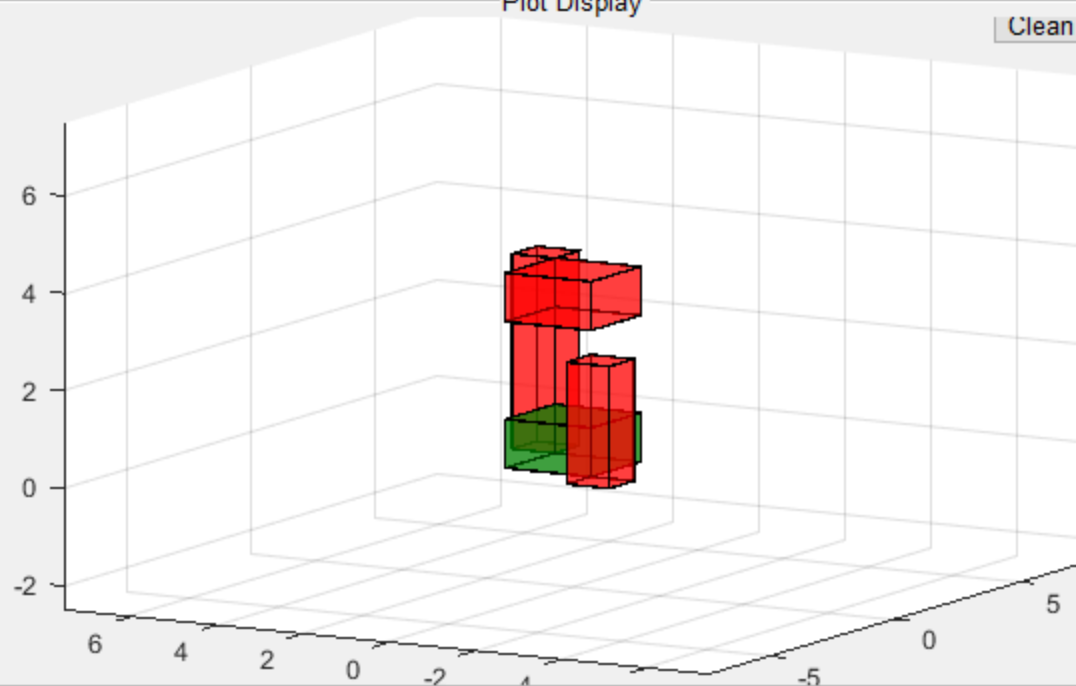




Plot Display

[Clean Map](#)

Mission Planner

Map :
of drones :
of goals :
of ext obs :
Smooth (C) : Time between waypoints (s) :
No. of Waypoints :
Samp. Time (s) :
Drone Sep. (m) :
Mission

Mission Info

Mission : Missio
Status : Ready
Robustness : 0.499
Time (s) : 20.0

	Drones	Start	v & a	Goal1
1	Drone1	[0,0,2]	[0 5; ...	
2	Drone2	[3,-3,3]	[0 15]	
3	Drone3	[3,3,3]	[7 10]	

	Goals
1	[-1,-1,0,1,1,1]

	Obstacles
1	[-1,-1,3,1,1,4]

Control