

CMPE 310 Systems Design and Programming

L19: Chapter 3 – Addressing Modes

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L19 Objectives

- * Addressing modes
 - * Recognize the addressing modes of the x86

Review: Addressing modes

- * Addressing modes: how data is specified
 - * Register: MOV AX, BX
 - * Immediate: MOV AX, 1234H
 - * Memory
 - * Direct: MOV AX, [1010H]
 - * Will cover remaining modes today
 - * Can have at most one memory operand
 - * Segment base assumed to be DS; can override
- * How do we specify how many bytes we are moving?

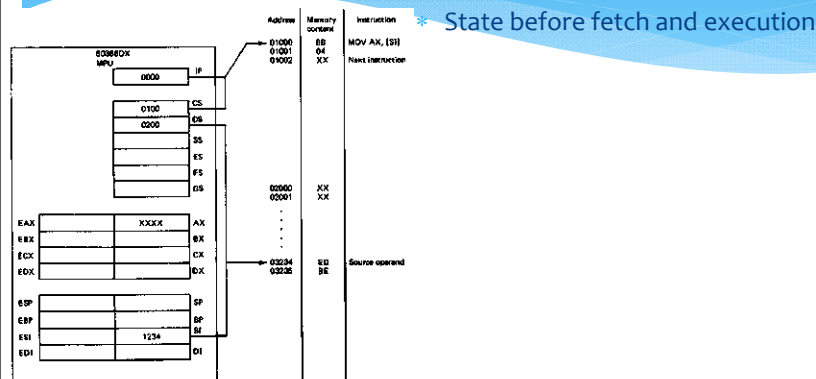
Register Indirect Addressing Mode

PA = Segment base: Indirect address

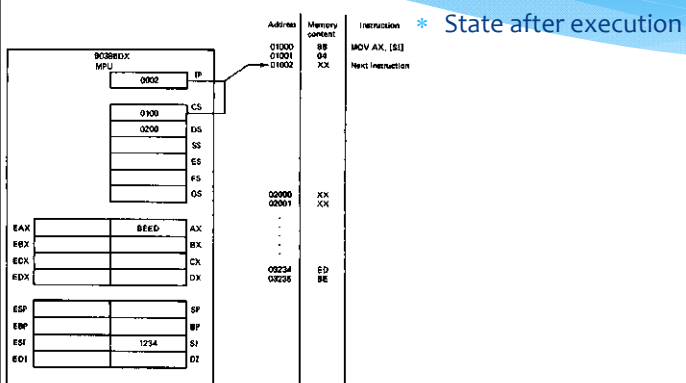
$$PA = \left\{ \begin{array}{c} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{array} \right\} : \left\{ \begin{array}{c} BX \\ BP \\ SI \\ DI \end{array} \right\}$$

- * Register indirect addressing mode
 - * Similar to direct addressing in that the effective address is combined with the contents of DS to obtain the physical address
 - * Effective address resides in either a base or index register
- * Physical address computation
 - PA = SBA:EA → 20-bit address
 - PA = SBA:[Rx] → 16-bit offset
 - * Segment base address is DS by default
 - PA = DS:[Rx]
 - * Segment override prefix (SEG) is required to enable use of another segment register
 - PA = ES:[Rx]

Register Indirect Addressing Mode (example: MOV AX, [SI])



Register Indirect Addressing Mode (example: MOV AX, [SI])



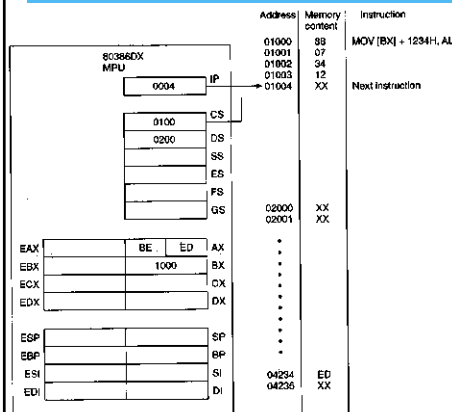
$$PA = \left\{ \begin{matrix} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{matrix} \right\} : \left\{ \begin{matrix} BX \\ BP \end{matrix} \right\} + \left\{ \begin{matrix} 8\text{-bit displacement} \\ 16\text{-bit displacement} \end{matrix} \right\}$$

The diagram illustrates the calculation of the address of Element n in memory. A Base register and a Displacement are added together. The result is then used to find Element n in a memory structure. The memory structure is shown as a vertical stack of elements: Element 0, Element 1, Element 2, ..., Data structure, ..., Element $n-1$, Element n . The Base register points to Element 0, and the Displacement points to Element $n-1$.

