CHAPTER FIVE

Basic Computer Organization and Design

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5-1 Instruction Codes

5.10

In this chapter we introduce a basic computer and show how its operation can be specified with register transfer statements. The organization of the computer is defined by its internal registers, the timing and control structure, and the set of instructions that it uses. The design of the computer is then carried out in detail. Although the basic computer presented in this chapter is very small compared to commercial computers, it has the advantage of being simple enough so we can demonstrate the design process without too many complications.

The internal organization of a digital system is defined by the sequence of microoperations it perfurms on date stored in its registers. The general-purpose digital computer is capable of executing various microoperations and, naddition, can be instructed as to what specific sequence of operations it must perform. The user of a computer can control the process by means of a program. A program is a set of instructions shat specify the operations,

operands, and the sequence by which processing has to occur. The dataprocessing task may be altered by specifying a new program with different instructions or specifying the same instructions with different data.

A computer instruction is a binary code that specifies a sequence of microoperations for the computer. Instruction codes together with data are stored in memory. The computer reads each instruction from memory and places it in a control register. The control then interprets the binary code of the instruction and proceeds to execute it by issuing a sequence of microoperations. Every computer has its own unique instruction set. The ability to store and execute instructions, the stored program concept, is the most important property of a general-purpose computer.

instruction code

operation code

An instruction code is a group of bits that instruct the computer to perform a specific operation. It is usually divided into parts, each having its own particular interpretation. The most basic part of an instruction code is its operation part. The operation code of an instruction is a group of bits that define such operations as add, subtract, multiply, shift, and complement. The number of bits required for the operation code of an instruction depends on the total number of operations available in the computer. The operations code must consist of at least *n* bits for a given 2" (or less) distinct operations. As an illustration, consider a computer with 64 distinct operations, one of them being an ADD operation. The operation code consists of six bits, with a bit configuration 110010 assigned to the ADD operation. When this operation code is decoded in the control unit, the computer issues control signals to read an operand from memory and add the operand to a processor register.

At this point we must recognize the relationship between a computer operation and a microoperation. An operation is part of an instruction stored in computer memory. It is a binary code that tells the computer to perform a specific operation. The control unit receives the instruction from memory and interprets the operation code bits. It then issues a sequence of control signals to initiate microoperations in internal computer registers. For every operation code, the control issues a sequence of microoperations needed for the hardware implementation of the specified operation. For this reason, an operation code is sometimes called a macrooperation because it specifies a set of microoperations.

The operation part of an instruction code specifies the operation to be performed. This operation must be performed on some data stored in processor registers or in memory. An instruction code must therefore specify not only the operation but also the registers or the memory words where the operands are to be found, as well as the register or memory word where the result is to be stored. Memory words can be specified in instruction codes by their address. Processor registers can be specified by assigning to the instruction another binary code of k bits that specifies one of 2^k registers. There are many variations for arranging the binary code of instructions, and each computer has its own particular instruction code format. Instruction code formats are con-

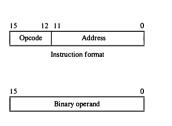
ceived by computer designers who specify the architecture of the computer. In this chapter we choose a particular instruction code to explain the basic organization and design of digital computers.

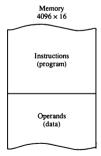
Stored Program Organization

The simplest way to organize a computer is to have one processor register and an instruction code format with two parts. The first part specifies the operation to be performed and the second specifies an address. The memory address tells the control where to find an operand in memory. This operand is read from memory and used as the data to be operated on together with the data stored in the processor register.

Figure 5-1 depicts this type of organization. Instructions are stored in one section of memory and data in another. For a memory unit with 4096 words we need 12 bits to specify an address since 2¹² = 4096. If we store each instruction code in one 16-bit memory word, we have available four bits for the operation code (abbreviated opcode) to specify one out of 16 possible operations, and 12 bits to specify the address of an operand. The control reads a 16-bit instruction from the program portion of memory. It uses the 12-bit address part of the instruction to read a 16-bit operand from the data portion of memory. It then executes the operation specified by the operation code.

Figure 5-1 Stored program organization.





Processor register (accumulator or AC)

opcode

accumulator (AC)

Computers that have a single-processor register usually assign to it the name accumulator and label it AC. The operation is performed with the memory operand and the content of AC.

