



Chapter 2

Numerical Methods for Solving Nonlinear Equations

Fatemeh Baharifard

Methods

Extra Topics

Bisection Method

False Position Method

Secant Method

Newton–Raphson Method

Simple Iterative or Fixed Point Method

Methods

Extra Topics

Horner Method for Evaluating Polynomials

Generalized Newton–Raphson Method

Solving Non-Linear Equations

$f(x) = ax + b = 0$ (a Linear Equation)

Otherwise, the equation is non-linear.

Solving Non-Linear Equations

$$f(x)=0 \quad x= ?$$

$$f(x) = ax^2 + bx + c \rightarrow x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

but $b^2 - 4ac$ may not be an integer root!

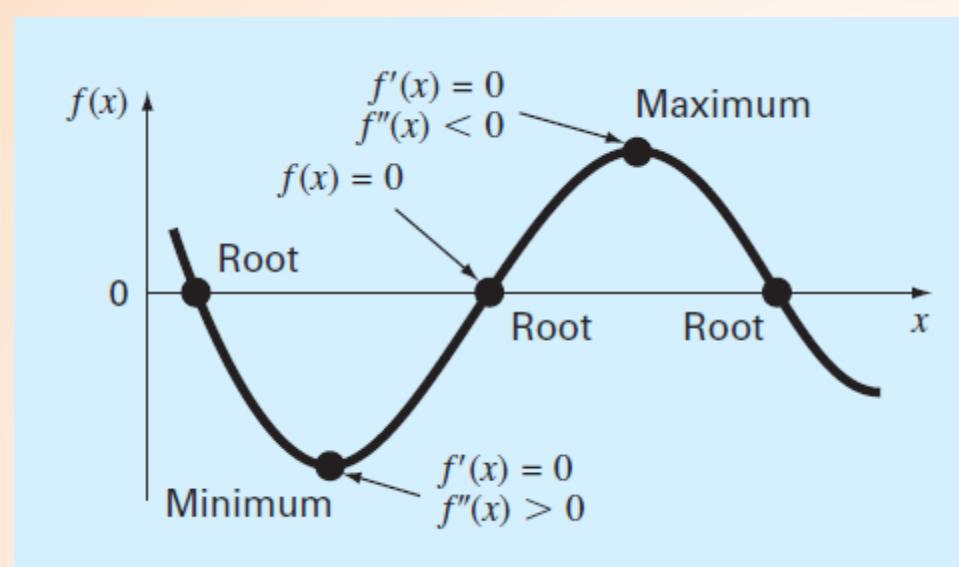
What about other functions?

Solving Non-Linear Equations

$$f(x) = x^{10} + x - 1 = 0$$

$$f(x) = x + \cos(x) = 0$$

$$f(x) = e^{-x} - \cos(x) = 0$$

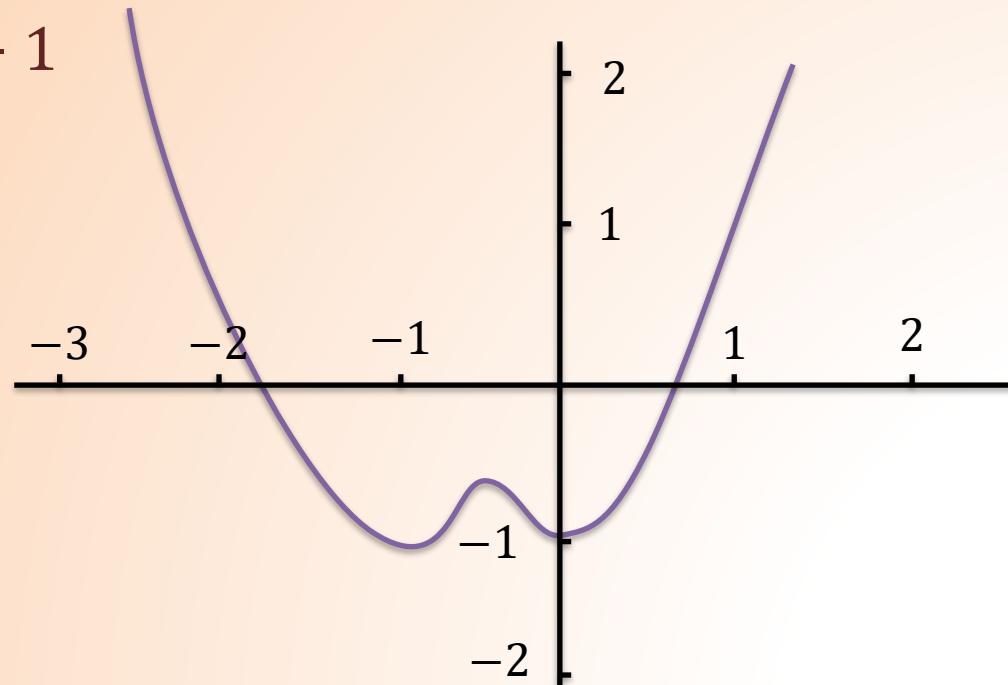


Solution

Plot the graph of $f(x)$ and find its intersection with the x axis.

Example:

$$f(x) = x^4 + 2x^3 - x - 1$$

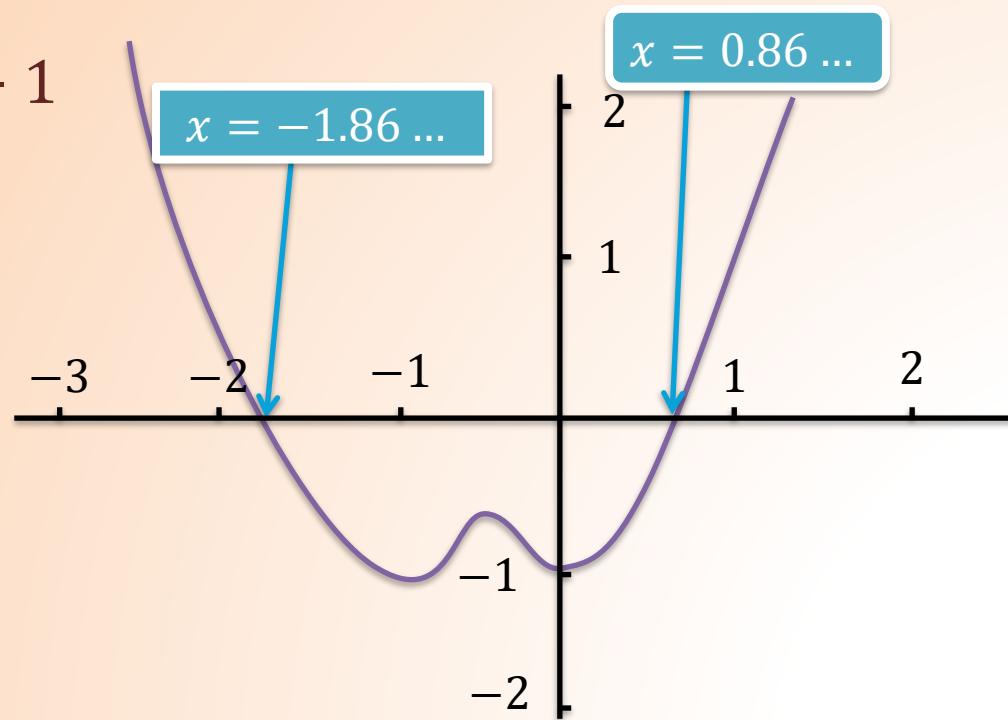


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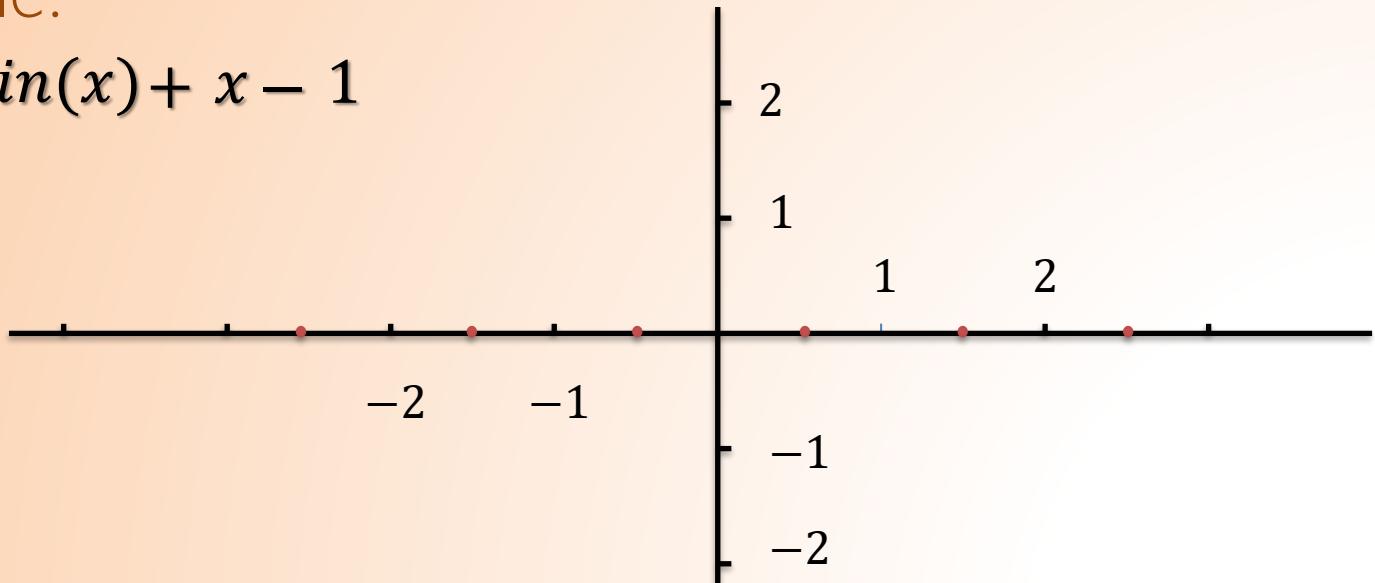


Solution

If $f(x) = f_1(x) - f_2(x)$, we can plot $f_1(x)$ and $f_2(x)$, then find their intersection(s).

■ Example:

$$f(x) = \sin(x) + x - 1$$



Solution

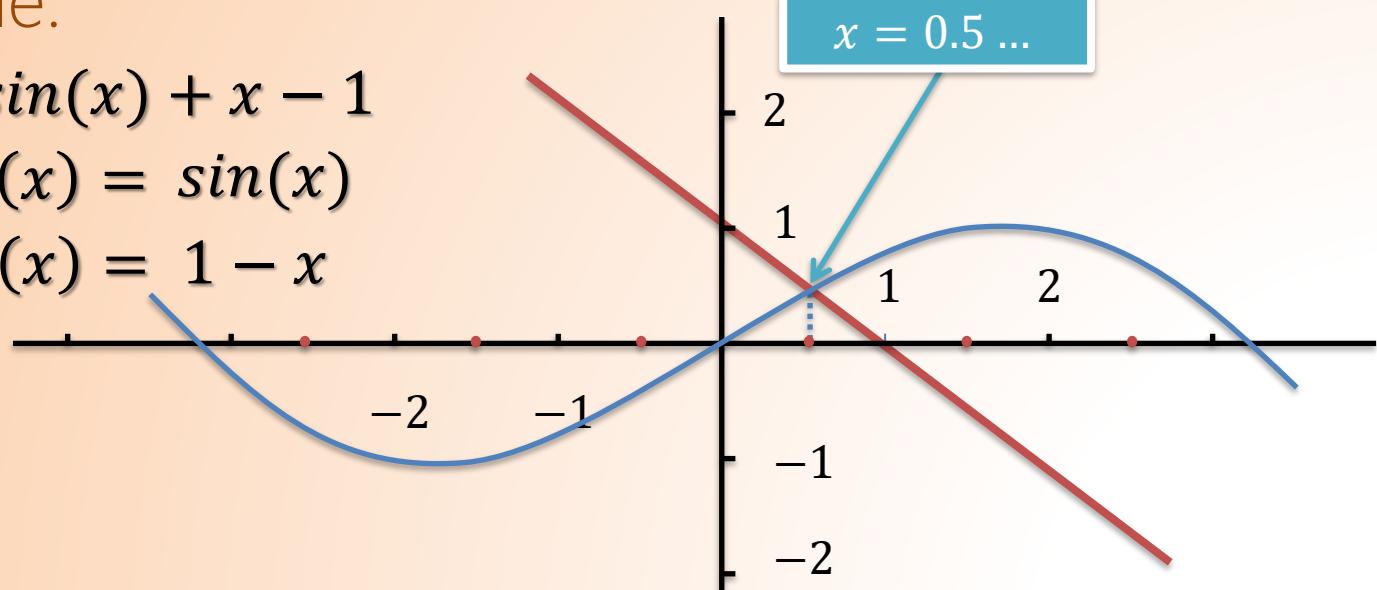
If $f(x) = f_1(x) - f_2(x)$, we can plot $f_1(x)$ and $f_2(x)$, then find their intersection(s).

■ Example:

$$f(x) = \sin(x) + x - 1$$

$$f_1(x) = \sin(x)$$

$$f_2(x) = 1 - x$$



Other Solutions

Problems:

We cannot calculate the exact amount of x by plotting!

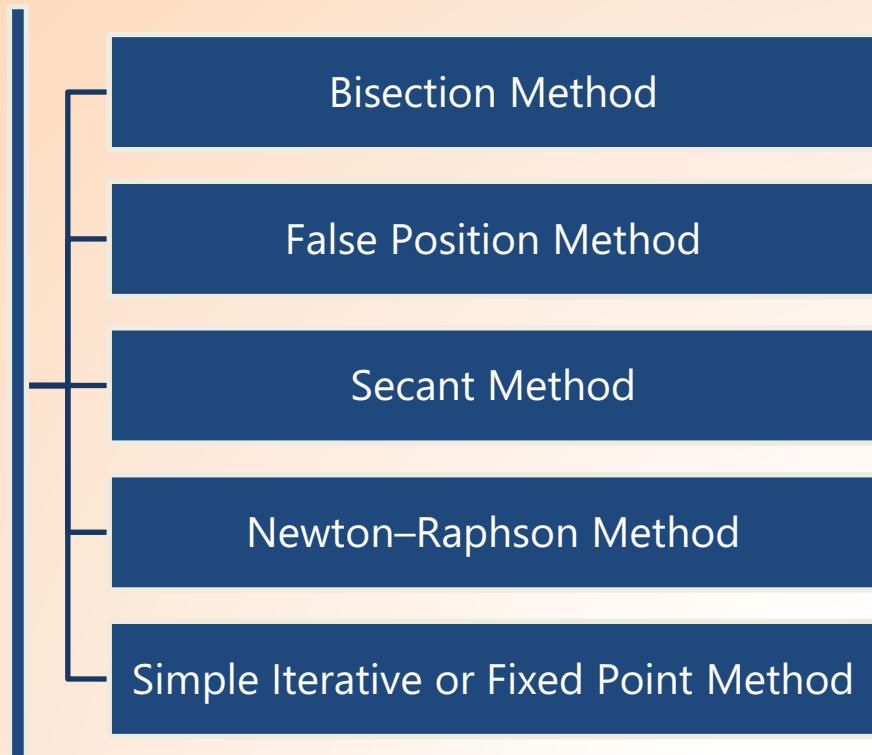
Sometimes it is hard to plot $f(x)$.

Solution:

NUMERICAL METHODS

NUMERICAL METHODS

Other Solutions



Numerical Methods

Initially guess an x_0 or an interval (x_0, x_1) ,

And get the series of x_i s.

The sequence x_0, x_1, x_2, \dots must converge to the exact value of x^* :

- $e(x_0) = |x^* - x_0| = e_0, e(x_1) = |x^* - x_1| = e_1, \dots, e(x_i) = |x^* - x_i| = e_i$
- $e_0 > e_1 > e_2 > \dots > e_i \rightarrow 0$

Each convergent sequence has a degree of convergence, i.e.

$$e_{i-1}^{\textcolor{red}{m}} \times \textcolor{blue}{c} = e_i \quad 0 < c < 1$$

$\textcolor{red}{m}$ is convergence degree.

Numerical Methods

A sequence (x_n) that converges to x^* is said to have *order of convergence* $m \geq 1$ and *rate of convergence* c if

$$\lim_{n \rightarrow \infty} \frac{|x_{n+1} - x^*|}{|x_n - x^*|^m} = c$$

or

$$\lim_{n \rightarrow \infty} \frac{|e_{n+1}|}{|e_n|^m} = c$$

Numerical Methods(cont.)

If the degree of convergence is larger, the sequence will converge faster.

There is usually a maximum expected error ε .

Termination condition is :

$$e_i < \varepsilon \rightarrow |x_i - x^*| < \varepsilon$$

Because x^* is unknown to us, we use x_{i-1} instead:

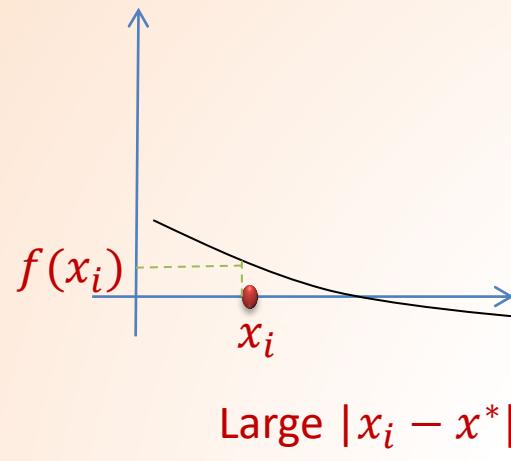
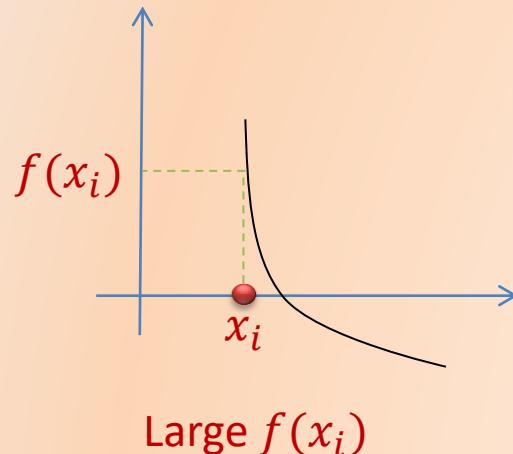
$$|x_{i-1} - x_i| < \varepsilon$$

Numerical Methods(cont.)

Other termination conditions:

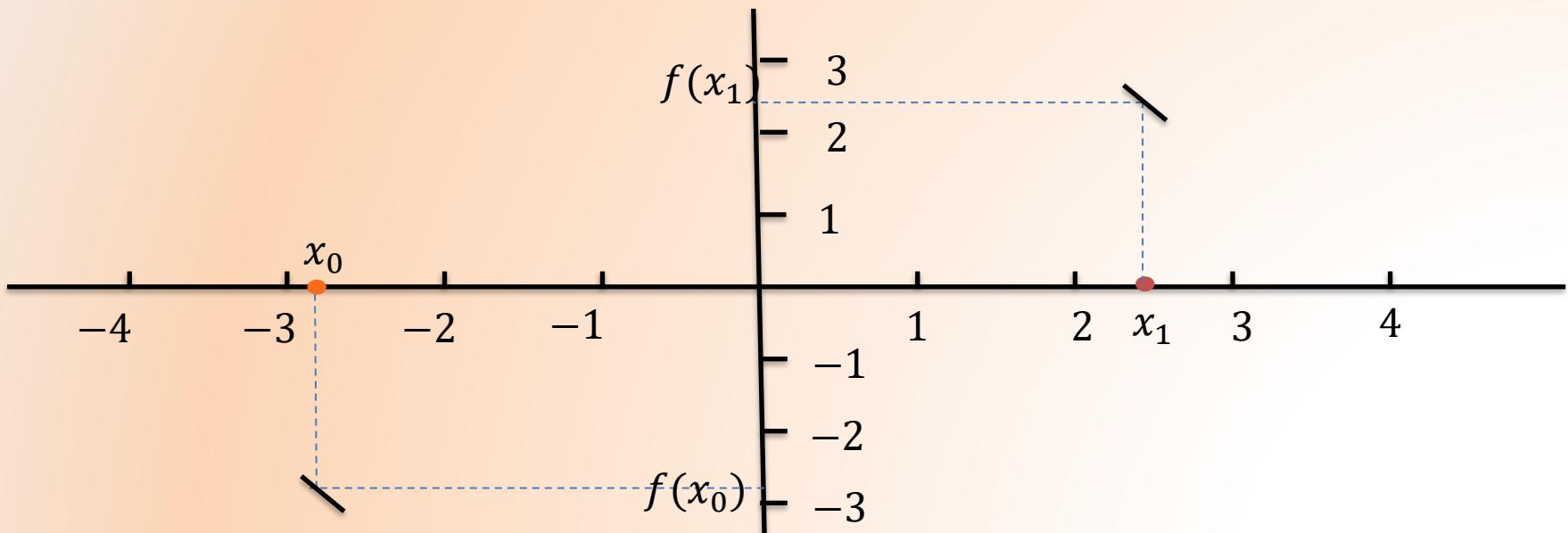
$$f(x_i) < \varepsilon$$

$$i \geq \#iteration$$



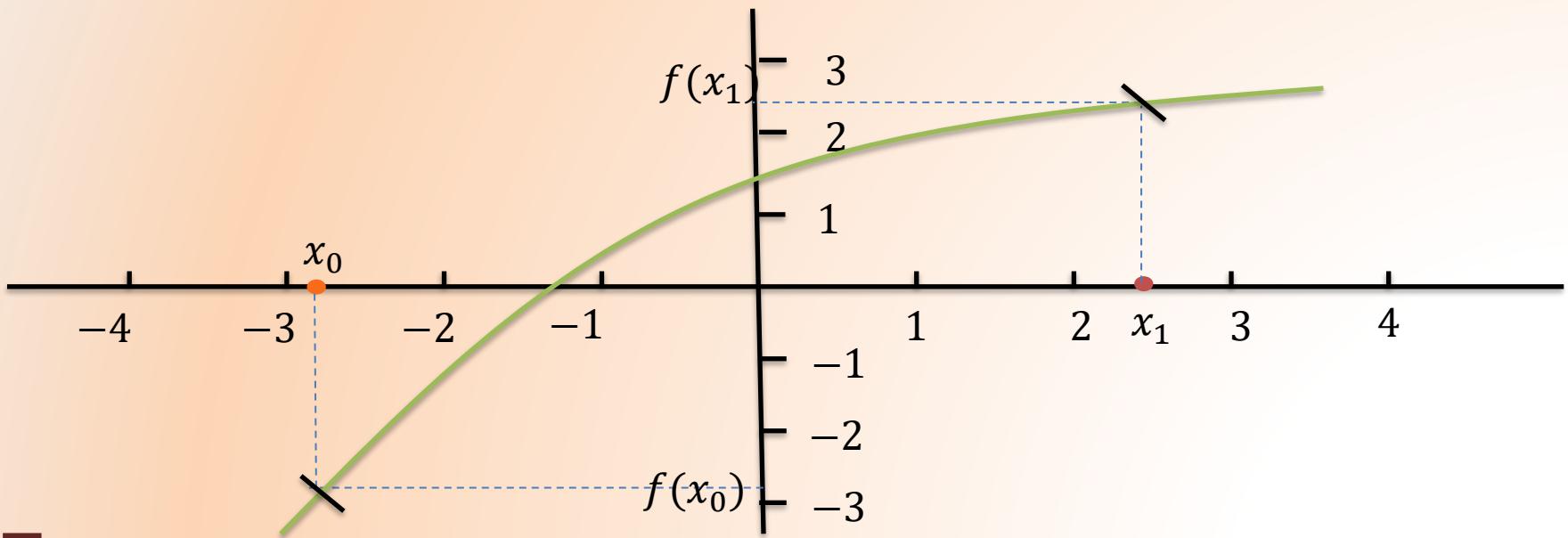
Bolzano's Theorem

If $f(x)$ is a real-valued continuous function on the interval $[a,b]$, and $f(x_0) \times f(x_1) < 0$, then f has at least one root in this interval.



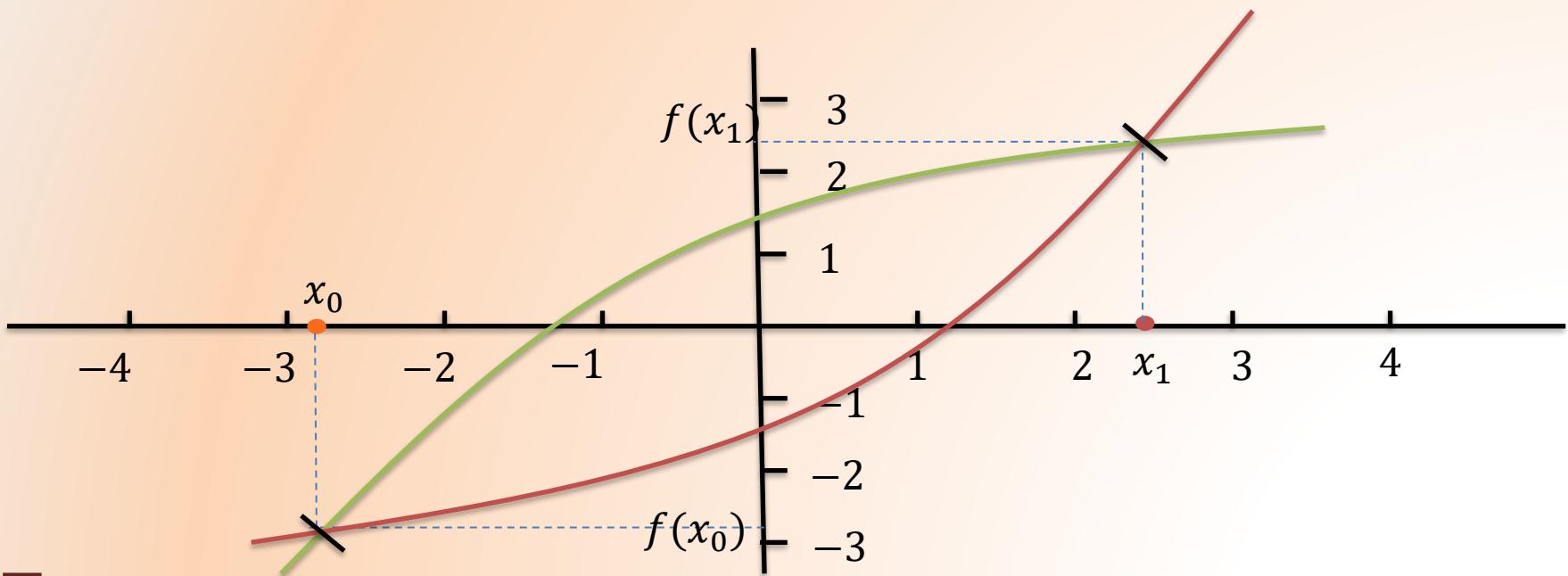
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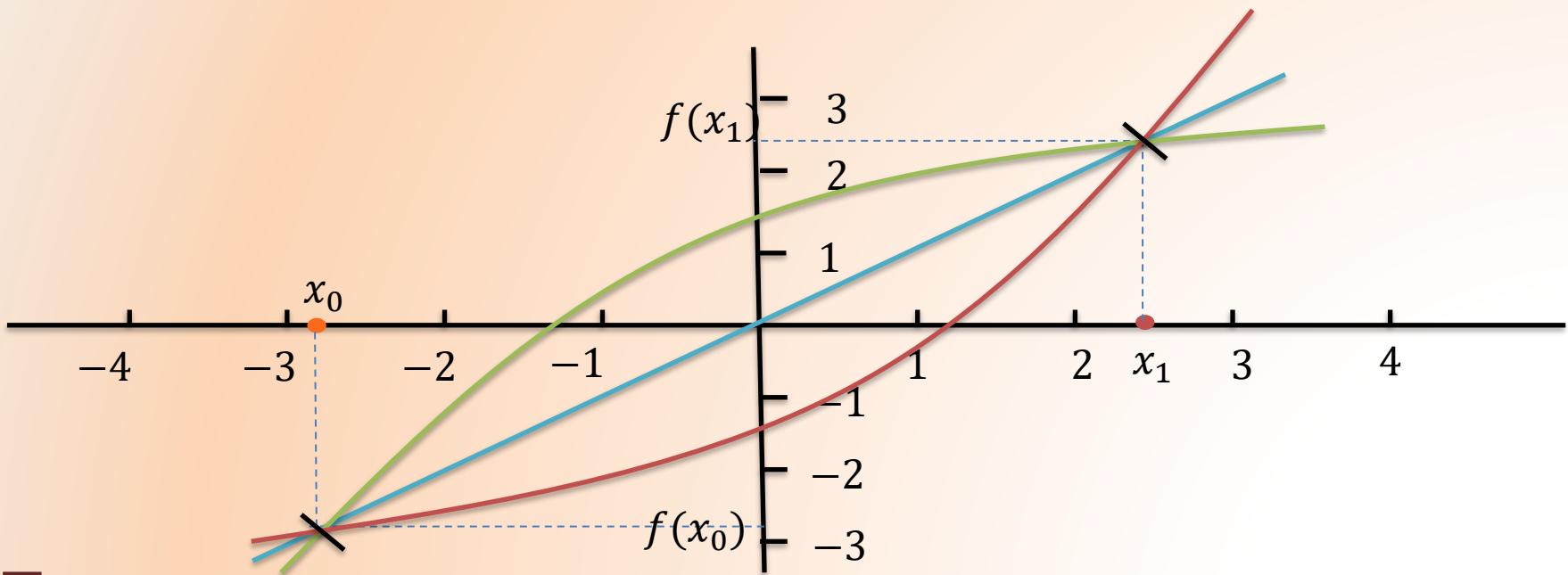
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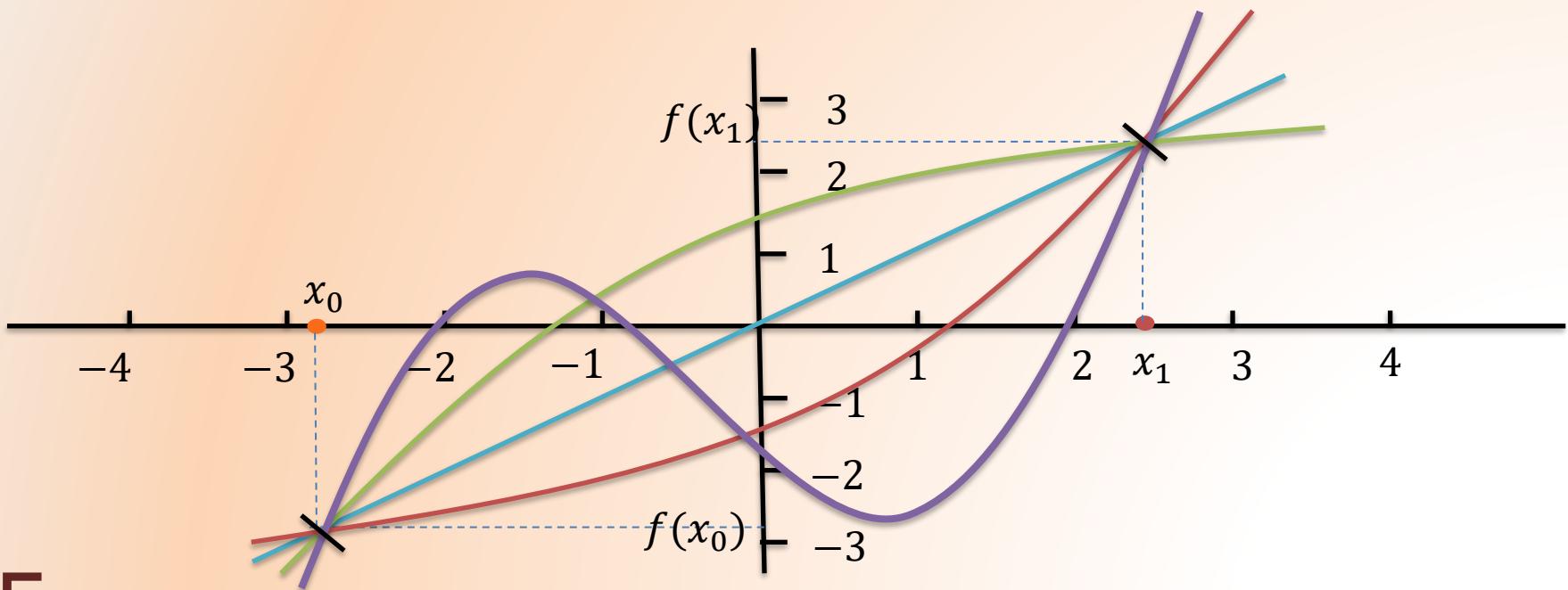
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Bolzano's Theorem

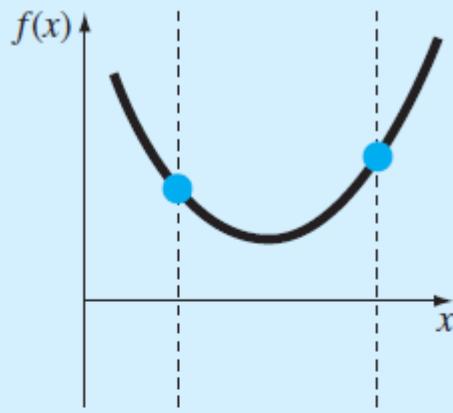
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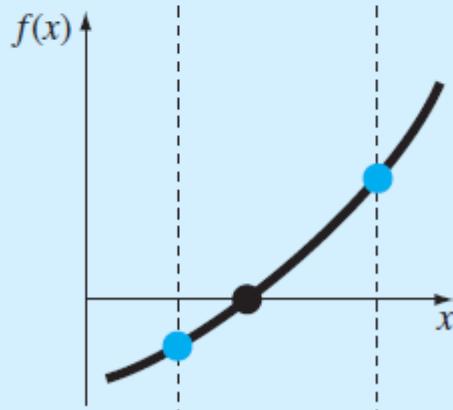
Bolzano's Theorem

If f is strictly ascending (or descending) in interval $[x_0, x_1]$ then f has exactly one root in this interval.

