



Laplace Transforms IV: Other Properties of the Laplace Transform

▪ Initial Value Theorem

$$\lim_{s \rightarrow \infty} (sF(s)) = f(0^+)$$

▪ Final Value Theorem

$$\lim_{s \rightarrow 0} (sF(s)) = \lim_{t \rightarrow \infty} f(t)$$

▪ The “zero s ” theorem

$$\int_{-\infty}^{\infty} x(\tau) d\tau = \int_{-\infty}^{\infty} x(\tau) e^{0\tau} d\tau = \left(\int_{-\infty}^{\infty} x(\tau) e^{s\tau} d\tau \right)_{s=0} = X(0)$$

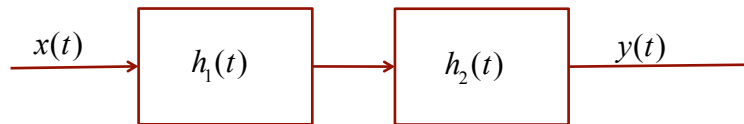
The Convolution Theorem

- One of the primary application of the Laplace (and later Fourier) Domain(s) is the Convolution Theorem
- What is the LT of the convolution?

$$\begin{aligned}
 \mathcal{L}(x * h) &= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau \right) e^{-st} dt \\
 &= \int_{-\infty}^{\infty} x(\tau) \underbrace{\left(\int_{-\infty}^{\infty} h(t - \tau) e^{-st} dt \right)}_{\text{time shift property!}} d\tau = \int_{-\infty}^{\infty} x(\tau) (e^{-s\tau} H(s)) d\tau \\
 &= H(s) \int_{-\infty}^{\infty} x(\tau) e^{-s\tau} d\tau = H(s) X(s) = X(s) H(s) (!! \\
 &\quad R \supset R_X \cap R_H
 \end{aligned}$$

So what?

- Remember our concatenation of systems?



$$y(t) = x * h = x * (h_1 * h_2)$$

$$H(s) = \mathcal{L}(h_1 * h_2) = H_1(s) H_2(s)$$

$$Y(s) = \mathcal{L}(x * h) = X(s) H(s) = X(s) H_1(s) H_2(s)$$

- A convolution in the time domain is equivalent to a multiplication in the frequency domain...
- ...and *vice versa*

One sided Laplace Transforms

- For *causal* systems, we have $h(t) = 0, t < 0$
- ...then $\mathcal{L}(h(t)) = \int_{-\infty}^{\infty} h(t)e^{-st} dt = \int_0^{\infty} h(t)e^{-st} dt$
- This is so common, that it's called the "one sided Laplace Transform"
- What's the RoC?
- ...no strips, no left side!
- This is the form your book (and many other texts) use!

Properties

- The same properties apply, except for the time derivative property
- Differentiation (1 sided)

$$\mathcal{L}\left(\frac{dx}{dt}\right) = sX(s) - x(0)$$

$$\frac{1}{s+a}, a < 0, \text{Re}[s] < a, -e^{-at}u(-t) \rightarrow 0 \text{ as } t \rightarrow -\infty$$

$$\mathcal{L}\left(\frac{d^2x}{dt^2}\right) = s^2X(s) - sx(0) - \frac{dx}{dt}\bigg|_{t=0}$$

Stability

- **Stability is generally “bounded input, bounded output” stability**
- **If $|x(t)| < C_1$ then $|y(t)| < C_2$**
- **Is our causal integrator $y(t) = \int_{-\infty}^t x(\tau) d\tau$ stable?**
- **To answer the question, we need to either prove that the condition holds or find a function where it doesn't hold**
- **Let $x(t) = u(t)$, then $y(t) = \int_0^t 1 d\tau = t$**
- **The input is bounded, but the output is not, because for any $C > 0$ I only need wait for $t > C$ for the output to exceed it.**
- **It is *not* BIBO stable!**

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What about the s-domain

- **Where are the poles of the integrator?**
- $$\mathcal{L}\left(\int_{-\infty}^t x(\tau) d\tau\right) = \frac{1}{s} \text{ for } \operatorname{Re}[s] > 0$$
- **What about $\mathcal{L}(e^{at}u(t)) = H(s) = \frac{1}{s+a}$, $a > 0$, $\operatorname{Re}[s] > a$**
- **This also “blows up”**
- $$y(t) = \int_{-\infty}^{\infty} x(t-\tau)e^{a\tau}u(\tau)d\tau = \int_0^{\infty} x(t-\tau)e^{a\tau}u(\tau)d\tau$$
- $$|x(t)| \leq C, \text{ so } y(t) \leq \int_0^{\infty} C_1 e^{a\tau} d\tau = \infty \Rightarrow \text{not stable}$$
- **A causal system must have its poles in the left half plane!**

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Anti causal system

- The reverse is true for anti causal systems

$$\frac{1}{s+a}, a > 0, \operatorname{Re}[s] < -a \Rightarrow -e^{-at}u(-t) \rightarrow \infty \text{ as } t \rightarrow -\infty$$

$$\frac{1}{s+a}, a < 0, \operatorname{Re}[s] < -a \Rightarrow -e^{-at}u(-t) \rightarrow 0 \text{ as } t \rightarrow -\infty$$

- And for two-sided systems, both terms must be stable.
- We will see later that the RoC must include the $j\omega$ axis for the system to be stable.

Examples

- Find the Laplace Transform of the unit amplitude pulse of duration T by two methods.
- Find the Laplace transform of a causal unit ramp,
 $y(t) = tu(t)$
- Find the response of $h(t) = \frac{1}{2}e^{-t}u(t) + \frac{1}{2}e^{-3t}u(t)$ to a causal unit ramp
- Find the initial and final values of that response.