If an operation in an instruction code does not need an operand from memory, the rest of the bits in the instruction can be used for other purposes. For example, operations such as clear AC, complement AC, and increment AC operate on data stored in the AC register. They do not need an operand from memory. For these types of operations, the second part of the instruction code (bits 0 through 11) is not needed for specifying a memory address and can be used to specify other operations for the computer.

Indirect Address

immediate

It is sometimes convenient to use the address bits of an instruction code not as an address but as the actual operand. When the second part of an instruction code specifies an operand, the instruction is said to have an immediate operand. When the second part specifies the address of an operand, the instruction is said to have a direct address. This is in contrast to a third possibility called indirect address, where the bits in the second part of the instruction designate an address of a memory word in which the address of the operand is found. One bit of the instruction code can be used to distinguish between a direct and an indirect address.

As an illustration of this configuration, consider the instruction code format shown in Fig. 5-2(a). It consists of a 3-bit operation code, a 12-bit address, and an indirect address mode bit designated by I. The mode bit is 0 for a direct address and 1 for an indirect address. A direct address instruction is shown in Fig. 5-2(b). It is placed in address 22 in memory. The I bit is 0, so the instruction is recognized as a direct address instruction. The opcode specifies an ADD instruction, and the address part is the binary equivalent of 457. The control finds the operand in memory at address 457 and adds it to the content of AC. The instruction in address 35 shown in Fig. 5-2(c) has a mode bit I = 1. Therefore, it is recognized as an indirect address instruction. The address part is the binary equivalent of 300. The control goes to address 300 to find the address of the operand. The address of the operand in this case is 1350. The operand found in address 1350 is then added to the content of AC. The indirect address instruction needs two references to memory to fetch an operand. The first reference is needed to read the address of the operand; the second is for the operand itself. We define the effective address to be the address of the operand in a computation-type instruction or the target address in a branch-type instruction. Thus the effective address in the instruction of Fig. 5-2(b) is 457 and in the instruction of Fig 5-2(c) is 1350.

effective address

The direct and indirect addressing modes are used in the computer presented in this chapter. The memory word that holds the address of the operand in an indirect address instruction is used as a pointer to an array of

AC

(c) Indirect address

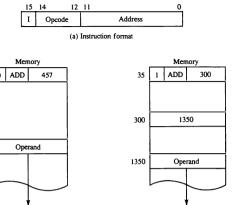


Figure 5-2 Demonstration of direct and indirect address.

data. The pointer could be placed in a processor register instead of memory as done in commercial computers.

5-2 Computer Registers

AC

(b) Direct address

22

457

Computer instructions are normally stored in consecutive memory locations and are executed sequentially one at a time. The control reads an instruction from a specific address in memory and executes it. It then continues by reading the next instruction in sequence and executes it, and so on. This type of instruction sequencing needs a counter to calculate the address of the next instruction after execution of the current instruction is completed. It is also necessary to provide a register in the control unit for storing the instruction

code after it is read from memory. The computer needs processor registers for manipulating data and a register for holding a memory address. These requirements dictate the register configuration shown in Fig. 5-3. The registers are also listed in Table 5-1 together with a brief description of their function and the number of bits that they contain.

The memory unit has a capacity of 4096 words and each word contains 16 bits. Twelve bits of an instruction word are needed to specify the address of an operand. This leaves three bits for the operation part of the instruction and a bit to specify a direct or indirect address. The data register (DR) holds the operand read from memory. The accumulator (AC) register is a general-purpose processing register. The instruction read from memory is placed in the instruction register (IR). The temporary register (TR) is used for holding temporary data during the processing.

Register symbol	Number of bits	Register name	Function	
3yiii001	OI OILS	Register name	1 unction	
DR 16	Data register	Holds memory operand		
AR	12	Address register	Holds address for memory	
AC	16	Accumulator	Processor register	
IR	16	Instruction register	Holds instruction code	
PC	12	Program counter	Holds address of instruction	
TR	16	Temporary register	Holds temporary data	
INPR	8	Input register Holds input character		
OUTR	8	Output register Holds output character		

TABLE 5-1 List of Registers for the Basic Computer

program counter (PC) The memory address register (AR) has 12 bits since this is the width of a memory address. The program counter (PC) also has 12 bits and it holds the address of the next instruction to be read from memory after the current instruction is executed. The PC goes through a counting sequence and causes the computer to read sequential instructions previously stored in memory. Instruction words are read and executed in sequence unless a branch instruction is encountered. A branch instruction calls for a transfer to a nonconsecutive instruction in the program. The address part of a branch instruction is transferred to PC to become the address of the next instruction. To read an instruction, the content of PC is taken as the address for memory and a memory read cycle is initiated. PC is then incremented by one, so it holds the address of the next instruction in sequence.

