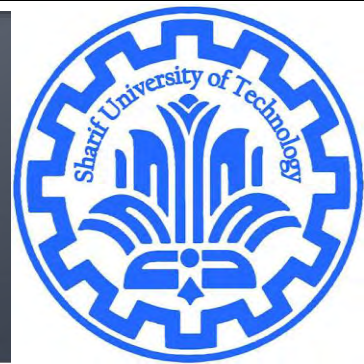


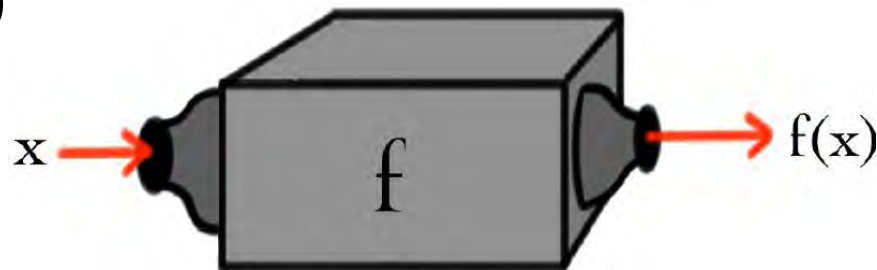
Scalar-valued Functions (Linear and Affine)

CE40282-1: Linear Algebra
Hamid R. Rabiee and Maryam Ramezani
Sharif University of Technology



What are Linear Functions?

- Think of a function as a machine f into which one may feed a real number. For each input x this machine outputs a single real number $f(x)$



(A) What number x satisfies $10x = 3$?

(B) What 3-vector u satisfies $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \times u = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$?

What vector X satisfies $f(X) = B$?

(C) What polynomial p satisfies $\int_{-1}^1 p(y) dy = 0$ and $\int_{-1}^1 yp(y) dy = 1$?

(D) What power series $f(x)$ satisfies $x \frac{d}{dx} f(x) - 2f(x) = 0$?

(E) What number x satisfies $4x^2 = 1$?

Note

Linear and affine functions in this session are scalar-valued. We focus on the linear function machine of the previous slide, which outputs are scalar values. Remains will discuss later.

What are Linear Functions?

- $f: R^n \rightarrow R$ means that f is a function that maps real n -vectors to real numbers
- $f(x)$ is the value of function f at x (x is referred to as the argument of the function).
- $f(x) = (x_1, x_2, \dots, x_n)$
- A function $f: R^n \rightarrow R$ is linear if it satisfies the following two properties:
 - **Homogeneity**: For any n -vector x and any scalar α : $f(\alpha x) = \alpha f(x)$
 - **Additivity**: For any n -vector x and y , $f(x + y) = f(x) + f(y)$
- **Superposition property**:
$$f(\alpha x + \beta y) = \alpha f(x) + \beta f(y)$$
- A function that satisfies the superposition property is called linear.

What are Linear Functions?

- Show that inner product has superposition property so it is a linear function.

$$f(x) = a^T x = a_1 x_1 + a_2 x_2 + \cdots + a_n x_n$$

What are Linear Functions?

- If a function f is linear, superposition extends to linear combinations of any number of vectors:

$$f(\alpha_1 x_1 + \cdots + \alpha_k x_k) = \alpha_1 f(x_1) + \cdots + \alpha_k f(x_k)$$

What are Linear Functions?

- A function defined as the inner product of its argument with some fixed vector is linear.
- If a function is linear, then it can be expressed as the inner product of its argument with some fixed vector.
 - Proof
- The representation of a linear function f as $f(x) = a^T x$ is unique, which means that there is only one vector a for which $f(x) = a^T x$ holds for all x .
 - Proof
- Is average a linear function?
- Is maximum a linear function?

Affine Function

- A function $f: R^n \rightarrow R$ is affine if and only if it can be expressed as $f(x) = a^T x + b$ (linear function plus a constant (offset))
- Superposition property for affine function:
$$f(\alpha x + \beta y) = \alpha f(x) + \beta f(y), \quad \alpha + \beta = 1$$
- Proof

Affine Function

- Any scalar-valued function that satisfies the restricted superposition property is affine.

