

# CMPE 310 Systems Design and Programming

## L12: Chapter 11 – BASIC I/O Interface

UMBC

AN HONORS UNIVERSITY IN MARYLAND

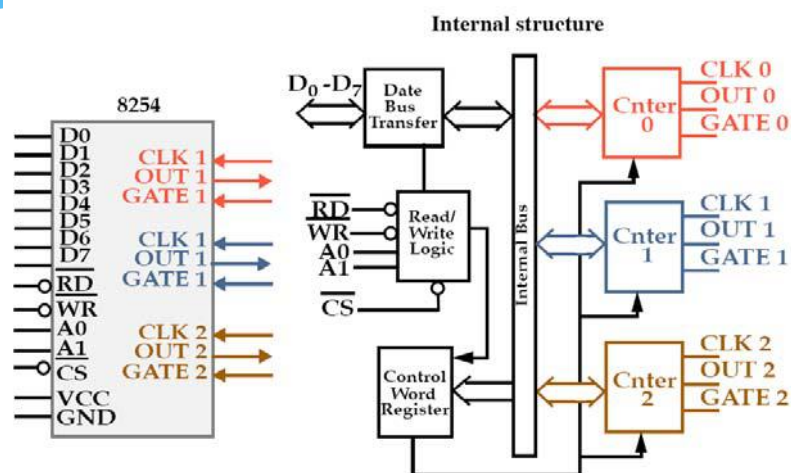
## L12 Objectives

- \* Describe the function of each pin of the 8254 PIT
  - \* Diagram how the 8254 PIT is connected to the x86/88 PC
  - \* Program the three counters of the 8254 PIT by use of the chip control word

## Programmable Interval Timer: 8254

- \* Three independent 16-bit programmable counters (**timers**).
  - \* Each capable of counting in binary or BCD with a maximum frequency of 10MHz.
- \* Used for controlling real-time events such as real-time clock, events counter, and motor speed and direction control.
- \* Usually decoded at port address 40H-43H
- \* Main functions:
  - \* Generates a basic timer interrupt that occurs at approximately 18.2Hz.
    - \* Interrupts the microprocessor at interrupt vector 8 for a clock tick.
  - \* Causes DRAM memory system to be refreshed.
    - \* Programmed for 15 us on PC to request DMA action
  - \* Provides a timing source to the internal speaker and other devices.

## 8254 Functional Description



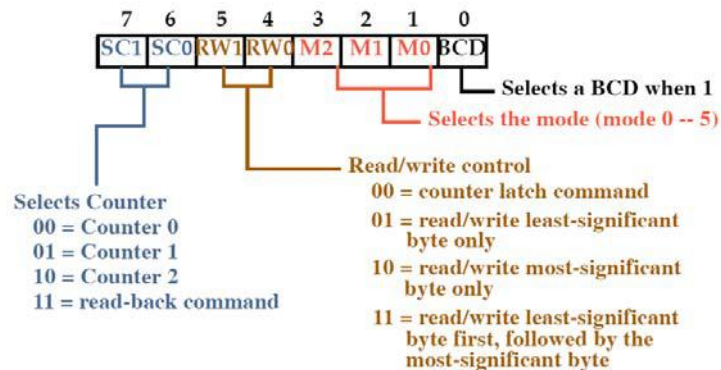
## 8254 Pin Definitions

- \* **A<sub>1</sub>, A<sub>0</sub>**: The **address inputs** select one of the four internal registers with the 8254
- \* **CLK**: The **clock** input is the timing source for each of the internal counters.
  - \* It is often connected to the PCLK signal from the bus controller.
- \*  **$\overline{CS}$** : **Chip Select** enables the 8254 for programming, and reading and writing.
- \* **G**: The **gate input** controls the operation of the counter in some modes.
- \* **OUT**: A **counter output** is where the wave-form generated by the timer is available.
- \*  **$\overline{RD}/\overline{WR}$** : **Read/Write** causes data to be read/written from the 8254 and often connects to the IORC/IOWC.

