

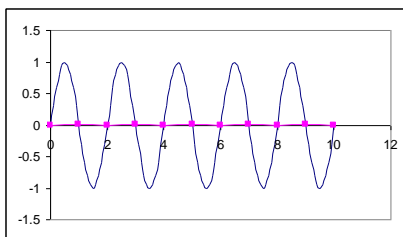
Unit-V

Pulse Communications

Sampling

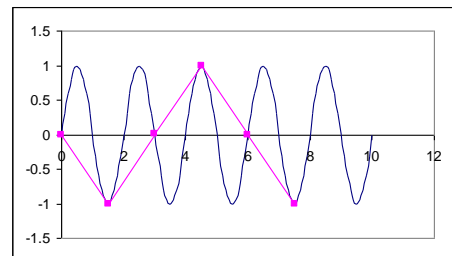
- It is process which converts continuous time continuous valued signal to discrete time continuous valued signal.
- Sampling rate, $f_s \geq 2f_m$
 f_m – frequency of the signal to be sampled

Poor Sampling



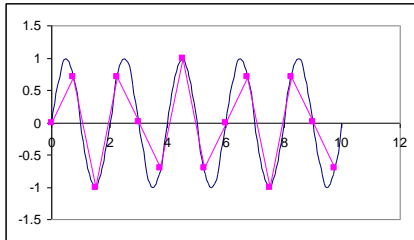
Sampling Frequency = $1/2 \times$ Wave Frequency

Even Worse



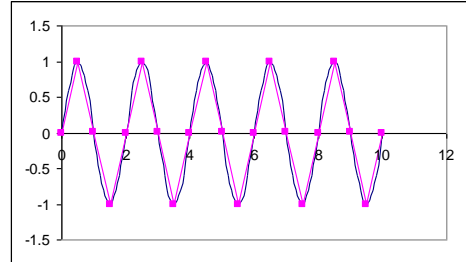
Sampling Frequency = $1/3 \times$ Wave Frequency

Higher Sampling Frequency



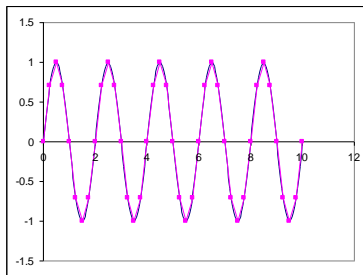
Sampling Frequency = $2/3$ Wave Frequency

Getting Better



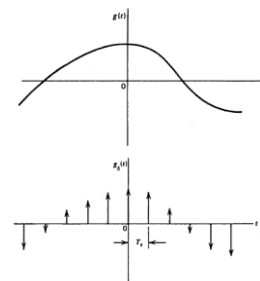
Sampling Frequency = Wave Frequency

Good Sampling



Sampling Frequency = $2 \times$ Wave Frequency

Sampling Process



Contd...

From the definition of a delta function, we have

$$g(nT_s) \delta(t - nT_s) = g(t) \delta(t - nT_s)$$

$$\begin{aligned} g_\delta(t) &= g(t) \sum_{n=-\infty}^{\infty} \delta(t - nT_s) \\ &= g(t) \delta_{T_s}(t) \end{aligned}$$

$\delta_{T_s}(t)$ is the Dirac comb or ideal sampling function

Contd...

$$F[\delta_{T_s}(t)] = f_s \sum_{m=-\infty}^{\infty} \delta(f - mf_s)$$

$$G_\delta(f) = G(f) \star \left[f_s \sum_{m=-\infty}^{\infty} \delta(f - mf_s) \right]$$

$$G_\delta(f) = f_s \sum_{m=-\infty}^{\infty} G(f) \star \delta(f - mf_s)$$

$$G_\delta(f) = f_s \sum_{m=-\infty}^{\infty} G(f - mf_s)$$

process of uniformly sampling a signal in the time domain results in a periodic spectrum in the frequency domain with a period equal to the sampling rate.

Contd..

$$G_\delta(f) = \sum_{n=-\infty}^{\infty} g(nT_s) \exp(-j2\pi n f T_s)$$

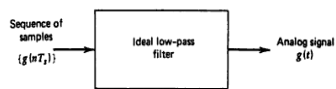
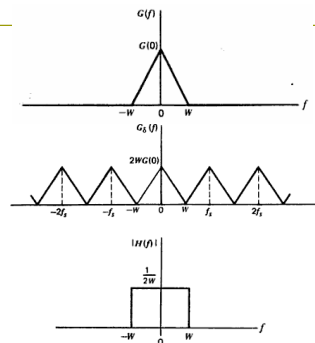


Figure Reconstruction filter.

Contd...



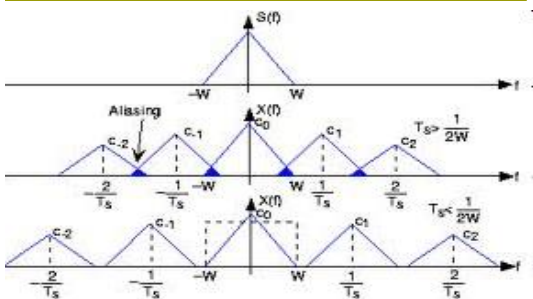
Sampling Theorem

1. If a finite-energy signal $g(t)$ contains no frequencies higher than W hertz, it is completely determined by specifying its ordinates at a sequence of points spaced $1/2W$ seconds apart.
2. If a finite energy signal $g(t)$ contains no frequencies higher than W hertz, it may be completely recovered from its ordinates at a sequence of points spaced $1/2W$ seconds apart.

