

STATS 315A Individual Problems

2.

• We have

$$z_i = a^T x_i, \text{ so } E[z_i] = E[a^T x_i] \\ = a^T E[x_i] = a^T \vec{0} = \boxed{0}$$

$$\text{Similarly, } \text{Var}[z_i] = \text{Var}[a^T x_i] \\ = a^T \text{Var}[x_i] a = a^T I_p a \\ = a^T a = \frac{x_0^T x_0}{\|x_0\|^2} = \boxed{1}$$

As normality is preserved under linear transformations,

$$z_i \sim N(E[z_i], \text{Var}[z_i]) \\ = N(0, 1)$$

$$\bullet E[z_i^2] = \text{Var}[z_i] + (E[z_i])^2 \\ = \boxed{1}$$

$$\therefore E[Z^T Z] = E\left[\sum_{i=1}^p z_i^2\right] = \sum_{i=1}^p E[z_i^2] \\ \text{Target point} = \boxed{p}$$

3

a.)

$$E[\hat{\beta} | X] = E[(X^T X)^{-1} X^T y | X]$$

$$= E[(X^T X)^{-1} X^T (X\beta + \varepsilon) | X]$$

$$= (\cancel{X}^T X)^{-1} X^T X E[\beta | X] + (X^T X)^{-1} X^T E[\varepsilon]$$

$$= E[\beta | X] + 0 = \boxed{\beta}$$

b) By tower property of expectation,

$$\text{Cov}[\hat{\beta}] = E[\text{Cov}[\hat{\beta} | X]] + \text{Cov}[E[\hat{\beta} | X]]$$

Using result from a),

$$= \sigma^2 E[(X^T X)^{-1}] + \text{Cov}[\beta]$$

d) Essentially, we repeatedly sample from X (each sample $X_{(i)}$), then

for i in $1:B$ {

(1) Calculate $(X_{(i)}^T X_{(i)})^{-1}$ and track moving avg. \rightarrow

(2) Calculate $\hat{\beta}_{(i)}$ via ols

(3) We use (1) to calculate

$\sigma^2 E[(X^T X)^{-1}]$ by using avg. as an approximation for expectation.

(4) We use (2) to calculate

$\text{Cov}[\beta]$ by approximating $\beta = \frac{\sum_{i=1}^B \beta_i}{B}$

4. a.) With the first approach we only calculate confidence intervals on a pointwise basis. However with the 2nd approach a confidence region is calculated using ~~the~~ ~~entire~~ parameters, hence requiring more coverage to ensure the same confidence level is met. Hence, the confidence bands produced by 2nd method will be wider.

b.) Yes, the bands constructed via approach 2 as $f(x_0)$ is contained within both upper & lower bands $\forall x_0$.

5.

The key idea we exploit is that the expected test error is the same regardless of M . In other words,

$$\begin{aligned} & E \left[\frac{1}{M} \sum_{i=1}^M (y_i' - \hat{\beta}^T x_i')^2 \right] \\ &= E \left[\frac{1}{N} \sum_{i=1}^N (y_i' - \hat{\beta}^T x_i')^2 \right] \end{aligned}$$

i.e. WLOG, test & training sets are same size.

Let $\tilde{\beta}$ be ols solution for (x_i', y_i') $\forall i$, then

$$E \left[\frac{1}{N} \sum_{i=1}^N (y_i - \tilde{\beta}^T x_i)^2 \right] = E \left[\frac{1}{N} \sum_{i=1}^N (\tilde{y}_i' - \tilde{\beta}^T x_i')^2 \right]$$

Since the avg. errors follow same distribution. But as $\tilde{\beta}$ is OLS, then by definition

$$E \left[\frac{1}{N} \sum_{i=1}^N (y_i' - \tilde{\beta}^T x_i')^2 \right] \leq E \left[\frac{1}{N} \sum_{i=1}^N (y_i' - \hat{\beta}^T x_i')^2 \right]$$

$$\therefore E[R_{tr}(\hat{\beta})] \leq E[R_{te}(\hat{\beta})]$$

6 a.) The OLS solution is not unique as when $p \gg N$, the matrix ~~$X^T X$~~ is invertible and thus multiple hyperplanes with \odot $RSS =$ can be fit.

b.) The solution is unique because adding λI_p to $X^T X$ ~~$X^T X$~~ ensures invertibility and by extension a unique solution.

c.) This approach causes the ~~\odot~~ solution to converge to the OLS solution $\hat{\beta}$ that minimizes the 2-norm of the residual vector $\vec{e} = Y - X\beta$

d.) Suppose SVD of X given by $X = U D V^T$ Then,

$$\begin{aligned}\hat{\beta} &= V (D^2)^{-1} D U^T y \\ &= \boxed{V D^{-1} U^T y}\end{aligned}$$