Roots



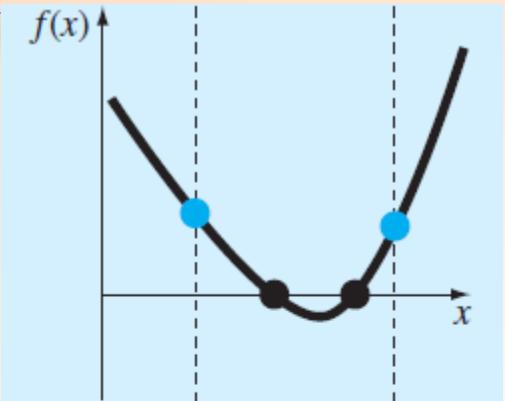
(a)



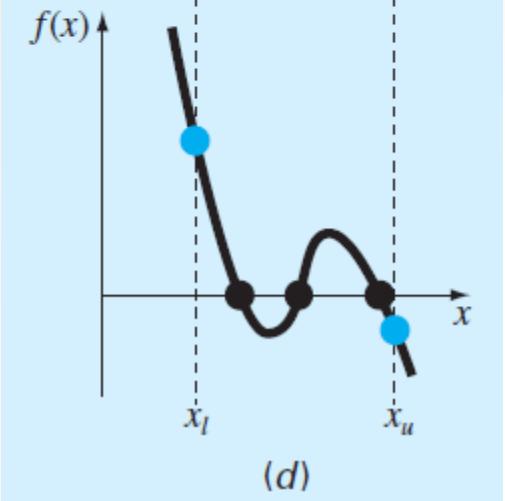
(b)

The same signs: #roots=even

Different signs: #roots=odd

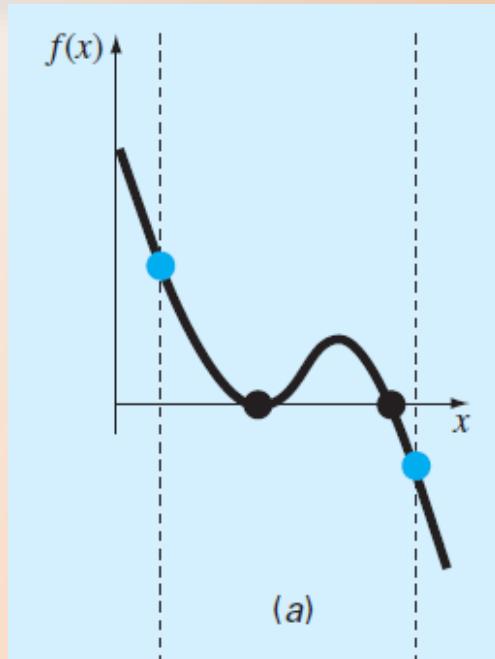


(c)

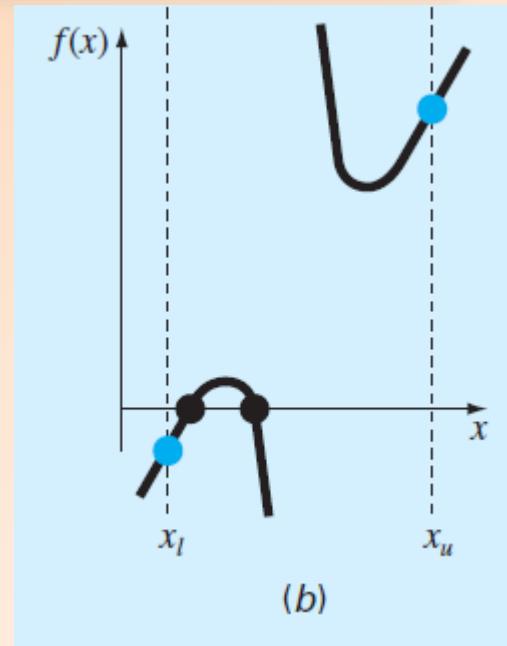


(d)

Roots



Different signs



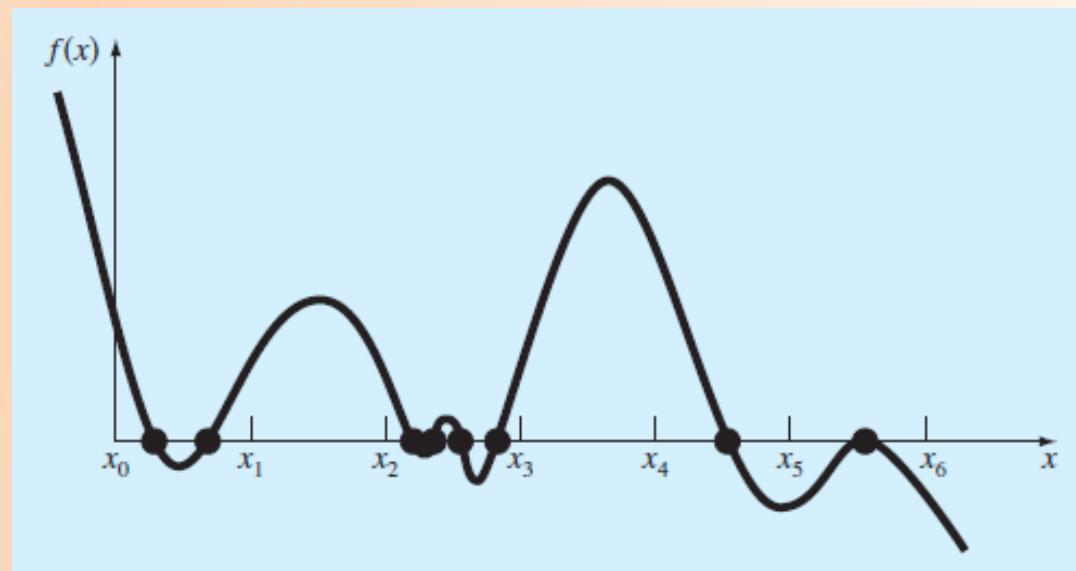
Multiple roots
#roots=even

Discontinuous functions
#roots=even

Incremental Search

Consider Δx and check the sign of $f(x_i) \times f(x_i + \Delta x)$

Cases where roots could be missed because the incremental length of the search procedure is too large. The last root on the right is multiple and would be missed regardless of the increment length.



Methods

Extra Topics

Bisection Method

False Position Method

Secant Method

Newton–Raphson Method

Simple Iterative or Fixed Point Method

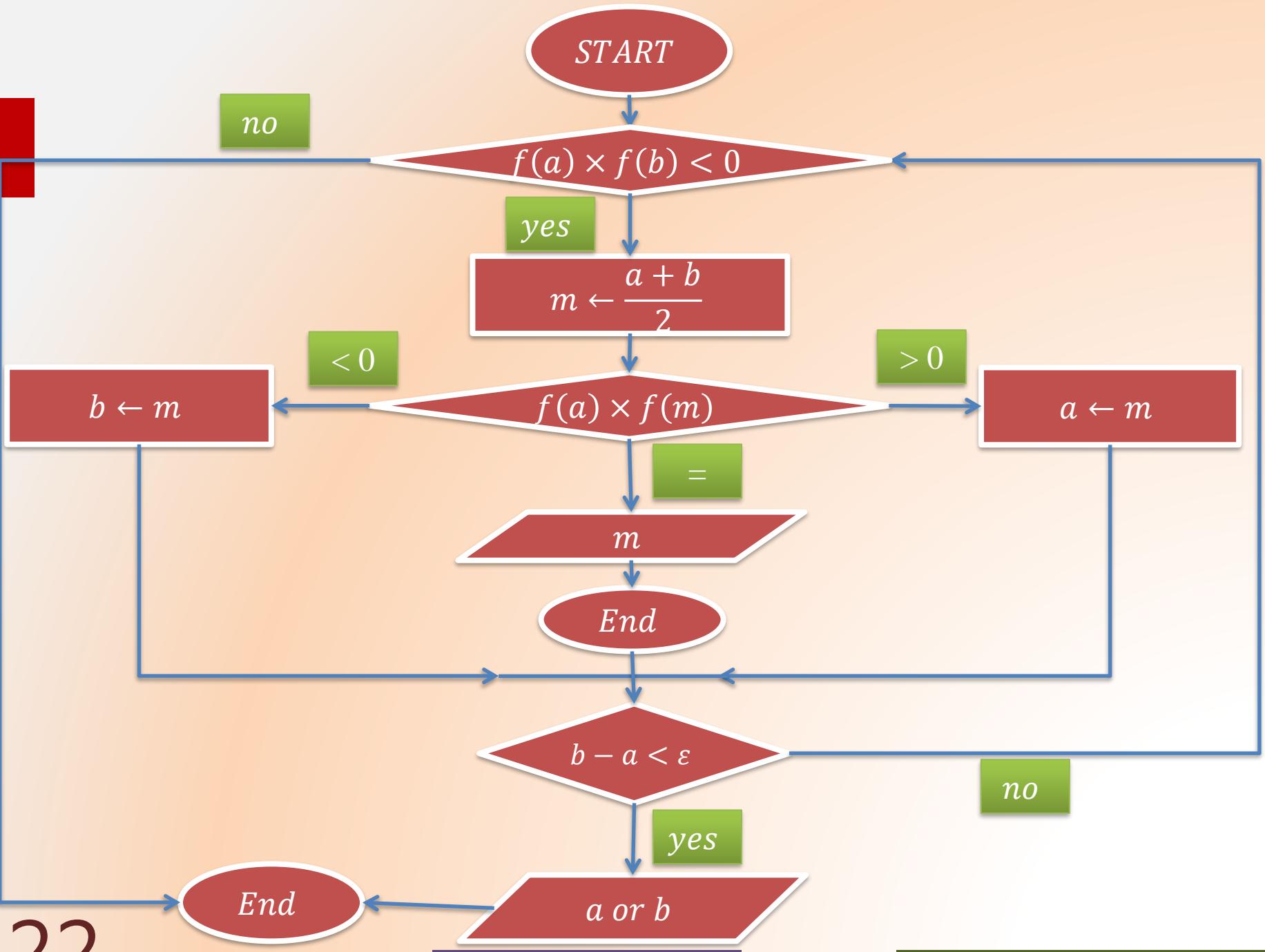
Bisection Method

Assumptions Example Advantages & Disadvantages

$$f(x) = 0$$

Initial assumption(s):

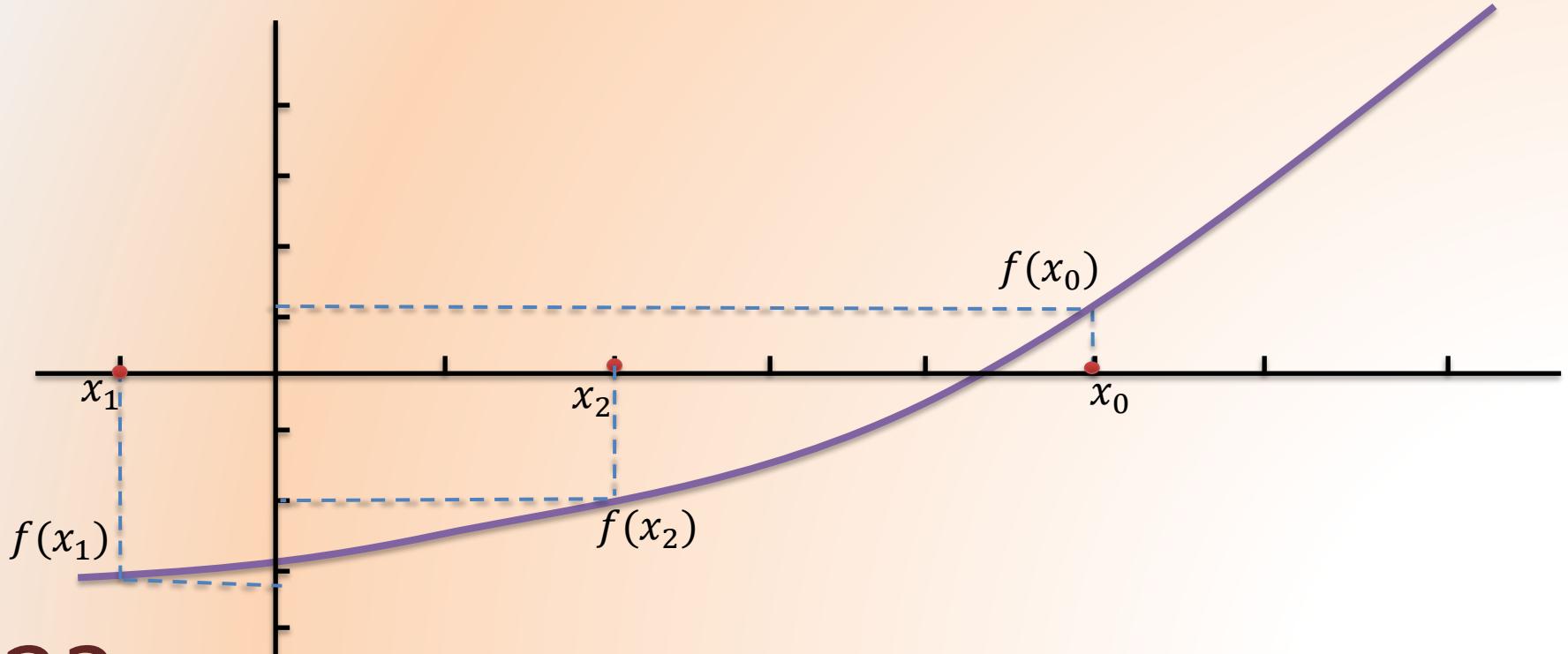
x_0 and x_1 such that $f(x_0) \times f(x_1) < 0$



Bisection Method

Assumptions Example Advantages & Disadvantages

$$f(x) = 0.25e^{2x} - 1.5 = 0 \quad x_0 = 1 \text{ and } x_1 = -0.2$$

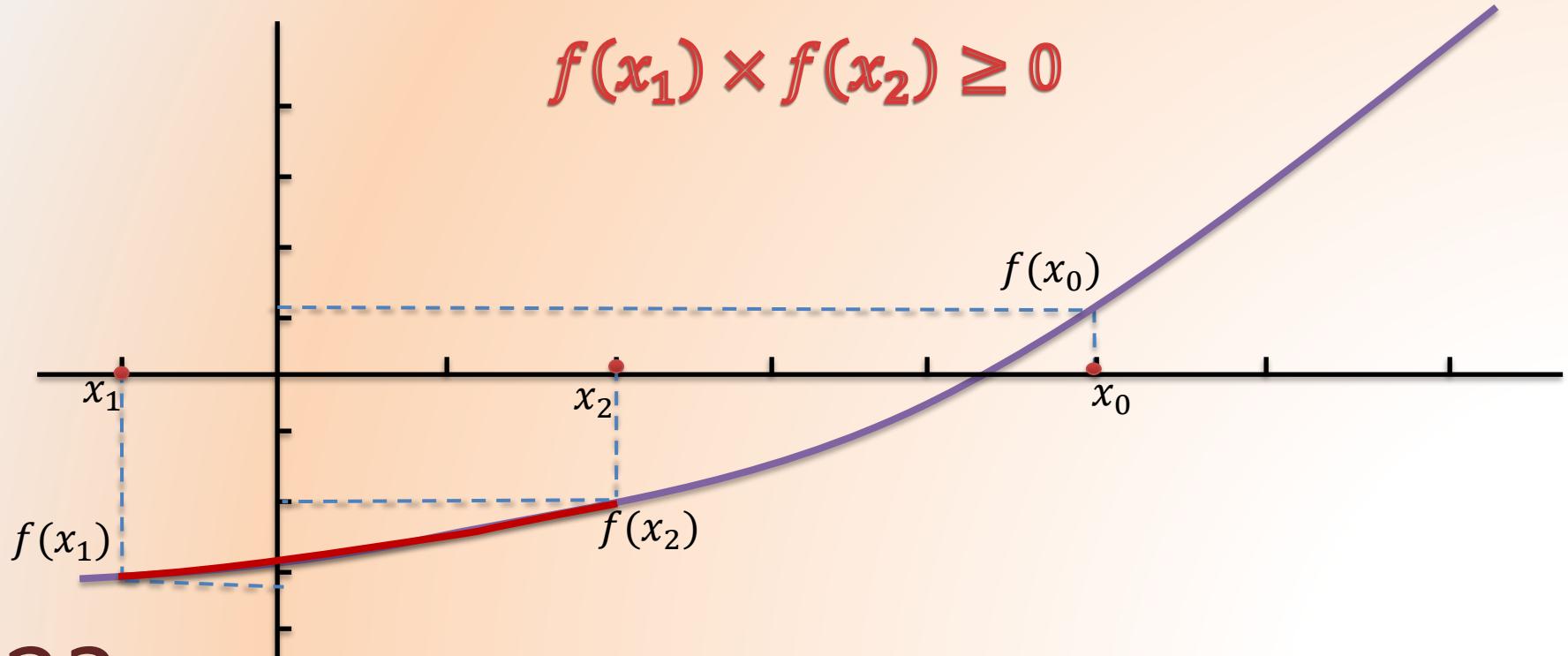


Bisection Method

Assumptions Example Advantages & Disadvantages

$$f(x) = 0.25e^{2x} - 1.5 = 0 \quad x_0 = 1 \text{ and } x_1 = -0.2$$

$$f(x_1) \times f(x_2) \geq 0$$

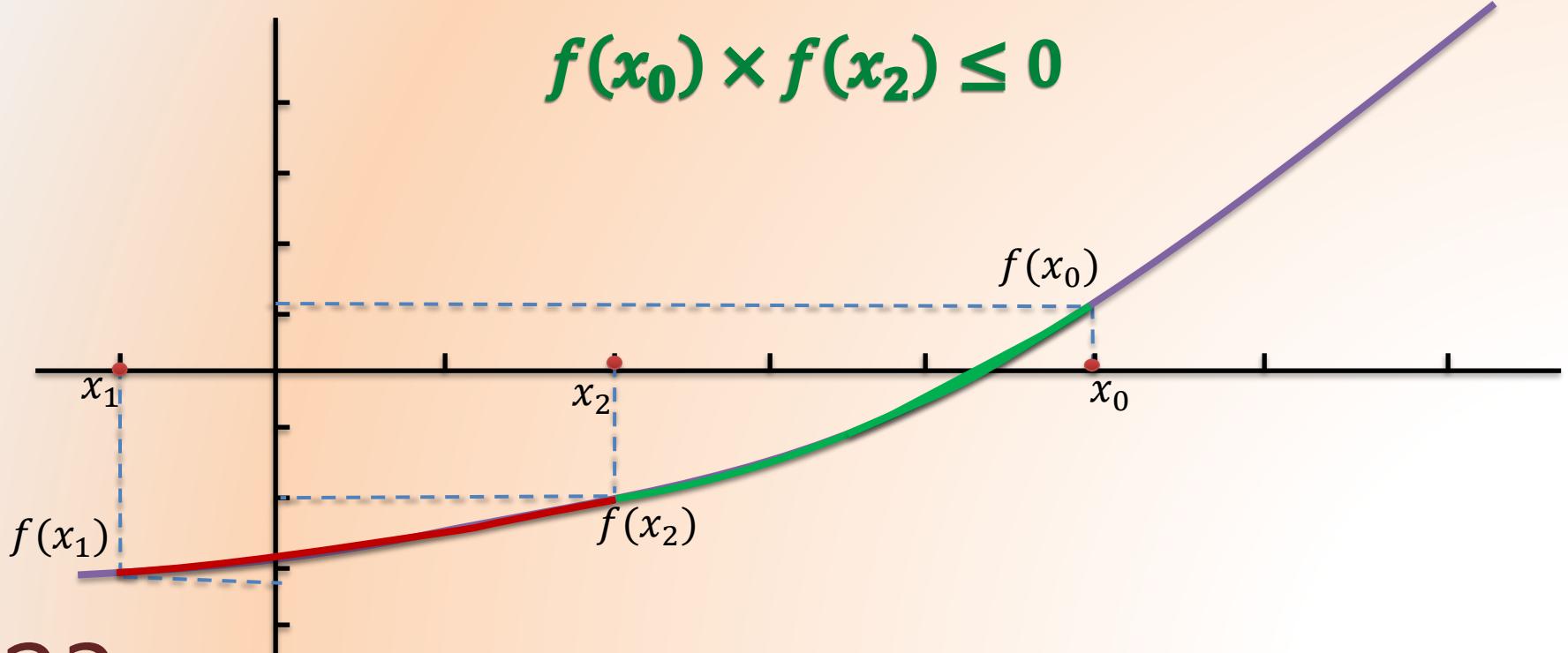


Bisection Method

Assumptions Example Advantages & Disadvantages

$$f(x) = 0.25e^{2x} - 1.5 = 0 \quad x_0 = 1 \text{ and } x_1 = -0.2$$

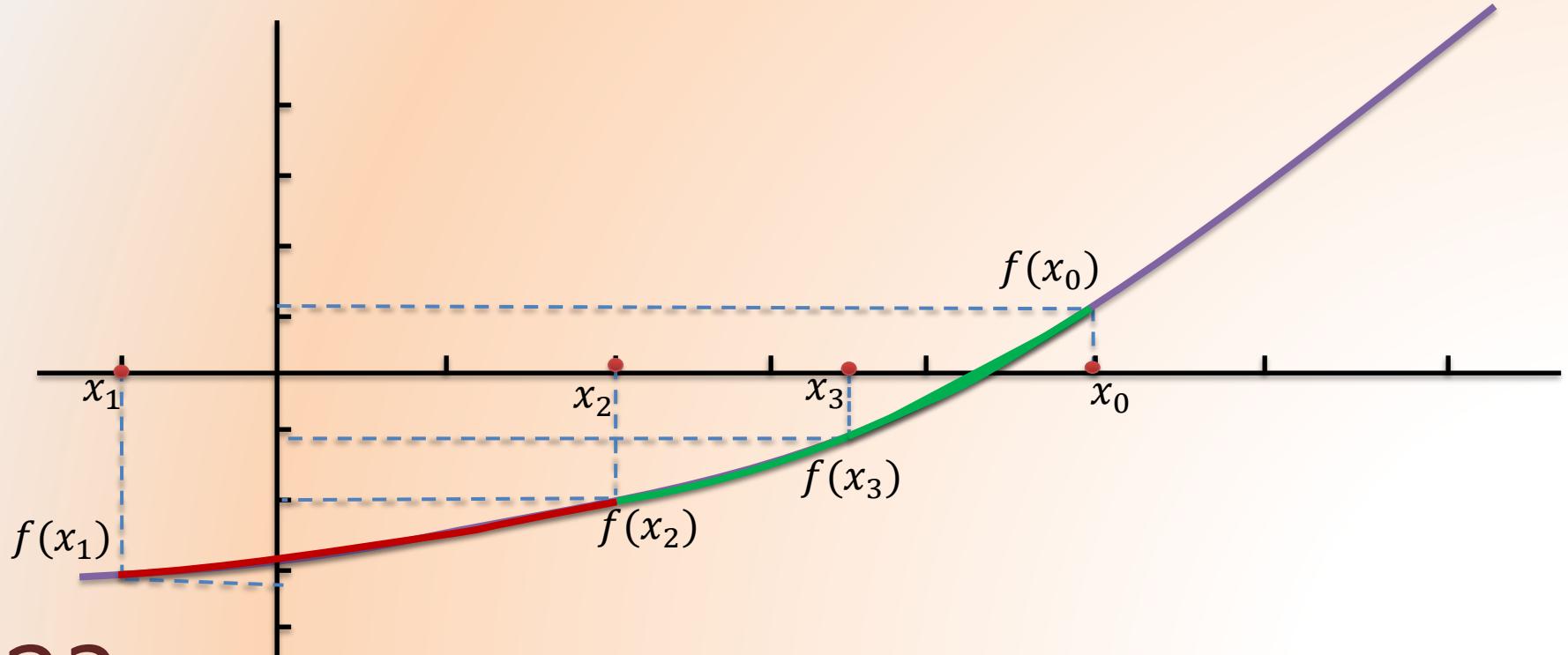
$$f(x_0) \times f(x_2) \leq 0$$



Bisection Method

Assumptions Example Advantages & Disadvantages

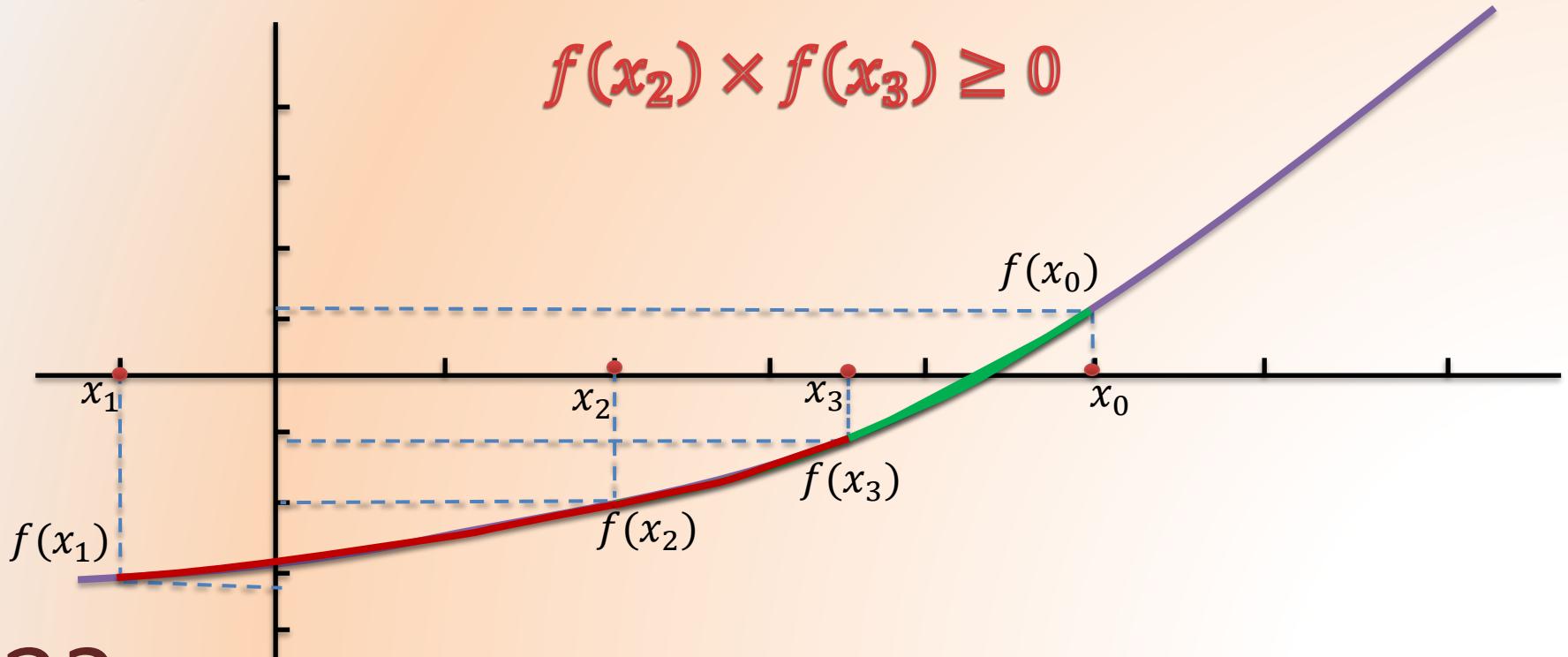
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Bisection Method

Assumptions Example Advantages & Disadvantages

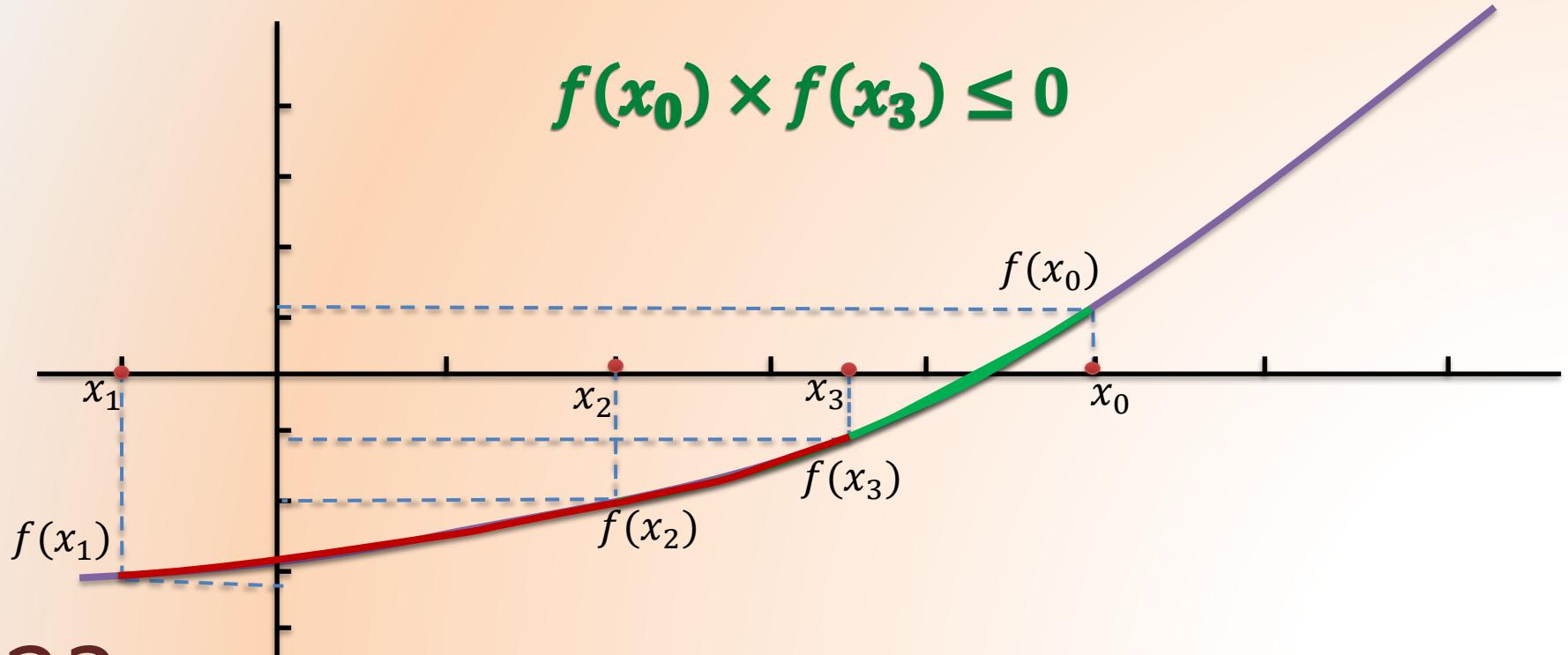
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Bisection Method

Assumptions Example Advantages & Disadvantages

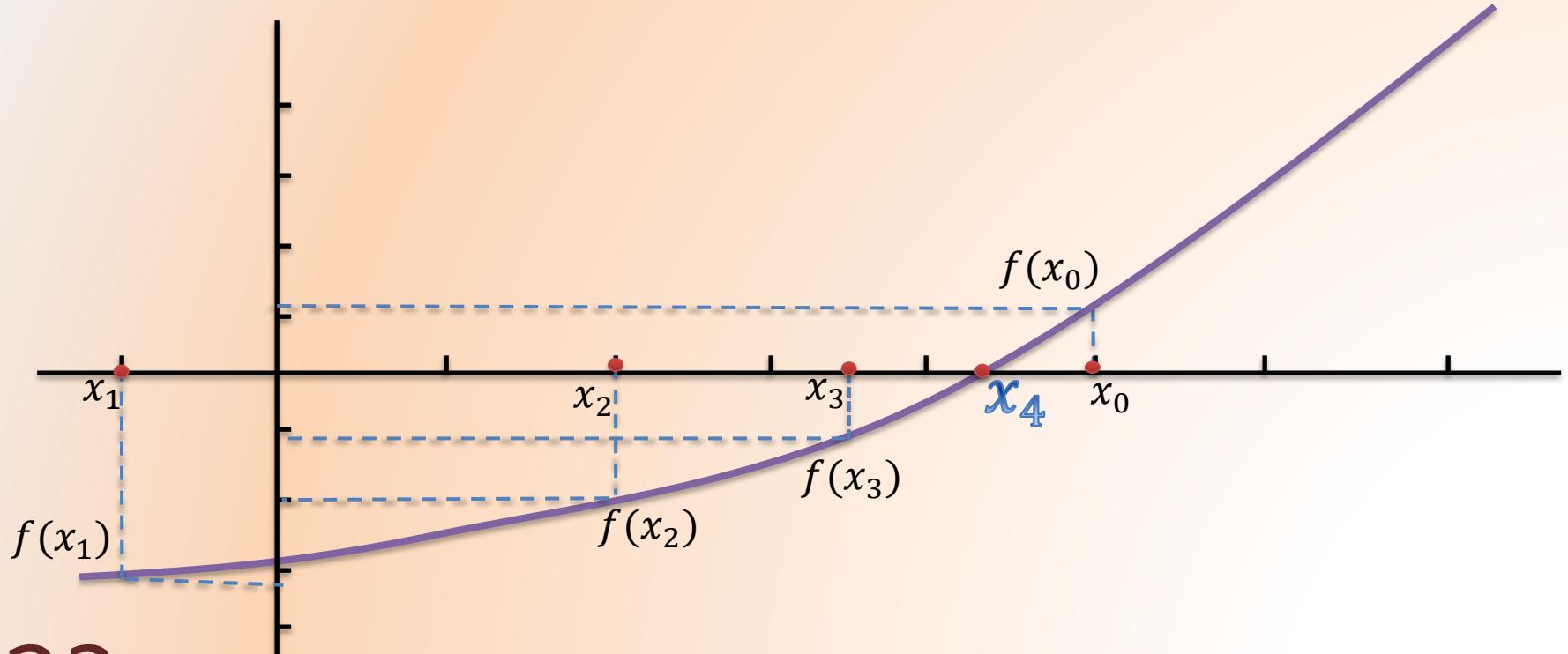
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Bisection Method

Assumptions Example Advantages & Disadvantages

$$f(x) = 0.25e^{2x} - 1.5 = 0 \quad x_0 = 1 \text{ and } x_1 = -0.2$$



Bisection Method

مثال ۳. تقریبی از ریشه معادله $x^4 - (1-x)^5 = 0$ را که در فاصله $(0, 1)$ قرار دارد با $4D$ به دست آورید به طوری که داشته باشیم $|f(x_n)| < 10^{-2}$ تقریب ریشه در تکرار n است.