- Proof

- Conclusion: Important note:

every affine function can be written as $f(x) = a^T x + b$ with:

$$a = (f(e_1) - f(0), f(e_2) - f(0), \dots, f(e_n) - f(0))$$

$$b = f(0)$$

Conclusion

■ Method 1:

■ Linear:

$$f(\alpha_1 x_1 + \cdots + \alpha_n x_n) = \alpha_1 f(x_1) + \cdots + \alpha_n f(x_n), \forall \alpha_1, \dots, \alpha_n$$

■ Affine:

$$f(\alpha_1 x_1 + \cdots + \alpha_n x_n) = \alpha_1 f(x_1) + \cdots + \alpha_n f(x_n), \alpha_1 + \cdots + \alpha_n = 1$$

■ Method 2:

■ Linear

$$f(x) = a^T x$$

■ Affine

$$f(x) = a^T x + b$$

Conclusion

- In many applications, scalar-valued functions of n variables, or relations between n variables and a scalar one, can be approximated as linear or affine functions, which is called “**Model**”.

Scalar-valued function of a scalar

- Derivative of function $f: R \rightarrow R$ at the point z : $(f'(z))$:

$$\lim_{t \rightarrow 0} \frac{f(z+t) - f(z)}{t}$$

- It gives the slope of the graph of f at the point $(z; f(z))$.
- $f'(z)$ is a scalar-valued function of a scalar variable

Scalar-valued function of a vector

- The **partial derivative** of function $f: R^n \rightarrow R$ at the point z , with respect to its i th argument

$$\begin{aligned}\frac{\partial f}{\partial x_i}(z) &= \lim_{t \rightarrow 0} \frac{f(z_1, \dots, z_{i-1}, z_i + t, z_{i+1}, \dots, z_n) - f(z)}{t} \\ &= \lim_{t \rightarrow 0} \frac{f(z + te_i) - f(z)}{t},\end{aligned}$$

- The partial derivative is the derivative with respect to the i th argument, with all other arguments fixed.

Gradient

- **Gradient**: The partial derivatives of f with respect to its n arguments can be collected into an n vector called the gradient of f (at z):

$$\nabla f(z) = \begin{bmatrix} \frac{\partial f}{\partial x_1}(z) \\ \vdots \\ \frac{\partial f}{\partial x_n}(z) \end{bmatrix}.$$

- Gradient of a combination of functions

$$f(x) = ag(x) + bh(x).$$

$$\nabla f(z) = a\nabla g(z) + b\nabla h(z)$$

How to find an approximate affine model

- $f: R^n \rightarrow R$ is differentiable: its partial derivatives exist
- The (first-order) Taylor approximation of f near (or at) the point z :

$$\hat{f}(x) = f(z) + \frac{\partial f}{\partial x_1}(z)(x_1 - z_1) + \cdots + \frac{\partial f}{\partial x_n}(z)(x_n - z_n),$$

- z is n -vector
- $\hat{f}(x)$ is a linear function or a affine function?

$$\hat{f}(x) = \underbrace{f(z)}_{\text{Constant- value of function at } z} + \underbrace{\nabla f(z)^T (x - z)}_{\text{Deviation or Perturbation of } x \text{ from } z}$$