Two registers are used for input and output. The input register (INPR) receives an 8-bit character from an input device. The output register (OUTR) holds an 8-bit character for an output device.

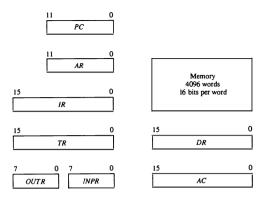


Figure 5-3 Basic computer registers and memory.

Common Bus System

The basic computer has eight registers, a memory unit, and a control unit (to be presented in Sec. 5-4). Paths must be provided to transfer information from one register to another and between memory and registers. The number of wires will be excessive if connections are made between the outputs of each register and the inputs of the other registers. A more efficient scheme for transferring information in a system with many registers is to use a common bus. We have shown in Sec. 4-3 how to construct a bus system using multiplexers or three-state buffer gates. The connection of the registers and memory of the basic computer to a common bus system is shown in Fig. 5-4.

The outputs of seven registers and memory are connected to the common bus. The specific output that is selected for the bus lines at any given time is determined from the binary value of the selection variables S_2 , S_1 , and S_0 . The number along each output shows the decimal equivalent of the required binary selection. For example, the number along the output of DR is 3. The 16-bit outputs of DR are placed on the bus lines when $S_2S_1S_0 = 011$ since this is the binary value of decimal 3. The lines from the common bus are connected to the inputs of each register and the data inputs of the memory. The particular register whose LD (load) input is enabled receives the data from the bus during the next clock pulse transition. The memory receives the contents of the bus when its write input is activated. The memory places its 16-bit output onto the bus when the read input is activated and $S_2S_1S_0 = 111$.

Four registers, DR, AC, IR, and TR, have 16 bits each. Two registers, AR

load (LD)

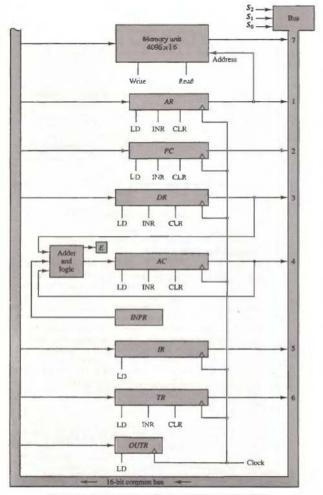


Figure 5-4 Basic computer registers connected to a common bus.

and *PC*, have 12 bits each since they hold a memory address. When the contents of *AR* or *PC* are applied to the 16-bit common bus, the four most significant bits are set to 0's. When *AR* or *PC* receive information from the bus, only the 12 least significant bits are transferred into the register.

The input register INPR and the output register OUTR have 8 bits each and communicate with the eight least significant bits in the bus. INPR is connected to provide information to the bus but OUTR can only receive information from the bus. This is because INPR receives a character from an input device which is then transferred to AC. OUTR receives a character from AC and delivers it to an output device. There is no transfer from OUTR to any of the other registers.

The 16 lines of the common bus receive information from six registers and the memory unit. The bus lines are connected to the inputs of six registers and the memory. Five registers have three control inputs: LD (load), INR (increment), and CLR (clear). This type of register is equivalent to a binary counter with parallel load and synchronous clear similar to the one shown in Fig. 2-11. The increment operation is achieved by enabling the count input of the counter. Two registers have only a LD input. This type of register is shown in Fig. 2-7.

The input data and output data of the memory are connected to the common bus, but the memory address is connected to AR. Therefore, AR must always be used to specify a memory address. By using a single register for the address, we eliminate the need for an address bus that would have been needed otherwise. The content of any register can be specified for the memory data input during a write operation. Similarly, any register can receive the data from memory after a read operation except AC.