حل:

n	a	b	$x_n = \frac{a+b}{2}$	علامت $f(a)f(x_n)$	$f(x_n)$
۱	۰	۱	۰,۵	-	۰,۲۱۸۷۵
۲	۰	۰,۵	۰,۲۵	+	-۰,۱۷۴۸۰
۳	۰,۲۵	۰,۵	۰,۳۷۵	-	۰,۰۴۵۲۶
۴	۰,۲۵	۰,۳۷۵	۰,۳۱۲۵	+	-۰,۰۰۵۹۳
۵	۰,۳۱۲۵	۰,۳۷۵	۰,۳۴۳۷۵	+	-۰,۰۰۳۵۵

چون $|f(x_5)| = ۰,۰۰۳۵۵ < 10^{-2}$ بنابراین تقریب ریشه با $4D$ عبارتست از:

$$\alpha \approx ۰,۳۴۳۷$$

Bisection Method

Number of iterations is n ,

if $\frac{b-a}{2^n} \leq \varepsilon$

In the interval $[0, 1]$:

ε	10^{-2}	10^{-3}	10^{-4}	10^{-5}	10^{-6}	10^{-7}
n	7	10	14	17	20	24

One step is devoted to the selection of the interval.

The degree of convergence for this method is 1.

(This method converges linearly.)

$$e_{k+1} = \frac{1}{2} e_k$$

Bisection Method

Assumptions Example Advantages & Disadvantages

Advantages :

- Always converges to the answer.
- This method is very simple.
- There is no need to compute the exact value of f . It is only required to know whether f is positive or negative.
- Number of iterations does not relate to the function.

Disadvantages :

- It is very slow (convergence degree is equal to 1).

Methods

Extra Topics

Bisection Method

False Position Method

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Newton–Raphson Method

Simple Iterative or Fixed Point Method

False Position Method

Assumptions Example Advantages & Disadvantages

$$f(x) = 0$$

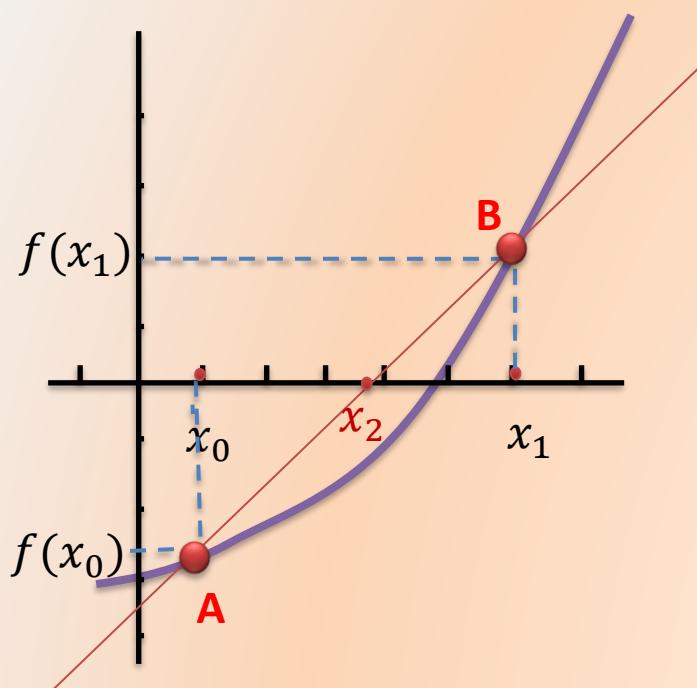
Initial assumptions:

x_0 and x_1 such that $f(x_0) \times f(x_1) < 0$

False Position Method

Assumptions Example Advantages & Disadvantages

method:



The equation of line AB:

$$y - f(x_0) = \frac{f(x_1) - f(x_0)}{x_1 - x_0} (x - x_0)$$

The point $(x_2, 0)$ lies on line AB, so:

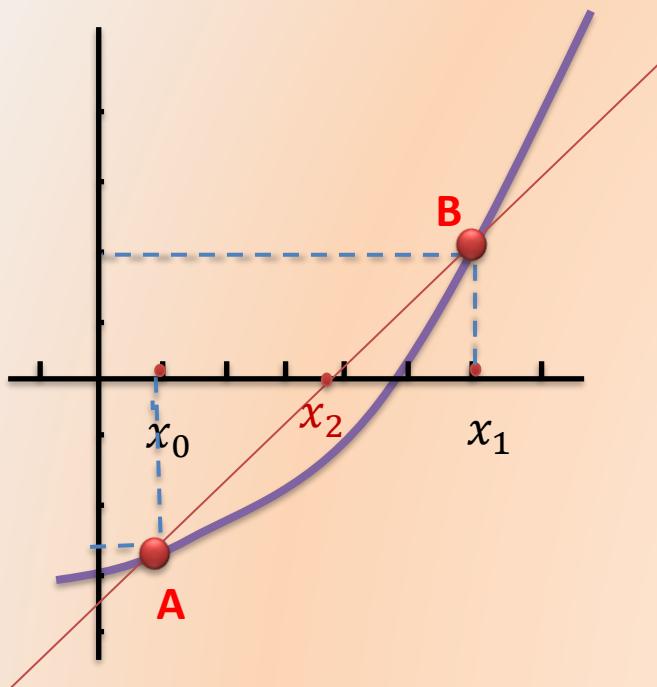
$$0 - f(x_0) = \frac{f(x_1) - f(x_0)}{x_1 - x_0} (x_2 - x_0)$$

$$x_2 = \frac{x_0 f(x_1) - x_1 f(x_0)}{f(x_1) - f(x_0)}$$

False Position Method

Assumptions Example Advantages & Disadvantages

method:

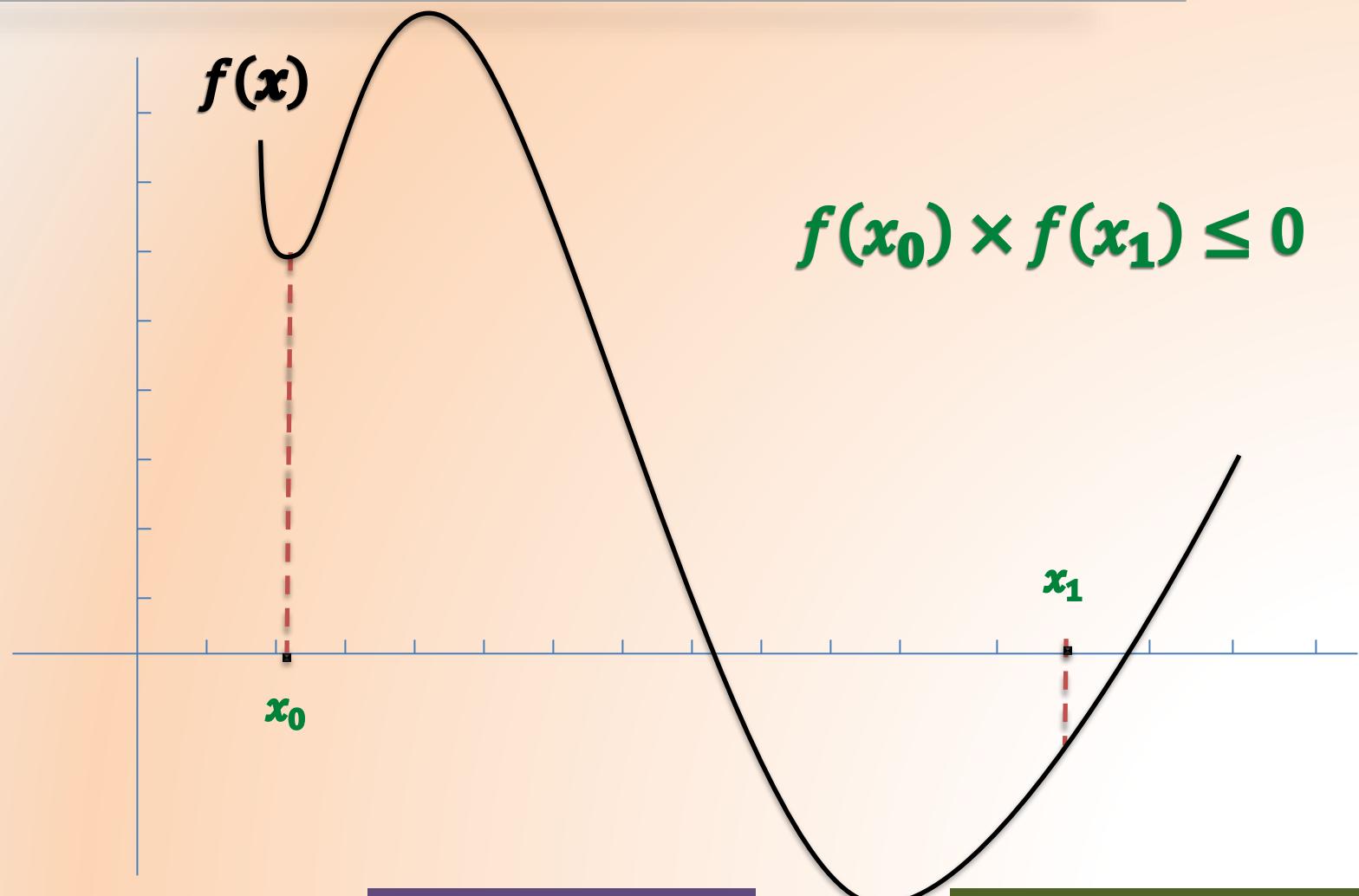


$$x_2 = \frac{x_0 f(x_1) - x_1 f(x_0)}{f(x_1) - f(x_0)}$$

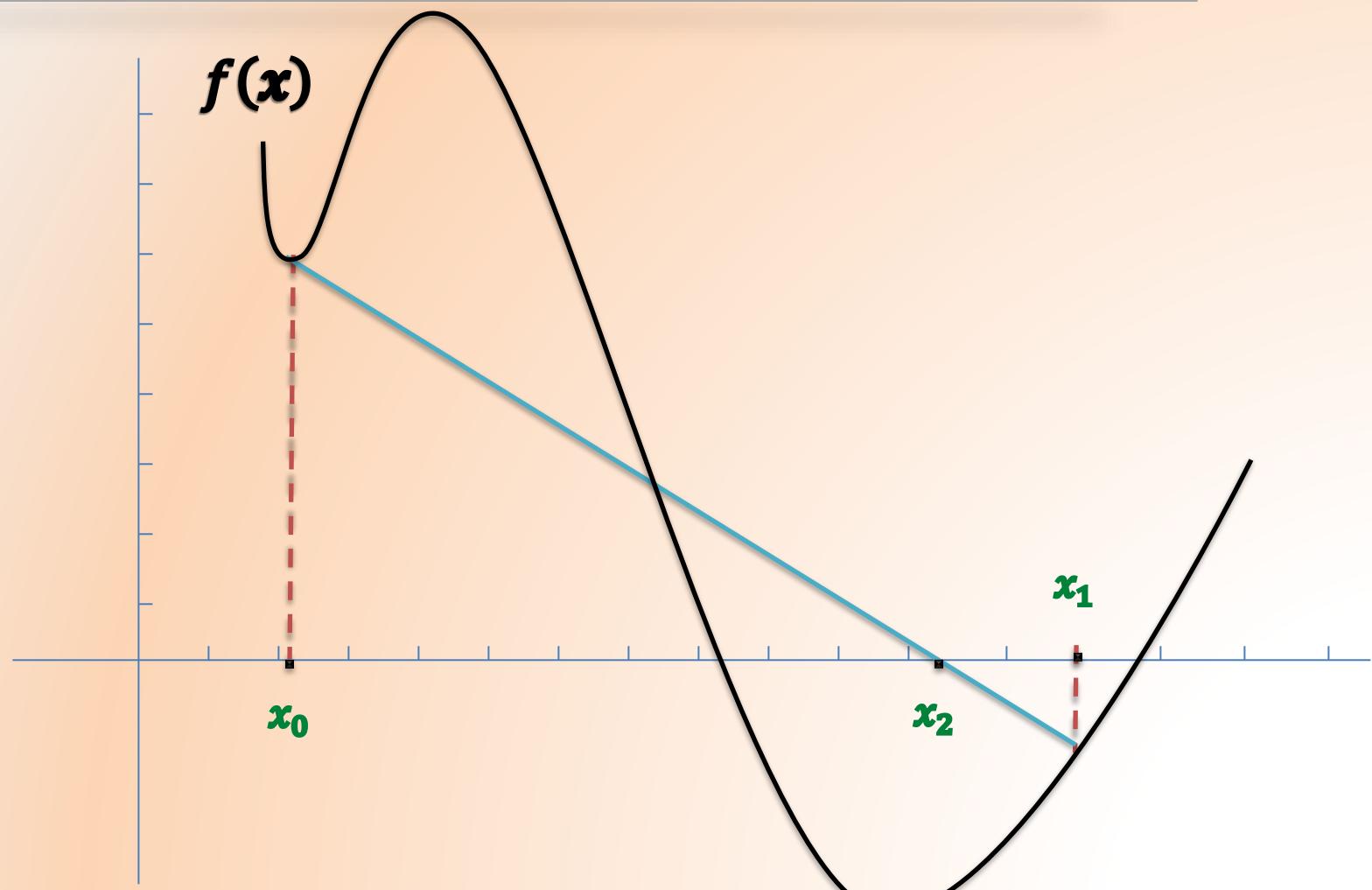
Know, check the Bolzano theorem between
 $f(x_2), f(x_0)$
And
 $f(x_2), f(x_1)$
To update point A or B

Repeat the above process to
get a termination condition

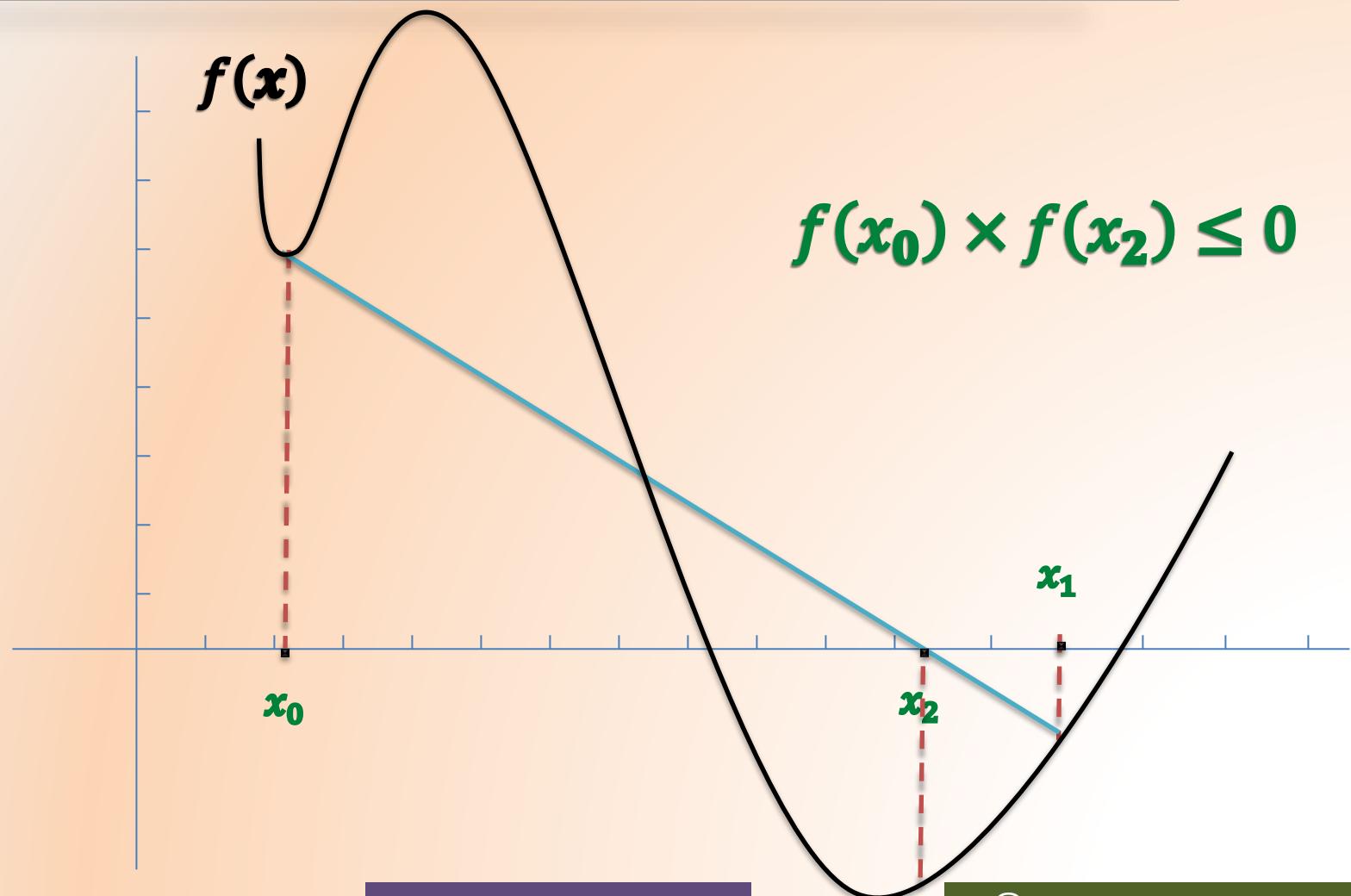
False Position Method



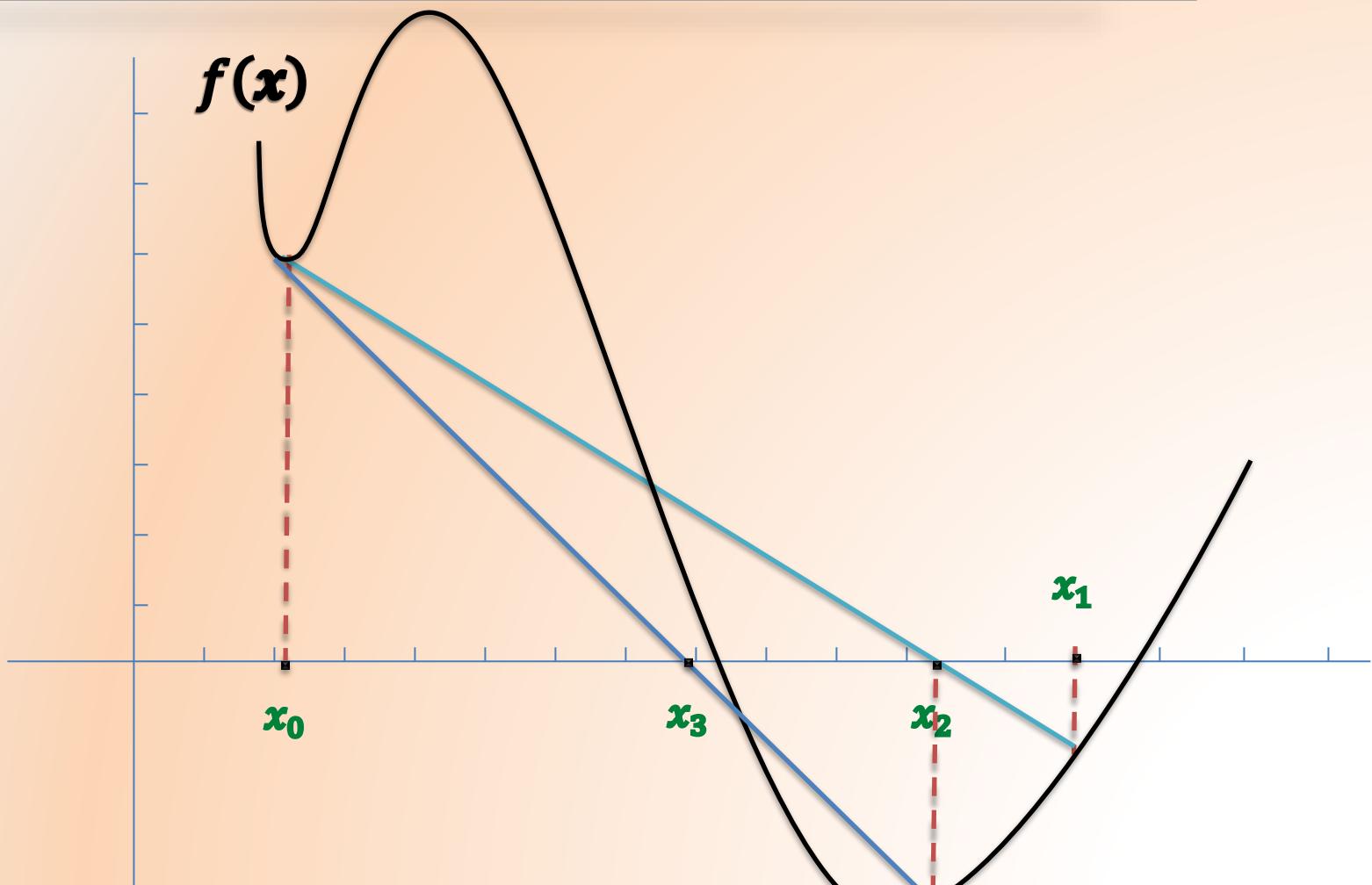
False Position Method



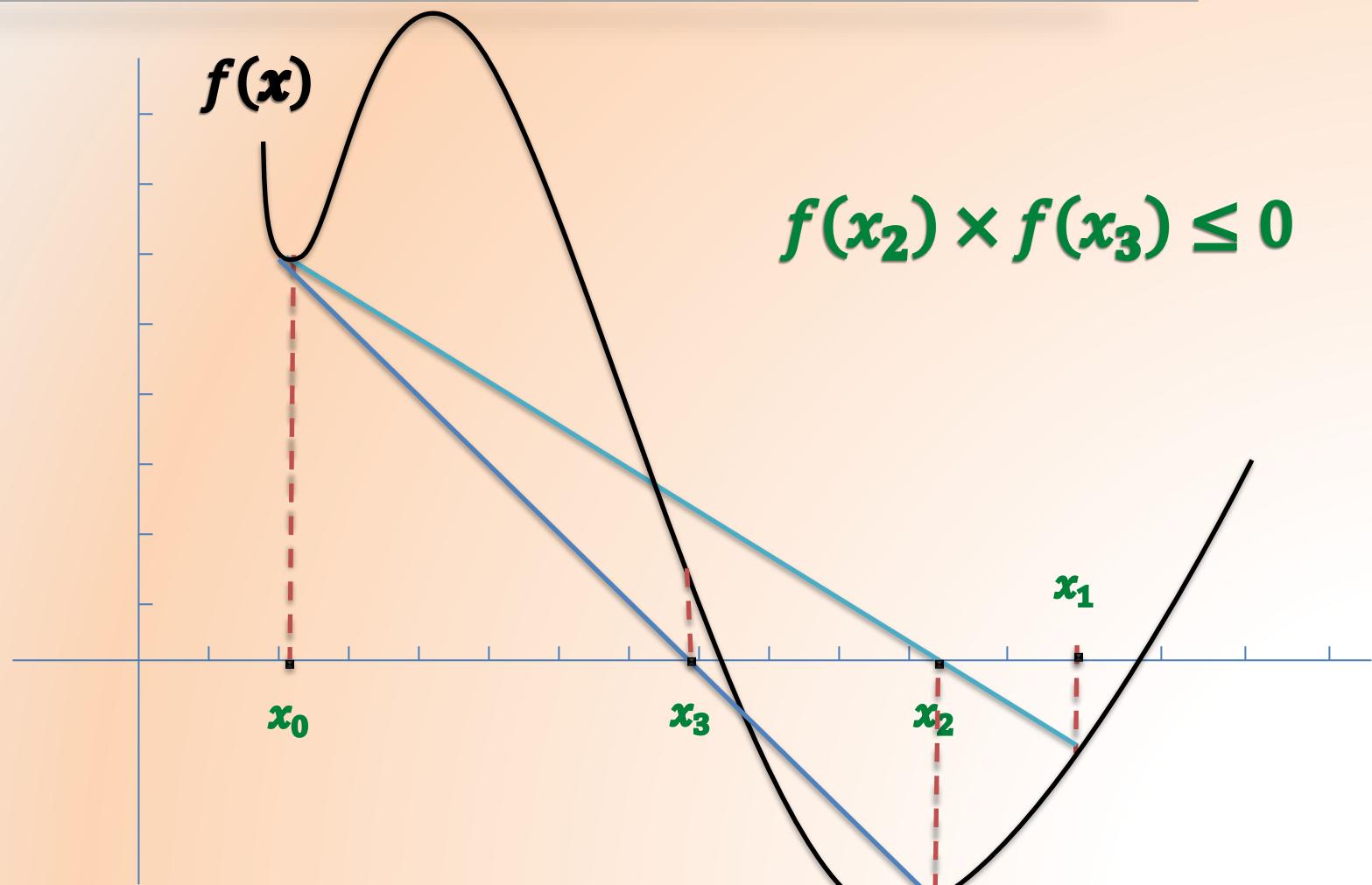
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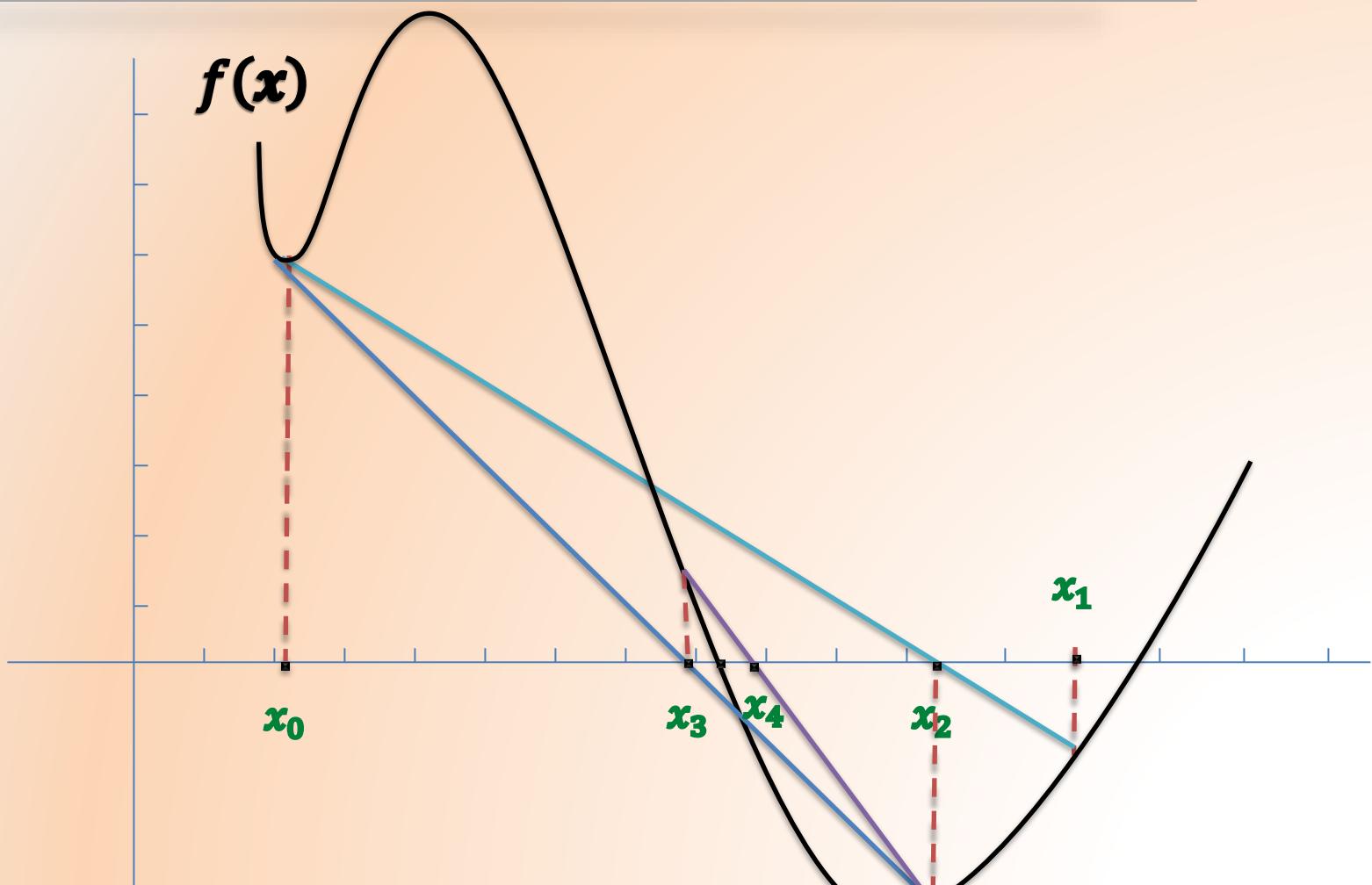
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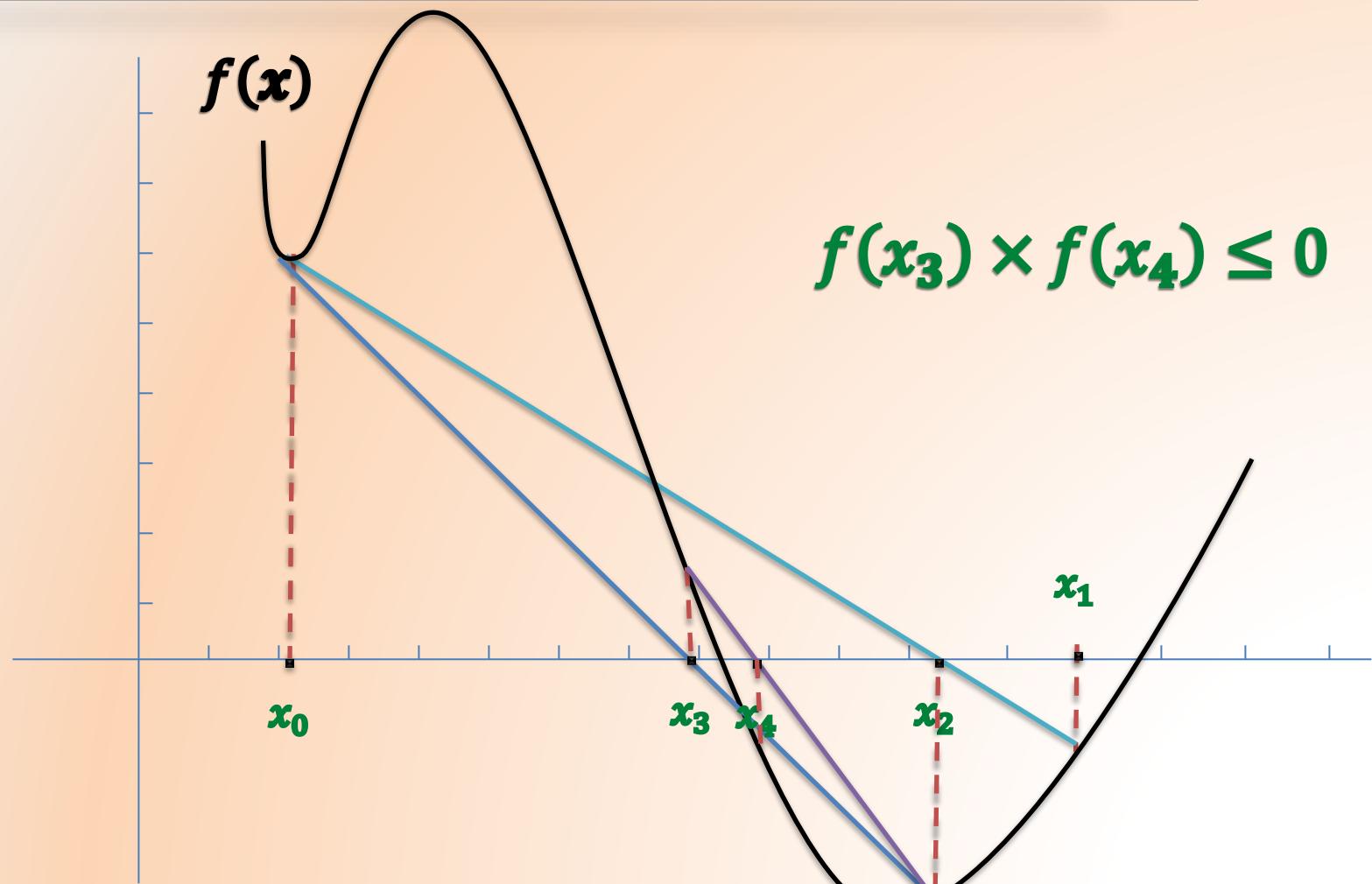
False Position Method



