

# Assignment 6

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11/21/2021

## Question 1

Consider the following activity-on-arc project network, where the 12 arcs (arrows) represent the 12 activities (tasks) that must be performed to complete the project and the network displays the order in which the activities need to be performed. The number next to each arc (arrow) is the time required for the corresponding activity. Consider the problem of finding the longest path (the largest total time) through this network from start (node 1) to finish (node 9), since the longest path is the critical path.

### Solution:

#### Objective Function

Maximize:  $5X_{12} + 3X_{13} + 4X_{24} + 2X_{25} + 3X_{35} + X_{46} + 4X_{47} + 6X_{57} + 2X_{58} + 5X_{69} + 4X_{79} + 7X_{89}$   
Here,  $X_{ij}$  (i=Starting Node, j=Ending node)

#### Starting Node

$$5X_{12} + 3X_{13} = 1$$

#### Intermediate Node

$$5X_{12} - 2X_{25} - 4X_{24} = 0$$

$$3X_{13} - 3X_{35} = 0$$

$$4X_{24} - X_{46} - 4X_{47} = 0$$

$$3X_{35} - 2X_{25} - 2X_{58} - 6X_{57} = 0$$

$$X_{46} - 5X_{69} = 0$$

$$6X_{57} - 4X_{47} - 4X_{24} = 0$$

$$2X_{58} - 7X_{89} = 0$$

#### Ending Node

$$7X_{89} - 4X_{79} - 5X_{69} = 1$$

```
library(lpSolveAPI)
lpprec <- make.lp(0,12)
lp.control(lpprec, sense="max")
```

```
## $anti.degen
## [1] "fixedvars" "stalling"
##
## $basis.crash
## [1] "none"
##
```

```

## $bb.depthlimit
## [1] -50
##
## $bb.floorfirst
## [1] "automatic"
##
## $bb.rule
## [1] "pseudononint" "greedy"      "dynamic"      "rcostfixing"
##
## $break.at.first
## [1] FALSE
##
## $break.at.value
## [1] 1e+30
##
## $epsilon
##      epsb      epsd      epsel      epsint  epsperturb  epspivot
##      1e-10      1e-09      1e-12      1e-07      1e-05      2e-07
##
## $improve
## [1] "dualfeas" "thetagap"
##
## $infinite
## [1] 1e+30
##
## $maxpivot
## [1] 250
##
## $mip.gap
## absolute relative
##      1e-11      1e-11
##
## $negrange
## [1] -1e+06
##
## $obj.in.basis
## [1] TRUE
##
## $pivoting
## [1] "devex"      "adaptive"
##
## $presolve
## [1] "none"
##
## $scalelimit
## [1] 5
##
## $scaling
## [1] "geometric"  "equilibrate" "integers"
##
## $sense
## [1] "maximize"
##
## $simplextype

```

```
## [1] "dual"    "primal"
##
## $timeout
## [1] 0
##
## $verbose
## [1] "neutral"
```

```
time <- c(5, 3, 4, 2, 3, 1, 4, 6, 2, 5, 4, 7) # objective function
set.objfn(lprec, 1*time)
set.type(lprec, 1:12, "binary")
add.constraint(lprec,c(1,1),"=",1,indices = c(1,2)) # starting node
add.constraint(lprec,c(1,-1,-1),"=",0,indices = c(1,3,4)) # intermediate node
add.constraint(lprec,c(1,-1),"=",0,indices = c(2,5))
add.constraint(lprec,c(1,-1,-1),"=",0,indices = c(3,6,7))
add.constraint(lprec,c(1,1,-1,-1),"=",0,indices = c(4,5,8,9))
add.constraint(lprec,c(1, -1),"=",0,indices = c(6,10))
add.constraint(lprec,c(1,1,-1),"=",0,indices = c(7,8,11))
add.constraint(lprec,c(1,-1),"=",0,indices = c(9,12))
add.constraint(lprec,c(1,1,1),"=",1,indices = c(10,11,12)) # Ending node
solve(lprec)
```

```
## [1] 0
```

```
get.objective(lprec)
```

```
## [1] 17
```

```
get.variables(lprec)
```

```
## [1] 1 0 0 1 0 0 0 1 0 0 1 0
```

```
get.constraints(lprec)
```

```
## [1] 1 0 0 0 0 0 0 0 1
```

```
arc <- c("X12", "X13", "X24", "X25", "X35", "X46", "X47", "X57", "X58", "X69", "X79", "X89")
var<-get.variables(lprec)
output<-data.frame(arc,var)
output
```

```
##      arc var
## 1  X12    1
## 2  X13    0
## 3  X24    0
## 4  X25    1
## 5  X35    0
## 6  X46    0
## 7  X47    0
## 8  X57    1
```

```
## 9 X58 0
## 10 X69 0
## 11 X79 1
## 12 X89 0
```