A <sub>1</sub>	A <sub>0</sub>	Function
0	0	Counter 0
0	1	Counter 1
1	0	Counter 2
1	1	Control Word

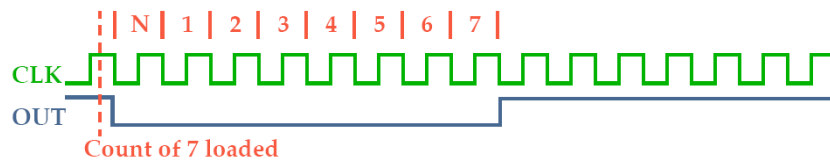
## 8254 Programming

- \* Each counter is individually programmed by writing a control word, followed by the initial count.
- \* The control word allows the programmer to select the counter, mode of operation, binary or BCD count and type of operation (read/write).



## 8254 Programming

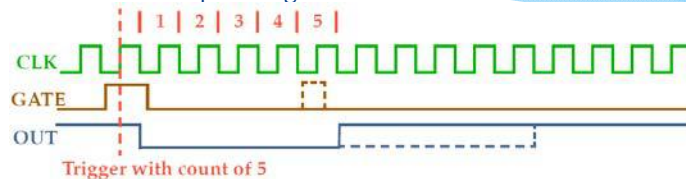
- \* Each counter may be programmed with a count of 1 to FFFFH.
  - \* Minimum count is 1 all modes except 2 and 3 with minimum count of 2.
- \* Each counter has a program control word used to select the way the counter operates.
  - \* If two bytes are programmed, then the first byte (LSB) stops the count, and the second byte (MSB) starts the counter with the new count.
- \* There are 6 modes of operation for each counter:
  - \* **Mode 0:** An events counter enabled with G.
    - \* The output becomes a logic 0 when the control word is written and remains there until N plus the number of programmed counts.



## 8254 Modes

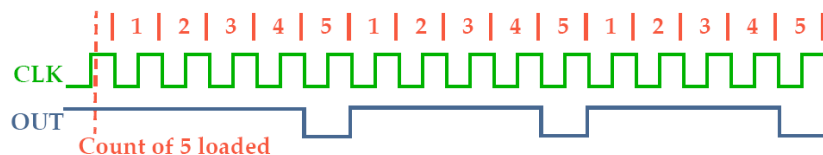
### Mode 1: One-shot mode.

- \* The G input triggers the counter to output a 0 pulse for the duration of the count.
- \* Counter reloaded if G is pulsed again.



### Mode 2: Counter generates a series of pulses that are 1 clock pulse wide.

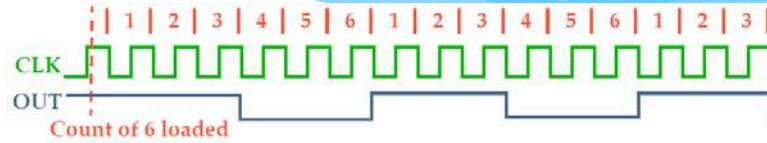
- \* The separation between pulses is determined by the count.
- \* The cycle is repeated until reprogrammed or G pin set to 0.



## 8254 Modes

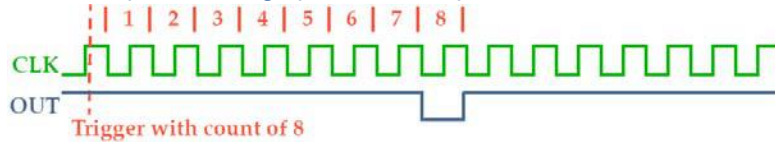
**Mode 3:** Generates a continuous square-wave with G set to 1.

- \* If count is even, 50% duty cycle otherwise OUT is high 1 cycle longer.



**Mode 4:** Software triggered one-shot (G must be 1).

- \* Count to be decremented by 1 clock pulse
- \* Allow counter to produce a single pulse at the output



**Mode 5:** Hardware triggered one-shot. G controls similar to Mode 1

- \* Functions as Mode 4 except counting is started by a trigger pulse on G.
- \* Strobe pulse is output after the count is decremented to 0

## Next Time

- \* Programmable Communications Interface

STOP