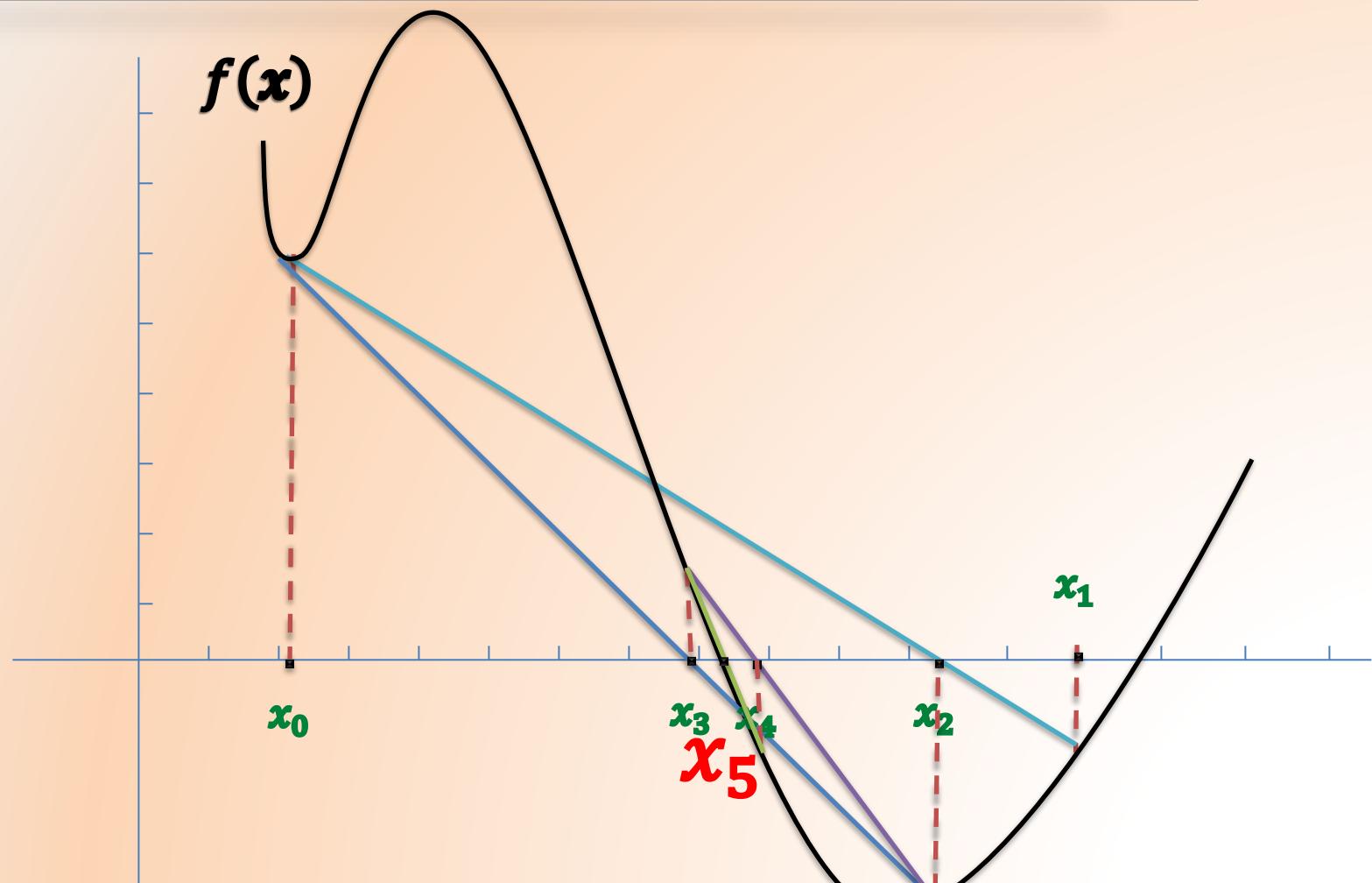
False Position Method



False Position Method



False Position Method



False Position Method

Termination condition:

$$|x_n - x_{n-1}| < \varepsilon$$

Degree of convergence:

$$\frac{1+\sqrt{5}}{2} = 1.618 \quad \text{Golden Ratio}$$

False Position Method

Assumptions Example Advantages & Disadvantages

$$2x - \log x = 7 \quad x \in (3.5, 4) \quad (2 \text{ steps})$$

$$f(x) = 2x - \log x - 7 \rightarrow \begin{cases} f(4) = 0.39794 = f_1 \\ f(3.5) = -0.54407 = f_0 \end{cases}$$

Step 1:

$$x_2 = x_1 - \left[\frac{x_1 - x_0}{f_1 - f_0} \right] f_1 = 3.78878$$

$$f_2 = f(x_2) = -0.00104$$

Step 2:

$$x_3 = x_2 - \left[\frac{x_2 - x_1}{f_2 - f_1} \right] f_2 = 3.78934$$

False Position Method

مثال ۵. تقریبی از ریشه معادله $f(x) = x^4 - 2x + 1 = 0$ در فاصله $(-1, 0)$ قرار دارد به روش نابجایی با $4D$ به دست آورید به طوری که $|f(x_n)| < 10^{-2}$

حل: هرگاه قرار دهیم $x_n = \frac{af(b) - bf(a)}{f(b) - f(a)}$ جدول زیر را خواهیم داشت:

n	a	b	x_n	$f(a)$	$f(x_n)$	علامت $f(a)f(x_n)$
۱	-1	0	-0,66667	0,5	-0,18002	-
۲	-1	-0,66667	-0,75688	0,5	-0,01892	-
۳	-1	-0,75688	-0,76574	0,5	-0,00179	-

چون $|f(x_3)| = 0,00179 < 10^{-2}$ با $4D$ تقریب ریشه x_3 مورد نظر ریشه است. لذا با $4D$ تقریب ریشه عبارت است از:

$$\alpha \approx -0,76574$$

False Position Method

مثال ۱. تقریبی از ریشه معادله $f(x) = 3x - e^{-x} = 0$ که در فاصله $(0, 25, 0, 27)$ قرار دارد، با سه رقم اعشار به دست آورید، به طوری که داشته باشیم: $|f(x_n)| < 0.0001$. تقریب ریشه در تکرار n است.

Bisection method

n	a	b	$x_n = \frac{a+b}{2}$	$f(a)f(x_n)$	علامت	$f(x_n)$
۱	۰,۲۵	۰,۲۷	۰,۲۶	-	-	۰,۰۰۸۹
۲	۰,۲۵	۰,۲۶	۰,۲۵۵	+	+	-۰,۰۰۹۹
۳	۰,۲۵۵	۰,۲۶	۰,۲۵۷۵	+	+	-۰,۰۰۰۵

چون $0.0005 < 0.0001$ بنابراین x_3 را به عنوان تقریب ریشه معادله در نظر می‌گیریم. لذا هرگاه α ریشه مورد نظر باشد، با سه رقم اعشار قرار می‌دهیم:

$$\alpha \approx 0,258$$

False Position Method

مثال ۱. تقریبی از ریشه معادله $f(x) = 3x - e^{-x} = 0$ که در فاصله $(0, 25, 0, 27)$ قرار دارد، با سه رقم اعشار به دست آورید، به طوری که داشته باشیم: $|f(x_n)| < 0.001$ که تقریب ریشه در تکرار n است.

False position method

$$x_1 = \frac{0.25 \times 0.466 - 0.27 \times (-0.0288)}{0.466 - (-0.0288)} = 0.2576$$

$$f(x_1) = -0.0001$$

لذا $|f(x_1)| = 0.0001 < 2 \times 10^{-4}$ بنابراین x_1 تقریب ریشه بوده و این تقریب با سه رقم اعشار عبارت است از:

$$\alpha \approx 0.258$$

False Position Method

Here bisection method works better.

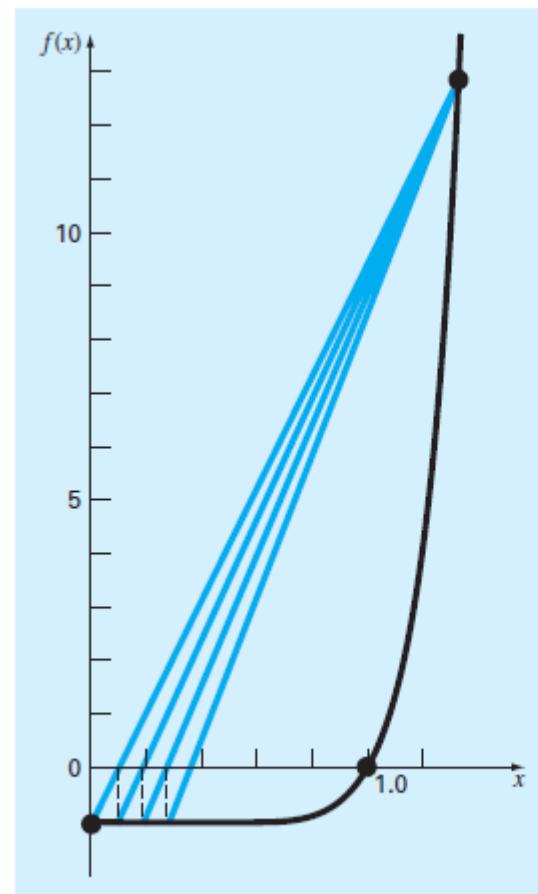


FIGURE 5.9
Plot of $f(x) = x^{10} - 1$, illustrating slow convergence of the false-position method.

False Position Method

Assumptions Example Advantages & Disadvantages

Advantages :

- Always converges to the answer.
- It converges faster than Bisection method.

Disadvantages :

- It is more difficult than bisection method, because the number of operations are more.
- If all of x_i s (or most of them) are in one side of root, this method converges slower.
- All calculations strictly depend on the function $f(x)$.

Methods

Extra Topics

Bisection Method

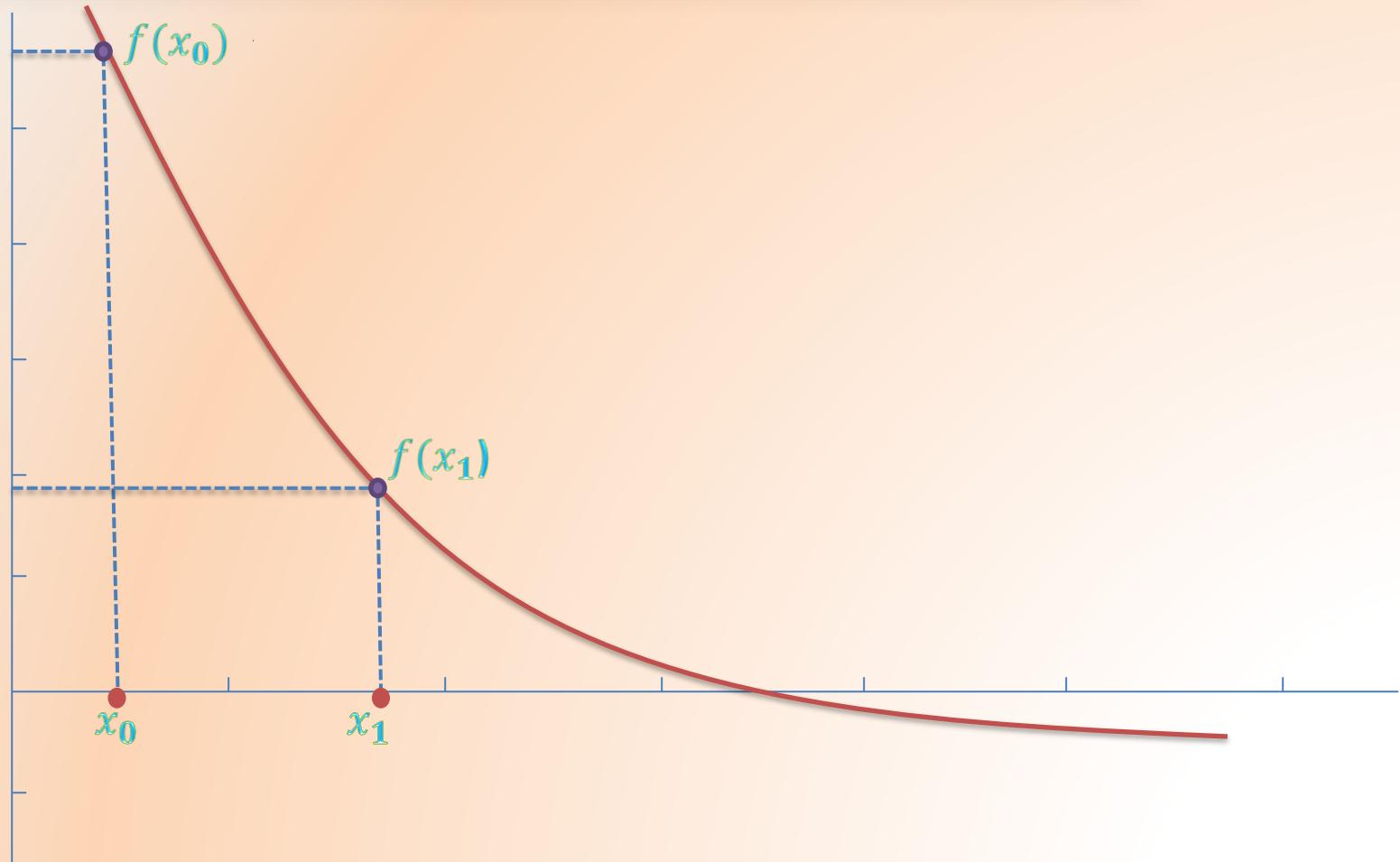
False Position Method

Secant Method

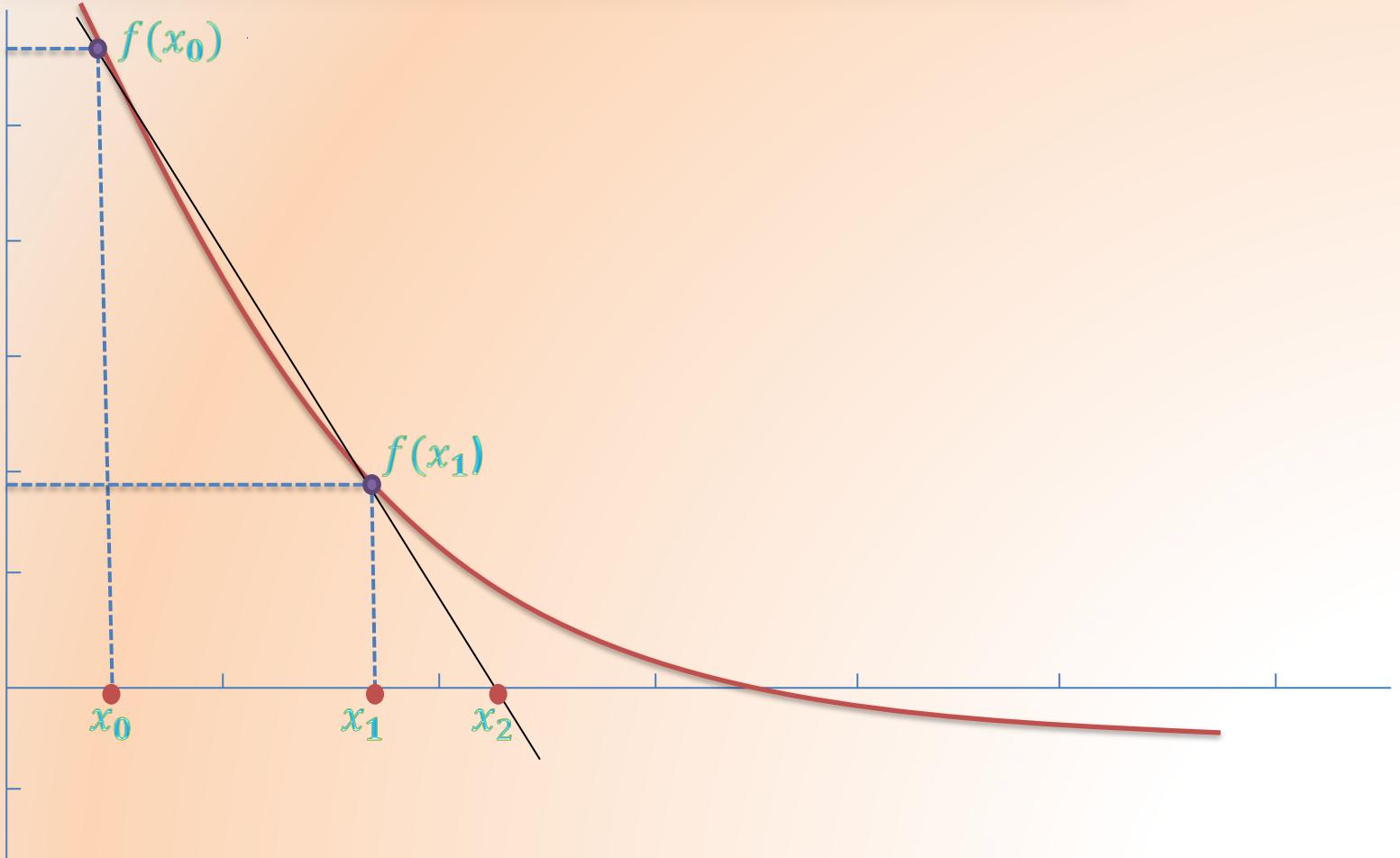
Newton–Raphson Method

Simple Iterative or Fixed Point Method

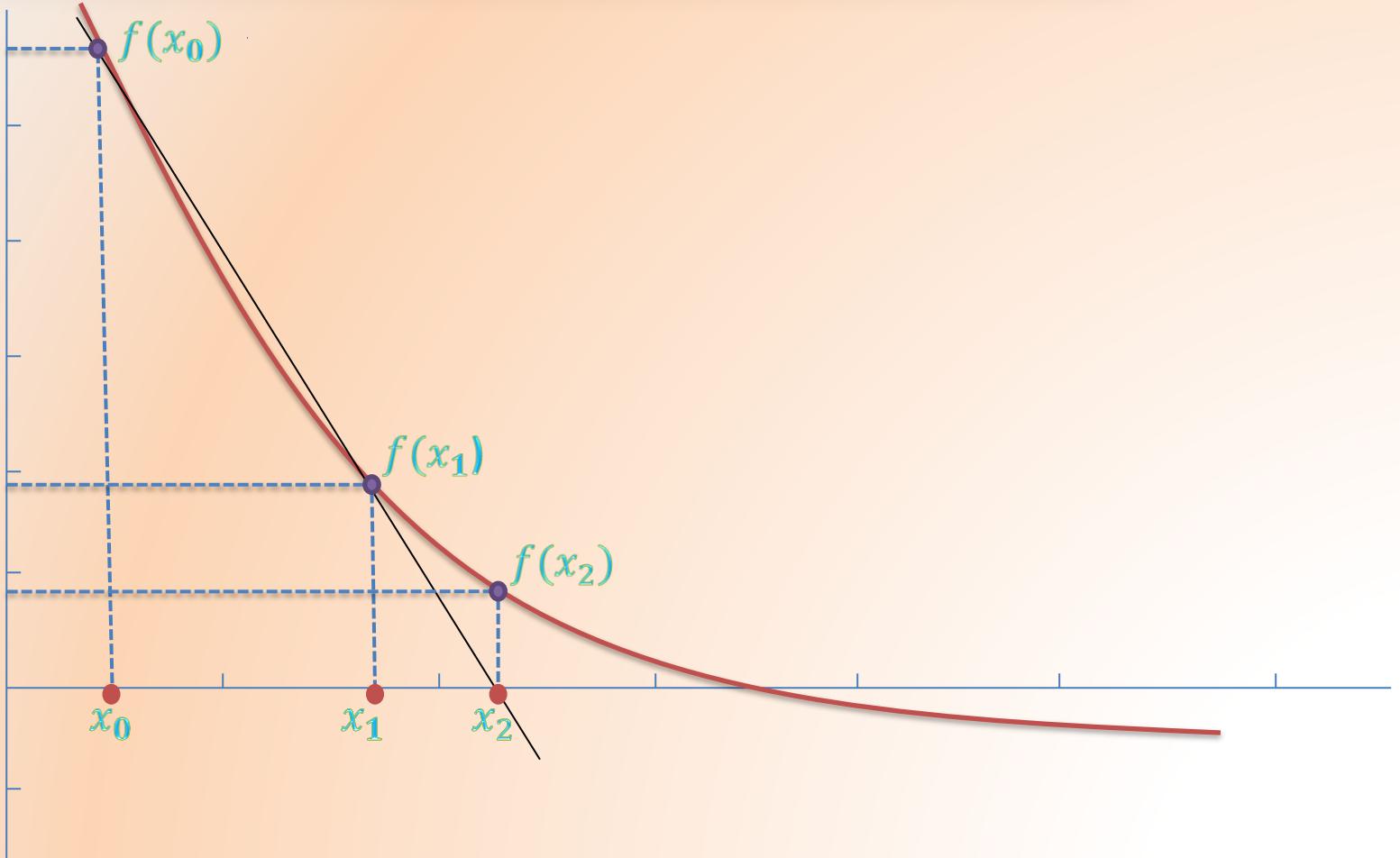
Secant Method



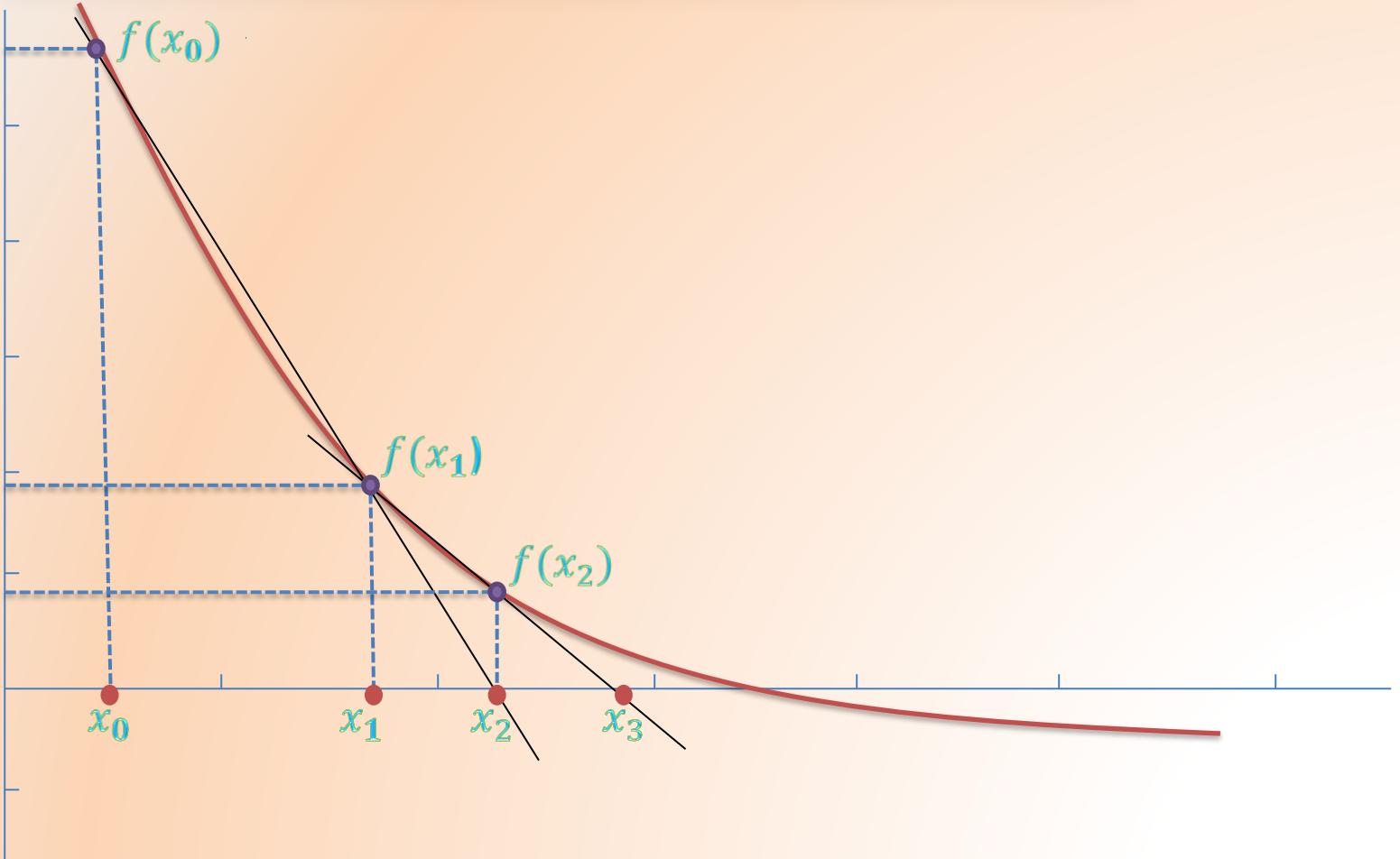
Secant Method



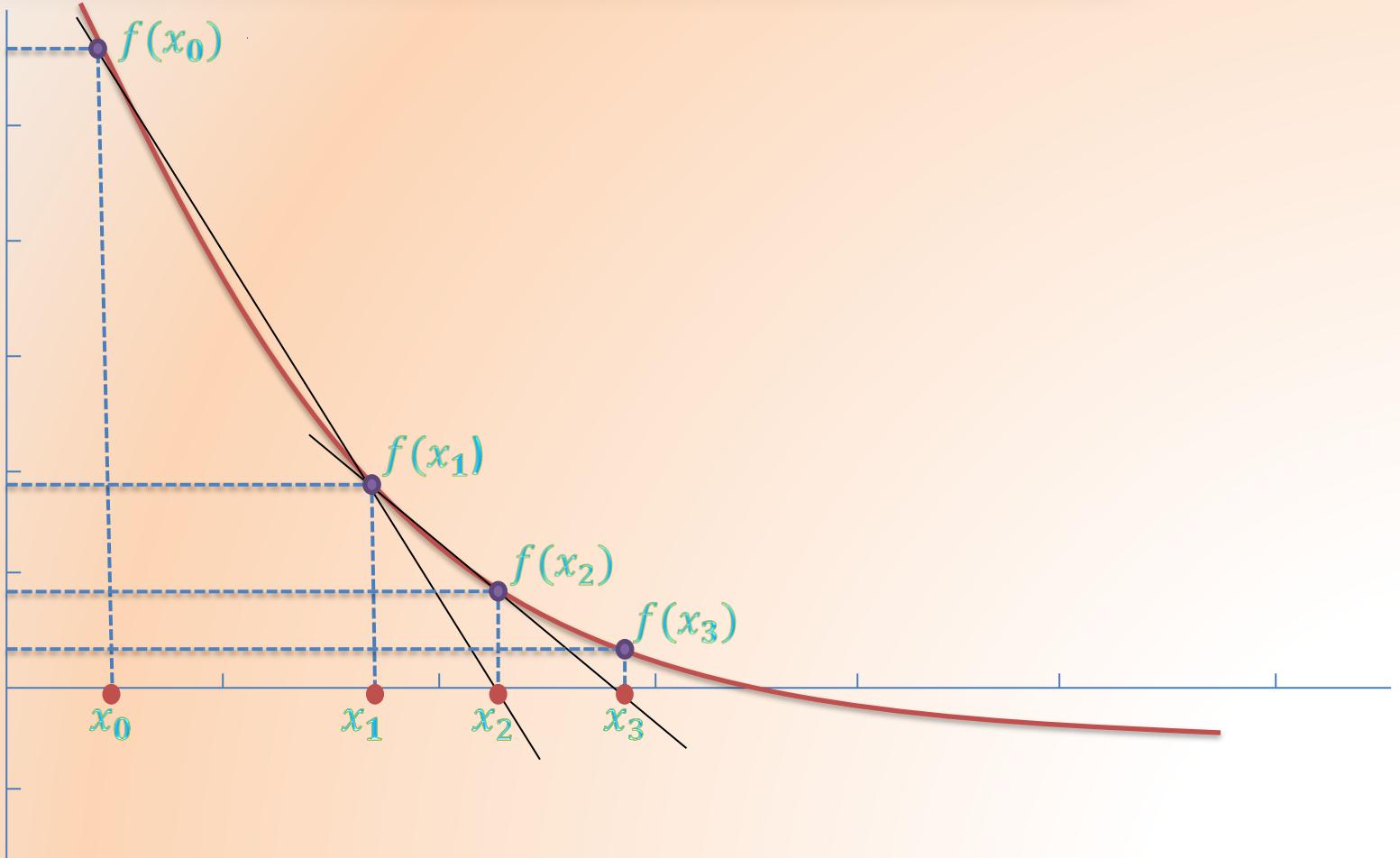
Secant Method



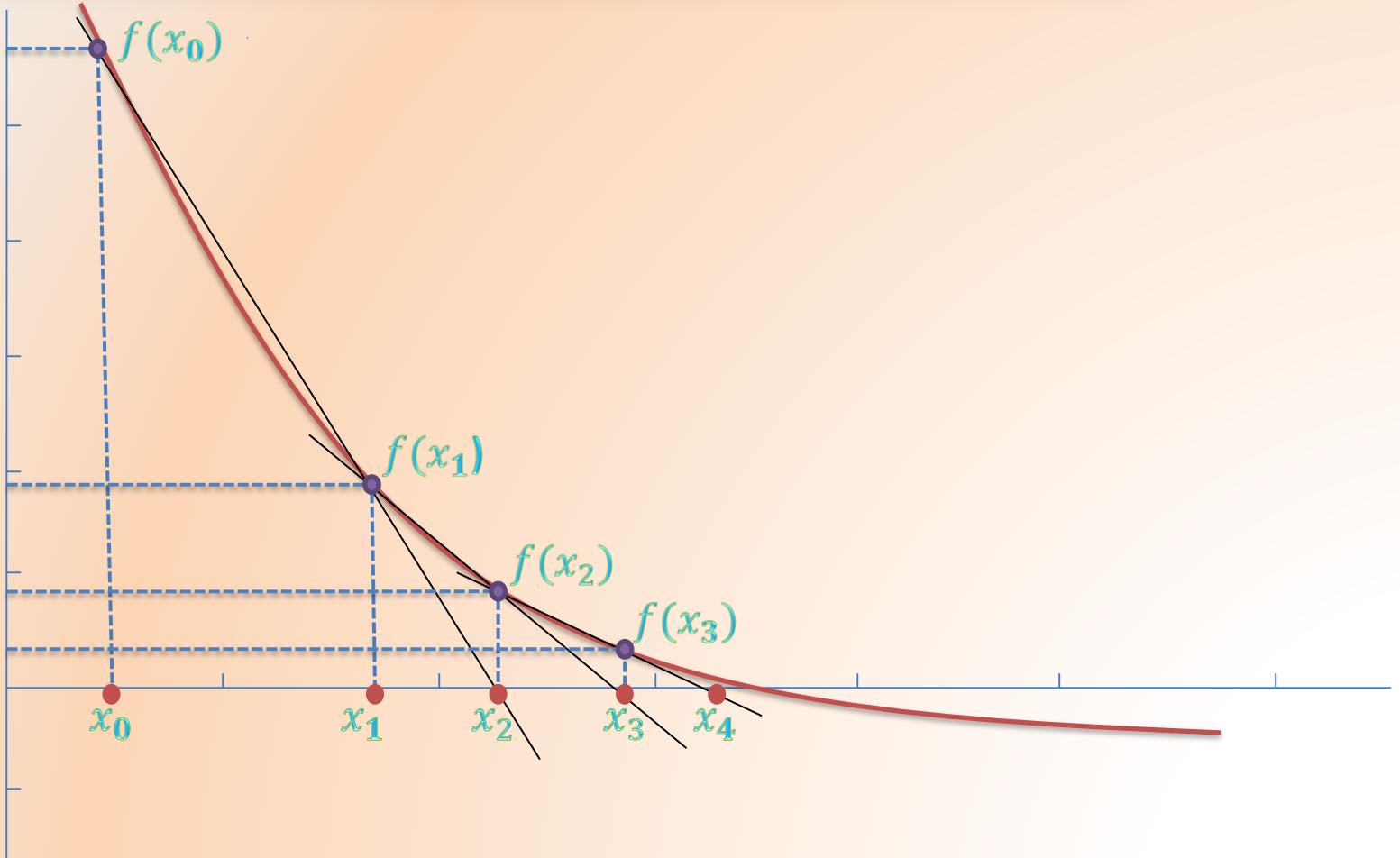
Secant Method



Secant Method



Secant Method



Secant Method

Assumptions Example Advantages & Disadvantages

Secant method is very similar to False-Position method except that Bolzano's theorem is not needed to be checked.

