

CMPE 320: Probability, Statistics, and Random Processes

Lecture 19: Conditional expectation, Independence, and Bayes rule

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Announcement

- Special review sessions
 - For those who feel extra shaky about basic problem solving
 - Will mainly review midterm 1 and 2 problems
 - 2~3 times before the final, once a week, taught by the TA
- If interested, please e-mail by tomorrow (5/1) to the TA (lee43@umbc.edu)
 - Will try to find the common time slot online

Conditional expectation

- Instead of ordinary PDFs, use conditional PDFs
- Analogous formulas to discrete RVs, except sums are replaced by integrals

$$E[X|A] = \int_{-\infty}^{\infty} x f_{X|A}(x) dx$$

$$E[X|Y=y] = \int_{-\infty}^{\infty} x f_{X|Y}(x|y) dx$$

For a function $g(X)$

$$E[g(X)|A] = \int_{-\infty}^{\infty} g(x) f_{X|A}(x) dx$$

$$E[g(X)|Y=y] = \int_{-\infty}^{\infty} g(x) f_{X|Y}(x|y) dx$$

Total expectation

- Let A_1, A_2, \dots, A_n be disjoint events that form a partition of Ω with $P(A_i) > 0$

Recall the total probability theorem for PDF

$$f_X(x) = \sum_{i=1}^n P(A_i) f_{X|A_i}(x)$$

Multiply both sides by x and integrate

$$\int_{-\infty}^{\infty} x f_X(x) dx = \int_{-\infty}^{\infty} x \sum_{i=1}^n P(A_i) f_{X|A_i}(x) dx = \sum_{i=1}^n P(A_i) \int_{-\infty}^{\infty} x f_{X|A_i}(x) dx$$

$$E[X] = \sum_{i=1}^n P(A_i) E[X|A_i]$$

Similarly,

$$E[X] = \int_{-\infty}^{\infty} f_Y(y) E[X|Y=y] dy$$

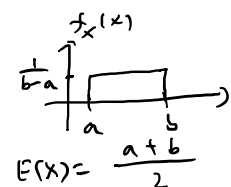
← start from
 $f_X(x) = f_{X|Y}(x|y) f_Y(y)$

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Example 3.17. Mean and Variance of a Piecewise Constant PDF. Suppose that the random variable X has the piecewise constant PDF

$$f_X(x) = \begin{cases} 1/3, & \text{if } 0 \leq x \leq 1, \\ 2/3, & \text{if } 1 < x \leq 2, \\ 0, & \text{otherwise,} \end{cases}$$



$$E(X) = \frac{a+b}{2}$$

$$E(X^2) = \int_a^b x^2 \frac{1}{b-a} dx = \frac{a^2 + ab + b^2}{3}$$

Compute $E[X]$ and $\text{var}(X)$ by using the total expectation theorem considering the events

$A_1 = \{X \text{ lies in the first interval } [0, 1]\},$

$A_2 = \{X \text{ lies in the second interval } (1, 2]\}.$

$$E[X] = \underbrace{E[X|A_1]}_{f_{X|A_1} \text{ is uniform in } [0, 1]} P(A_1) + \underbrace{E[X|A_2]}_{f_{X|A_2} \text{ uniform in } [1, 2]} P(A_2)$$

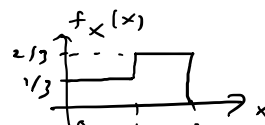
$f_{X|A_1}$ is uniform
in $[0, 1]$

$f_{X|A_2}$ uniform
in $[1, 2]$

$$= \frac{1}{2} \cdot \frac{1}{3} + \frac{3}{2} \cdot \frac{2}{3} = \frac{1}{6} + 1 = \frac{7}{6}$$

$$\begin{aligned} E[X^2] &= E[X^2|A_1] P(A_1) + E[X^2|A_2] P(A_2) \\ &= \frac{0^2 + 0 \cdot 1 + 1^2}{3} \cdot \frac{1}{3} + \frac{1^2 + 1 \cdot 2 + 2^2}{3} \cdot \frac{2}{3} = \frac{5}{3} \end{aligned}$$

$$\text{var}(X) = E(X^2) - (E[X])^2 = \frac{5}{3} - \left(\frac{7}{6}\right)^2 = \frac{11}{36}$$



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Conditional expectation with multiple RVs

$$E[g(X, Y) | Y = y] = \int_{-\infty}^{\infty} g(x, y) f_{X|Y}(x|y) dx$$

$$E[g(X, Y)] = \int_{-\infty}^{\infty} E[g(X, Y) | Y = y] f_Y(y) dy$$

Independence

- Two RVs X and Y are independent if the joint PDF is the product of marginals

$$f_{X,Y}(x,y) = f_X(x) f_Y(y) \quad \text{for all } x, y$$

Compare with $f_{X,Y}(x,y) = f_{X|Y}(x|y) f_Y(y)$

$$f_{X|Y}(x|y) = f_X(x) \quad \text{for all } x, y \text{ with } f_Y(y) > 0$$

Similarly, $f_{Y|X}(y|x) = f_Y(y) \quad \text{for all } x, y \text{ with } f_X(x) > 0$

- For more than 2 RVs

$$f_{X,Y,Z}(x,y,z) = f_X(x) f_Y(y) f_Z(z) \quad \text{for all } x,y,z$$

Example 3.18. Independent Normal Random Variables. Let X and Y be independent normal random variables with means μ_x, μ_y , and variances σ_x^2, σ_y^2 , respectively. What is their joint PDF? Also, plot the contour $\{(x,y) | f_{X,Y}(x,y) = c\}$.

