j)
                best-eval = eval
    return best-move
```

```
if eval > best_eval:  
    best_eval = eval  
    best_move = (i, j)  
return best_move
```

while not is_full() and not check_winner("X") and not check_winner("O");

```
print_board()  
row = input("Enter row: ")  
col = int(input("Enter column: "))  
if board[row][col] == " ":  
    board[row][col] = "X"  
    if check_winner("X"):  
        print_board()  
        print("You win!")  
        break  
    if is_full():  
        print_board()  
        print("It's a draw!")  
        break  
    ai_row, ai_col = best_move()  
    board[ai_row][ai_col] = "O"  
    if check_winner("O"):  
        print_board()  
        print("AI wins!")  
        break  
    else:  
        print("Cell is already occupied")
```

OUTPUT

Enter row : 0

Enter col : 0

X	
	O

Enter row : 2

Enter col : 2

X	O
	O
	X

Enter row : 2

Enter col : 1

X	O
	O

O X | X

Enter row : 0

Enter col : 1

X | O | X

X | O | O

O | X | X

It's a draw

~~QUESTION~~

Iterative Deepening Search

AIM

Implement Iterative Deepening Search

from collection import defaultdict

class graph:

def __init__(self, vertices):

self.v = vertices

self.graph = defaultdict(list)

def addEdge(self, u, v):

self.graph[u].append(v)

def DLS(self, src, target, maxDepth):

if src == Target:

return True

if maxDepth <= 0:

return False

if i in self.graph[src]:

if self.DLS(i, target, maxDepth - 1):

return True

return False

def IDDFS(self, src, target, maxDepth):

for i in range(maxDepth):

if self.DLS(src, target, i):

return True

return False

```
n = int(input("Enter number of Vertices : "))
```

```
g = Graph(n)
```

```
e = int(input("Enter the number of Edge : "))
```

```
for _ in range(e):
```

```
    u,v = map(int, input("Enter edge(u,v) : ").split())
```

```
    g.addEdge(u,v)
```

```
src = int(input("Enter the source node : "))
```

```
target = int(input("Enter the target node : "))
```

```
maxDepth = int(input("Enter maximum depth : "))
```

~~if g.BFS(src, target, maxDepth):~~

~~print(f"Target {target} is reachable from source~~

~~{src} with max depth {maxDepth}")~~

~~else~~

~~print(f"Target {target} is Not reachable from source~~

~~{src} with max depth {maxDepth}")~~

OUTPUT