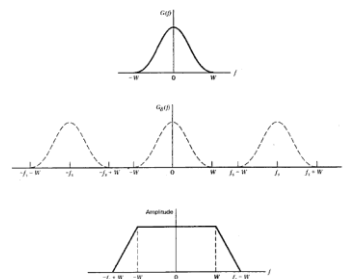
Aliasing or Foldover

- HF component in the spectrum of signal taking identity of a LF in the spectrum of its sampled version
- Pre-Alias Filter
- $f_s > 2W$
- Physically realizable reconstruction filter

Contd...



Contd....

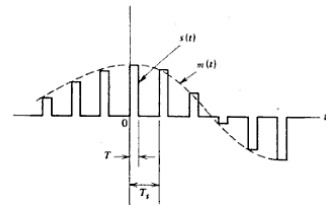


Types of Pulse Modulation

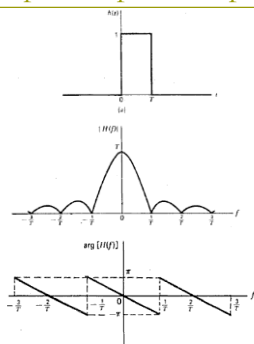
- ▣ Pulse Amplitude Modulation
- ▣ Pulse Width/Duration/Length Modulation
- ▣ Pulse Position Modulation

Pulse Amplitude Modulation

- ▣ The amplitude of regularly spaced pulses are varied in proportion to the corresponding sample values of a continuous message signal



Rectangular pulse, spectrum, phase



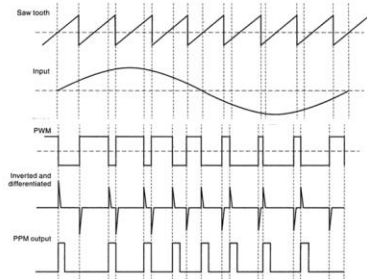
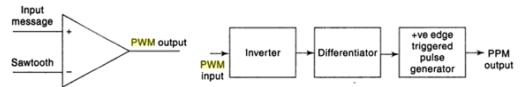
PAM

- ▣ Derivation- generation
- ▣ Aperture Effect

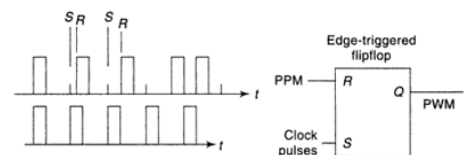
PPM/PWM

- Definition
- Generation and detection- Refer Principles of Communication by Taub and Schilling or Communication Systems by Simon Haykins

PWM/PPM

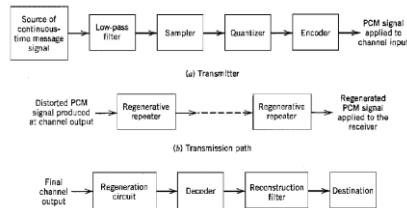


PPM to PWM



Pulse Code Modulation (PCM)

In PCM, a message signal is represented by a sequence of coded pulses, which is accomplished by representing the signal in discrete form in both time and amplitude



Quantization

Process in which discrete-time continuous amplitude signal is converted to discrete-time discrete amplitude signal

Rounding off to the nearest Integer

Types – Uniform
Non- Uniform

Uniform Quantization

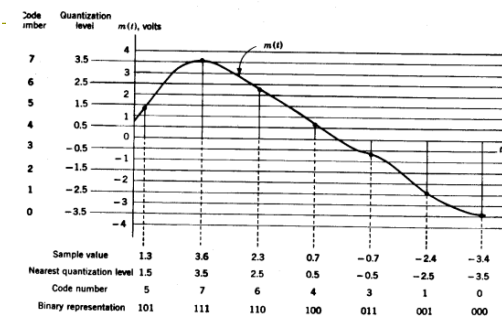


Figure 5.9-1 A message signal is regularly sampled. Quantization levels are indicated. For each sample the quantized value is given and its binary representation is indicated

Encoding

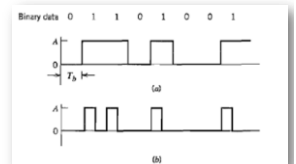
Electrical representation of binary data

NRZ-Full symbol width
RZ – Half symbol width

NRZ-Non-Return to Zero
RZ- Return to Zero

(a) NRZ – Unipolar
• 1- presence of pulse
• 0-absence of pulse

(b) RZ- Unipolar
• 1- presence of pulse for half symbol period
• 0-absence of pulse

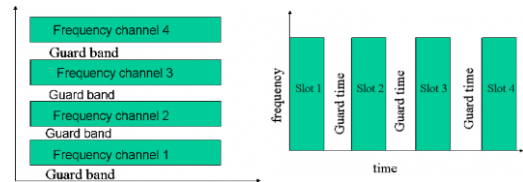


Regenerative Repeaters

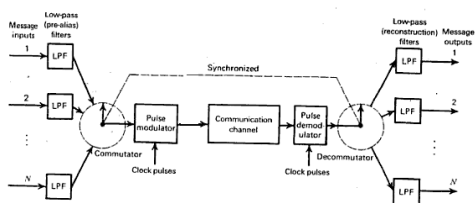
- ❑ Helps to control the effects of distortion and channel noise in PCM
- ❑ Reconstructing PCM signal from the transmitted signal
- ❑ Generates a clean pulse using equalization, timing, and decision making devices

Multiplexing

- ❑ Definition
A no. of independent signals are combined into a composite signal suitable for transmission over a common channel
- ❑ Types – TDM, FDM



Time Division Multiplexing



Frequency Division Multiplexing

- ❑ **Transmitter**
 - The signals from the N sources are shifted to another frequency range by modulation.
 - Usually SSB/SC is preferred
 - BPF filters are used to avoid any spill into the adjacent spectra.
- ❑ **Receiver**
 - Demodulation and BPF is done
 - Filtered signals send to respective destinations

Block Diagram