Initial approximations: an interval (x_0, x_1)

$$x_{n+1} = \frac{x_{n-1} \times f(x_n) - x_n \times f(x_{n-1})}{f(x_n) - f(x_{n-1})}$$

Or

$$x_{n+1} = x_n - \frac{f(x_n)(x_n - x_{n-1})}{f(x_n) - f(x_{n-1})}$$

Secant Method

Assumptions Example Advantages & Disadvantages

- Termination condition: $|x_n - x_{n-1}| < \varepsilon$
- Degree of convergence: $\frac{1+\sqrt{5}}{2}$
- Convergence condition:
The function $f(x)$ should be twice continuously differentiable and the root should be simple.

Secant Method

Assumptions Example Advantages & Disadvantages

$$f(x) = \cos x - x^2 = 0 \quad (5 \text{ steps}) \qquad (x_1 = 1, x_0 = 0)$$

$$f(x_0) = 1 - 0 = 1$$

$$f(x_1) = 0.9998 - 1 = -0.0002$$

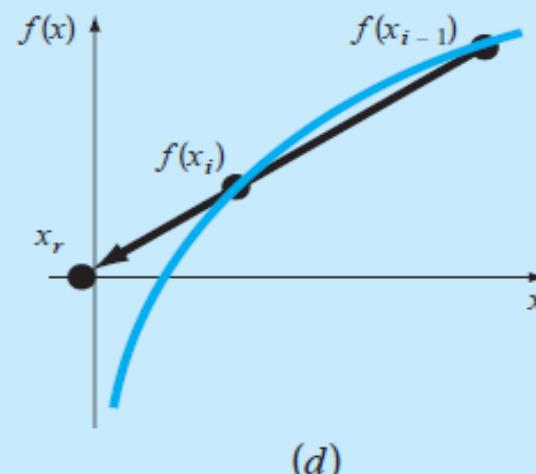
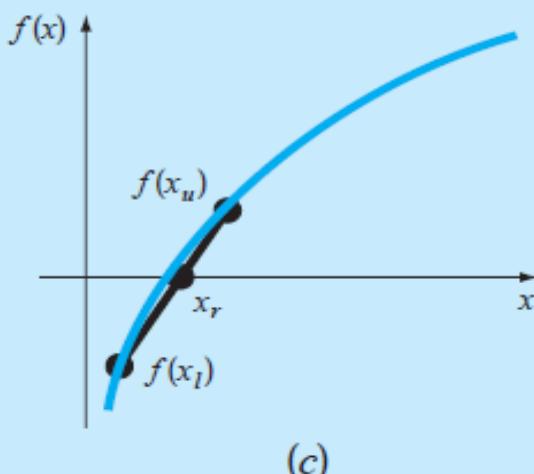
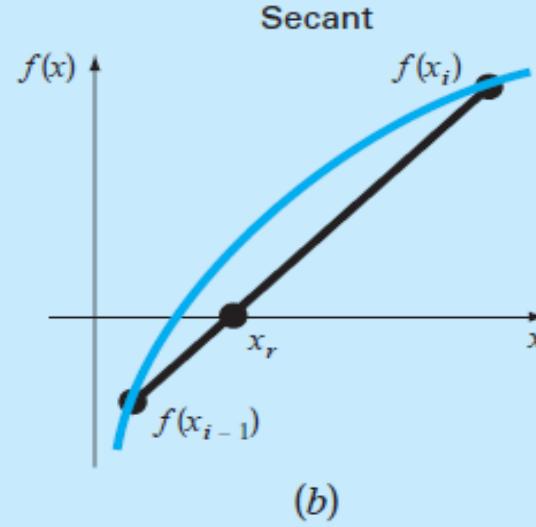
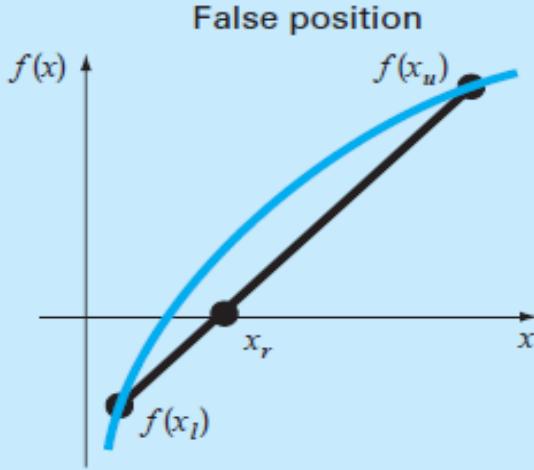
$$x_2 = 1 - \frac{(1-0)(-0.0002)}{0.0006-(-0.0002)} = 0.99995$$

$$f_3 = f(0.99995) = -0.0000023$$

$$x_4 = 0.9995 \quad f_4 = 0.001347$$

$$x_5 = 0.99995$$

Secant Method



Secant Method

Assumptions Example Advantages & Disadvantages

Advantages :

- It converges faster than bisection method.
- Bolzano's theorem is not needed.

Disadvantages :

- It is harder than bisection method.
- Sometimes it does not converge.
- If the initial guess is not close to the answer, then there is no guarantee it converges to the answer.

Methods

Extra Topics

Bisection Method

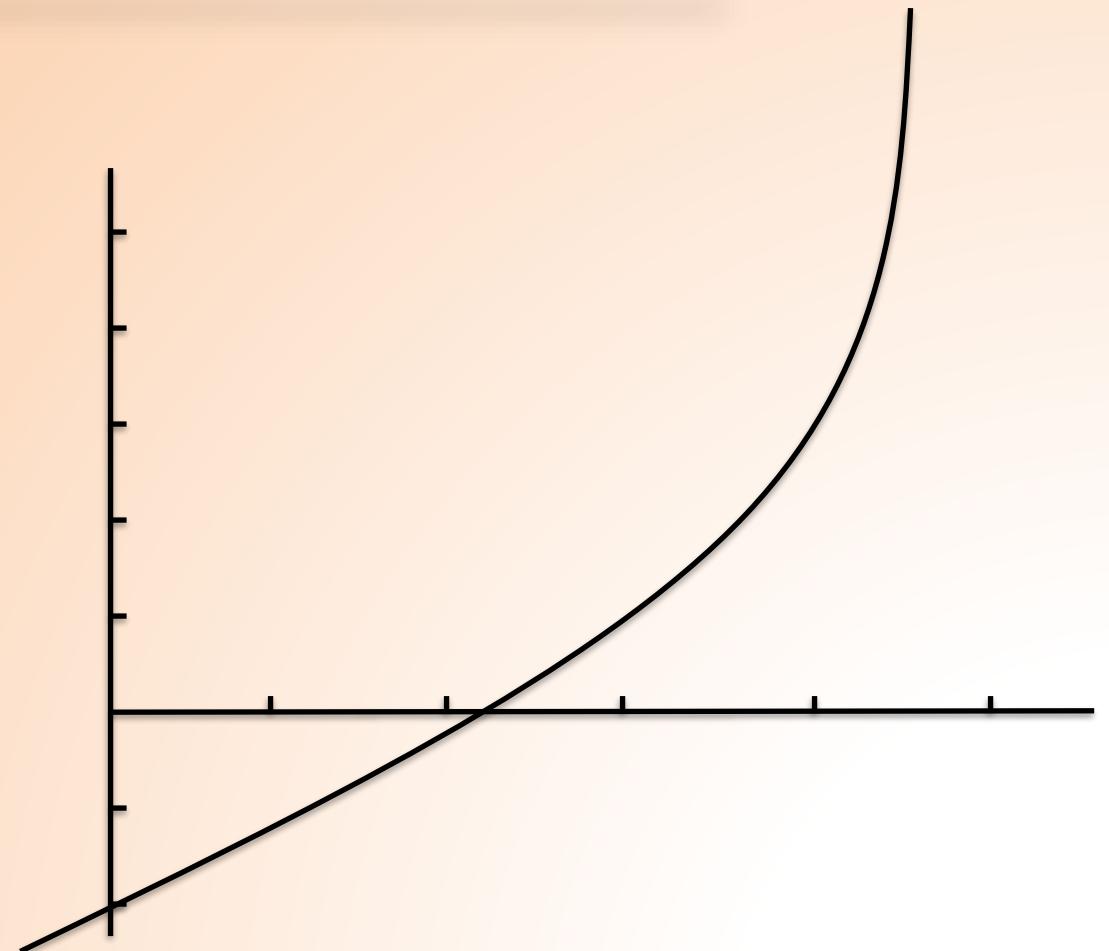
False Position Method

Secant Method

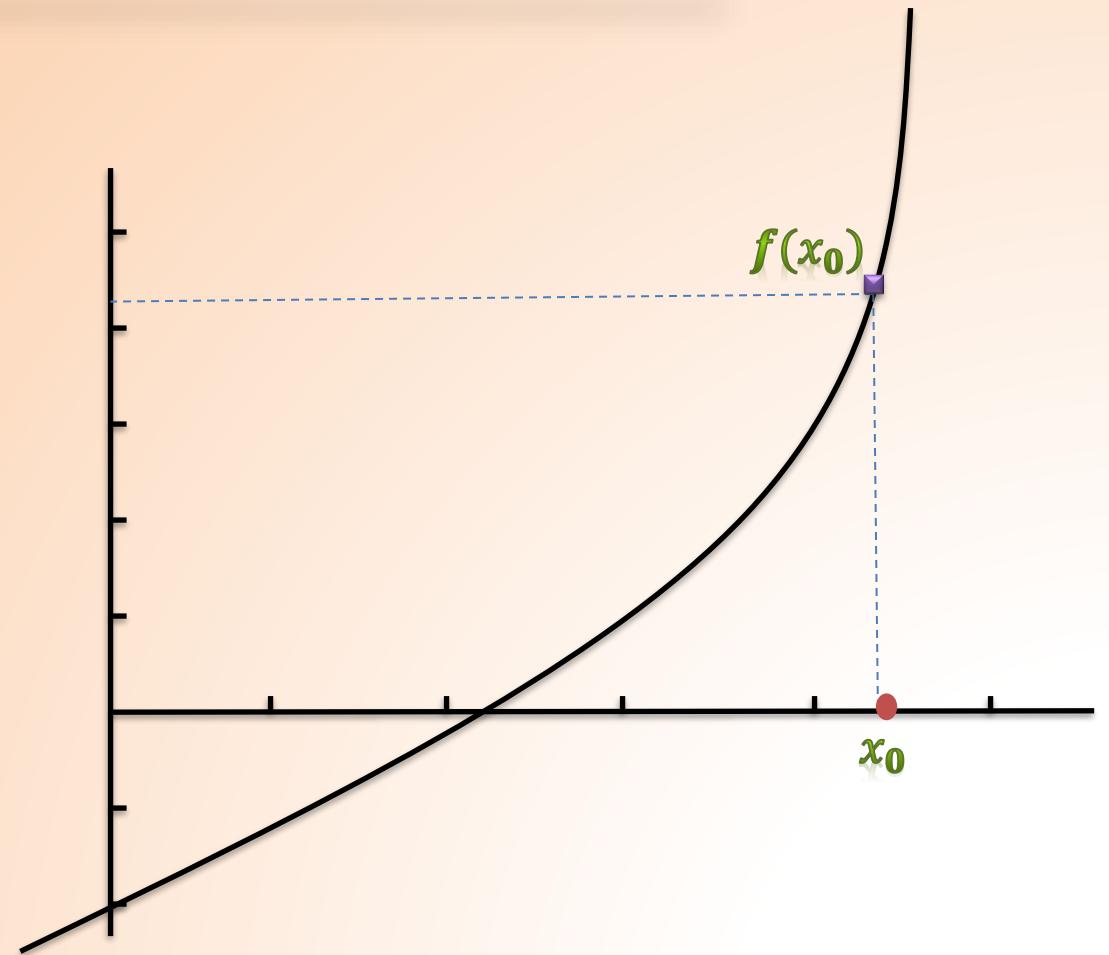
Newton–Raphson Method

Simple Iterative or Fixed Point Method

Newton-Raphson Method



Newton-Raphson Method

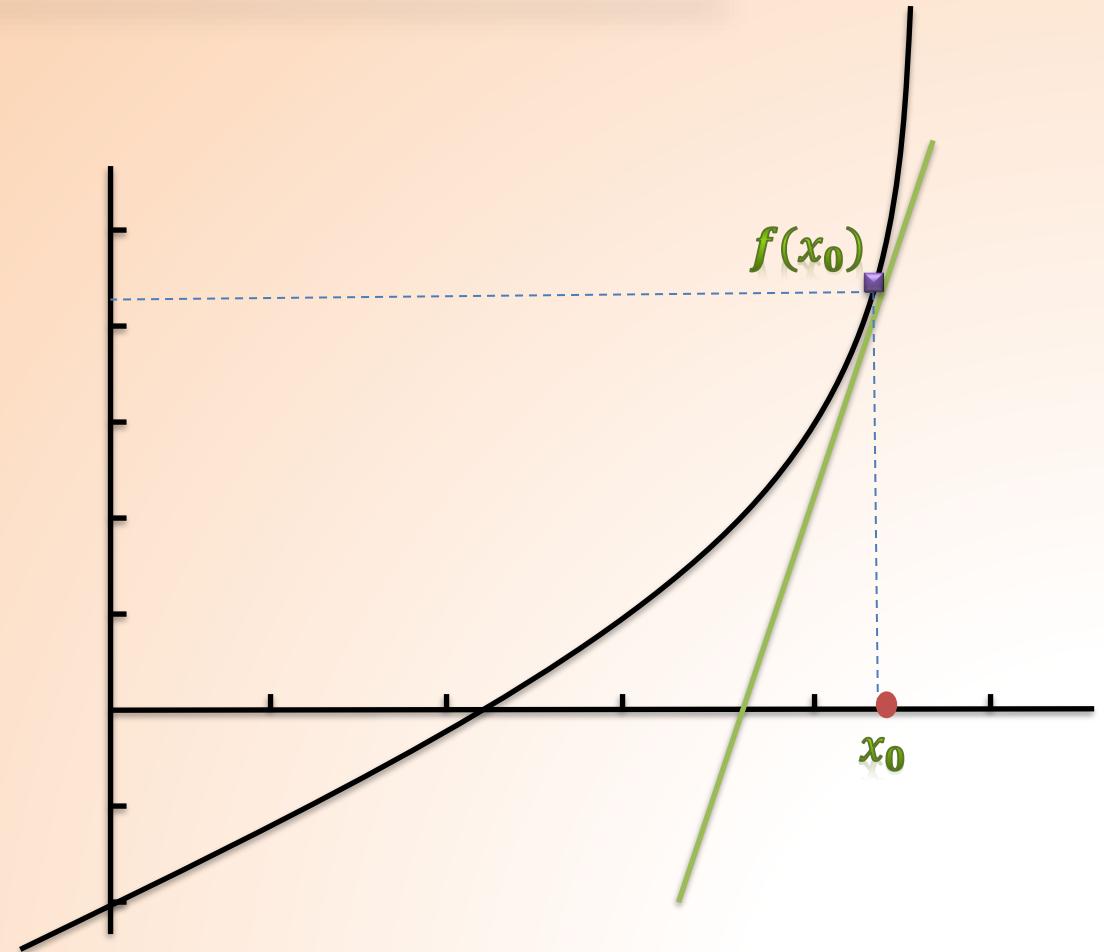


Newton-Raphson Method

Slope of tangent line:

$$\frac{0 - f(x_0)}{x_1 - x_0} = f'(x_0)$$

$$\Rightarrow x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

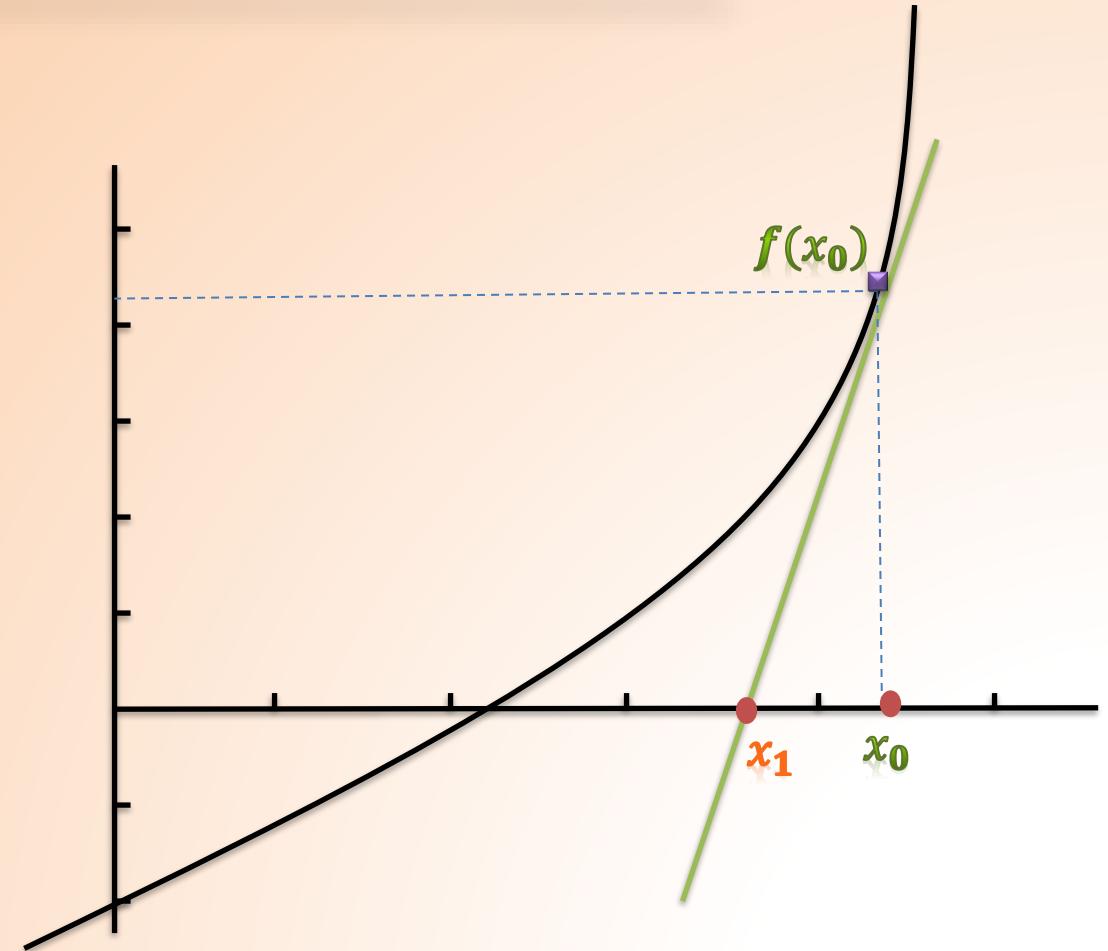


Newton-Raphson Method

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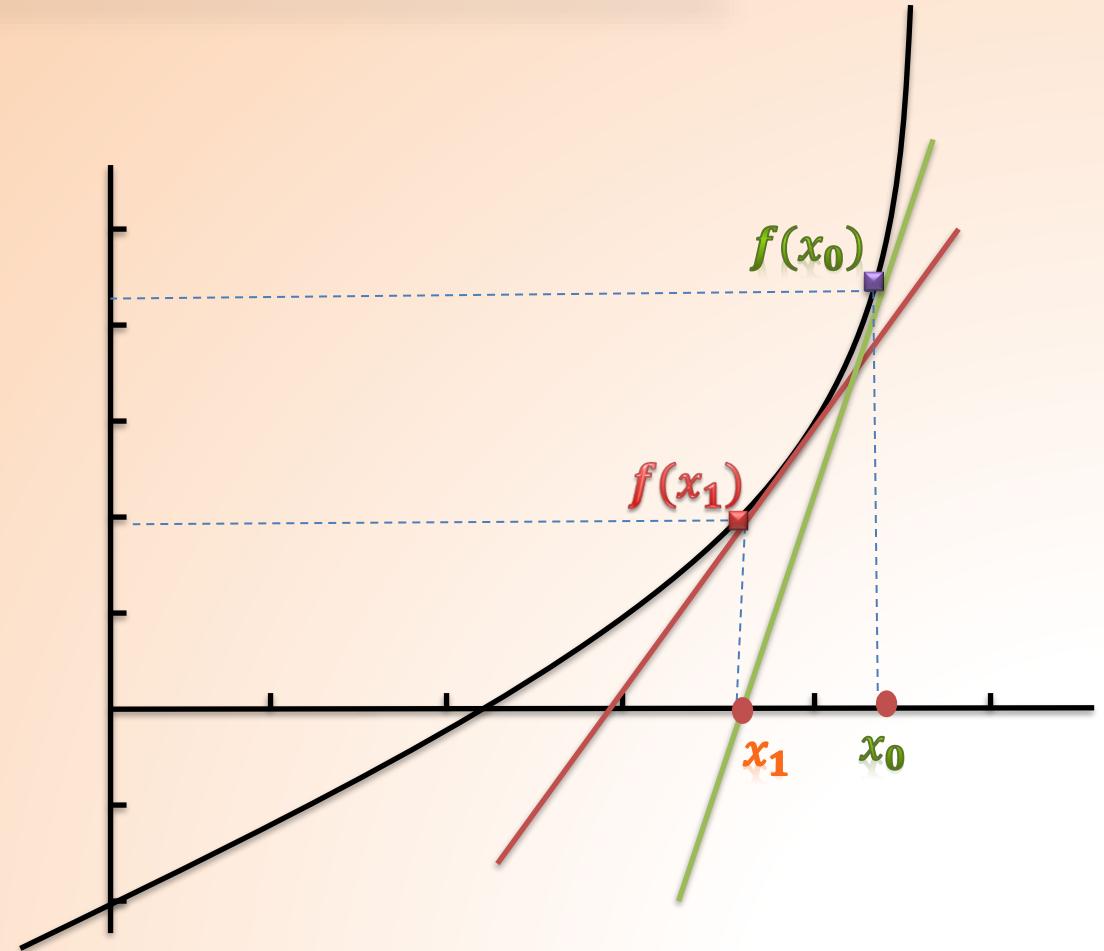


Newton-Raphson Method

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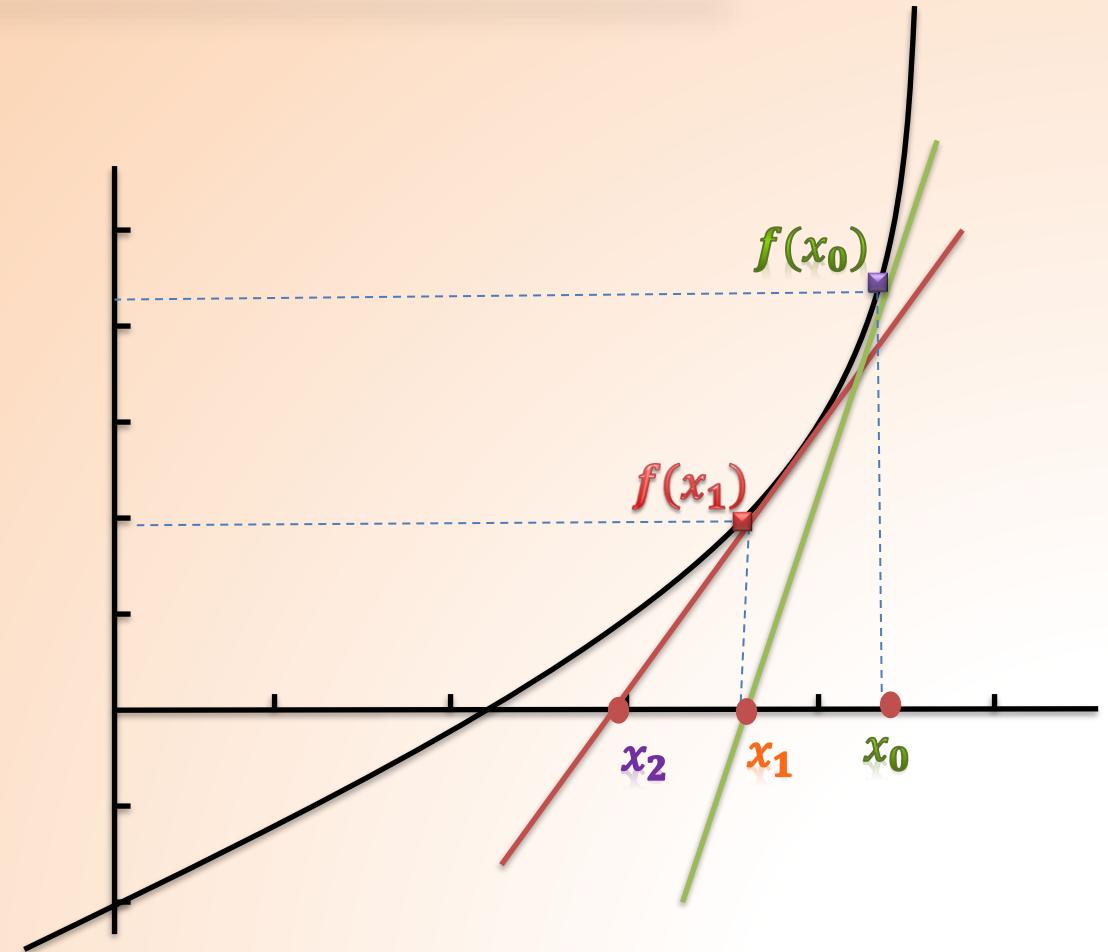


Newton-Raphson Method

Slope of tangent line:

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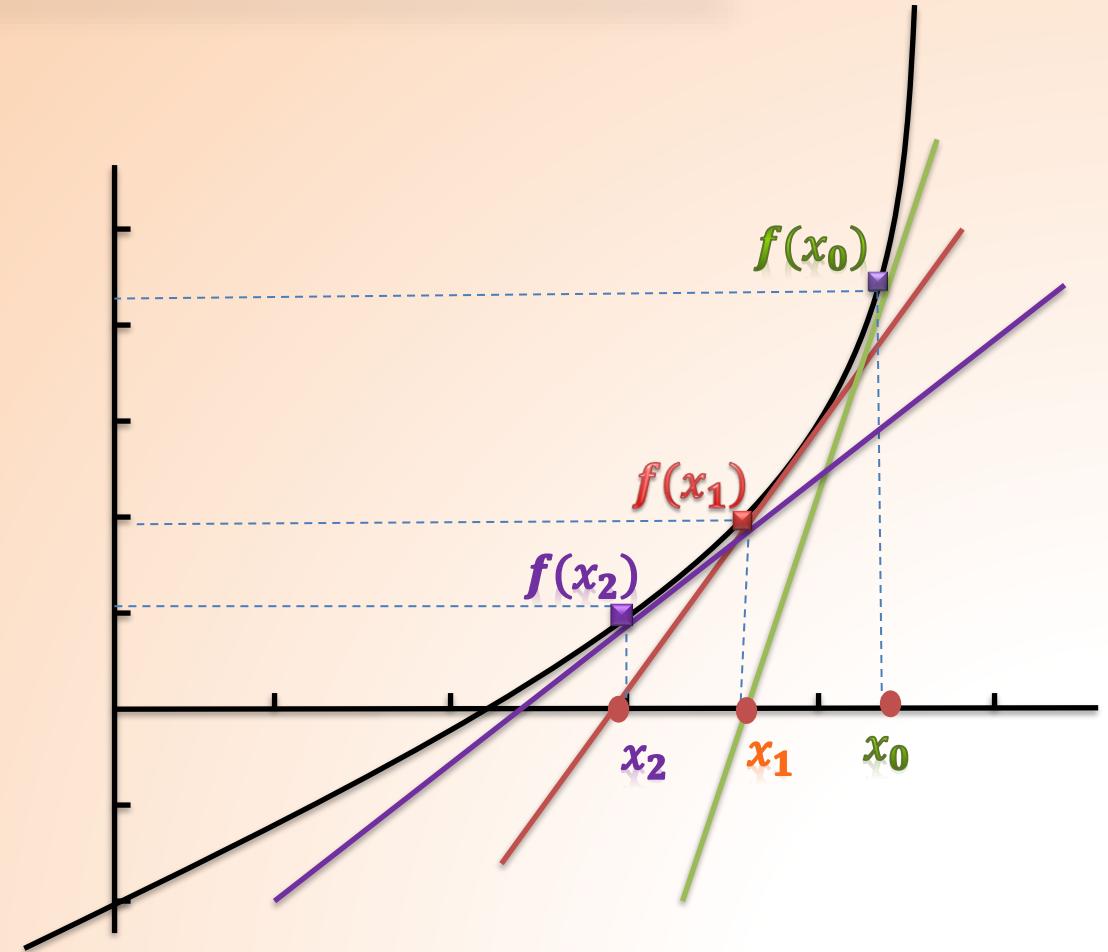


Newton-Raphson Method

Slope of tangent line:

$$\frac{0 - f(x_0)}{x_1 - x_0} = f'(x_0)$$

$$\Rightarrow x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

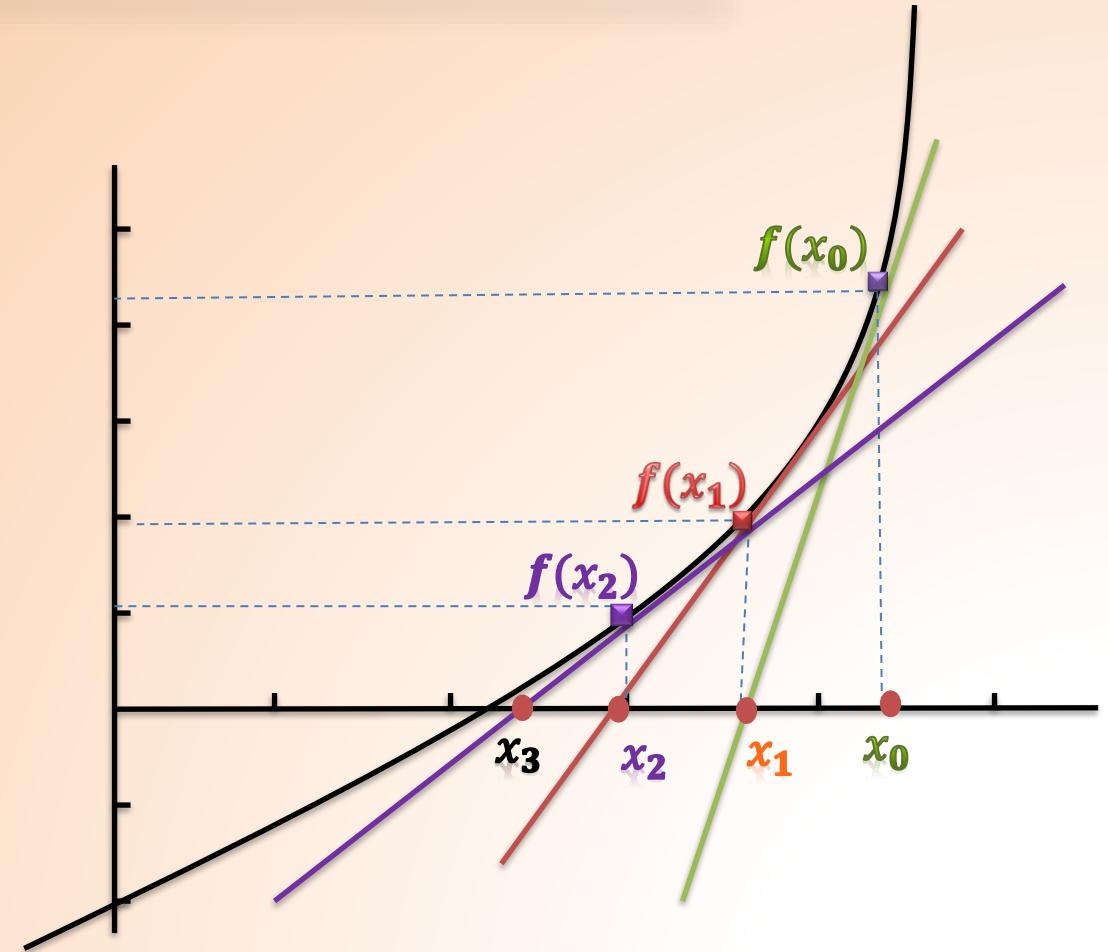


Newton-Raphson Method

Slope of tangent line:

$$\frac{0 - f(x_0)}{x_1 - x_0} = f'(x_0)$$

$$\Rightarrow x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$



Newton-Raphson Method

Assumptions Example Advantages & Disadvantages

Initial assumption: x_0

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

Newton-Raphson Method

مقداری میں نہیں پھرنا

از سب سے نزدیکی x_n کے ساتھ

$$f(x) = f(x_n) + (x - x_n) f'(x_n) + \frac{(x - x_n)^r}{r!} f''(x_n) \quad x_n < x_n < x$$

$f(x_n)$ اول

$$0 = f(x_n) + (\alpha - x_n) f'(x_n) + \frac{(\alpha - x_n)^r}{r!} f''(x_n) \quad x_n < x_n < \alpha$$

ذیلی نتائج، مرادیوں

$$\underbrace{\alpha - x_n}_{-x_{n+1}} + \frac{f(x_n)}{f'(x_n)} = - \frac{1}{r} (\alpha - x_n)^{r-1} \frac{f''(x_n)}{f'(x_n)}$$

نیچے $f'(x_n)$ کا تابع

$$\underbrace{\alpha - x_{n+1}}_{e_{n+1}} = - \frac{1}{r} (\alpha - x_n)^{r-1} \underbrace{\frac{f''(x_n)}{f'(x_n)}}_{e_n} \Rightarrow e_{n+1} = \left| \frac{f''(x_n)}{f'(x_n)} \right|^{1/r} e_n$$

Newton-Raphson Method

Assumptions Example Advantages & Disadvantages

Termination condition:

$$|x_n - x_{n-1}| < \varepsilon$$

Convergence condition:

$$\left| \frac{f(x) \times f''(x)}{f'^2(x)} \right| < 1$$

Degree of convergence:

2

Note that the convergence degree is 2 , only in case of simple roots

Newton-Raphson Method

Assumptions Example Advantages & Disadvantages

مثال ۷. ریشه معادله $f(x) = x - \cos x = 0$ را که در فاصله $[0, 1]$ قرار دارد به روش نیوتن با چهار رقم اعشار به دست آورید به طوری که $|x_n - x_{n-1}| < 10^{-4}$ که x_n تقریب ریشه مورد نظر در تکرار n ام است. قرار دهید $5,0^\circ$.

