college-assignment (/github/sachi1406/college-assignment/tree/main)
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IP Expt 6 Sachi Shah.ipynb (/github/sachi1406/college-assignment/tree/main/IP Expt 6 Sachi Shah.ipynb)

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IP-Experiment Number 6

Edge Detection using Sobel Mask

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Aim:

- 1. Apply Sobel's mask on the given test image to obtain component of gradient $|g_x|,|g_y|$ and $|g_x+g_y|$.
- 2. Apply 5x5 averaging filter on the test image and then implement the sequence in step a.
- 3. Summarize your observations after comparing the results obtained in step a and b.

Import Libraries

In []:

```
import cv2
from skimage import io
import matplotlib.pyplot as plt
import numpy as np
from scipy import signal
```

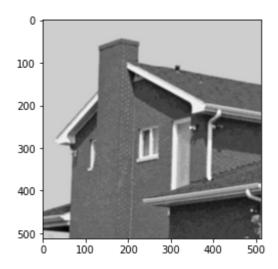
Theory:

The Sobel operator performs a 2-D spatial gradient measurement on an image and so emphasizes regions of high spatial frequency that correspond to edges.

```
# Load the image house.tiff and read the same
img = cv2.imread('house.tif', 0)
plt.imshow(img, cmap='gray')
```

Out[]:

<matplotlib.image.AxesImage at 0x7fa7160f3750>



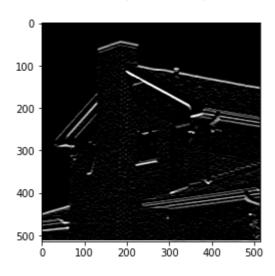
Sobel operator for horizontal edges

-1	-2	-1
0	0	0
1	2	1

```
#Detect horizontal edges using in built convolution function
mask_hor = [[-1,-2,-1],[0,0,0],[1,2,1]]
hor = signal.convolve2d(img,mask_hor)
plt.imshow(hor,cmap = 'gray',vmin = 0,vmax = 255)
```

Out[]:

<matplotlib.image.AxesImage at 0x7fa715b84c10>



Sobel operator for vertical edges

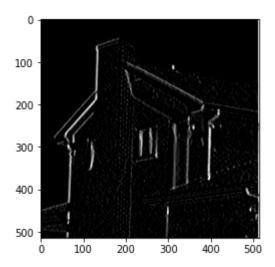
-1	0	1
-2	0	2
-1	0	1

In []:

```
#Detect vertical edges using inbuilt function for convolution
mask_ver = [[-1,0,1],[-2,0,2],[-1,0,1]]
ver = signal.convolve2d(img,mask_ver)
plt.imshow(ver,cmap = 'gray',vmin = 0,vmax = 255)
```

Out[]:

<matplotlib.image.AxesImage at 0x7fa715af72d0>



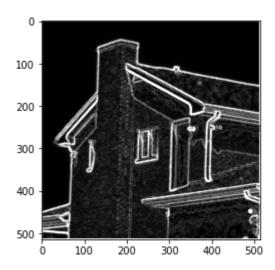
Detecting vertical and horizontal edges using |gx|+|gy|

In []:

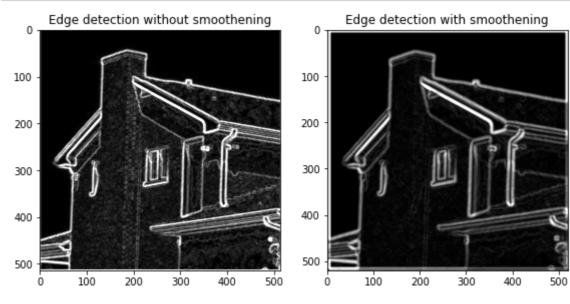
```
#Detecting vertical and horizontal edges
final = abs(hor) + abs(ver)
plt.imshow(final,cmap = 'gray',vmin = 0,vmax = 255)
```

Out[]:

<matplotlib.image.AxesImage at 0x7fa714fc95d0>



```
#remove fine details
#effect of smoothening and then performing edge detection
#smoothening
mask = np.ones((7,7),dtype = int)
mask_s = mask/49
smooth = signal.convolve2d(img,mask_s)
mask_hor = [[-1,-2,-1],[0,0,0],[1,2,1]]
hor_smoothened = signal.convolve2d(smooth,mask_hor)
mask_ver = [[-1,0,1],[-2,0,2],[-1,0,1]]
ver_smoothened = signal.convolve2d(smooth,mask_ver)
output_after_smoothening = abs(hor_smoothened) + abs(ver_smoothened)
plt.figure(figsize=(8,8))
plt.subplot(121)
plt.imshow(final,cmap='gray',vmin = 0,vmax = 255)
plt.title('Edge detection without smoothening')
plt.subplot(122)
plt.imshow(output_after_smoothening,cmap='gray',vmin = 0,vmax = 255)
plt.title('Edge detection with smoothening')
plt.tight_layout()
```