Also ,we can read the .lp file and solve the problem

```
x<- read.lp("BIP.lp")
x
```

```
## Model name:
## a linear program with 12 decision variables and 9 constraints
```

Solve Model

```
solve(x)
```

```
## [1] 0
```

```
get.objective(x)
```

```
## [1] 17
```

```
get.variables(x)
```

```
## [1] 1 0 1 0 0 0 1 0 0 0 1 0
```

```
get.constraints(x)
```

```
## [1] 1 0 0 0 0 0 0 0 0 1
```

## Question 2

Selecting an Investment Portfolio An investment manager wants to determine an optimal portfolio for a wealthy client. The fund has \$2.5 million to invest, and its objective is to maximize total dollar return from both growth and dividends over the course of the coming year. The client has researched eight high-tech companies and wants the portfolio to consist of shares in these firms only. Three of the firms (S1 – S3) are primarily software companies, three (H1–H3) are primarily hardware companies, and two (C1–C2) are internet consulting companies. The client has stipulated that no more than 40 percent of the investment be allocated to any one of these three sectors. To assure diversification, at least \$100,000 must be invested in each of the eight stocks. Moreover, the number of shares invested in any stock must be a multiple of 1000.

The table gives estimates from the investment company's database relating to these stocks. These estimates include the price per share, the projected annual growth rate in the share price, and the anticipated annual dividend payment per share.

1) Determine the maximum return on the portfolio. What is the optimal number of shares to buy for each of the stocks? What is the corresponding dollar amount invested in each stock?

**Solution:**

To determine the maximum return on the portfolio the objective function includes the price per share, the projected annual growth in the share price & the anticipated annual dividend payment per share .This can be expressed as follows :

$$\text{Returns} = (\text{Price per share}) * (\text{Growth Rate}) + (\text{Dividend payment per share})$$

### Objective Function

$$\text{Maximize, } Z = 4XS_1 + 6.5XS_2 + 5.9XS_3 + 5.4XH_1 + 5.15XH_2 + 10XH_3 + 8.4XC_1 + 6.25XC_2$$

Investment constraints,

$$40 XS_1 + 50 XS_2 + 80 XS_3 + 60 XH_1 + 45 XH_2 + 60 XH_3 + 30 XC_1 + 25 XC_2 \leq 2500000$$

Number of shares that are invested in stock should be a multiple of 1000.

$$1000 X_{SI} \geq 0 \text{ (I = 1,2,3)}$$

$$1000 X_{HI} \geq 0 \text{ (I = 1,2,3)}$$

$$1000 X_{CI} \geq 0 \text{ (I = 1,2)}$$

Also, at least \$100,000 must be invested in each of the eight stocks.