The 16 inputs of AC come from an adder and logic circuit. This circuit has threesets of inputs. One set of 16-bit inputs come from the outputs of AC. They are used to implement register microoperations such as complement AC and shift AC. Another set of 16-bit inputs come from the data register DR. The inputs from DR and AC are used for arithmetic and logic microoperations, such as add DR to AC or AND DR to AC. The result of an addition is transferred to AC and the end carry-out of the addition is transferred to flip-flop E (extended AC bit). A third set of 8-bit inputs come from the input register INPR. The operation of INPR and OUTR is explained in Sec. 5-7.

Note that the content of any register can be applied onto the bus and an operation can be performed in the adder and logic circuit during the same clock cycle. The clock transition at the end of the cycle transfers the content of the bus into the designated destination register and the output of the adder and logic circuit into AC. For example, the two microoperations

$$DR \leftarrow AC$$
 and $AC \leftarrow DR$

can be executed at the same time. This can be done by placing the content of AC on the bus (with $S_2S_1S_0 = 100$), enabling the LD (load) input of DR, trans-

memory address

ferring the content of DR through the adder and logic circuit into AC, and enabling the LD (load) input of AC, all during the same clock cycle. The two transfers occur upon the arrival of the clock pulse transition at the end of the clock cycle.

Computer Instructions 5-3

Instruction format

The basic computer has three instruction code formats, as shown in Fig. 5-5. Each format has 16 bits. The operation code (opcode) part of the instruction contains three bits and the meaning of the remaining 13 bits depends on the operation code encountered. A memory-reference instruction uses 12 bits to specify an address and one bit to specify the addressing mode I. I is equal to 0 for direct address and to 1 for indirect address (see Fig. 5-2). The registerreference instructions are recognized by the operation code 111 with a 0 in the leftmost bit (bit 15) of the instruction. A register-reference instruction specifies an operation on or a test of the AC register. An operand from memory is not needed; therefore, the other 12 bits are used to specify the operation or test to be executed. Similarly, an input-output instruction does not need a reference to memory and is recognized by the operation code 111 with a 1 in the leftmost bit of the instruction. The remaining 12 bits are used to specify the type of input-output operation or test performed.

The type of instruction is recognized by the computer control from the four bits in positions 12 through 15 of the instruction. If the three opcode bits in positions 12 though 14 are not equal to 111, the instruction is a memory-reference type and the bit in position 15 is taken as the addressing mode I. If the 3-bit opcode is equal to 111, control then inspects the bit in position 15. If this bit is 0, the

15 14 12 11 Opcode Address (Opcode = 000 through 110) (a) Memory - reference instruction 15 12 11 0 n Register operation (Opcode = 111, I = 0)(b) Register - reference instruction 15 12 11 0 1 I/O operation

(Opcode = 111, I = 1)

Figure 5-5 Basic computer instruction formats.

(c) Input - output instruction

instruction is a register-reference type. If the bit is 1, the instruction is an input—output type. Note that the bit in position 15 of the instruction code is designated by the symbol *I* but is not used as a mode bit when the operation code is equal to 111.

Only three bits of the instruction are used for the operation code. It may seem that the computer is restricted to a maximum of eight distinct operations. However, since register-reference and input—output instructions use the remaining 12 bits as part of the operation code, the total number of instructions can exceed eight. In fact, the total number of instructions chosen for the basic computer is equal to 25.

The instructions for the computer are listed in Table 5-2. The symbol designation is a three-letter word and represents an abbreviation intended for

TABLE 5-2 Basic Computer Instructions

			<u> </u>		
Hexadecimal code					
Symbol	<i>I</i> = 0	<i>I</i> = 1	Description		
AND	Оххх	8xxx	AND memory word to AC		
ADD	1xxx	9xxx	Add memory word to AC		
LDA	2xxx	Axxx	Load memory word to AC		
STA	3xxx	Bxxx	Store content of AC in memory		
BUN	4xxx	Cxxx	Branch unconditionally		
BSA	5xxx	Dxxx	Branch and save return address		
ISZ	6ххх	Exxx	Increment and skip if zero		
CLA	7800		Clear AC		
CLE	7400		Clear E		
CMA	7200		Complement AC		
CME	7100		Complement E		
CIR	7080		Circulate right AC and E		
CIL	7040		Circulate left AC and E		
INC	7020		Increment AC		
SPA	7010		Skip next instruction if AC positive		
SNA	7008		Skip next instruction if AC negative		
SZA	7004		Skip next instruction if AC zero		
SZE	7002		Skip next instruction if E is 0		
HLT	7001		Halt computer		
INP	F800		Input character to AC		
OUT	F400		Output character from AC		
SKI	F200		Skip on input flag		
SKO	F100		Skip on output flag		
ION	F080		Interrupt on		
IOF	F040		Interrupt off		

