



Mission Planner

Map :	Empty_map....	No. of Waypoints :	24	Mission Name	patrol
# of drones :	4	Samp. Time (s) :	0.05	Solver	
# of goals :	2	Drone Sep. (m) :	0.25	<input checked="" type="radio"/> Matlab Sol...	Load Mission
# of ext_obs :	2			<input type="radio"/> C++ Sol...	patrol.mat
Smooth (C) :	30	Time between waypoints (s) :	1		Load to Planner

Mission Info

Mission : patrol
Status : Ready
Robustness : 0.000
Time (s) : 0.00

Control

Plan Mission

Plot Mission

Save Mission

	Drones	Start	v & a	Goal1	Goal2
1	Drone1	[-1.5,-...	[2 2]	[0 6;12 18]	[6 12;18 ...
2	Drone2	[-1.5,+...	[2 2]	[0 6;12 18]	[6 12;18 ...
3	Drone3	[+1.5,-...	[2 2]	[6 12;18 ...	[0 6;12 18]
4	Drone4	[+1.5,...	[2 2]	[6 12;18 ...	[0 6;12 18]

	Goals
1	[1,1,1,1.5,1.5,1.5
2	[-1.5,-1.5,1,-1,-...

	Obstacles
1	[-0.5,-0.5,0,0.5,...