```
Enter no of Vertices : 8
```

```
Enter no of edges : 7
```

```
Enter edge (u,v) : 0 1
```

```
Enter edge (u,v) : 0 2
```

```
Enter edge (u,v) : 1 3
```

```
Enter edge (u,v) : 1 4
```

```
Enter edge (u,v) : 2 5
```

```
Enter edge (u,v) : 2 6
```

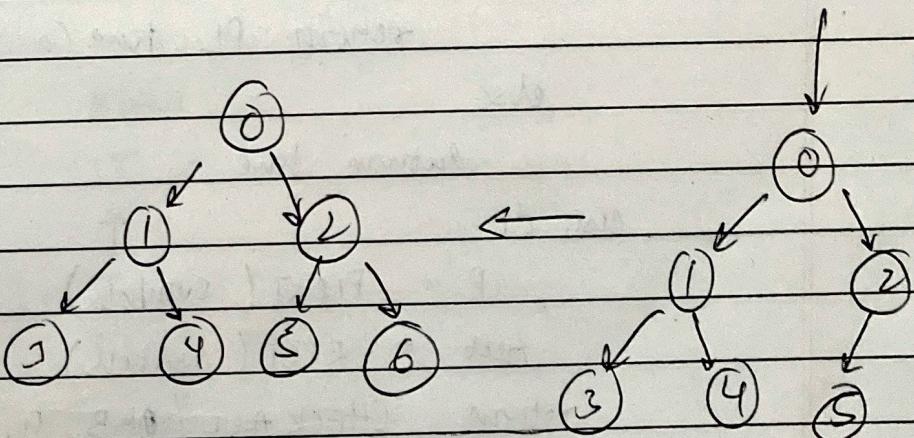
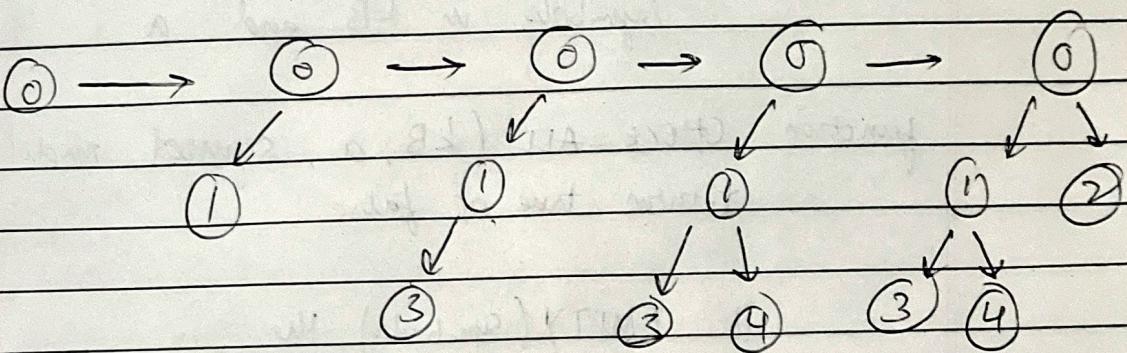
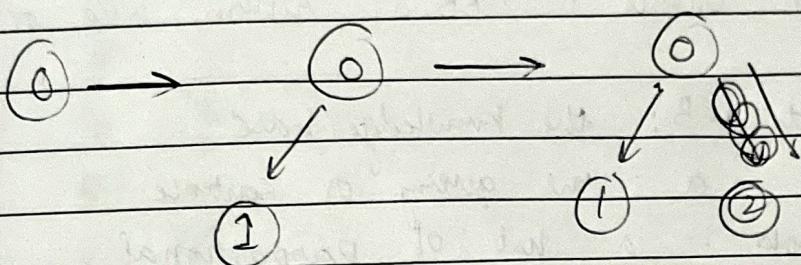
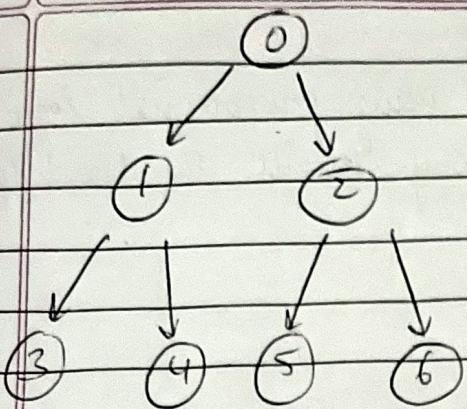
```
Enter edge (u,v) : 3 7
```