hexadecimal code

programmers and users. The hexadecimal code is equal to the equivalent hexadecimal number of the binary code used for the instruction. By using the hexadecimal equivalent we reduced the 16 bits of an instruction code to four digits with each hexadecimal digit being equivalent to four bits. A memory-reference instruction has an address part of 12 bits. The address part is denoted by three x's and stand for the three hexadecimal digits corresponding to the 12-bit address. The last bit of the instruction is designated by the symbol I. When I=0, the last four bits of an instruction have a hexadecimal digit equivalent from 0 to 6 since the last bit is 0. When I=1, the hexadecimal digit equivalent of the last four bits of the instruction ranges from 8 to E since the last bit is 1.

Register-reference instructions use 16 bits to specify an operation. The leftmost four bits are always 0111, which is equivalent to hexadecimal 7. The other three hexadecimal digits give the binary equivalent of the remaining 12 bits. The input—output instructions also use all 16 bits to specify an operation. The last four bits are always 1111, equivalent to hexadecimal F.

Instruction Set Completeness

Before investigating the operations performed by the instructions, let us discuss the type of instructions that must be included in a computer. A computer should have a set of instructions so that the user can construct machine language programs to evaluate any function that is known to be computable. The set of instructions are said to be complete if the computer includes a sufficient number of instructions in each of the following categories:

- 1. Arithmetic, logical, and shift instructions
- Instructions for moving information to and from memory and processor registers
- Program control instructions together with instructions that check status conditions
- 4. Input and output instructions

Arithmetic, logical, and shift instructions provide computational capabilities for processing the type of data that the user may wish to employ. The bulk of the binary information in a digital computer is stored in memory, but all computations are done in processor registers. Therefore, the user must have the capability of moving information between these two units. Decision-making capabilities are an important aspect of digital computers. For example, two numbers can be compared, and if the first is greater than the second, it may be necessary to proceed differently than if the second is greater than the first. Program control instructions such as branch instructions are used to change the sequence in which the program is executed. Input and output instructions are needed for communication between the computer and the

user. Programs and data must be transferred into memory and results of computations must be transferred back to the user.

The instructions listed in Table 5-2 constitute a minimum set that provides all the capabilities mentioned above. There is one arithmetic instruction, ADD, and two related instructions, complement AC(CMA) and increment AC(INC). With these three instructions we can add and subtract binary numbers when negative numbers are in signed-2's complement representation. The circulate instructions, CIR and CIL, can be used for arithmetic shifts as well as any other type of shifts desired. Multiplication and division can be performed using addition, subtraction, and shifting. There are three logic operations: AND, complement AC(CMA), and clear AC(CLA). The AND and complement provide a NAND operation. It can be shown that with the NAND operation it is possible to implement all the other logic operations with two variables (listed in Table 4-6). Moving information from memory to AC is accomplished with the load AC(LDA) instruction. Storing information from AC into memory is done with the store AC(STA) instruction. The branch instructions BUN, BSA, and ISZ, together with the four skip instructions, provide capabilities for program control and checking of status conditions. The input (INP) and output (OUT) instructions cause information to be transferred between the computer and external devices.

Although the set of instructions for the basic computer is complete, it is not efficient because frequently used operations are not performed rapidly. An efficient set of instructions will include such instructions as subtract, multiply, OR, and exclusive-OR. These operations must be programmed in the basic computer. The programs are presented in Chap. 6 together with other programming examples for the basic computer. By using a limited number of instructions it is possible to show the detailed logic design of the computer. A more complete set of instructions would have made the design too complex. In this way we can demonstrate the basic principles of computer organization and design without going into excessive complex details. In Chap. 8 we present a complete list of computer instructions that are included in most commercial computers.

The function of each instruction listed in Table 5-2 and the microoperations needed for their execution are presented in Secs. 5-5 through 5-7. We delay this discussion because we must first consider the control unit and understand its internal organization.

Timing and Control

The timing for all registers in the basic computer is controlled by a master clock clock pulses generator. The clock pulses are applied to all flip-flops and registers in the system, including the flip-flops and registers in the control unit. The clock pulses do not change the state of a register unless the register is enabled by