$$40 X_{S1} \geq 100000;$$

$$50 X_{S2} \geq 100000;$$

$$80 X_{S3} \geq 100000;$$

$$60 X_{H1} \geq 100000;$$

$$45 X_{H2} \geq 100000;$$

$$60 X_{H3} \geq 100000;$$

$$30 X_{C1} \geq 100000;$$

$$25 X_{C2} \geq 100000$$

Also, no more than 40% of the investment should be allocated to these 3 sectors

$$40 X_{S1} + 50 X_{S2} + 80 X_{S3} \leq 1000000$$

$$60 X_{H1} + 45 X_{H2} + 60 X_{H3} \leq 1000000$$

$$30 X_{C1} + 25 X_{C2} \leq 1000000$$

where  $X_{SI}, X_{HI}, X_{CI} \geq 0$  are integers.

```
library(lpSolveAPI)
lprec<-make.lp(0,8)
lp.control(lprec,sense="max")
```

```
## $anti.degen
## [1] "fixedvars" "stalling"
##
## $basis.crash
## [1] "none"
##
## $bb.depthlimit
## [1] -50
##
## $bb.floorfirst
## [1] "automatic"
##
```

```

## $bb.rule
## [1] "pseudononint" "greedy"      "dynamic"      "rcostfixing"
##
## $break.at.first
## [1] FALSE
##
## $break.at.value
## [1] 1e+30
##
## $epsilon
##      epsb      epsd      epsel      epsint  epsperturb  epspivot
##      1e-10      1e-09      1e-12      1e-07      1e-05      2e-07
##
## $improve
## [1] "dualfeas" "thetagap"
##
## $infinite
## [1] 1e+30
##
## $maxpivot
## [1] 250
##
## $mip.gap
## absolute relative
##      1e-11      1e-11
##
## $negrange
## [1] -1e+06
##
## $obj.in.basis
## [1] TRUE
##
## $pivoting
## [1] "devex"      "adaptive"
##
## $presolve
## [1] "none"
##
## $scalelimit
## [1] 5
##
## $scaling
## [1] "geometric"  "equilibrate" "integers"
##
## $sense
## [1] "maximize"
##
## $simplextype
## [1] "dual"      "primal"
##
## $timeout
## [1] 0
##
## $verbose

```

```
## [1] "neutral"
```

```
set.objfn(lprec,c(4,6.5,5.9,5.4,5.15,10,8.4,6.25))
set.type(lprec,c(1:8),type = "integer")
add.constraint(lprec,c(40,50,80,60,45,60,30,25), "<=", 2500000, indices = c(1:8))
add.constraint(lprec,1000,">=",0,indices = 1)
add.constraint(lprec,1000,">=",0,indices = 2)
add.constraint(lprec,1000,">=",0,indices = 3)
add.constraint(lprec,1000,">=",0,indices = 4)
add.constraint(lprec,1000,">=",0,indices = 5)
add.constraint(lprec,1000,">=",0,indices = 6)
add.constraint(lprec,1000,">=",0,indices = 7)
add.constraint(lprec,1000,">=",0,indices = 8)
add.constraint(lprec,40,">=",100000,indices = 1)
add.constraint(lprec,50,">=",100000,indices = 2)
add.constraint(lprec,80,">=",100000,indices = 3)
add.constraint(lprec,60,">=",100000,indices = 4)
add.constraint(lprec,45,">=",100000,indices = 5)
add.constraint(lprec,60,">=",100000,indices = 6)
add.constraint(lprec,30,">=",100000,indices = 7)
add.constraint(lprec,25,">=",100000,indices = 8)
add.constraint(lprec,c(40,50,80), "<=", 1000000, indices = c(1,2,3))
add.constraint(lprec,c(60,45,60), "<=", 1000000, indices = c(4,5,6))
add.constraint(lprec,c(30,25), "<=", 1000000, indices = c(7,8))
solve(lprec)
```

```
## [1] 0
```

```
get.objective(lprec)
```

```
## [1] 487145.2
```

```
get.variables(lprec)
```

```
## [1] 2500 6000 1250 1667 2223 13332 30000 4000
```

```
get.constraints(lprec)
```

```
## [1] 2499975 2500000 6000000 1250000 1667000 2223000 13332000 30000000
## [9] 4000000 100000 300000 100000 100020 100035 799920 900000
## [17] 100000 500000 999975 1000000
```

Using lpsolve with integer restriction we get the objective function, maximum returns as 487145.2 and number of stocks are S1= 2500, S2= 6000, S3= 1250, H1= 1667, H2= 2223, H3= 13332, C1= 30000, C2= 4000.

The amount that is invested in each stock S1= 100000, S2= 300000, S3= 100000, H1= 100020, H2= 100035, H3= 799920, C1= 900000, C2= 100000.

