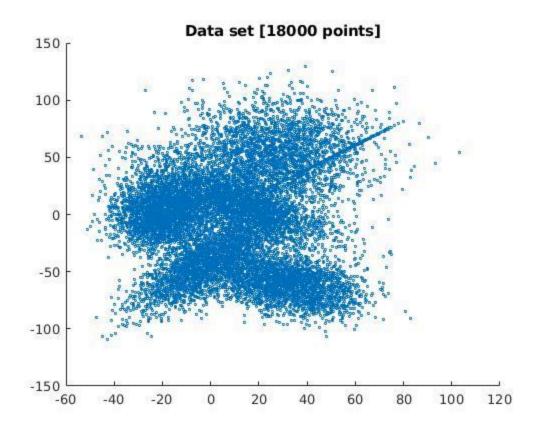
Table of Contents

```
Threshdold difference 4
%%Skylar Tamke - Project 3 EM Clustering
% I have estimated 6 clusters for this set of data. This parameter
% changed easily by modifying the variable M. When using the algorithm
% initial conditions are very key to how
% successful the algorithm is. If the starting conditions are bad the
% algorithm will cluster badly for a 2d array.
clc
clear
close all
warning('off','all')
%number of clusterings
M = 6;
%load data file
load("data.mat");
%initialize data set
x = data;
[N, d] = size(x);
mean = zeros(M, 2);
pi val = zeros(1,M);
pi_val(:) = 1/M;
%plot Data
scatter(data(:,1),data(:,2),3);
hold on
title("Data set [18000 points]")
%automatically finds clusters based on the kmeans method, initial
quess
[idx1,C1] = kmeans(data,M);
% C1 = rand(6,2)*100
%getting the mean for each point. initially
for i = 1:M
  mu(i,:) = C1(i,:);
end
```

```
% scatter(C1(:,1),C1(:,2),100)
% initialize cov values for each Gaussian (M) scalable
for m = 1:M
    Em(:,:,m) = eye(2);
end
% creating booleans to use when determining if continued EM is needed
boolean = 1;
covarience_threshhold = .01
loopcount = 0

covarience_threshhold =
    0.0100

loopcount =
    0
```



Algorithm

The algorithm will run until the end condition is met

```
while( boolean)
           loopcount = loopcount + 1;
            % Expectation algorithm step
           cond_sum = zeros(N,1);
            for i = 1:N
                       % first the probability that the data point is in a certain
   cluster
                       for m=1:M
                                        cond prob(i,m) = mvnpdf(x(i,:),mu(m,:),Em(:,:,m));
                                   cond_prob(i,m) =
   (((2*pi)^{(d/2)})*((det(Em(:,:,m)))^{(-.5)})) ...
                                   * \exp((-.5*(x(i,:)-mu(m,:))*(inv(Em(:,:,m)))*(x(i,:)-
(mu(m,:)));
                       end
                       for m = 1:M
                                   cond_sum(i) = cond_prob(i,m)*pi_val(m) + cond_sum(i);
                       % calculate the expectation of each data point
                                   z(i,m) = cond_prob(i,m)*pi_val(m)/cond_sum(i);
                       end
           end
            %getting rid of any NaNs, which are the result of the
            %conditional_probabilities that ended up being zero.
           for i = 1:N
                       for m = 1:M
                                   if(isnan(z(i,m)))
                                            z(i,m) = 0;
                                   end
                       end
            end
           %resetting this sumation so that algorithm doesn't run away
           cov_num = zeros(2,2,6);
            % % % M step
           for m = 1:M
                       z sum = sum(z(:,m));
                       for i = 1:N
                                   cov_num(:,:,m) = z(i,m) * (x(i,:) - mu(m,:))' * (x(i,:) - mu(m,:
  mu(m,:)) + cov_num(:,:,m);
                       %calculate new covarience matrices
                       Em(:,:,m) = cov num(:,:,m)/sum(z(:,m));
                       %record old means so we can compare to check convergence
```

```
old_mu = mu;
for i = 1:N
    mu_num(i,:) = z(i,m) * x(i,:);
end
sum_num = sum(mu_num);
%calculate new means
mu(m,:) = sum_num/(z_sum);
%calculate new prior probabilities
pi_val(m) = z_sum/N;
```

end

Threshdold difference

This is where convergence of EM properties are checked to see if the algorithm is successfull or not

```
%reset convergence check
mu_difference = 0;
for m = 1:M
    mu_difference = abs(old_mu(m) - mu(m)) + mu_difference;
end

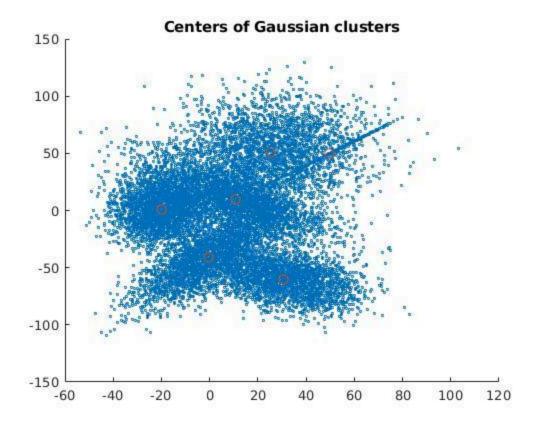
if(mu_difference < covarience_threshhold)
    boolean = 0;
end</pre>
```

Centriod plot

plot each centriod change, commented out for publish scatter(mu(:,1),mu(:,2),50)

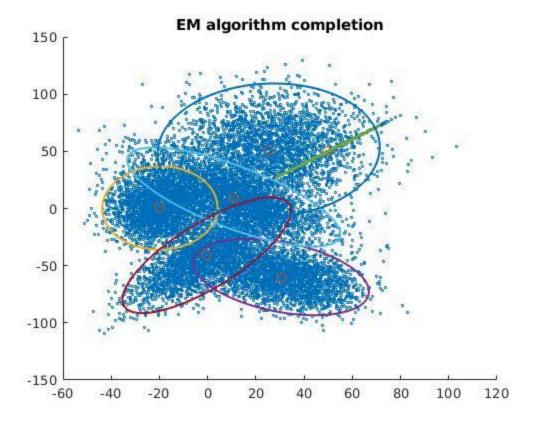
```
end
```

```
% A count of how many times the algorithm ran before finding a
loopcount
% A plot of the completed centers
scatter(mu(:,1),mu(:,2),50)
title("Centers of Gaussian clusters")
loopcount =
42
```



Ellipse plotting

this is a function linked for the class to use to



Published with MATLAB® R2018b