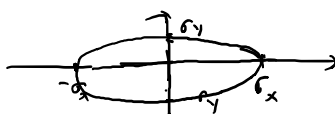
Since X and Y are independent

$$\begin{aligned} f_{X,Y}(x,y) &= f_X(x) f_Y(y) = \frac{1}{\sqrt{2\pi}\sigma_x} e^{-\frac{(x-\mu_x)^2}{2\sigma_x^2}} \cdot \frac{1}{\sqrt{2\pi}\sigma_y} e^{-\frac{(y-\mu_y)^2}{2\sigma_y^2}} \\ &= c e^{-\left[\frac{(x-\mu_x)^2}{2\sigma_x^2} + \frac{(y-\mu_y)^2}{2\sigma_y^2}\right]} \end{aligned}$$

Setting $f_{X,Y}(x,y) = c$, take \ln

$$\frac{(x-\mu_x)^2}{\sigma_x^2} + \frac{(y-\mu_y)^2}{\sigma_y^2} = c', \quad \text{consider } c' = 1, \mu_x = \mu_y = 0$$

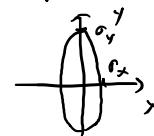
If $\sigma_x^2 > \sigma_y^2$



$\sigma_x^2 = \sigma_y^2$



$\sigma_y^2 > \sigma_x^2$



Independence and CDF

- If X and Y are independent, so are $\{X \in A\}$ and $\{Y \in B\}$

$$\begin{aligned}
 P(X \in A, Y \in B) &= \int_A \int_B f_{X,Y}(x,y) dy dx \\
 &= \int_A \int_B f_X(x) f_Y(y) dy dx \quad \leftarrow x, y : \text{independent} \\
 &= \int_A f_X(x) dx \int_B f_Y(y) dy \\
 &= P(X \in A) P(Y \in B)
 \end{aligned}$$

Let $A = (-\infty, x]$, $B = (-\infty, y]$

$$P(X \leq x, Y \leq y) = P(X \leq x) P(Y \leq y)$$

$$F_{X,Y}(x,y) = F_X(x) \cdot F_Y(y) \quad \text{for all } x, y$$

True even for discrete RVs, also useful for mixed cases
e.g. X : continuous, Y : discrete

Independence and expectation

- If X and Y are **independent**,

$$E[XY] = E[X] E[Y]$$

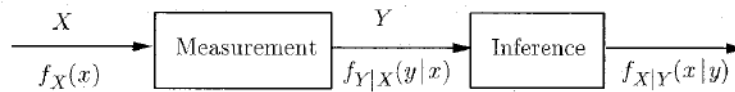
Same as discrete RVs

$$\text{var}(X+Y) = \text{var}(X) + \text{var}(Y)$$

- If X and Y are independent, so are $g(X)$ and $h(Y)$ for any functions g and h

$$E(g(X) h(Y)) = E(g(X)) E(h(Y))$$

Continuous Bayes' rule



X : Some unobserved phenomenon $\sim f_X(x)$

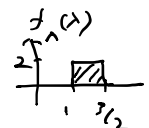
Y : Noisy measurement related to X via $f_{Y|X}(y|x)$

Want to infer about X based on $\{Y=y\}$

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)} = \frac{f_{Y|X}(y|x) f_X(x)}{f_Y(y)} = \frac{f_{Y|X}(y|x) f_X(x)}{\int_{-\infty}^{\infty} f_{Y|X}(y|x) f_X(x) dx}$$

Example 3.19. A light bulb produced by the General Illumination Company is known to have an exponentially distributed lifetime Y . However, the company has been experiencing quality control problems. On any given day, the parameter λ of the PDF of Y is actually a random variable, uniformly distributed in the interval $[1, 3/2]$. We test a light bulb and record its lifetime. What can we say about the underlying parameter λ ?