2) Compare the solution in which there is no integer restriction on the number of shares invested. By how much (in percentage terms) do the integer restrictions alter the value of the optimal objective function? By how much (in percentage terms) do they alter the optimal investment quantities?

**Solution:**

```
library(lpSolveAPI)
lprec<-make.lp(0,8)
lp.control(lprec,sense="max")
```

```
## $anti.degen
## [1] "fixedvars" "stalling"
##
## $basis.crash
## [1] "none"
##
## $bb.depthlimit
## [1] -50
##
## $bb.floorfirst
## [1] "automatic"
##
## $bb.rule
## [1] "pseudononint" "greedy"      "dynamic"      "rcostfixing"
##
## $break.at.first
## [1] FALSE
##
## $break.at.value
## [1] 1e+30
##
## $epsilon
##      epsb      epsd      epsel      epsint  epsperturb  epspivot
##      1e-10      1e-09      1e-12      1e-07      1e-05      2e-07
##
## $improve
## [1] "dualfeas" "thetagap"
##
## $infinite
## [1] 1e+30
##
## $maxpivot
## [1] 250
##
## $mip.gap
## absolute relative
##      1e-11      1e-11
##
## $negrange
## [1] -1e+06
##
## $obj.in.basis
## [1] TRUE
##
## $pivoting
## [1] "devex"      "adaptive"
##
## $presolve
## [1] "none"
```



```

##
## $scalelimit
## [1] 5
##
## $scaling
## [1] "geometric" "equilibrate" "integers"
##
## $sense
## [1] "maximize"
##
## $simplextype
## [1] "dual" "primal"
##
## $timeout
## [1] 0
##
## $verbose
## [1] "neutral"

set.objfn(lprec,c(4,6.5,5.9,5.4,5.15,10,8.4,6.25))
add.constraint(lprec,c(40,50,80,60,45,60,30,25),"<=",2500000,indices = c(1:8))
add.constraint(lprec,1000,">=",0,indices = 1)
add.constraint(lprec,1000,">=",0,indices = 2)
add.constraint(lprec,1000,">=",0,indices = 3)
add.constraint(lprec,1000,">=",0,indices = 4)
add.constraint(lprec,1000,">=",0,indices = 5)
add.constraint(lprec,1000,">=",0,indices = 6)
add.constraint(lprec,1000,">=",0,indices = 7)
add.constraint(lprec,1000,">=",0,indices = 8)
add.constraint(lprec,40,">=",100000,indices = 1)
add.constraint(lprec,50,">=",100000,indices = 2)
add.constraint(lprec,80,">=",100000,indices = 3)
add.constraint(lprec,60,">=",100000,indices = 4)
add.constraint(lprec,45,">=",100000,indices = 5)
add.constraint(lprec,60,">=",100000,indices = 6)
add.constraint(lprec,30,">=",100000,indices = 7)
add.constraint(lprec,25,">=",100000,indices = 8)
add.constraint(lprec,c(40,50,80),"<=",1000000,indices = c(1,2,3))
add.constraint(lprec,c(60,45,60),"<=",1000000,indices = c(4,5,6))
add.constraint(lprec,c(30,25),"<=",1000000,indices = c(7,8))
solve(lprec)

## [1] 0

get.objective(lprec)

## [1] 487152.8

get.variables(lprec)

## [1] 2500.000 6000.000 1250.000 1666.667 2222.222 13333.333 30000.000
## [8] 4000.000

```

```
get.constraints(lprec)
```

```
## [1] 2500000 2500000 6000000 1250000 1666667 2222222 13333333 30000000
## [9] 4000000 100000 300000 100000 100000 100000 800000 900000
## [17] 100000 500000 1000000 1000000
```

Using lpsolve without integer restriction we get the objective function, maximum returns as 487152.8 and number of stocks are S1= 2500.0, S2= 6000.0, S3= 1250.0, H1= 1666.667, H2= 2222.222, H3= 13333.333, C1= 30000.0, C2= 4000.0

The amount that is invested in each stock S1= 100000, S2= 300000, S3= 100000, H1= 100000, H2= 100000, H3= 800000, C1= 900000, C2= 100000.

The Percentage difference in objective functions with and without integer restriction is 0.00156