Newton-Raphson Method

Assumptions Example Advantages & Disadvantages

$$f'(x) = 1 + \sin x \text{ و } f(x) = x - \cos x \text{ داریم: حل:}$$

$$x_{n+1} = x_n - \frac{x_n - \cos x_n}{1 + \sin x_n}$$

با قرار دادن $x_0 = 0$ داریم:

$$x_1 = 0,78522$$

$$x_2 = 0,73914$$

$$x_3 = 0,73909$$

چون $10^{-5} < 10^{-4}$ لذا تقریب ریشه مورد نظر است و با D این

تقریب عبارتست از:

$$\alpha \approx 0,7391$$

Newton-Raphson Method

Assumptions Example Advantages & Disadvantages

Calculating $\sqrt{5}$ using Newton-Raphson method.

(Newton-Raphson is a good method for calculating $\sqrt[k]{a}$.)

$$x = \sqrt{5} \rightarrow x^2 = 5$$

$$f(x) = x^2 - 5 = 0 \rightarrow f'(x) = 2x$$

$$x_{i+1} = x_i - \frac{x_i^2 - 5}{2x_i}$$

$$\rightarrow x_{i+1} = \frac{x_i^2 + 5}{2x_i}$$

$$\rightarrow x_{i+1} = \frac{1}{2} \left(x_i + \frac{5}{x_i} \right)$$

i	x_i
0	2
1	2.25
2	2.236111111
3	2.236067978
4	2.236067978

Newton-Raphson Method

Assumptions Example Advantages & Disadvantages

Calculating $\sqrt{5}$ using Newton-Raphson method.

(Newton-Raphson is a good method for calculating $\sqrt[k]{a}$.)

$$x = \sqrt{5} \rightarrow x^2 = 5$$

$$f(x)$$

$$x_{i+1} :$$

$$x_{i+1} = \frac{1}{k} [(k - 1)x_i + ax_i^{1-k}]$$

$$\rightarrow x_{i+1} = \frac{x_i^2 + 5}{2x_i}$$

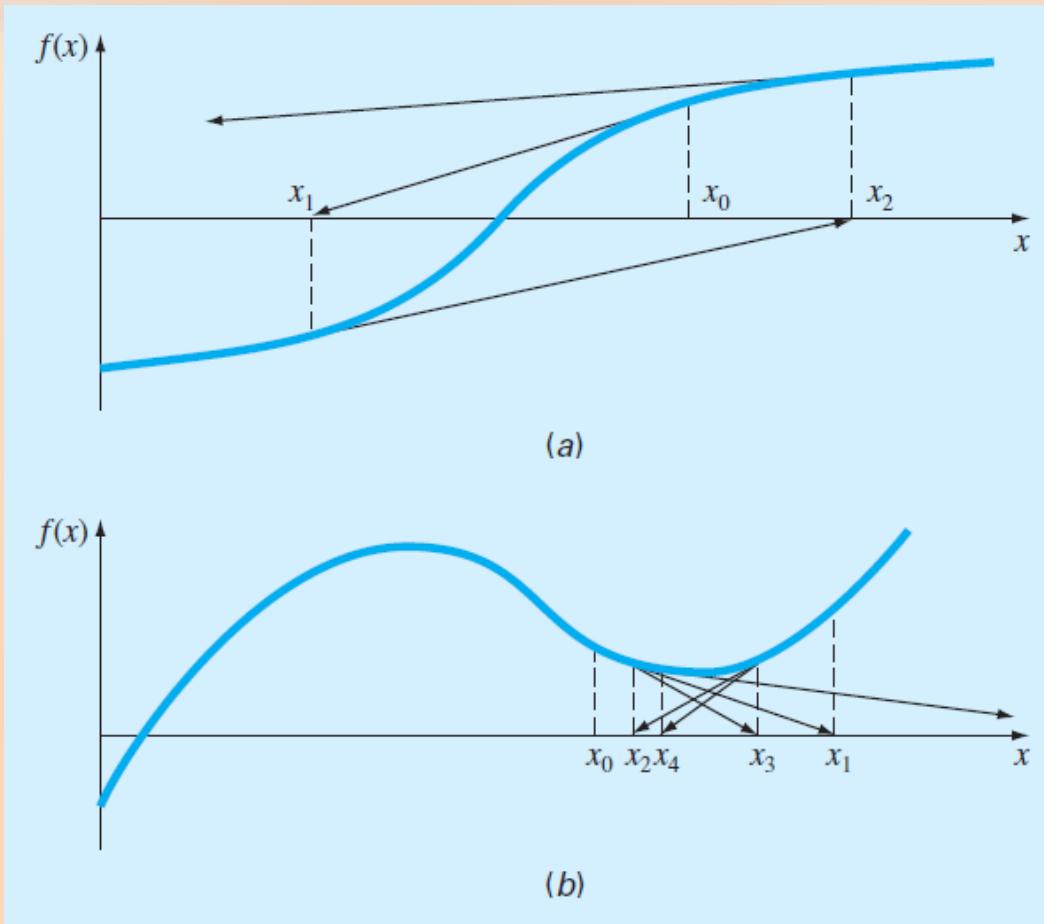
$$\rightarrow x_{i+1} = \frac{1}{2} \left(x_i + \frac{5}{x_i} \right)$$

2	2.236111111
3	2.236067978
4	2.236067978

Newton-Raphson Method

Selecting initial approximation (x_0) is very important so it is better to approximate x_0 by plotting $f(x)$.

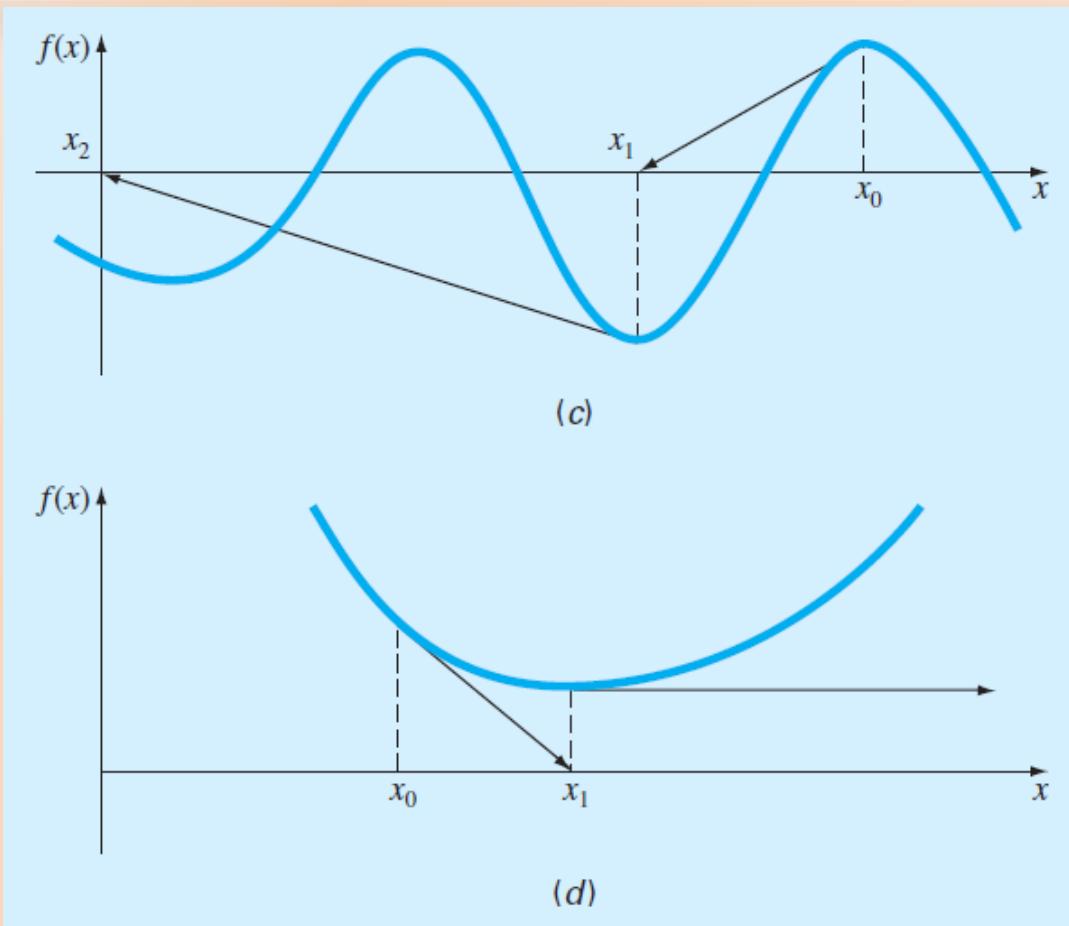
Newton-Raphson Method



56

The cases where the Newton-Raphson method exhibits poor convergence

Newton-Raphson Method



The cases where the Newton-Raphson method exhibits poor convergence

Newton-Raphson Method

Assumptions Example Advantages & Disadvantages

Advantages :

- It converges very fast.

Disadvantages :

- No guarantee to converge to answer.
- Calculating derivation may be hard.
- All calculations and convergence of this method strictly depend on the function $f(x)$ and initial value of x_0 .

Methods

Extra Topics

Bisection Method

False Position Method

Secant Method

Newton–Raphson Method

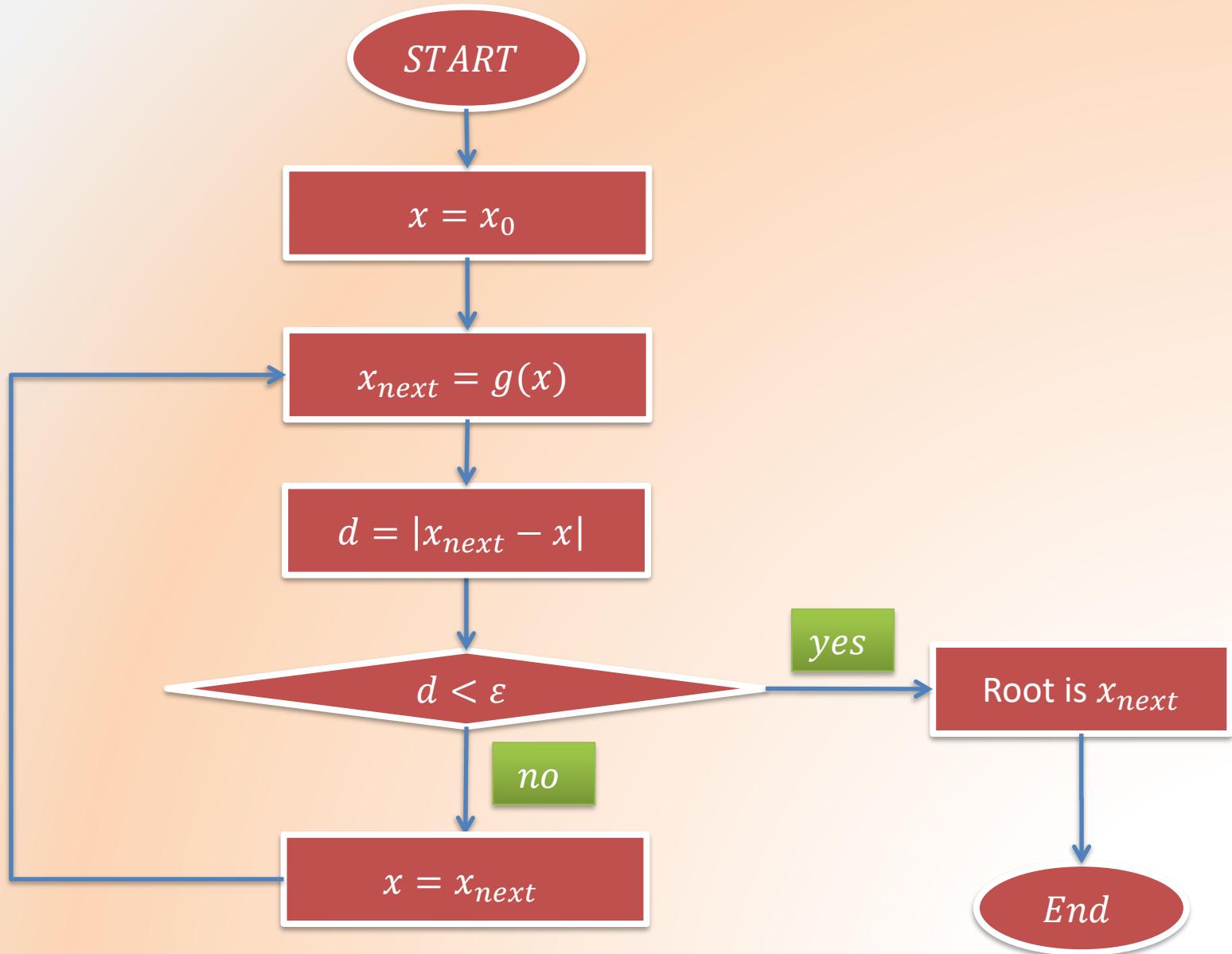
Simple Iterative or Fixed Point Method

Fixed Point Method

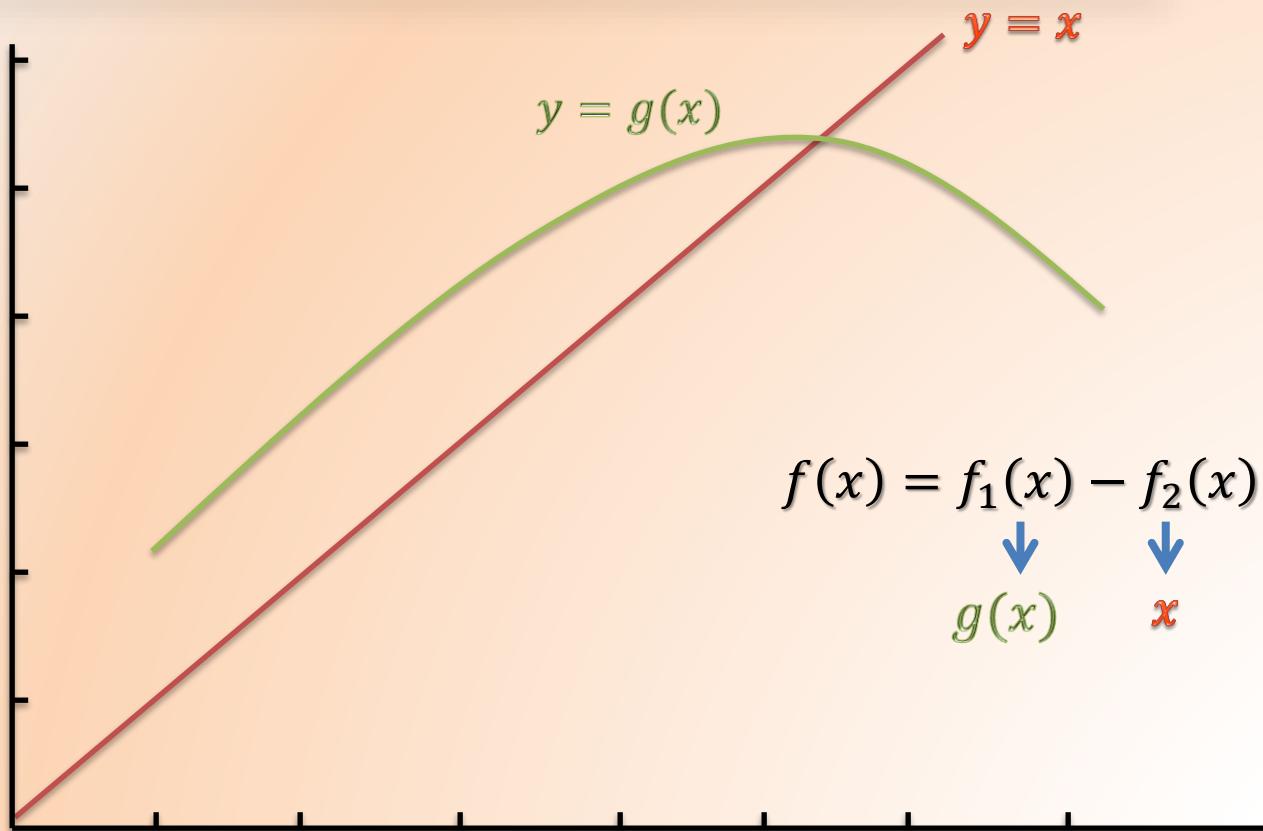
Assumptions Example Advantages & Disadvantages