```
Enter source node : 0
```

```
Enter target : 7
```

```
Enter max depth : 2
```

```
Target 7 is not reachable from 0 with maxdepth 2
```



Implement 8-puzzle problem using A* algo

A* algo

Optimized value $f(n) = g(n) + h(n)$

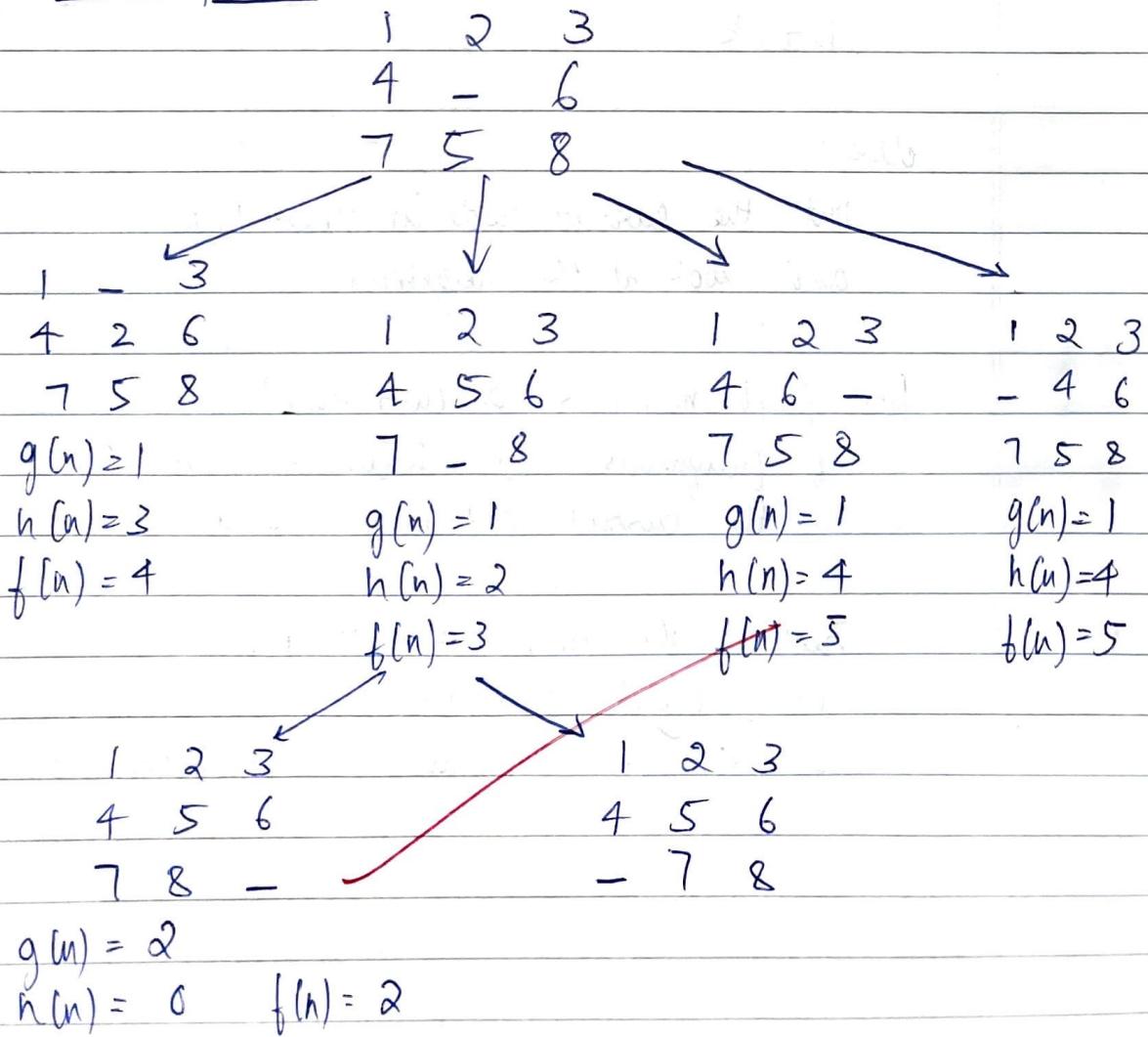
Start State

$$\begin{matrix} 1 & 2 & 3 \\ 4 & - & 6 \\ 7 & 5 & 8 \end{matrix}$$

Goal State

$$\begin{matrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & - \end{matrix}$$

State Space Tree:



Algorithm :

Input : Graph (G_1) - Heuristic value $f(n)$,
start state (s), Goal node (g_1)

Output : Cost of the path

- Make an open list containing only start node
- Make an empty closed list

while (@ goal state not reached) :

 Consider the node with the
 lowest $f(n)$ value in the
 open list

if (node is destination node):

 print the cost
 break

else :

 put the current node in closed list
 and look at the neighbours

for (each neighbour of curr node) :

 if (neighbour has / lower g value) :
 the current node is in closed list .

 replace the neighbour with the
 new, lower g value

 current node is now the neighbour's parent

use it (current g value is lower and this neighbour is in open list);

replace the neighbour with the new lower g value.

Change the neighbour's parent to our current node

else if (the neighbour is not in both the lists)

add it to the open list and set its g value

~~df~~ ~~gfb~~
~~gfb~~ 08.01.24

Program 6

Create a knowledge bot using propositional logic
Show that the given query entails the knowledge base or not.

Algorithm

function Entails ? (KB, a) return true or false

input KB : the knowledge base

a : the query or sentence

Symbols : a list of propositional symbols in KB and a

function CHECK-ALL (KB, a, symbol, model)
return true or false

if EMPTY (symbols) then

if PL-true ? (KB, model) then