$$f_Y(y) = \begin{cases} \lambda e^{-\lambda y}, & y \geq 0 \\ 0, & \text{other.} \end{cases}$$



$$f_{\lambda}(\lambda) = \begin{cases} 2, & \lambda \in [1, 3/2] \\ 0, & \text{otherwise} \end{cases}, \quad f_{Y|\lambda}(y|\lambda) = \begin{cases} \lambda e^{-\lambda y}, & \text{if } y \geq 0 \\ 0, & \text{otherwise} \end{cases}$$

$$\begin{aligned} f_{\lambda|Y}(\lambda|y) &= \frac{f_{Y|\lambda}(y|\lambda) f_{\lambda}(\lambda)}{f_Y(y)} = \frac{f_{Y|\lambda}(y|\lambda) f_{\lambda}(\lambda)}{\int_{-\infty}^{\infty} f_{Y|\lambda}(y|\lambda) f_{\lambda}(\lambda) d\lambda} \\ &= \begin{cases} \frac{\lambda e^{-\lambda y} \cdot 2}{\int_1^{3/2} \lambda e^{-\lambda y} \cdot 2 d\lambda}, & 1 \leq \lambda \leq 3/2 \\ 0, & \text{otherwise} \end{cases}, \quad y \geq 0 \end{aligned}$$

Inference on an event based on continuous RV

- Want to infer about an event A based on observation $Y = y$
 - Binary signal corrupted by normally distributed noise
 - Medical diagnosis from continuous measurements (temperature, blood counts, etc.)

Given: $P(A)$, $f_{Y|A}(y)$ and $f_{Y|A^c}(y)$

$$\begin{aligned}
 \text{Want: } P(A|Y=y) &= \frac{P(A, Y=y)}{P(Y=y)} \quad \frac{0}{0} \\
 &\approx \frac{P(A, y \leq Y \leq y+\delta)}{P(y \leq Y \leq y+\delta)} \quad \delta \text{ small} \\
 &\approx \frac{P(y \leq Y \leq y+\delta|A)P(A)}{f_Y(y)\delta} = \frac{\int_y^{y+\delta} f_{Y|A}(t) dt \cdot P(A)}{f_Y(y)\delta} = \frac{f_{Y|A}(y) \cdot P(A)}{f_Y(y) \cdot \delta} = \frac{f_{Y|A}(y)P(A)}{f_Y(y)P(A) + f_{Y|A^c}(y)P(A^c)} \leftarrow \text{total prob.} \\
 &= \frac{f_{Y|A}(y)P(A)}{f_{Y|A}(y)P(A) + f_{Y|A^c}(y)P(A^c)}
 \end{aligned}$$

Inference about a discrete RV

Apply the previous result to events of the form $\{N=n\}$ discrete RV

$$\begin{aligned}
 P(N=n|Y=y) &= \frac{P(N=n)f_{Y|N}(y|n)}{f_Y(y)} \quad f_{Y|\{N=n\}}(y) \\
 &= \frac{P(N=n)f_{Y|N}(y|n)}{\sum_i P(N=i)f_{Y|N}(y|i)}
 \end{aligned}$$

If Y is discrete

$$P(N=n|Y=k) = \frac{P(N=n, Y=k)}{P(Y=k)} = \frac{P(Y=k|N=n)P(N=n)}{P(Y=k)}$$

Example 3.20. Signal Detection. A binary signal S is transmitted, and we are given that $P(S = 1) = p$ and $P(S = -1) = 1 - p$. The received signal is $Y = N + S$, where N is normal noise, with zero mean and unit variance, independent of S . What is the probability that $S = 1$, as a function of the observed value y of Y ?

$$P(S = 1 | Y = y) = \frac{f_{Y|S=1}(y) P(S=1)}{f_Y(y)}$$

$$= \frac{\frac{1}{\sqrt{2\pi}} e^{-\frac{(y-1)^2}{2}} \cdot p}{\frac{1}{\sqrt{2\pi}} e^{-\frac{(y-1)^2}{2}} \cdot p + \frac{1}{\sqrt{2\pi}} e^{-\frac{(y+1)^2}{2}} \cdot (1-p)}$$

$$\begin{aligned} f_{Y|S=1}(y) &= \text{Normal w. mean 1, var. 1} = \frac{1}{\sqrt{2\pi}} e^{-\frac{(y-1)^2}{2}} \\ f_{Y|S=-1}(y) &= \text{Normal w. mean -1, var. 1} = \frac{1}{\sqrt{2\pi}} e^{-\frac{(y+1)^2}{2}} \\ f_Y(y) &= f_{Y|S=1} P(S=1) + f_{Y|S=-1} P(S=-1) \\ &= \frac{1}{\sqrt{2\pi}} e^{-\frac{(y-1)^2}{2}} \cdot p + \frac{1}{\sqrt{2\pi}} e^{-\frac{(y+1)^2}{2}} \cdot (1-p) \end{aligned}$$

Inference based on discrete observations

$$\begin{aligned} f_{Y|A}(y) &= \frac{P(A|Y=y) f_Y(y)}{P(A)} \\ &= \frac{P(A|Y=y) f_Y(y)}{\int_{-\infty}^{\infty} P(A|Y=y) f_Y(y) dy} \end{aligned}$$

When $\{N = n\}$

$$f_{Y|N}(y|n) = \frac{P(N=n|Y=y) f_Y(y)}{P(N=n)} = \frac{P(N=n|Y=y) f_Y(y)}{P_N(n)}$$