- $f(x) = 0 \Rightarrow x - g(x) = 0$
 $x = g(x)$
- Initial approximation: x_0

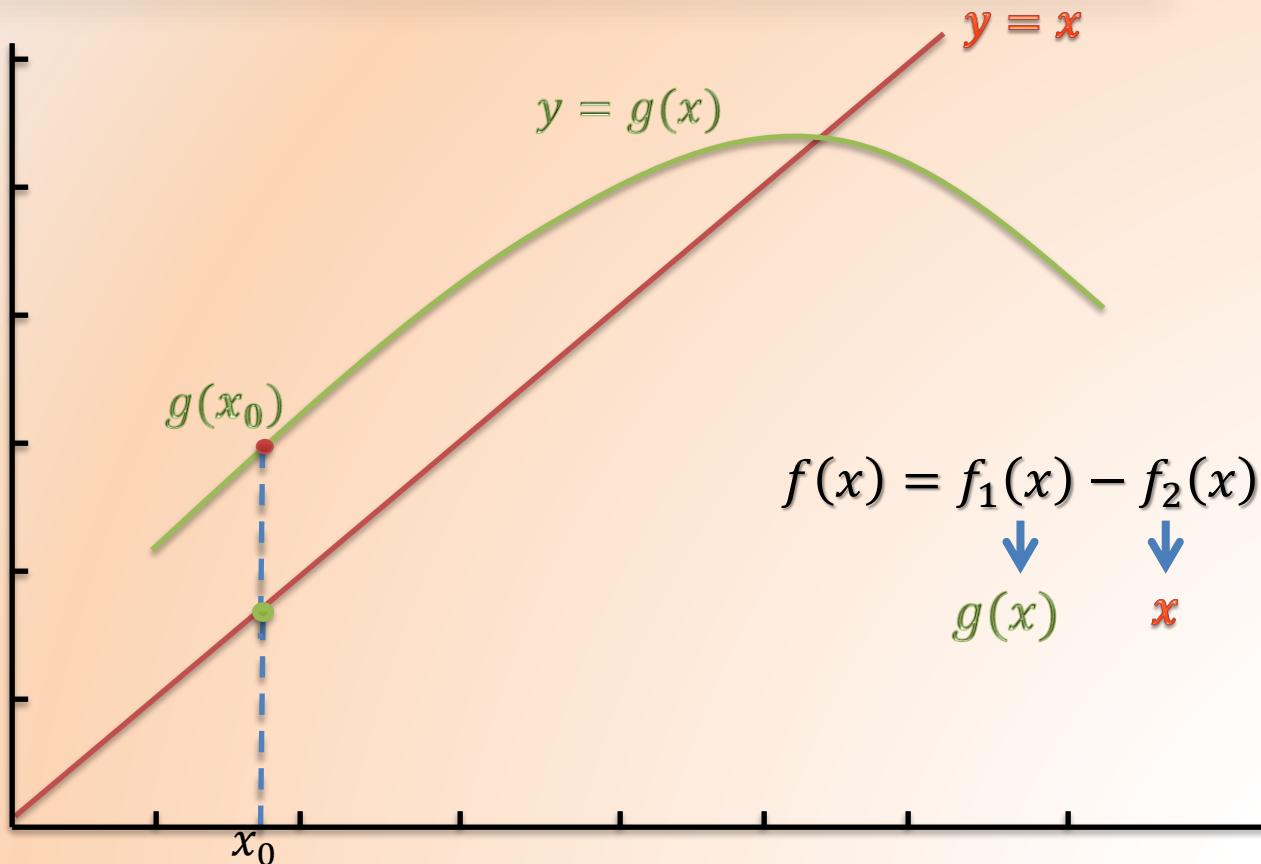
$$x_{i+1} = g(x_i)$$



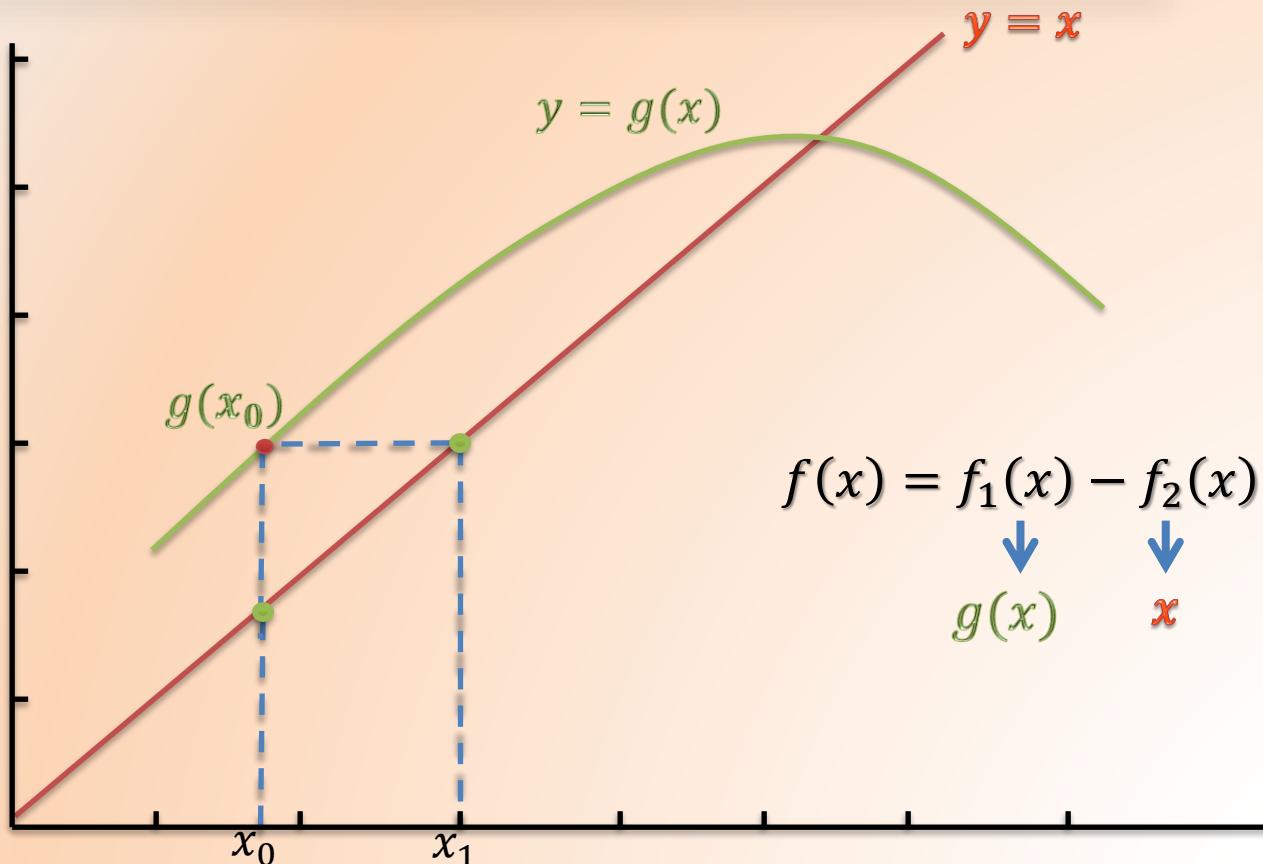
Fixed Point Method



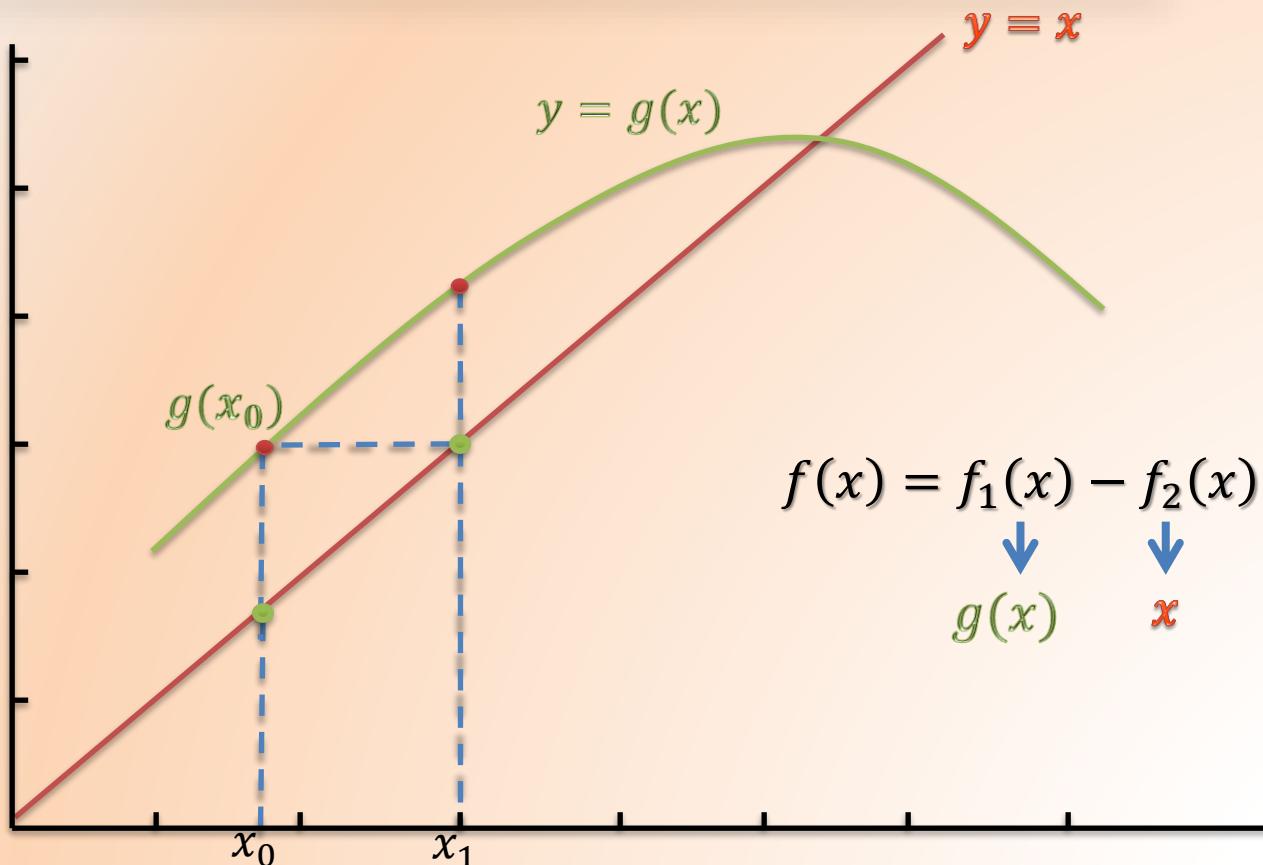
Fixed Point Method



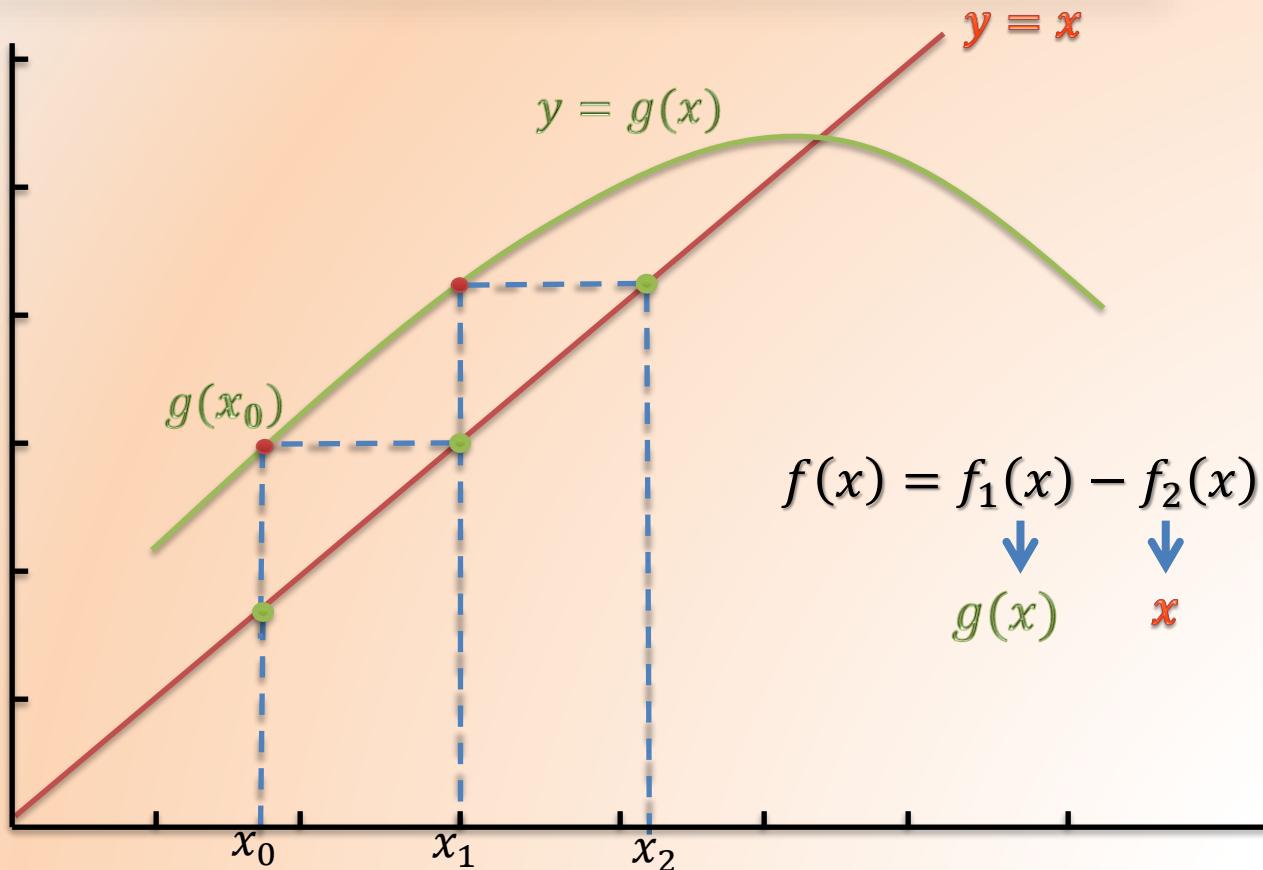
Fixed Point Method



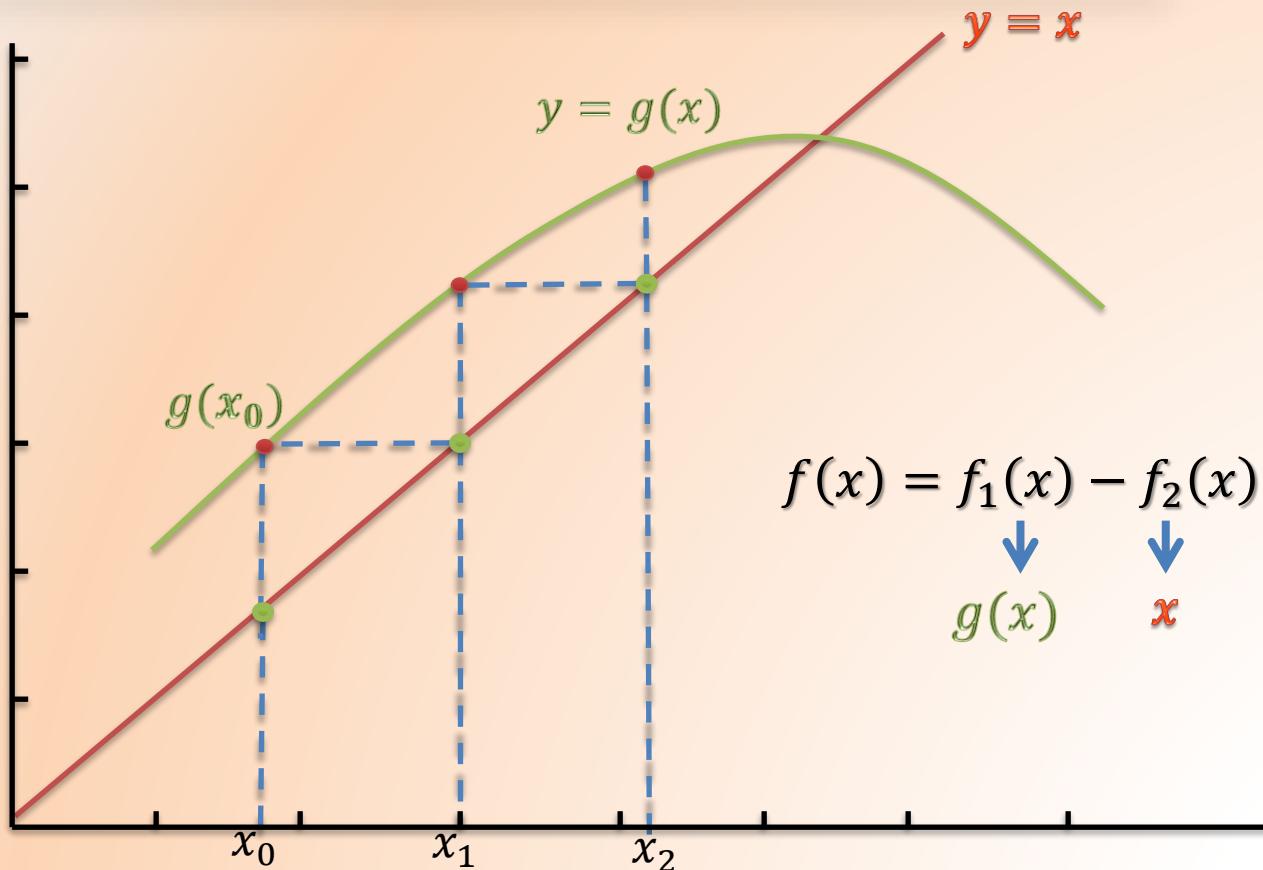
Fixed Point Method



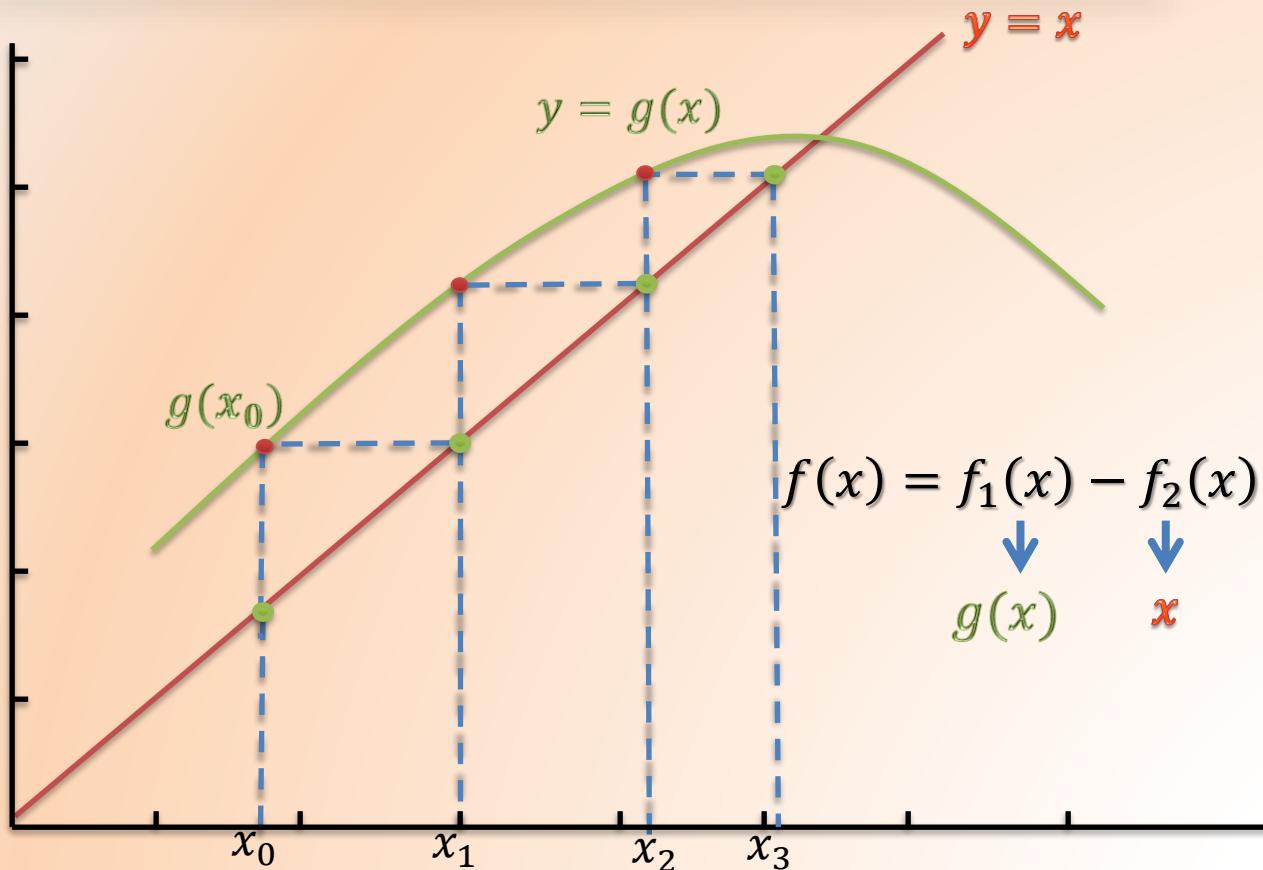
Fixed Point Method



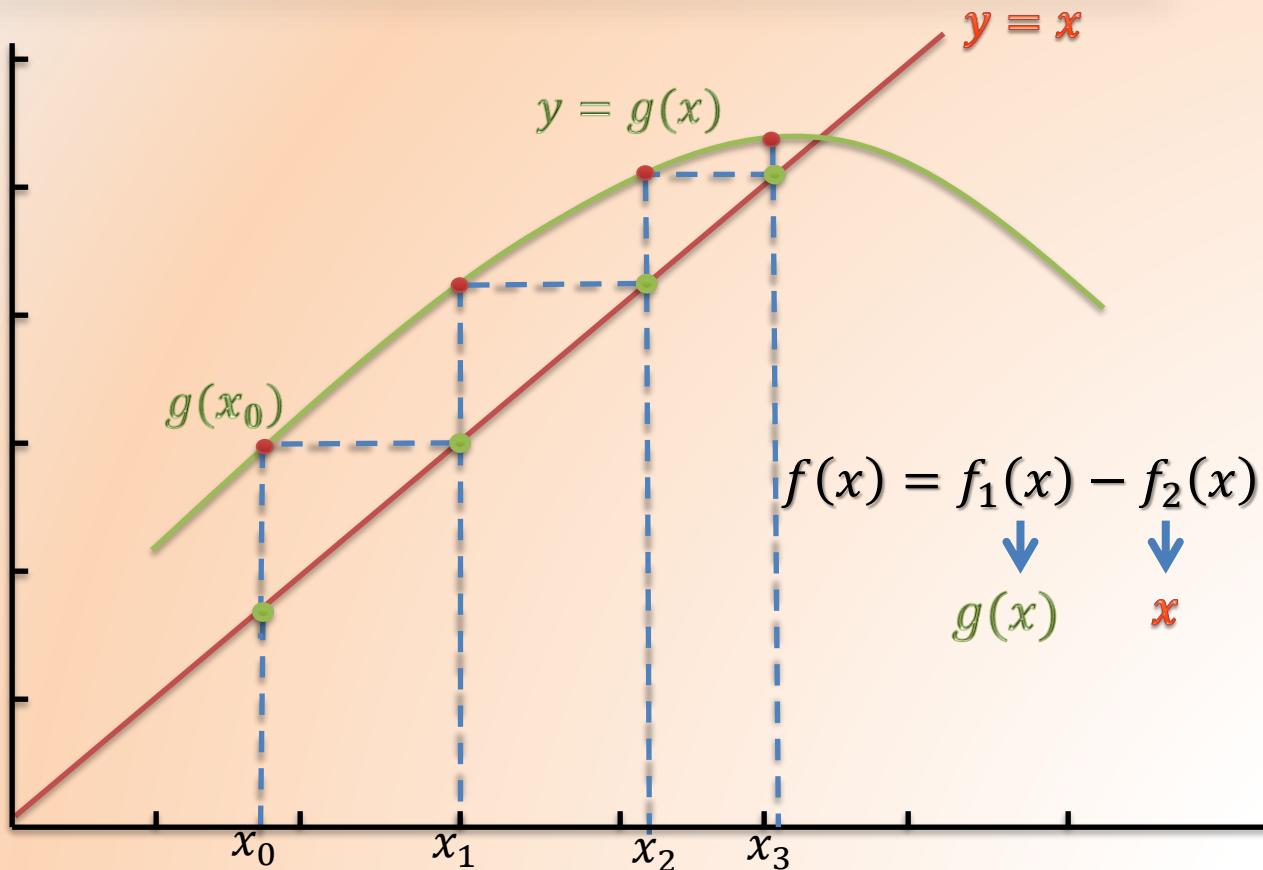
Fixed Point Method



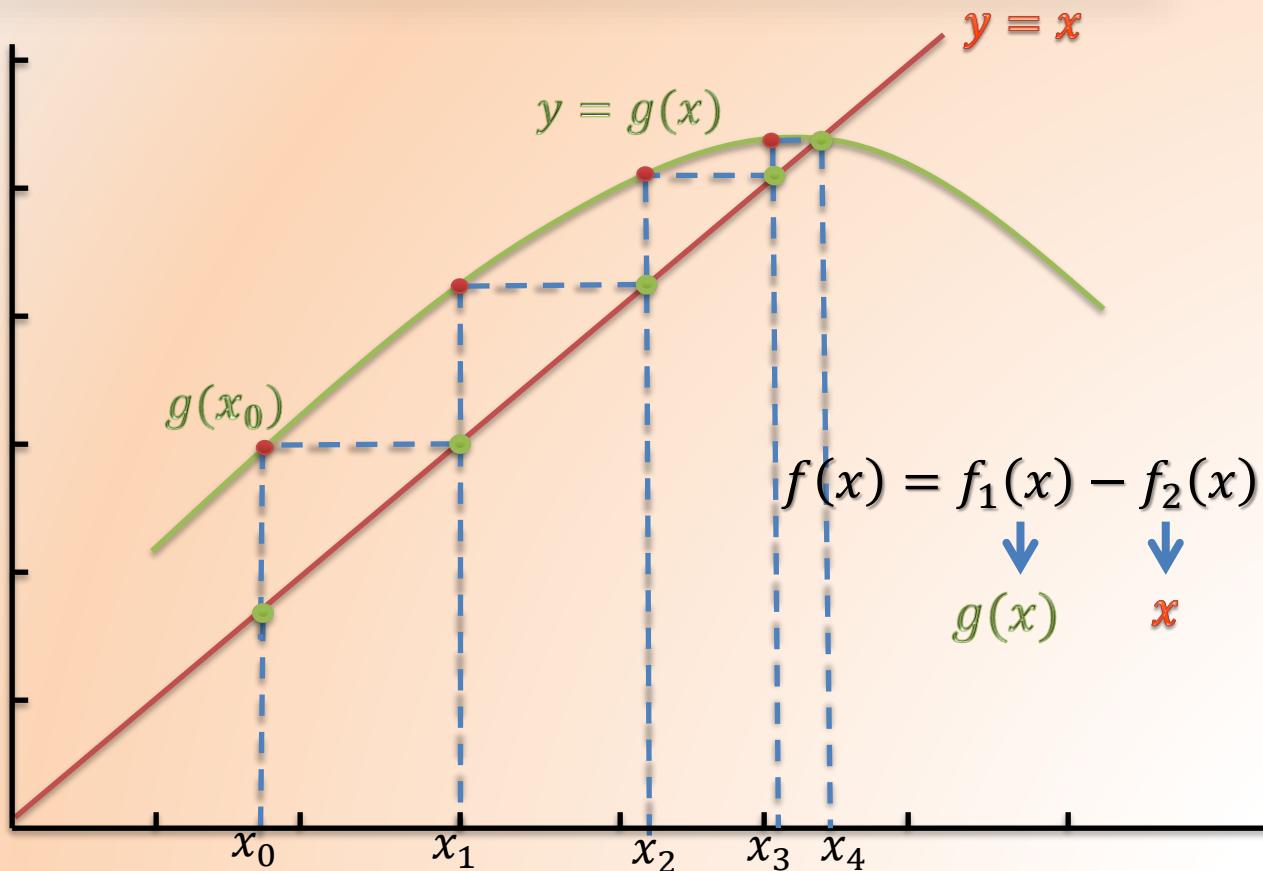
Fixed Point Method



Fixed Point Method



Fixed Point Method



Fixed Point Method

Assumptions Example Advantages & Disadvantages

مثال: تقریب از ریشه نسبت معادله $x^2 + x - 1 = 0$ با استفاده از روش شرمند است.

طبق روش شرمند $x_0 = 1.0$ دارای $g(x) = 1 - x^2$ می‌باشد.

$$x_{n+1} = g(x_n) = 1 - x_n^2$$

$$x_1 = g(x_0) = 0.707 \dots , x_2 = g(x_1) = 0.6457 \dots , x_3 = g(x_2) = 0.618 \dots$$

$$x_4 = 0.6174 \dots , x_5 = 0.6174 \dots$$

نمایه شده کشیده و حاصل از این سه تا زرد به ۱ و زینه حاصل از این دو کمی از پیش بصر عوایست. بنابراین دلیل مانع

{ x_n } صفر است.

$$g(x) = \sqrt{1-x}$$

سپس $g'(x)$ و دوسری تحریفی رسم:

$$x_{n+1} = g(x_n) = \sqrt{1-x_n}$$

در این طبقه دو روش داریم: ۱) می‌توانیم $\{x_n\} = x_0 = 0.6174 \dots$ باشد. ۲) می‌توانیم $\{x_n\} = x_0 = 1$ باشد. بعد از ۳۴ مرحله به صورت مکرر خواهد شد.

Fixed Point Method

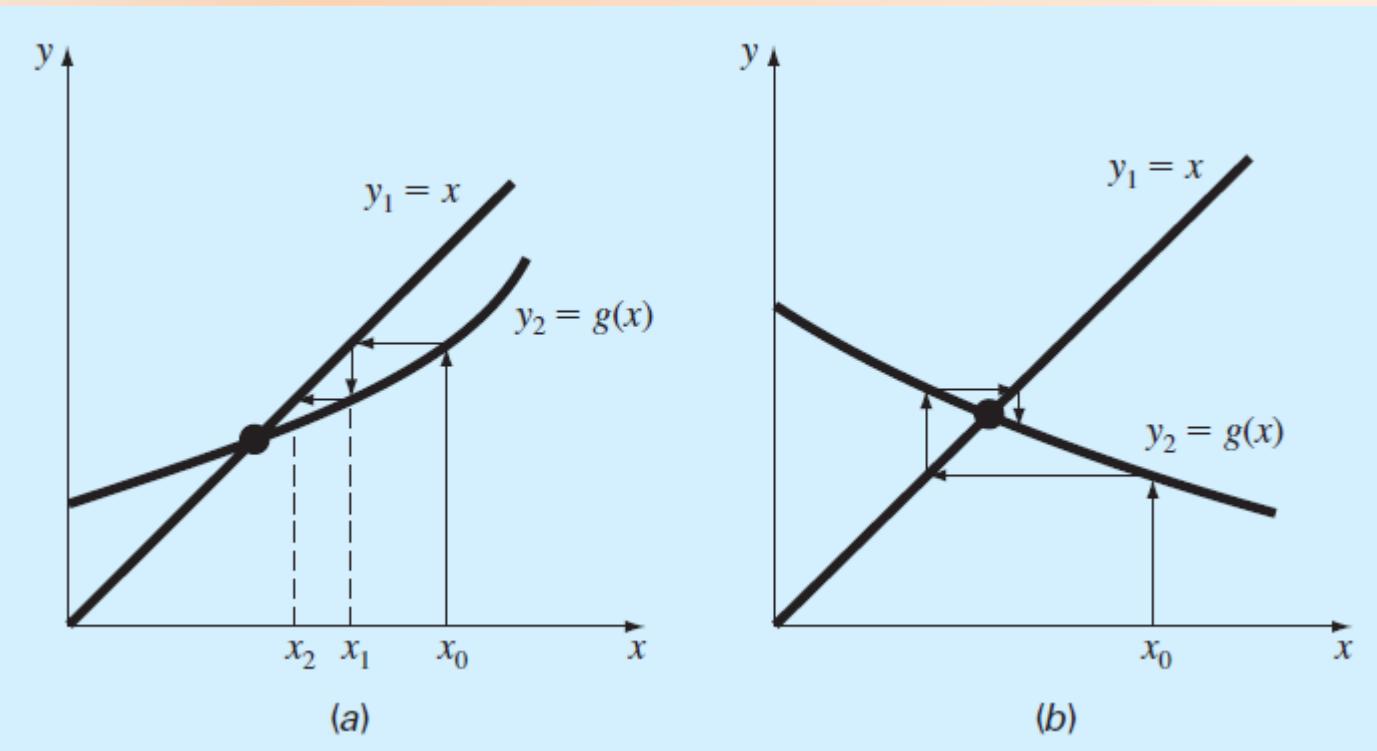
$g(x)$ must be selected such that it can be used for the next step.

Convergence conditions :

- $x_0 \in (a, b)$
- $g'(x)$ must be continuous in (a, b)
- $\forall x \in (a, b) : |g'(x)| < 1$
- $\forall x \in (a, b) : g(x) \in (a, b)$

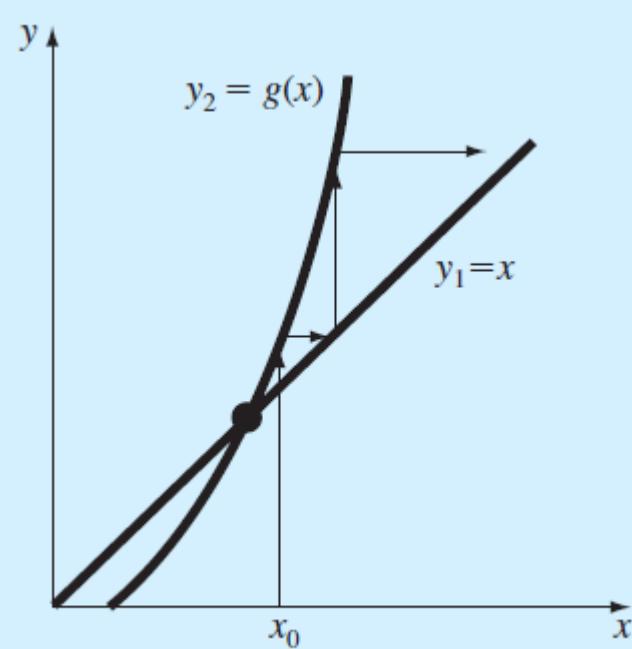
Fixed Point Method

Assumptions Example Advantages & Disadvantages

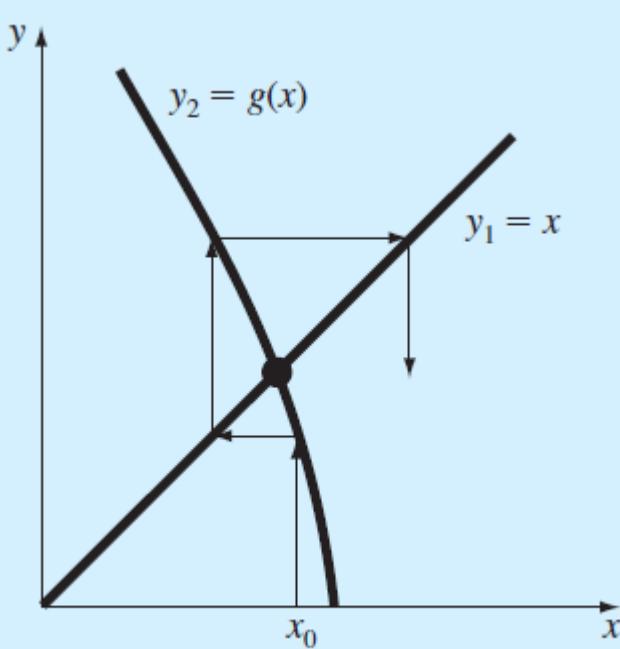


Fixed Point Method

Assumptions Example Advantages & Disadvantages



(c)



(d)

Fixed Point Method

$$|x_n - x_{n-1}| < t^{-k} \quad \text{مشط توقیت: } rx - \ln x - f = 0 \quad \text{حل معادله: } f(x) = 0$$

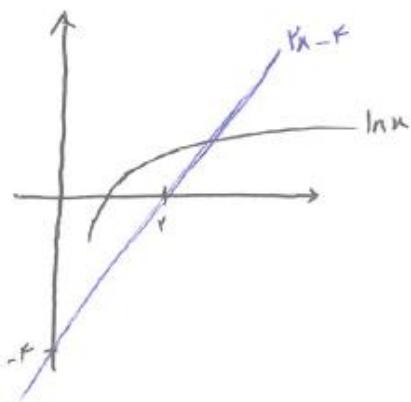
$$f(x) = rx - \ln x - f$$

استدلالی نیم طبقه ای درست در این روش طبقه بندی است.

$$\begin{cases} f(1) = -\ln r < 0 \\ f(r) = r - \ln r > 0 \end{cases}$$

$f(x)$ در بازه $(1, r)$ صفر ندارد.
پس مقدار r در بازه $(1, r)$ قرار دارد.

همچنین نظریه محدود است: $y = \ln x$, $g = rx - f$
با توجه به $y = \ln x$ در بازه $(1, r)$ صفر ندارد.



پس بازه $(1, r)$ را نظریه محدود است: $y = \ln x$ و $g(x) = rx - f$

$$x = r + \frac{1}{r} \ln x = g(x)$$

Fixed Point Method

$$r < r \Rightarrow \ln r < \ln x < \ln r \Rightarrow$$

جایگزینی کنید

$$r + \frac{1}{r} \ln r < r + \frac{1}{r} \ln x < r + \frac{1}{r} \ln r \Rightarrow r < r + \frac{1}{r} \ln x < r \Rightarrow r(g(x)) < r$$

شرط ۱ برآورده است ✓

$$g'(x) = \frac{1}{rx} \Rightarrow - < g'(x) < \frac{1}{r} \quad \forall x \in (r, R) \quad \text{شرط ۲ برآورده است ✓}$$

$$x_0 = r$$

شرط ۳ برآورده است ⇐

$$x_{n+1} = g(x_n) = r + \frac{1}{r} \ln x_n \quad n = 0, 1, \dots$$

$$x_1 = r, \text{ فرضیه}$$

$$x_2 = r, \text{ فرضیه}$$

$$x_3 = r, \text{ فرضیه}$$

$$x_4 = r, \text{ فرضیه}$$

$$x_5 = r, \text{ فرضیه}$$

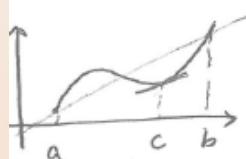
$$x_6 = r, \text{ فرضیه} \Rightarrow x \approx r$$

Fixed Point Method

داله متعديه در دامنه ثابت است:

نحوه تعاریف میشوند: کارخانه $[a, b]$ از دو دارجه $f(a)$ و $f(b)$ دارد و دو دارجه $c \in [a, b]$ نیز داشته باشد که $f(c) = c$ باشد.

$$\frac{f(b) - f(a)}{b - a} = f'(c)$$



آنچه متعديه است، در اینجا دو دارجه ثابت داريم:

$$|e_{k+1}| = |\alpha - x_{k+1}| = |g(\alpha) - g(x_k)| = |g'(c)| |\alpha - x_k| \Rightarrow$$

$\underbrace{|g'(c)|}_{\text{نحوه تعاریف}} \underbrace{|\alpha - x_k|}_{e_k}$

$$|e_{k+1}| = \underbrace{|g'(c)|}_{|c| < 1} |e_k| \Rightarrow \text{داله متعديه است } m=1$$

داله متعدي در اين زمينه خوب است، $|g'(c)| < 1$ است، بنابرادر آنها است.

حال طوره اين مسند است در شرط متعدي دين مانند در شرط هاست.

Fixed Point Method

Assumptions Example Advantages & Disadvantages

Advantages :

- Can divide $f(x)$

Disadvantages :

- No guarantee to converge to answer.
- Convergence conditions for this method are hard to be checked.
- The degree of convergence for this method is linear and equal to 1 .
- All calculations and convergence of this method strictly depend on the function $g(x)$ and initial value of x_0 .

Fixed Point Method

(درین چای خواهیم سطح قبول روش نیوتن- رافسون را حالت خاص از روش نتیجه نایاب است را در بین نظر داشتیم. درین روش نظر داشتیم که مقدار x_n را می‌خواهیم تا $f(x_n) = 0$ باشد.

قضیه: نرخ نسبی دنباله $\{x_n\}$ به صالحة $x_{n+1} = g(x_n)$ باشد و طبق مسئله دهم پیشنهاد شده

- اگر $g'(a) \neq 0$ \leftarrow رتبه چهارمی روشن نتیجه نایاب برابر باشد.
- اگر $g'(a) = 0$ \leftarrow رتبه چهارمی روشن نتیجه نایاب صاحل ۲ است.
- اگر $g'(a) = 0$ و $g''(a) \neq 0$ \leftarrow رتبه چهارمی روشن نتیجه نایاب (فعلاً) است.

* به طور معمولی تأثیر ندارد: اگر دنباله $\{x_n\}$ به صالحة $x_{n+1} = g(x_n)$ باشد و مسئله دهم پیشنهاد شده

$$g'(a) = g''(a) = \dots = g^{(k-1)}(a) = 0 \Rightarrow g^{(k)}(a) \neq 0.$$

نکته: $\{x_n\}$ برای k اول است.

Newton-Raphson Method

$$f(x) = 0, \quad x = x - \frac{f(x)}{f'(x)}$$

$$g(x) = x - \frac{f(x)}{f'(x)}$$

$$g(\alpha) = \alpha - \frac{f(\alpha)}{f'(\alpha)} \Rightarrow g(\alpha) = \alpha$$

$$g'(x) = 1 - \frac{f'(x) f''(x) - f''(x) f(x)}{(f'(x))^2} = 1 - 1 + \frac{f(x) f''(x)}{(f'(x))^2} = \frac{f(x) f''(x)}{f'^2(x)}$$

* درین نتیجه روش نیوتن رافسون سطح خالی این مکان را
برای محاسبه می کند.

Newton-Raphson Method

$$g'(a) = \frac{f(a) - f''(a)}{f'(a)} = 0$$

مسنونه زدنی خاروس نیز میگویند $g'(a) = 0$ است \rightarrow مسنونه زدنی هرگز حلشی یافته داشته باشد $f''(a) \neq 0$ و توجه کنید که زیرا هرگز دفعیانه یافته شود.

$$g''(a) = \frac{f''(a)}{f'(a)} \neq 0$$

مکالمه سایر اثباتات

Methods

Extra Topics

Horner Method for Evaluating Polynomials

Generalized Newton–Raphson Method

Newton-Raphson Method

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

$$x_{k+1} = x_k - \frac{P_n(x_k)}{P'_n(x_n)}$$

Horner Method for Evaluating Polynomials

کوئی دوسرے بند، جوں صعبہ خوب نہیں ہے، میں اسے
میں عوام میں،

$$\textcircled{1} \quad P(x) = a_r x^r + a_{r-1} x^{r-1} + \dots + a_1 x + a_0 \Rightarrow a_r \cdot x \cdot x \cdot x + a_{r-1} \cdot x \cdot x + \dots + a_1 \cdot x + a_0. \quad \left. \begin{array}{l} \text{آخر} \\ \text{مع} \end{array} \right\}$$

وی کوئی دوسرے میں ایسے نہیں، نہ کوئی صعبہ خوب نہیں.

$$\textcircled{2} \quad P(x) = ((a_r x + a_{r-1}) x + a_1) x + a_0 \Rightarrow ((a_r \cdot x + a_{r-1}) \cdot x + a_1) \cdot x + a_0. \quad \left. \begin{array}{l} \text{آخر} \\ \text{مع} \end{array} \right\}$$

لیکن $1 + r + \dots + n = \frac{n(n+1)}{r} \cdot P_n(x)$ سے، \textcircled{1} میں کوئی صعبہ خوب نہیں،
لیکن $n \cdot P_n(x)$ سے، \textcircled{2} میں کوئی صعبہ خوب نہیں.