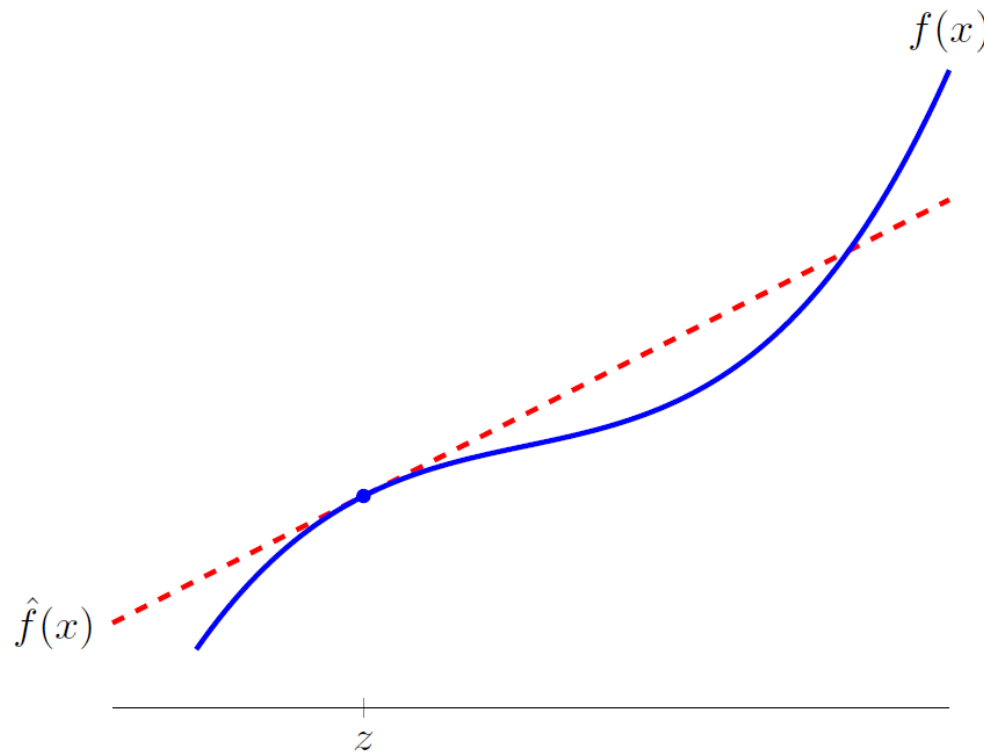
Constant- value of function at z

Deviation or Perturbation of x from z

$$\hat{f}(x) = \underbrace{\nabla f(z)^T x}_{\text{Linear function}} + \underbrace{(f(z) - \nabla f(z)^T z)}_{\text{Constant}}$$

Taylor approximation

- The Taylor approximation is sometimes called the linear approximation or linearized approximation of f (at z)



A function f of one variable, and the first-order Taylor approximation $\hat{f}(x) = f(z) + f'(z)(x - z)$ at z

Taylor approximation

■ Example:

Consider the function $f : \mathbf{R}^2 \rightarrow \mathbf{R}$ given by $f(x) = x_1 + \exp(x_2 - x_1)$, the Taylor approximation \hat{f} near the point $z = (1, 2)$

x	$f(x)$	$\hat{f}(x)$	$ \hat{f}(x) - f(x) $
(1.00, 2.00)	3.7183	3.7183	0.0000
(0.96, 1.98)	3.7332	3.7326	0.0005
(1.10, 2.11)	3.8456	3.8455	0.0001
(0.85, 2.05)	4.1701	4.1119	0.0582
(1.25, 2.41)	4.4399	4.4032	0.0367

Regression model

- Regression model is (the affine function of x)

$$\hat{y} = x^T w + w_0$$

Regression model

■ Example

- ▶ y is selling price of house in \$1000 (in some location, over some period)
- ▶ regressor is

$$x = (\text{house area, \# bedrooms})$$

(house area in 1000 sq.ft.)

