1[true]: tp=0, truck_balance=A

H(basictruck):C(garbage_bin).bid(e,H(basictruck))

H(basictruck).LOST[C(garbage_bin).](e)

2[true]: tp=0, truck_balance=(A + -e)

H(basictruck).WIN[C(garbage_bin).]()

H(basictruck):C(garbage_bin).empty(H(basictruck))

3[true]: tp=0, truck_balance=(A + -e)