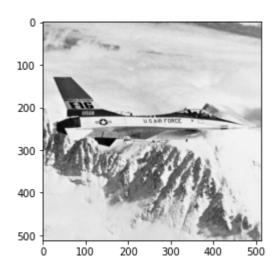


Students have to perform all the above steps for jetplane.tif image

```
# load the jetplane.tif image and read the same
img_jet = cv2.imread('jetplane.tif', 0)
plt.imshow(img_jet, cmap='gray')
```

Out[]:

<matplotlib.image.AxesImage at 0x7fa711b44910>

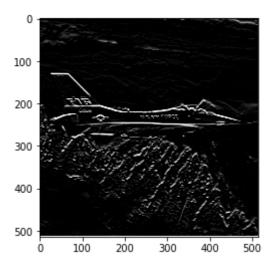


In []:

```
#Detect horizontal edges using in built convolution function
mask_hor_jet = [[-1,-2,-1],[0,0,0],[1,2,1]]
hor_jet = signal.convolve2d(img_jet,mask_hor_jet)
plt.imshow(hor_jet,cmap = 'gray',vmin = 0,vmax = 255)
```

Out[]:

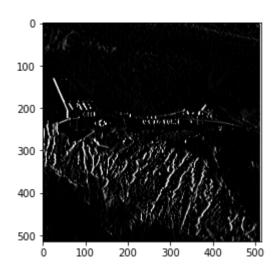
<matplotlib.image.AxesImage at 0x7fa711a96c50>



```
#Detect vertical edges using inbuilt function for convolution
mask_ver_jet = [[-1,0,1],[-2,0,2],[-1,0,1]]
ver_jet = signal.convolve2d(img_jet,mask_ver_jet)
plt.imshow(ver_jet,cmap = 'gray',vmin = 0,vmax = 255)
```

Out[]:

<matplotlib.image.AxesImage at 0x7fa711a0a410>



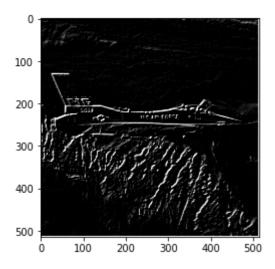
In []:

```
# Detecting Diagonal with inbuilt convolve (forward Diagonal)

mask_diag_forward = [[-2,-1,0],[-1,0,1],[0,1,2]]
diag_forward = signal.convolve2d(img_jet,mask_diag_forward)
plt.imshow(diag_forward,cmap = 'gray',vmin = 0,vmax = 255)
```

Out[]:

<matplotlib.image.AxesImage at 0x7fa711915e90>



Backward diagonal edges

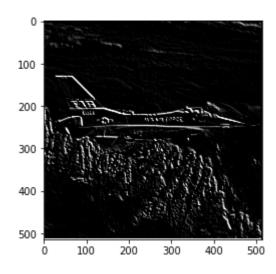
0	-1	-2
1	0	-1
2	1	0

```
# Detecting Diagonal with inbuilt convolve (Backward Diagonal)

mask_diag_backward = [[0,-1,-2],[1,0,-1],[2,1,0]]
diag_backward = signal.convolve2d(img_jet,mask_diag_backward)
plt.imshow(diag_backward,cmap = 'gray',vmin = 0,vmax = 255)
```

Out[]:

<matplotlib.image.AxesImage at 0x7fa711882950>

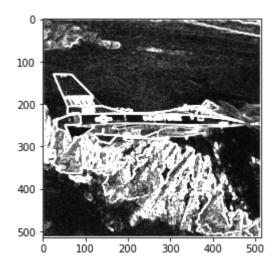


Edge in all four directions

#Horizontal, vertical and diagonal edges
final_jet = abs(hor_jet) + abs(ver_jet) + abs(diag_forward) + abs(diag_backward)
plt.imshow(final_jet,cmap = 'gray',vmin = 0,vmax = 255)

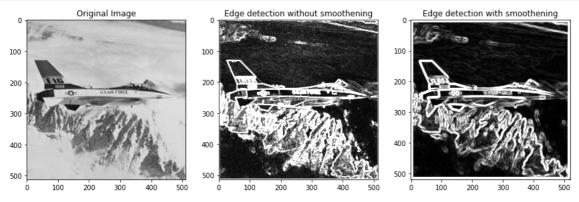
Out[]:

<matplotlib.image.AxesImage at 0x7fa709b99310>



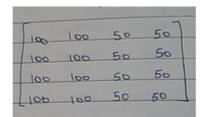
```
In [ ]:
```

```
#remove fine details
#effect of smoothening and then performing edge detection
#smoothening
mask = np.ones((7,7), dtype = int)
mask_s = mask/49
smooth_jet = signal.convolve2d(img_jet,mask_s)
jet_mask_hor = [[-1,-2,-1],[0,0,0],[1,2,1]]
jet_hor_smoothened = signal.convolve2d(smooth_jet,jet_mask hor)
jet_mask_ver = [[-1,0,1],[-2,0,2],[-1,0,1]]
jet_ver_smoothened = signal.convolve2d(smooth_jet,jet_mask_ver)
jet_mask_diag_backward = [[0,-1,-2],[1,0,-1],[2,1,0]]
jet_diag_backward_smoothened = signal.convolve2d(smooth_jet,jet_mask_diag_backward)
jet_mask_diag_forward = [[-2,-1,0],[-1,0,1],[0,1,2]]
jet_diag_forward_smoothened = signal.convolve2d(smooth_jet,jet_mask_diag_forward)
output_after_smoothening_jet = abs(jet_hor_smoothened) + abs(jet_ver_smoothened) + abs
plt.figure(figsize=(12,12))
plt.subplot(131)
plt.imshow(img_jet,cmap='gray',vmin = 0,vmax = 255)
plt.title('Original Image')
plt.subplot(132)
plt.imshow(final_jet,cmap='gray',vmin = 0,vmax = 255)
plt.title('Edge detection without smoothening')
plt.subplot(133)
plt.imshow(output_after_smoothening_jet,cmap='gray',vmin = 0,vmax = 255)
plt.title('Edge detection with smoothening')
plt.tight_layout()
```



The following question has to be solved by students. Scan and copy-paste the answer here.

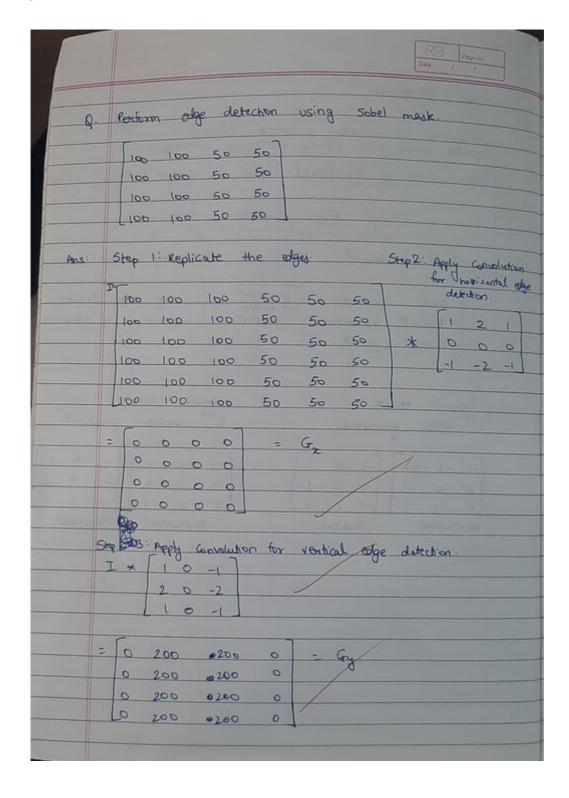
Q. consider the given image matrix

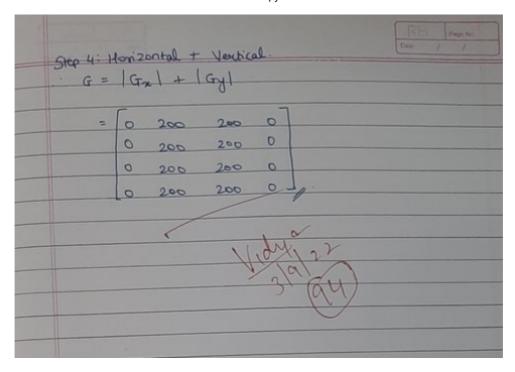


Replicate the edges and apply sobel mask to detect the gradient in :

(i) horizontal firection (ii) vertical direction (iii) horizonatla and vertical direction

Answer





Conclusion:

- 1. We implemented the code for edge detection using Sobel Mask. Sobel mask is based on second order derivative.
- 2. We detected the horizontal, vertical and diagonal edges of the given image however the sobel mask also detects the minute details that are sometimes unrequired.
- 3. These can be removed by first smoothening the image using the average filter and then doing edge detection.