Horner Method for Evaluating Polynomials

i. $p_n(x) = a_0 + a_1x + a_2x^2 + a_3x^3 + \dots + a_nx^n = \sum_{i=0}^n a_i x^i$

ii. $p_n(x_0) = ?$

$$b_n = a_n$$

$$b_{n-1} = a_{n-1} + b_n x_0$$

$$b_{n-2} = a_{n-2} + b_{n-1} x_0$$

...

$$b_0 = a_0 + b_1 x_0$$

Horner Alg :

input a_k $K = 0, 1, \dots, n$

input x_0

$$b_n = a_n$$

for $K = n - 1$ to 0

$$b_K = b_{K+1} x_0 + a_K$$

$$\underline{p(x_0) = b_0}$$

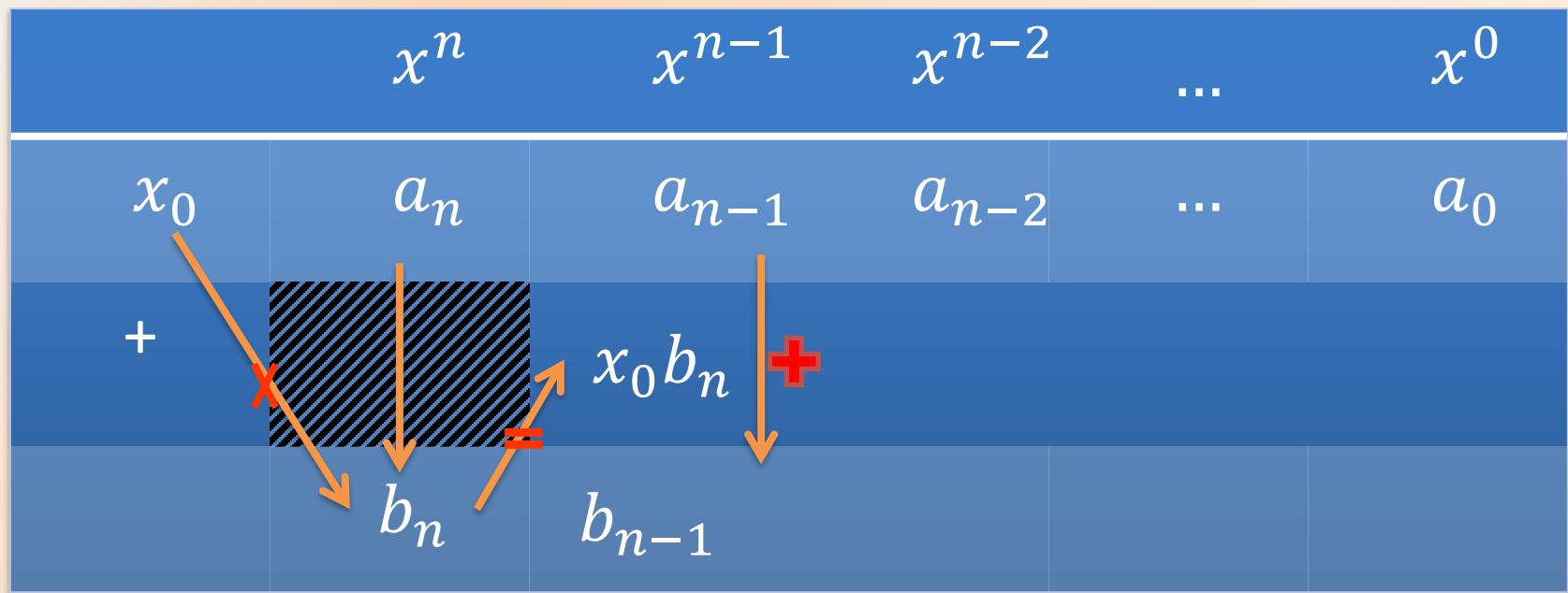
Horner Method for Evaluating Polynomials

x^n	x^{n-1}	x^{n-2}	...	x^0	
x_0	a_n	a_{n-1}	a_{n-2}	\dots	a_0
+					

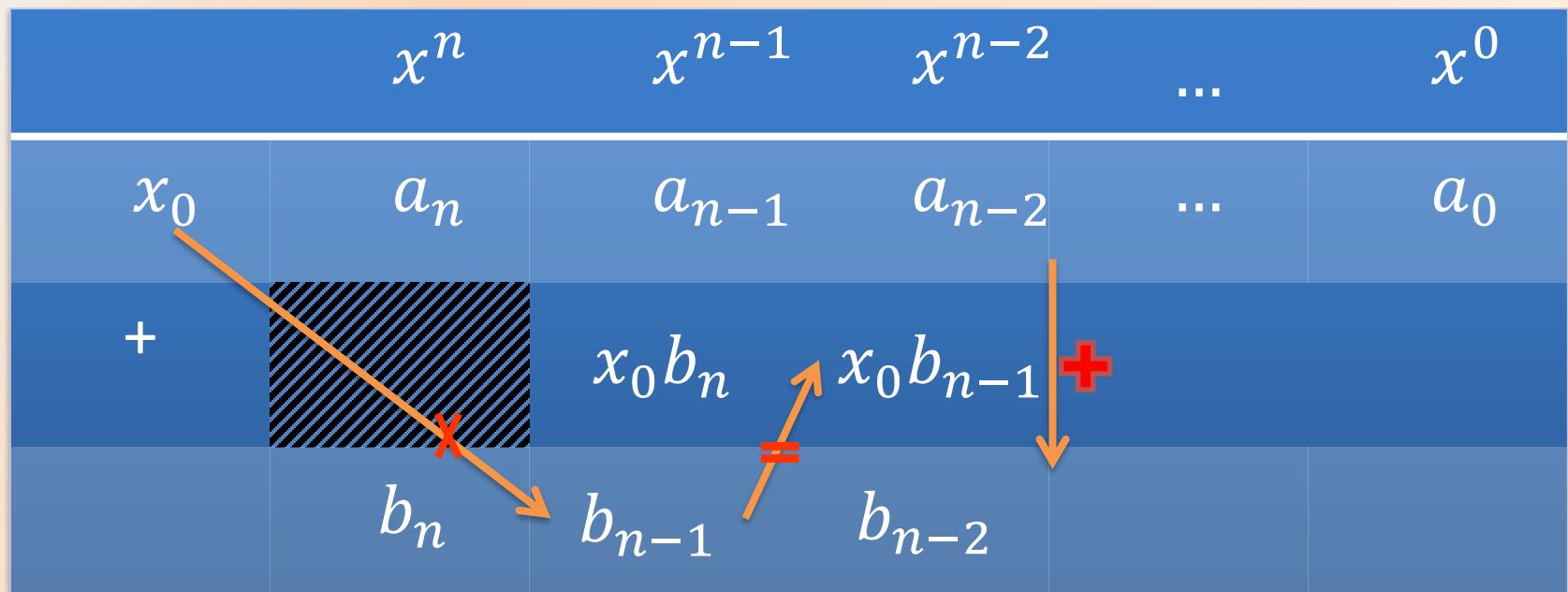
Horner Method for Evaluating Polynomials

x^n	x^{n-1}	x^{n-2}	...	x^0
x_0	a_n	a_{n-1}	a_{n-2}	a_0
+				
	b_n			

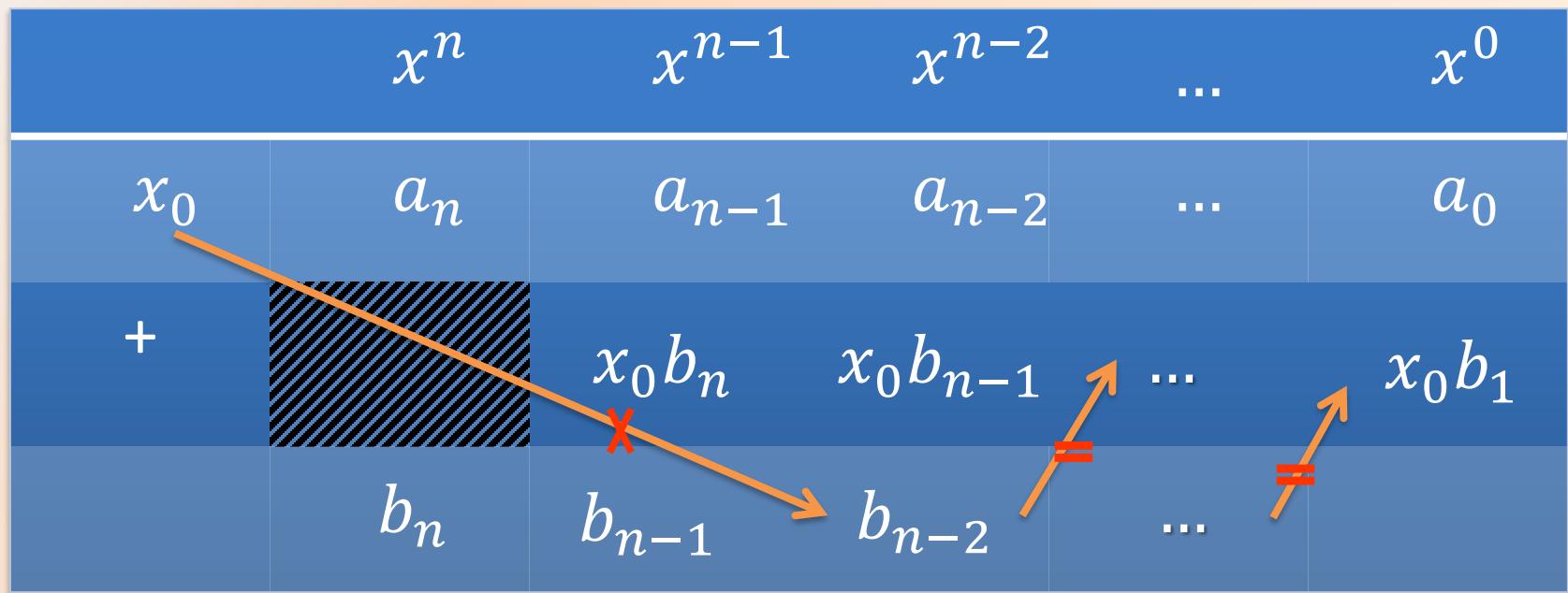
Horner Method for Evaluating Polynomials



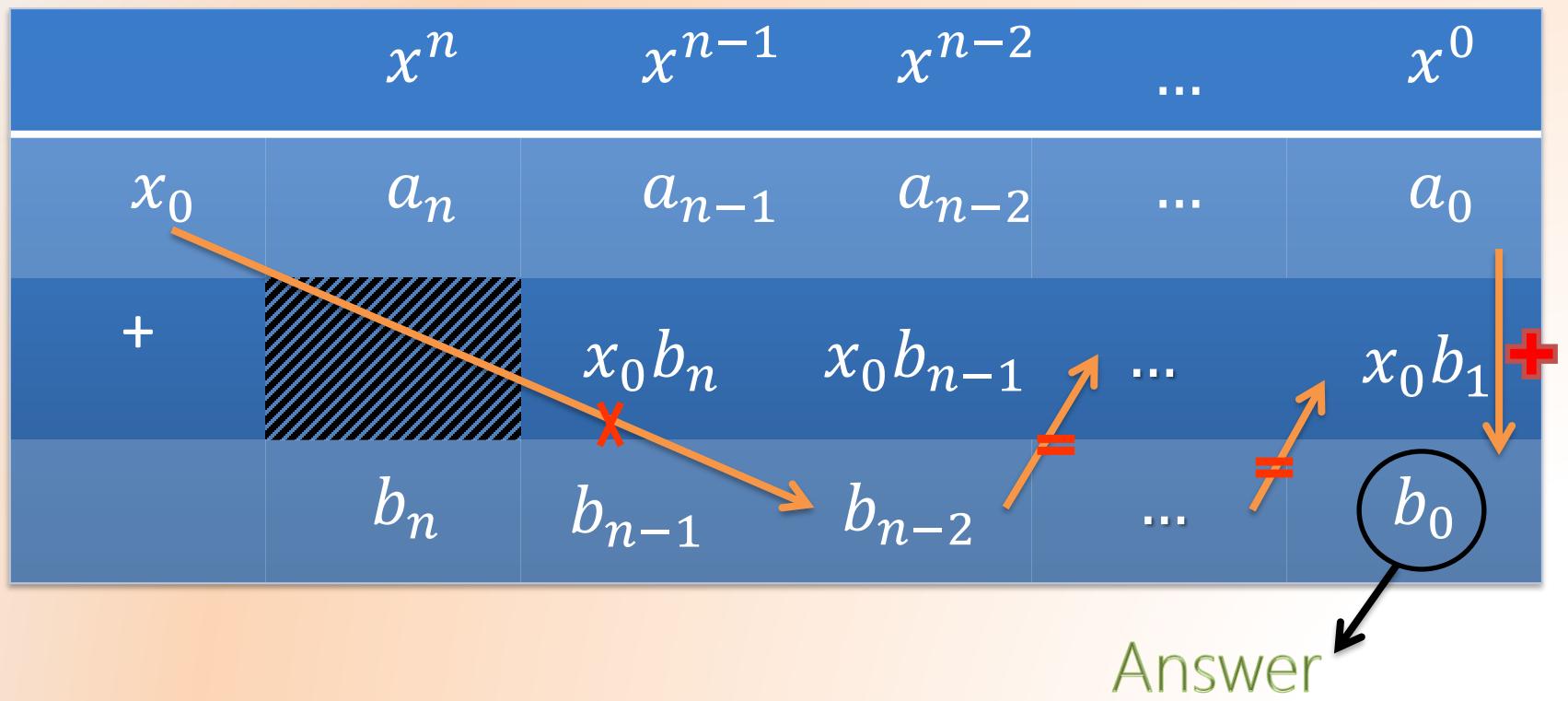
Horner Method for Evaluating Polynomials



Horner Method for Evaluating Polynomials



Horner Method for Evaluating Polynomials



Horner Method for Evaluating Polynomials

Example:

$$f(x) = 2x^3 - 6x^2 + 2x - 1 \quad f(3) = ?$$

$$b_3 = a_3 = 2$$

$$b_2 = a_2 + b_3 x_0 = -6 + 2 \times 3 = 0$$

$$b_1 = a_1 + b_2 x_0 = 2 + 0 = 2$$

$$b_0 = a_0 + b_1 x_0 = -1 + 2 \times 3 = 5$$

$$\rightarrow f(3) = 5$$

Horner Method for Evaluating Polynomials

$$b_3 = a_3 = 2$$

$$b_2 = a_2 + b_3 x_0 = -6 + 2 \times 3 = 0 \quad f(3) = 5$$

$$b_1 = a_1 + b_2 x_0 = 2 + 0 = 2, \quad \Rightarrow \quad b_0 = a_0 + b_1 x_0 = -1 + 2 \times 3 = 5$$

	x^3	x^2	x^1	x^0
x_0	2	-6	2	-1
+				

Horner Method for Evaluating Polynomials

$$b_3 = a_3 = 2$$

$$b_2 = a_2 + b_3 x_0 = -6 + 2 \times 3 = 0 \quad f(3) = 5$$

$$b_1 = a_1 + b_2 x_0 = 2 + 0 = 2, \quad \Rightarrow \quad b_0 = a_0 + b_1 x_0 = -1 + 2 \times 3 = 5$$

	x^3	x^2	x^1	x^0
x_0	2	-6	2	-1
+				
	2	$2 \times 3 = 6$		

The diagram illustrates the Horner method for evaluating the polynomial $f(x) = 2x^3 - 6x^2 + 2x - 1$ at $x_0 = 3$. The coefficients are arranged in a row: 2, -6, 2, -1. An arrow points from the first coefficient (2) to the second column, labeled x^3 . Another arrow points from the second coefficient (-6) to the third column, labeled x^2 . A third arrow points from the third coefficient (2) to the fourth column, labeled x^1 , with the label $2 \times 3 = 6$ written below it. The final result, 2, is shown in the fifth column, labeled x^0 .

Horner Method for Evaluating Polynomials

$$b_3 = a_3 = 2$$

$$b_2 = a_2 + b_3 x_0 = -6 + 2 \times 3 = 0 \quad f(3) = 5$$

$$b_1 = a_1 + b_2 x_0 = 2 + 0 = 2, \quad \Rightarrow \quad b_0 = a_0 + b_1 x_0 = -1 + 2 \times 3 = 5$$

	x^3	x^2	x^1	x^0
x_0	2	-6	2	-1
+				
	2	$2 \times 3 = 6$	$6 - 6 = 0$	

Horner Method for Evaluating Polynomials

$$b_3 = a_3 = 2$$

$$b_2 = a_2 + b_3 x_0 = -6 + 2 \times 3 = 0 \quad f(3) = 5$$

$$b_1 = a_1 + b_2 x_0 = 2 + 0 = 2, \quad \Rightarrow \quad b_0 = a_0 + b_1 x_0 = -1 + 2 \times 3 = 5$$

	x^3	x^2	x^1	x^0
x_0	2	-6	2	-1
+		$2 \times 3 = 6$	$3 \times 0 = 0$	
	2	$6 - 6 = 0$		

Horner Method for Evaluating Polynomials

$$b_3 = a_3 = 2$$

$$b_2 = a_2 + b_3 x_0 = -6 + 2 \times 3 = 0 \quad f(3) = 5$$

$$b_1 = a_1 + b_2 x_0 = 2 + 0 = 2, \quad \Rightarrow \quad b_0 = a_0 + b_1 x_0 = -1 + 2 \times 3 = 5$$

	x^3	x^2	x^1	x^0
x_0	2	-6	2	-1
+		$2 \times 3 = 6$	$3 \times 0 = 0$	
	2	$6 - 6 = 0$	2	

Horner Method for Evaluating Polynomials

$$b_3 = a_3 = 2$$

$$b_2 = a_2 + b_3 x_0 = -6 + 2 \times 3 = 0 \quad f(3) = 5$$

$$b_1 = a_1 + b_2 x_0 = 2 + 0 = 2, \quad \Rightarrow \quad b_0 = a_0 + b_1 x_0 = -1 + 2 \times 3 = 5$$

	x^3	x^2	x^1	x^0
x_0	2	-6	2	-1
+	$2 \times 3 = 6$	$3 \times 0 = 0$	$2 \times 3 = 6$	5

Answer

Horner Method for Evaluating Polynomials

(1) بحث الورقة (K=0, ..., n) b_k خصوصية تعرف شرط صفر $p(x)$ في x_0

$$Q(x) = b_n x^{n-1} + b_{n-1} x^{n-2} + \dots + b_1 x + b_0 \quad \text{تعريف شرط صفر}$$

$$p(x) = (x - x_0) Q(x) + b_0 \quad \text{لذلك}$$

$$\left\{ \begin{array}{l} p(x) = (x - x_0) Q(x) + b_0 \\ Q(x) = b_n x^{n-1} + b_{n-1} x^{n-2} + \dots + b_1 x + b_0 \end{array} \right.$$

لذلك

الآن $p(x)$

يمكننا كتابة $Q(x)$ كـ $Q(x) = b_n x^{n-1} + b_{n-1} x^{n-2} + \dots + b_1 x + b_0$ و $p(x) = (x - x_0) Q(x) + b_0$

Horner Method for Evaluating Polynomials

Example: $P(x) = 2x^4 - 3x^2 + 3x - 4 \quad P(-2) = ? \quad P'(-2) = ?$

x	x^4	x^3	x^2	x^1	x^0
$\rightarrow (-2)$	r	0	$-r$	r	$-r$
$+$	$=$	$(-r) \times r = -r$	$(-r)(-r) = r$	$(-r) \times 0 = 0$	$(-r) \times (-r) = r$
r	$-r$	0	r	0	r

$\leftarrow P(x) \rightarrow \text{متر} : b_0 a_1$

$+$	$=$	$-r + 0 = -r$	$r + 0 = r$	$0 + r = r$	$r - r = 0$
r	$-r$	0	r	0	r
$+$	$=$	$(-r) \times r = -r^2$	$(-r)(-r) = r^2$	$(-r) \times 0 = 0$	$(-r) \times (-r) = r^2$

$\leftarrow Q(x) \rightarrow \text{متر} : b_0 b_1$

$+$	$=$	$-r^2 + 0 = -r^2$	$r^2 + 0 = r^2$	$0 + 0 = 0$	$r^2 - r^2 = 0$
r	$-r^2$	0	r^2	0	0
$+$	$=$	$(-r^2) + (-r^2) = -2r^2$	$0 + 0 = 0$	$0 + 0 = 0$	$0 - 0 = 0$

$P(-2) = 0$

$P'(-2) = -2r^2$

Methods

Extra Topics

Horner Method for Evaluating Polynomials

Generalized Newton–Raphson Method

Generalized Newton–Raphson Method

A method for solving a system of n nonlinear functions with n variables.

$$\begin{cases} F(x) = 0 \\ f_1(x_1, x_2, \dots, x_n) = 0 \\ f_2(x_1, x_2, \dots, x_n) = 0 \\ \vdots \\ f_n(x_1, x_2, \dots, x_n) = 0 \end{cases}$$

Generalized Newton–Raphson Method

در روش نیوتون راسنون تعمیم یافته، مثل روش نیوتون راسنون، معکوس درایم بر صورت $(x_1^*, x_2^*, \dots, x_n^*)$ تعریف شده است که در این الگوریتم با استفاده از فریول نزدیکی می‌شوند.

$$x_{k+1} = x_k - J^{-1}(x_k) F(x_k)$$

فریول، J نیوتن راسنون است که در ادامه آن را تعریف می‌کنیم.

آخرین تغییر است برای فریول، فریول اصلی روش نیوتون راسنون را تعریف می‌کند.

$$(x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)})$$

فریول نیوتن راسنون، همان متفاوت است.

Generalized Newton–Raphson Method

دسترسی (XJ)، در لینی زیام ربط به متن ساده است و نسبت به تفسیر زیام ایسا:

$$J(x) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial x_1} & \dots & \frac{\partial f_n}{\partial x_n} \end{bmatrix}$$

Generalized Newton–Raphson Method

For instance, for 2 variables x and y , we have:

$$F(x, y) = 0$$

$$G(x, y) = 0$$

Approximate x_0 and y_0 :

$$x_{i+1} = x_i + \frac{D_1}{D}$$

$$y_{i+1} = y_i + \frac{D_2}{D}$$

Generalized Newton–Raphson Method

$$D = \begin{vmatrix} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial y} \\ \frac{\partial G}{\partial x} & \frac{\partial G}{\partial y} \end{vmatrix} = \frac{\partial F}{\partial x} \times \frac{\partial G}{\partial y} - \frac{\partial F}{\partial y} \times \frac{\partial G}{\partial x}$$

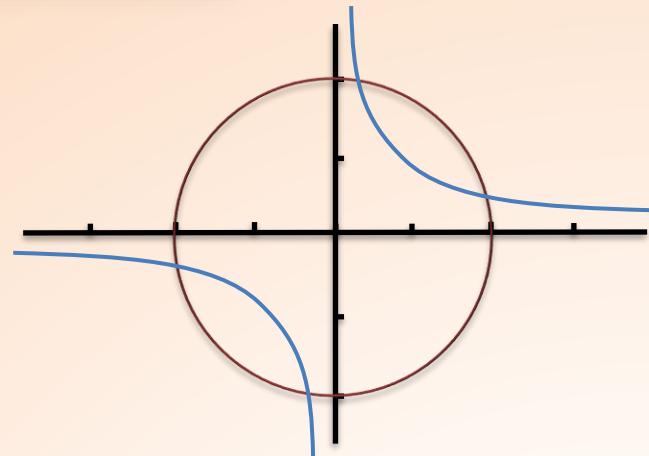
$$D_1 = \begin{vmatrix} -F(x, y) & \frac{\partial F}{\partial y} \\ -G(x, y) & \frac{\partial G}{\partial y} \end{vmatrix} \quad D_2 = \begin{vmatrix} \frac{\partial F}{\partial x} & -F(x, y) \\ \frac{\partial G}{\partial x} & -G(x, y) \end{vmatrix}$$

In each step, x_i and y_i are obtained from the previous step to calculate D, D_1 and D_2 .

Generalized Newton–Raphson Method

Example:

$$\begin{cases} F(x, y) = x^2 + y^2 - 4 = 0 \\ G(x, y) = xy - 1 = 0 \end{cases}$$



Generalized Newton–Raphson Method

Example:

$$\begin{cases} F(x, y) = x^2 + y^2 - 4 = 0 \\ G(x, y) = xy - 1 = 0 \end{cases}$$

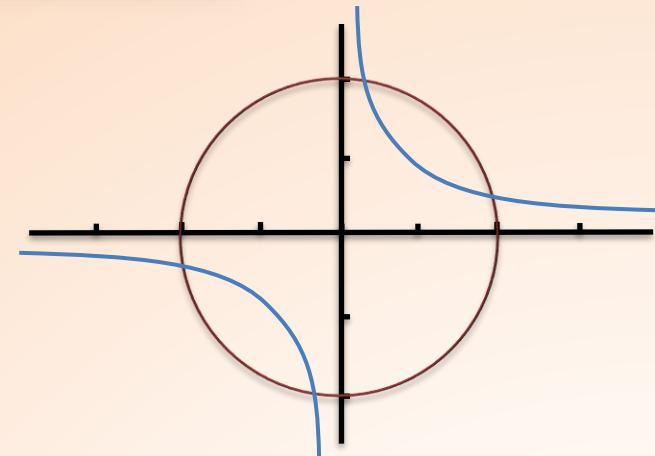
$$\frac{\partial F}{\partial X} = 2x,$$

$$\frac{\partial F}{\partial Y} = 2y$$

$$\frac{\partial G}{\partial X} = y,$$

$$\frac{\partial G}{\partial Y} = x$$

$$D = \begin{vmatrix} \frac{\partial F}{\partial X} & \frac{\partial F}{\partial Y} \\ \frac{\partial G}{\partial X} & \frac{\partial G}{\partial Y} \end{vmatrix} = 2x^2 - 2y^2$$



$$D_1 = \begin{vmatrix} -F(x, y) & \frac{\partial F}{\partial Y} \\ -G(x, y) & \frac{\partial G}{\partial Y} \end{vmatrix} = -(x^2 + y^2 - 4)(x) + (xy - 1)(2y)$$

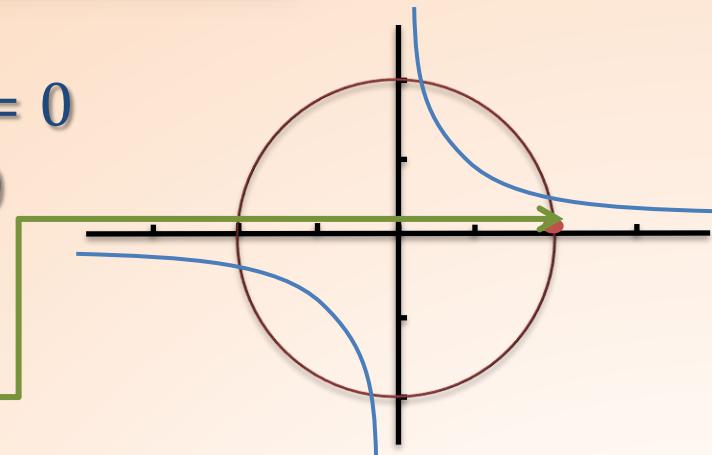
$$D_2 = \begin{vmatrix} \frac{\partial F}{\partial X} & -F(x, y) \\ \frac{\partial G}{\partial X} & -G(x, y) \end{vmatrix} = (2x)(-xy + 1) - (x^2 + y^2 - 4)(y)$$

Generalized Newton–Raphson Method

Example:

$$\begin{cases} F(x, y) = x^2 + y^2 - 4 = 0 \\ G(x, y) = xy - 1 = 0 \end{cases}$$

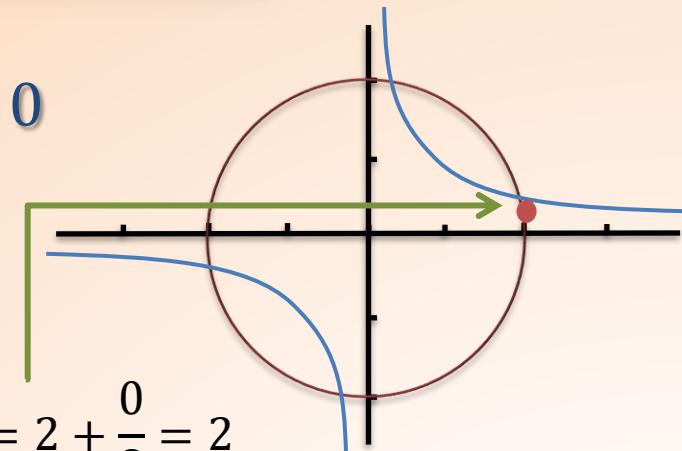
$$\begin{cases} x_{i+1} = x_i + \frac{D_1}{D} \\ y_{i+1} = y_i + \frac{D_2}{D} \end{cases} \quad \begin{cases} x_0 = 2 \\ y_0 = 0 \end{cases}$$



Generalized Newton–Raphson Method

Example: $\begin{cases} F(x, y) = x^2 + y^2 - 4 = 0 \\ G(x, y) = xy - 1 = 0 \end{cases}$

$$\begin{cases} x_{i+1} = x_i + \frac{D_1}{D} \\ y_{i+1} = y_i + \frac{D_2}{D} \end{cases} \quad \begin{cases} x_0 = 2 \\ y_0 = 0 \end{cases} \rightarrow \begin{cases} D = 8 \\ D_1 = 0 \\ D_2 = 3 \end{cases} \rightarrow \begin{cases} x_1 = 2 + \frac{0}{8} = 2 \\ y_1 = 0 + \frac{3}{8} = \frac{3}{8} \end{cases}$$

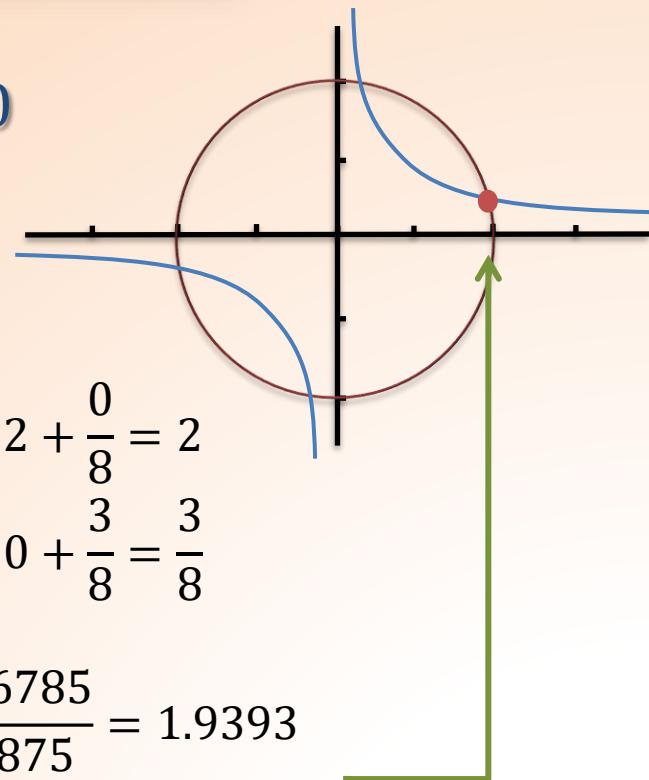


Generalized Newton–Raphson Method

Example: $\begin{cases} F(x, y) = x^2 + y^2 - 4 = 0 \\ G(x, y) = xy - 1 = 0 \end{cases}$

$$\begin{cases} x_{i+1} = x_i + \frac{D_1}{D} \\ y_{i+1} = y_i + \frac{D_2}{D} \end{cases} \quad \begin{cases} x_0 = 2 \\ y_0 = 1 \end{cases} \rightarrow \begin{cases} D = 8 \\ D_1 = 0 \\ D_2 = 3 \end{cases} \rightarrow \begin{cases} x_1 = 2 + \frac{0}{8} = 2 \\ y_1 = 0 + \frac{3}{8} = \frac{3}{8} \end{cases}$$

$$\begin{cases} x_1 = 2 \\ y_1 = \frac{3}{8} \end{cases} \rightarrow \begin{cases} D = 7.71875 \\ D_1 = -0.46785 \\ D_2 = -1.0527 \end{cases} \rightarrow \begin{cases} x_2 = 2 + \frac{-0.46785}{7.71875} = 1.9393 \\ y_2 = \frac{3}{8} + \frac{-1.0527}{7.71875} = 0.2386 \end{cases}$$



Any questions?