return PL-true (a, model)

else

return true

else do

P = FIRST (symbols)

rest = REST (symbols)

return CHECKALL (KB, a, rest, extend
(p, true, model))

and CHECKALL (KB, a, rest, extend
(p, false, model))

Knowledge base (Truth Table)

KB : $(P \vee Q) \wedge (P \wedge \neg R)$

P	Q	R	$P \vee Q$	$\neg R$	$P \wedge \neg R$	$(P \vee Q) \wedge (P \wedge \neg R)$
T	T	T	T	F	F	F
T	T	F	T	T	F	T
T	F	T	T	F	F	F
T	F	F	T	T	T	T
F	T	F	T	F	F	F
F	F	F	F	F	F	F
F	F	F	F	T	F	F

The knowledge base entails the query

OUTPUT

Enter rule: $(P \vee Q) \wedge (P \wedge \neg R)$

Enter query: P

Truth table

KB	Alpha
F	T
T	T
F	T
T	T
F	F
F	F
F	F

knowledge base entails query

If query = Y,

The knowledge base doesn't entail query.

Program 7

Create a knowledge base using propositional logic
and prove the given query using resolution

Algorithm

function PL-RESOLUTION (KB, X) Return true or false

inputs: $KB \rightarrow$ the knowledge base, a

① sentence in propositional logic

$X \rightarrow$ the query sentence in propositional clause
the set of clauses in CNF representation of

$KB \wedge \neg X$

new $\leftarrow \{ \}$

loop do

for each pair of clauses, c_i, c_j in clauses

resolve \leftarrow PL-RESOLVE(c_i, c_j)

if resolve contains empty clause

return true

new \leftarrow new \vee resolve

if new \subseteq clause then return false

clause \leftarrow clause \vee new

KB

P

Query

R

$P \wedge Q \rightarrow R$

$S \vee t \rightarrow Q \Rightarrow KB \vee \neg X$

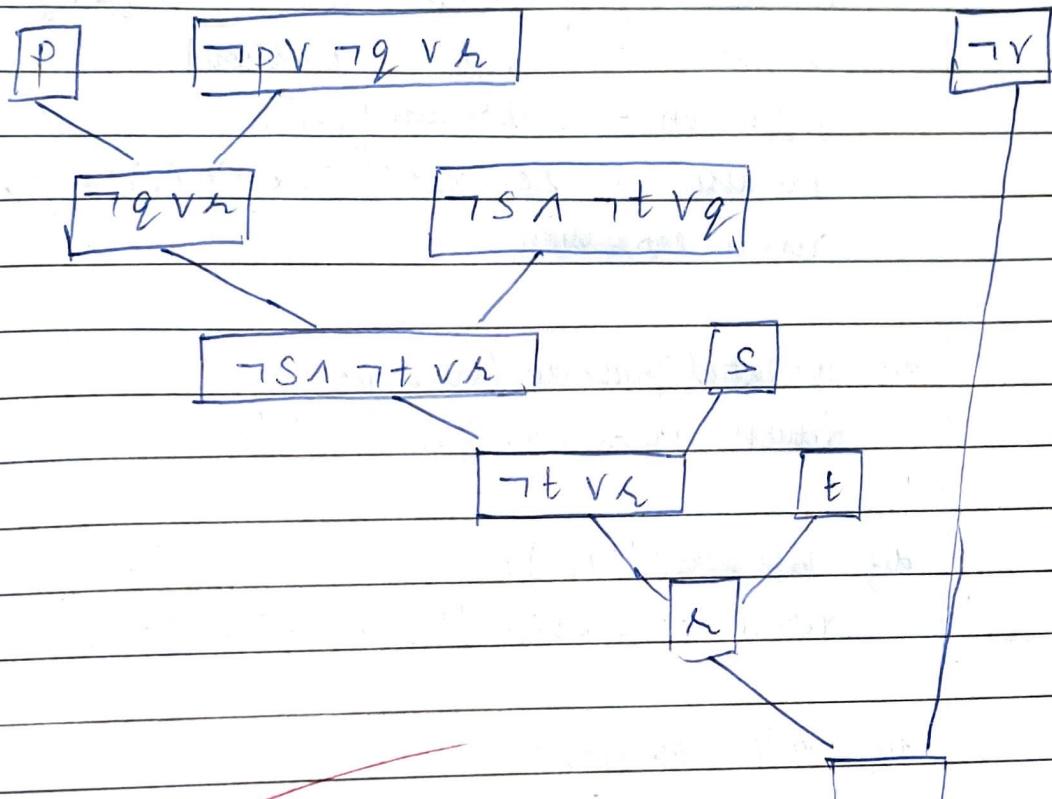
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S

Convert to CNF

$$\begin{aligned}\neg(p \wedge q) \vee r &\rightarrow \neg p \vee \neg q \vee r \\ \neg(s \vee t) \vee q &\rightarrow \neg s \wedge \neg t \vee q\end{aligned}$$

Resolution



OUTPUT
✓ True

Program 8

Implement unification in first order logic

import re