- ▶ regression model weight vector and offset are

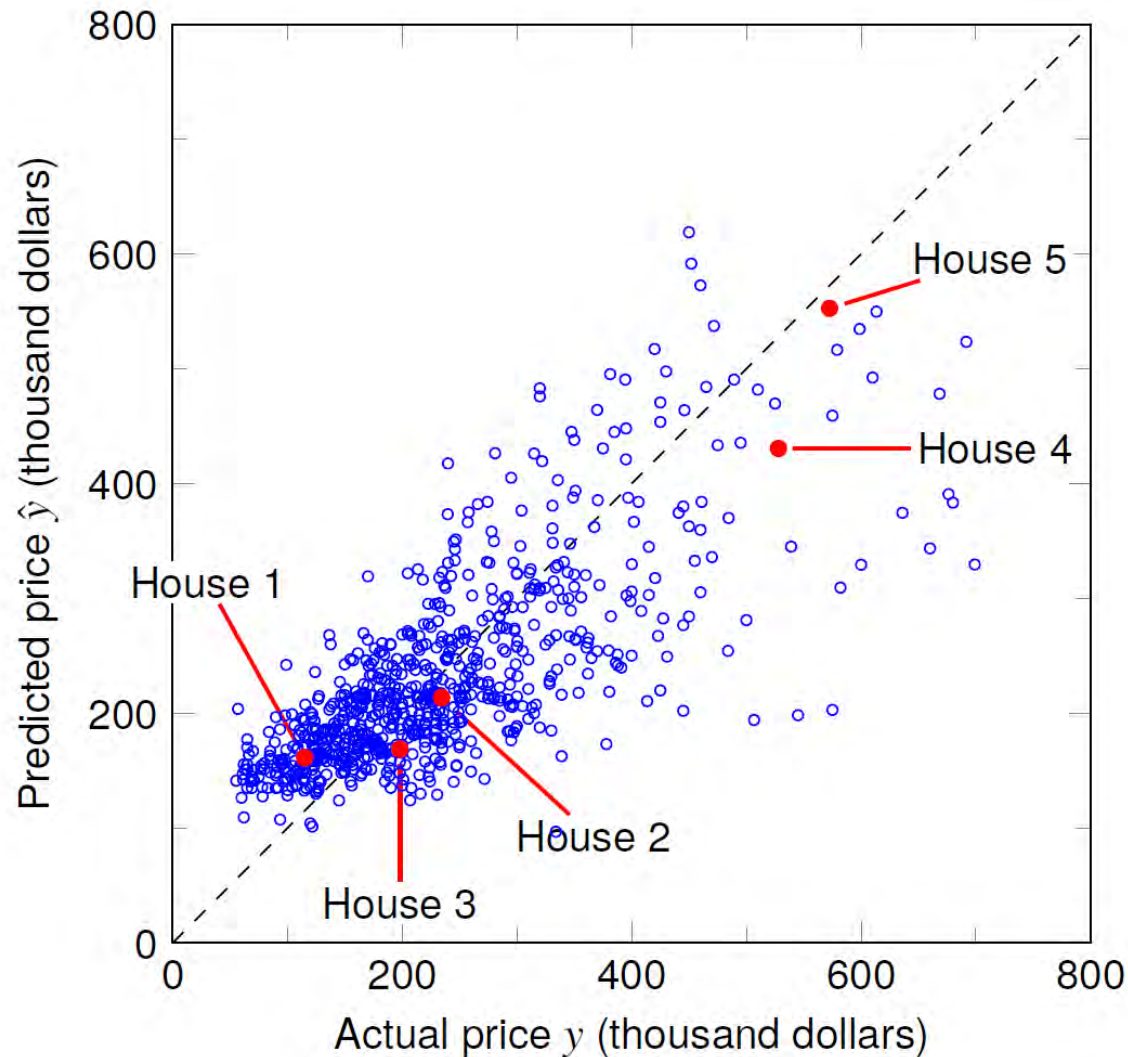
$$\beta = (148.73, -18.85), \quad v = 54.40$$

- ▶ we'll see later how to guess β and v from sales data

Regression model

House	x_1 (area)	x_2 (beds)	y (price)	\hat{y} (prediction)
1	0.846	1	115.00	161.37
2	1.324	2	234.50	213.61
3	1.150	3	198.00	168.88
4	3.037	4	528.00	430.67
5	3.984	5	572.50	552.66

Regression model



Reference

- Chapter 2: Introduction to Applied Linear Algebra
Vectors, Matrices, and Least Squares
- Part of chapter 1 and chapter 6: Linear Algebra
by David Cherney, etc.