

# *Conditional Random Fields*

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# Practice Question

Suppose you want to use a MaxEnt tagger to tag the sentence, “the light book”. We know that the top 2 POS tags for the words *the*, *light* and *book* are  $\{Det, Noun\}$ ,  $\{Verb, Adj\}$  and  $\{Verb, Noun\}$ , respectively. Assume that the MaxEnt model uses the following history  $h_i$  (context) for a word  $w_i$ :

$$h_i = \{w_i, w_{i-1}, w_{i+1}, t_{i-1}\}$$

where  $w_{i-1}$  and  $w_{i+1}$  correspond to the previous and next words and  $t_{i-1}$  corresponds to the tag of the previous word. Accordingly, the following features are being used by the MaxEnt model:

- $f_1: t_{i-1} = Det$  and  $t_i = Adj$
- $f_2: t_{i-1} = Noun$  and  $t_i = Verb$
- $f_3: t_{i-1} = Adj$  and  $t_i = Noun$
- $f_4: w_{i-1} = the$  and  $t_i = Adj$
- $f_5: w_{i-1} = the \& w_{i+1} = book$  and  $t_i = Adj$
- $f_6: w_{i-1} = light$  and  $t_i = Noun$
- $f_7: w_{i+1} = light$  and  $t_i = Det$
- $f_8: w_{i-1} = NULL$  and  $t_i = Noun$

Assume that each feature has a uniform weight of 1.0.

Use Beam search algorithm with a beam-size of 2 to identify the highest probability tag sequence for the sentence.

# *Problem with Maximum Entropy Models*

## *Per-state normalization*

All the mass that arrives at a state must be distributed among the possible successor states

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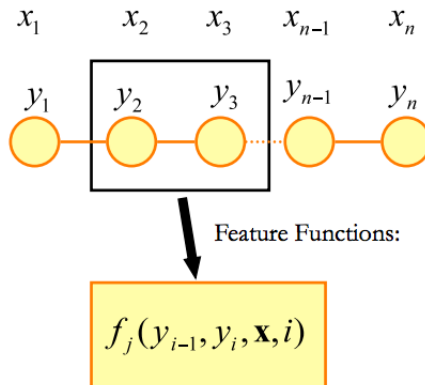
All the mass that arrives at a state must be distributed among the possible successor states

*This gives a 'label bias' problem*

Let's see the intuition (on paper)

- CRFs are conditionally trained, undirected graphical models.
- Let's look at the linear chain structure

# Conditional Random Fields: Feature Functions



Express some characteristic of the empirical distribution  
that we wish to hold in the model distribution

$$f_j(y_{i-1}, y_i, \mathbf{x}, i)$$

1 if  $y_{i-1} = IN$  and  
 $y_i = NNP$  and  
 $x_i = September$

0 otherwise

# Conditional Random Fields: Distribution

Label sequence modelled as a normalized product of feature functions:

$$P(\mathbf{y} \mid \mathbf{x}, \boldsymbol{\lambda}) = \frac{1}{Z(\mathbf{x})} \exp \sum_{i=1}^n \sum_j \lambda_j f_j(y_{i-1}, y_i, \mathbf{x}, i)$$

$$Z(\mathbf{x}) = \sum_{\mathbf{y} \in Y} \sum_{i=1}^n \sum_j \lambda_j f_j(y_{i-1}, y_i, \mathbf{x}, i)$$



- Have the advantages of MEMM but avoid the label bias problem
- CRFs are globally normalized, whereas MEMMs are locally normalized.
- Widely used and applied. CRFs have been (close to) state-of-the-art in many sequence labeling tasks.