```
def getAttributes(expression):
    expression = expression.split("(")[1:]
    expression = ".join(expression)
    expression = expression[:-1]
    expression = re.split("(?
```

```
def getInitialPredicate(expression):
    return expression.split("(")[0]
```

```
def isConstant(char):
    return char.isupper() and len(char) == 1
```

```
def isVariable(char):
    return char.islower() and len(char) == 1
```

```
def replaceAttributes(exp, old, new):
```

attributes = getAttributes(exp)

for index, val in enumerate(attributes):

if val == old:

attributes[index] = new

predicate = getInitialPredicate(exp)

return predicate + "(" + ", ".join(attributes) + ")"

```
def unify (exp1, exp2):
    if exp1 == exp2:
        return []
```

```
if isConstant (exp1) and isConstant (exp2):
    if exp1 != exp2:
        return False
```

```
if isConstant (exp1):
    return [exp1, exp2]
```

```
if isConstant (exp2):
    return [exp2, exp1]
```

```
if isVariable (exp1):
    if checkOccurs (exp1, exp2):
        return False
    else
        return [exp2, exp1]
```

```
if isVariable (exp2):
    if checkOccurs (exp2, exp1):
        return False
    else
        return [exp1, exp2]
```

✓

```
if getInitialPredicate (exp1) != getInitialPredicate (exp2):
    print ("Predicates do not match. Cannot be unified")
    return False
```

OUTPUT

Substitutions :

[('x', 'Richard')]

Program 9

Convert a given FOL statement into CNF

```
def getAttributes(string):
    expr = '\w+([^\w]+)+'
    matches = re.findall(expr, string)
    return [m for m in matches if m.isalpha()]
```

```
def getPredicates(string):
    expr = '[a-zA-Z~]+([A-Za-zA-Z, ]+)+'
    return re.findall(expr, string)
```

