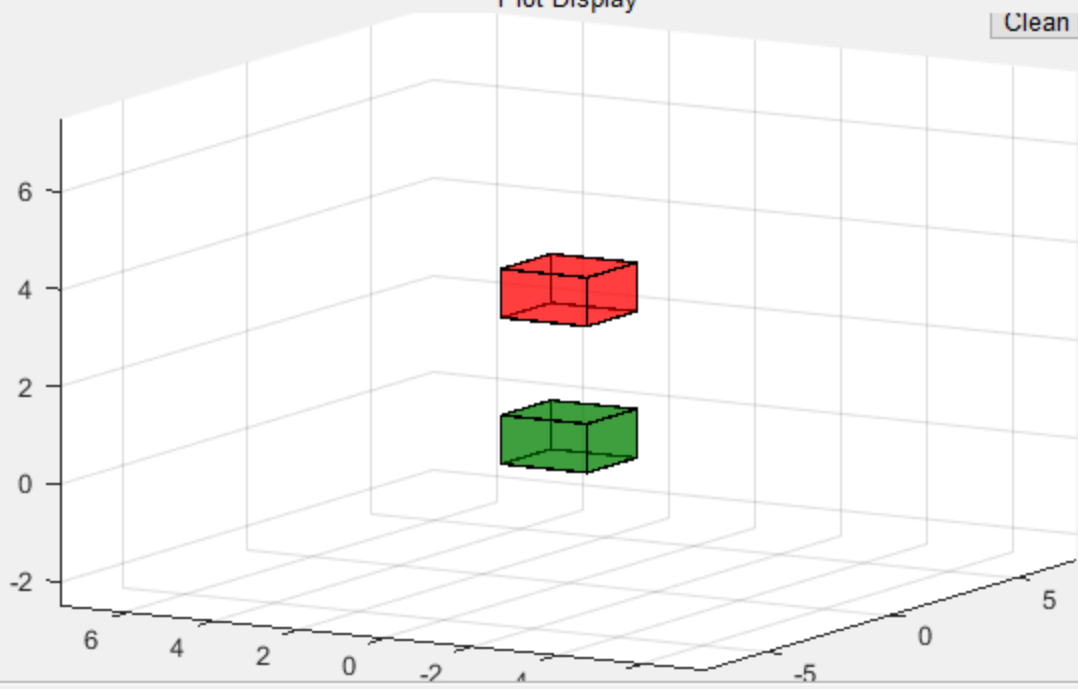




Plot Display

Clean Map



Mission Planner

Map : Empty_m...
of drones : 1
of goals : 1
of ext obs : 1
Smooth (C) : 2

No. of Waypoints : 20
Samp. Time (s) : 0.05
Drone Sep. (m) : 0.1
Time between waypoints (s) : 1

Mission

Load Mission Mission1.mat

Load to Planner

Mission Info

Mission :
Status : Not Ready
Robustness : 0.000
Time (s) : 0.00

Control

Plan Mission
Plot Mission
Save Mission

| | Drones | s | v & a | Goal1 |
|---|--------|------|-------|-------------|
| 1 | Drone1 | [2,2 | 2 4] | [0 5; 5 10] |

| | Goals |
|---|-----------------|
| 1 | [-1,-1,0,1,1,1] |

| | Obstacles |
|---|-----------------|
| 1 | [-1,-1,3,1,1,4] |