- * Based addressing makes it easy to access elements of data in an array
- * Address in base register points to start of the array
- * Displacement selects the element within the array
- * Value of the displacement is simply changed to access another element in the array
- * Program changes value in base register to select another array

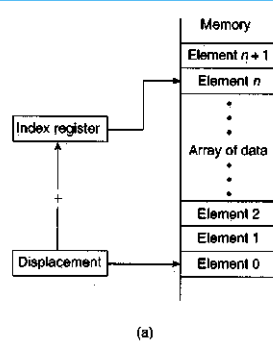
[illegible]

Base Addressing Mode (Example: MOV [BX] + 1234H, AL)



* State after execution

Indexed Addressing Mode



PA = Segment base: index + displacement

$$PA = \begin{Bmatrix} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{Bmatrix} : \begin{Bmatrix} SI \\ DI \end{Bmatrix} + \begin{Bmatrix} 8\text{-bit displacement} \\ 16\text{-bit displacement} \end{Bmatrix}$$

(b)

* Indexed addressing mode

- * Similar to based addressing, it makes accessing elements of data in an array easy
- * Displacement points to the beginning of array in memory
- * Index register selects element in the array
- * Program simply changes the value of the displacement to access another array
- * Program changes (recomputes) value in index register to select another element in the array

* Effective address formed from direct displacement and contents of an index register

- * Direct displacement is 8-bit or 16-bit
- * Index register is either SI → source operand or DI → destination operand

* Physical address computation

PA = SBA:EA → 20-bit address

PA = SBA: DA + [SI or DI]

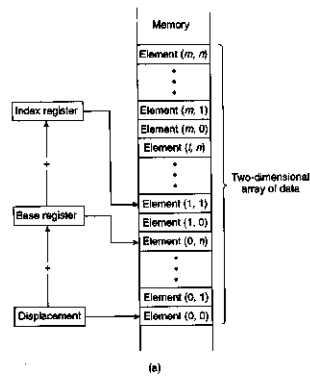
- * State before fetch and execution



- * **State after execution**



Based-Indexed Addressing Mode



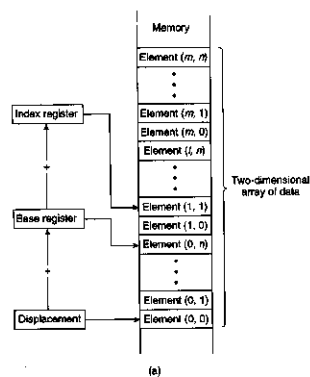
PA = Segment base: base + index + displacement

$$PA = \begin{Bmatrix} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{Bmatrix} : \left\{ \begin{Bmatrix} BX \\ BP \end{Bmatrix} \right\} + \left\{ \begin{Bmatrix} SI \\ DI \end{Bmatrix} \right\} + \left\{ \begin{array}{l} \text{8-bit displacement} \\ \text{16-bit displacement} \end{array} \right\}$$

(b)

- * Combines the functions of based and indexed addressing modes
- * Enables easy access to two-dimensional arrays of data
- * Displacement points to the beginning of array in memory
- * Base register selects a row (m) of elements
- * Index register selects an element in column (n)
- * Program simply changes the value of the displacement to access another array
- * Program changes (recomputes) value in base register to select another row of elements
- * Program changes (recomputes) the value of the index register to select the element in another column

Based-Indexed Addressing Mode



PA = Segment base: base + index + displacement

$$PA = \begin{Bmatrix} CS \\ DS \\ SS \\ ES \\ FS \\ GS \end{Bmatrix} : \left\{ \begin{Bmatrix} BX \\ BP \end{Bmatrix} \right\} + \left\{ \begin{Bmatrix} SI \\ DI \end{Bmatrix} \right\} + \left\{ \begin{array}{l} \text{8-bit displacement} \\ \text{16-bit displacement} \end{array} \right\}$$

(b)

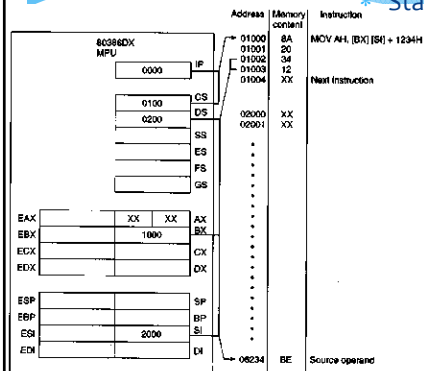
- * Effective address formed from direct displacement and contents of a base register and an index register
- * Direct displacement is 8-bit or 16bit
- * Base register either BX or BP (stack)
- * Index register is either SI \rightarrow source operand or DI \rightarrow destination operand
- * Physical address computation

PA = SBA:EA \rightarrow 20-bit address

PA = SBA:DA + [BX or BP] + [SI or DI]

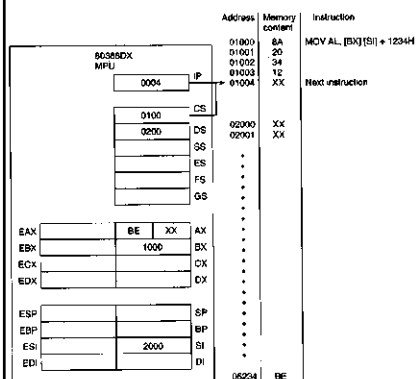
Based- Indexed Addressing Mode Example(MOV AH,[BX][SI] +1234H)

* State before fetch and execution



Based- Indexed Addressing Mode Example(MOV AH,[BX][SI] +1234H)

* State after execution



Next time

- * Data transfer instructions