```
def DeMorgan(sentence):
    string = " ".join(list(sentence).copy())
    string = string.replace('~', '')
    flag = '[' in string
    string = string.replace('`[', '')
    string = string.strip(']')
    for predicate in getPredicates(string):
        string = string.replace(predicate, f'`~{predicate}')
    return string
```

② ~~s = list(string)~~

~~for i, c in enumerate(string):~~

~~if c == '|':~~

~~s[i] = '&'~~

~~elif c == '&':~~

~~s[i] = '|'~~

~~string = ''.join(s)~~

~~string = string.replace('~`', '')~~

~~return f'[{string}]' if flag else string~~

def Skolemization (sentence) :

SKOLEM_CONSTANTS = [f' fchr(c)?' for c in range
(ord('A'), ord('Z')+1)]

Statement = ".join(list(sentence).copy())

matches = re.findall('`[+?]', statement)

for match in matches [::-1] :

Statement = Statement.replace(match, '')

Statements = re.findall('`[]`[[^?]+?]', statement)

for S in statements :

Statement = Statement.replace(S, S[1:-1])

for predicate in getPredicates(statement) :

attributes = getAttributes(predicate)

if ".join(attributes).islower():"

Statement = Statement.replace(match[1],

SKOLEM_CONSTANTS,

pop(0)

else :

aL = [a for a in attributes if a.islower()]

aU = [a for a in attributes if not a.islower()]

Statement = Statement.replace(aU, f'{SKOLEM_CONSTANTS}

pop(0)} (f'aL[0]' if len(aL) else

match[1]}))

return Statement.

~~print (Skolemization(fol_to_cnf ("animal(y) <=> loves(x,y)")))~~

~~print (Skolemization(fol_to_cnf ("forall x [forall y [animal(y) -> loves(x,y)] -> [exists z [loves(z,x)]]")))~~

~~print (fol_to_cnf ("american(x) & weapon(y) & sells(x,y,z) & hostile(z) -> criminal(x)"))~~

OUTPUT

$[\neg \text{animal}(y) \mid \text{loves}(x,y)] \wedge [\neg \text{loves}(x,y) \mid \text{animal}(y)]$

$[\text{animal}(G(x)) \wedge \neg \text{loves}(x, G(x))] \mid [\text{loves}(F(x), x)]$

$[\neg \text{american}(x) \mid \neg \text{weapon}(y) \mid \neg \text{seeks}(x,y,z) \mid \neg \text{hostile}(z)] \mid$
 $\text{Criminal}(x)$

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Program 10

Create a KB consisting of FOL statements and prove the given query using forward reasoning

import re

def isVariable(x):

return len(x) == 1 and x.islower() and x.isalpha()

def getAttributes(string):

expr = '[([^\"]+)]'

matches = re.findall(expr, string)

return matches

def getPredicates(string):

expr = '([a-zA-Z]+)\([^\d]+\)'

return re.findall(expr, string)

class Fact:

def __init__(self, expression):

self.expression = expression

predicate, params = self.splitExpression(expression)

self.predicate = predicate

self.params = params

self.result = any(self.getConstants())

def splitExpression(self, expression):

predicate = getPredicates(expression)[0]

params = getAttributes(expression)[0], skip("("))

split ',',)

return [predicate, params]

```
def getResult(self):  
    return self.default
```

```
def getConstants(self):
```

```
    return [None if isVariable(c) else c for c in self.constants]
```

```
def getVariables(self):
```

```
    return [v if isVariable(v) else None for v in self.variables]
```

```
class KB:
```

```
def __init__(self):
```

```
    self.facts = set()
```

```
    self.implications = set()
```

```
def tell(self, e):
```

```
    if '=>' in e:
```

```
        self.implications.add(Implication(e))
```

```
    else:
```

```
        self.facts.add(Fact(e))
```

```
for i in self.implications:
```

```
    res = i.evaluate(self.facts)
```

```
    if res:
```

```
        self.facts.add(res)
```

~~def query(self, e):~~ ~~facts = set([f.expression for f in self.facts])~~~~i = 1~~~~print(f'Querying {e}')~~~~for f in facts:~~ ~~if Fact(f).predicate == Fact(e).predicate:~~ ~~print(f'It is {f}'')~~~~i += 1~~

def display(self):

print("All facts : ")

for i, f in enumerate (set ([F.expression for f in
self.facts])):

print(f' {i+1} . {f})

kb = KB()

kb.tell ('missile (x) \Rightarrow weapon(x)')

kb.tell ('missile (M1)')

kb.tell ('enemy (x, America) \Rightarrow hostile (x)')

kb.tell ('american (West)')

kb.tell ('enemy (Nono, American)')

kb.tell ('owns (Nono, M1)')

kb.tell ('missile (x) & owns (Nono, x) \Rightarrow sells (West, x, Nono)')

kb.tell ('criminal (S1)')

kb.display()

OUTPUT

Querying Criminal (x) :

1. Criminal (West)

All facts :

1. criminal (West)

2. sells (West, M1, Nono)

3. weapon (M1)

4. hostile (Nono)

5. owns (Nono, M1)

6. American (West)

7. missile (M1)

8. enemy (Nono, America)

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